

COMP 3311

DATABASE MANAGEMENT

SYSTEMS

LECTURE 13

INDEXING:

HASH INDEX & BITMAP INDEX

HASH INDEX

- Hashing can be used not only for file organization, but also for creating an index.
- A **hash index** organizes the search keys, with their associated record pointers, into a hash file organization.

 **Hash indexes are always secondary indexes.**

- If the file itself is organized using hashing, a separate **primary hash index** on it **using the same search-key** is not necessary.

WHY?

- The hash index discussed here is for relatively static tables.
 - We want to build a hash index for an existing table; we expect the number of records not to change too much.

EXAMPLE HASH INDEX

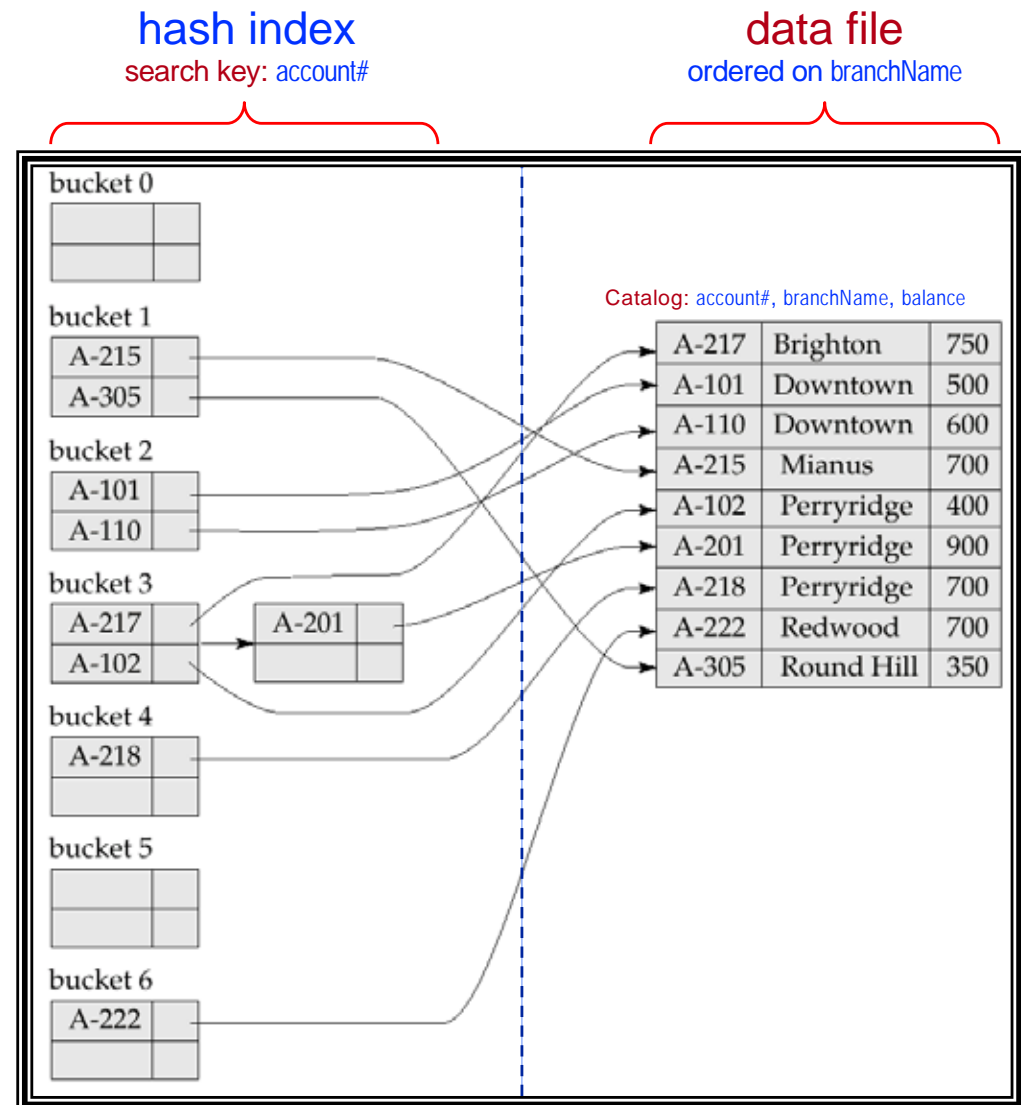
Issues to consider:

1. hash function

- We want **search-key values** to be **assigned** to pages **randomly**.
- Typical hash functions perform computation on the **internal binary representation** of the search key.

2. overflow

- We want to **avoid long chains** of overflow pages as this degrades performance.



STATIC HASHING FUNCTIONS

- In the worst case, the hash function maps all search-key values to the same page.
- This makes access time proportional to the number of search-key values in the file.
- The **ideal hash function is random**, so each page will have the same number of records assigned to it irrespective of the *actual distribution* of search-key values in the file.
- Typical hash functions perform computation on the internal binary representation of the search key.
 - For example, for a string search key, the binary representation of all the characters in the string could be added and the sum modulo the number of pages could be returned.

HANDLING Page OVERFLOWS

- Page overflow can occur because of
 - insufficient number of pages;
 - skew in the distribution of records, which can occur for two reasons.
 - Multiple records have the same search-key value.
 - The chosen hash function produces a non-uniform distribution of key values.
- Page overflow is handled by using *overflow pages*.
 - If overflow pages also overflow, they are **chained together in a linked list**.
 - Long chains degrade performance because a query must search all pages in the chain.

STATIC HASHING DEFICIENCIES

- In **static hashing**, a function h maps search-key values to **a fixed set B of page addresses**.
 - Databases usually grow over time.
 - If the initial number of fixed pages is too small, performance will degrade due to too many overflows.
 - If the file size at some point in the future is anticipated to grow and the number of pages allocated accordingly, a significant amount of space will be wasted initially.
 - If the database shrinks, again space will be wasted.
 - One option is periodic re-organization of the file with a new hash function, but this is very expensive. **WHY?**
- These problems can be avoided by using techniques that **allow dynamic modification of the hash function (i.e., dynamic modification of the number of pages)**.

DYNAMIC HASHING: EXTENDABLE HASHING

Situation

A page (primary page) becomes full and overflows.

Why not re-organize the file by *doubling the number of pages*?

👉 **However, reading and writing all pages is expensive!**

Idea

Use a directory of pointers to pages; to double the number of pages, *double the directory* and *split just the page that overflowed*.

- The directory is much smaller than the data file, so doubling it is much cheaper.
- Only one page of data entries is split. *No overflow page!*

👉 **The technique relies on how the hash function is adjusted!**

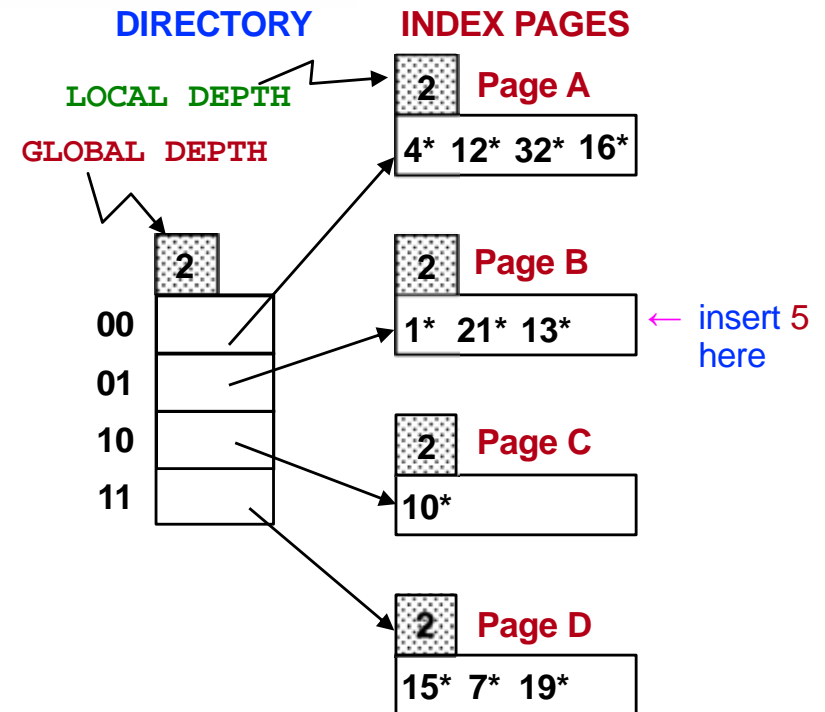
EXTENDABLE HASHING

Insertion: (page size is 4)

If r is the record to insert, first compute its hash $h(r)$.

To find the page to store r , use the right-most *global depth bits* of the binary representation of $h(r)$.

Example: If $h(r) = 5 \Rightarrow$ binary 101, r is stored in the page pointed to by 01 since global depth is 2 bits.



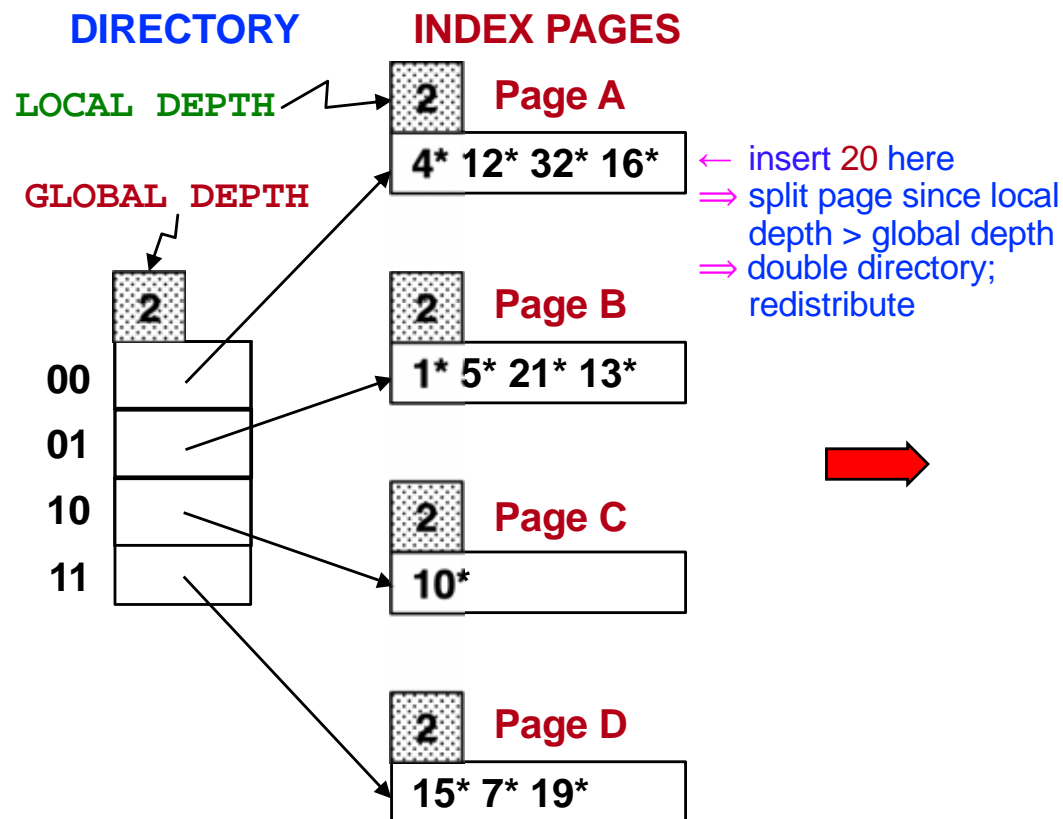
If a page is full, split it (*allocate a new page and redistribute*).

If necessary, double the directory. Splitting a page does not always require doubling the directory; to tell whether to double the directory, we **compare global depth with local depth for the split page**. If the local depth of the split page is greater than the global depth (i.e., we are using more bits in the page than in the directory), then the directory needs to be doubled.

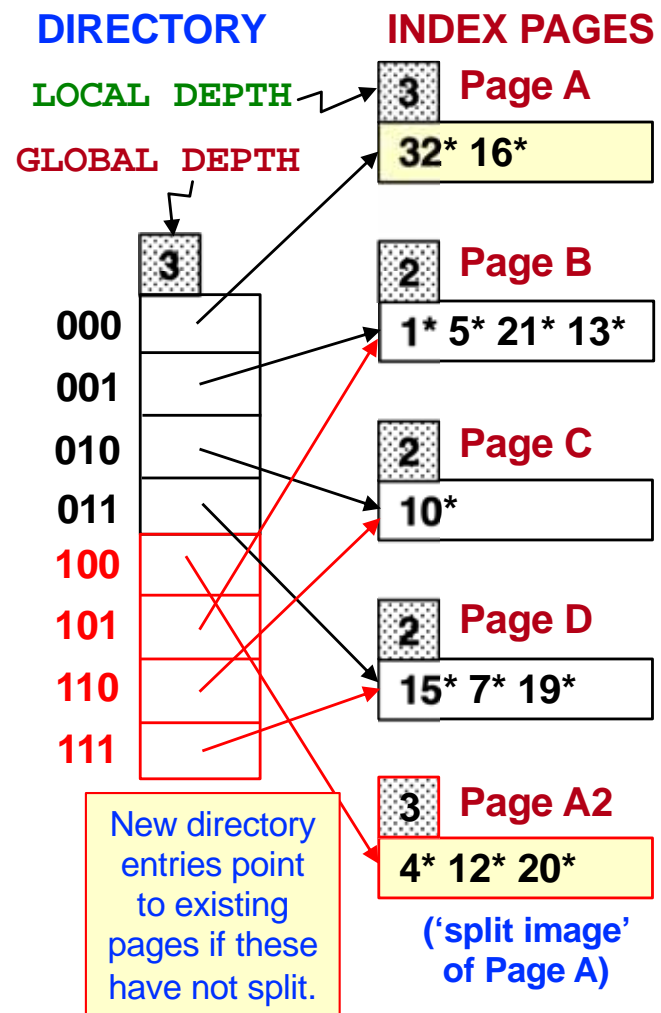
EXTENDABLE HASHING (CONTD)

Example: page splitting; directory doubling
(page size is 4)

Insert: $h(r)=20$ (100)



key value	4	12	16	32
binary value	100	100	000	000



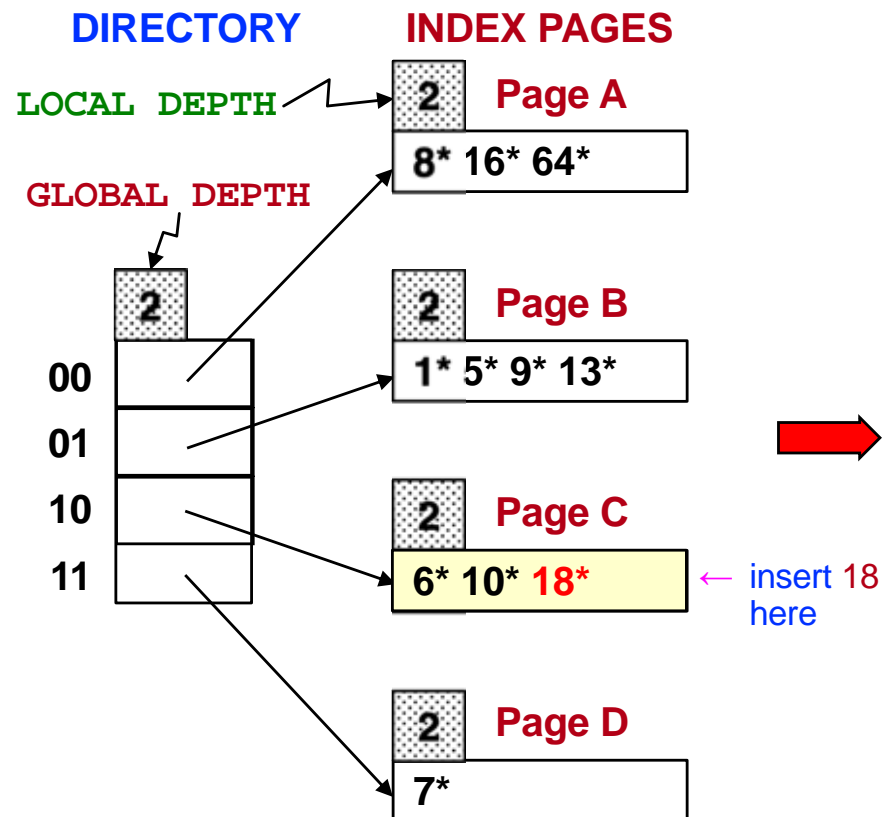
EXTENDABLE HASHING: POINTS TO NOTE

- 20 = binary 100. Last **2 bits** (00) tell us *r* belongs in **Page A** or **Page A2**. Last **3 bits** are needed to tell which page *r* belongs.
 - **Global depth of directory:** maximum number of bits needed to tell which page an entry belongs to.
 - **Local depth of a page:** number of bits used to determine if an entry belongs to this page.
- When does page split cause directory doubling?
 - Before an insert, *local depth* of page = *global depth*.
 - If an insert causes the *local depth* to become > *global depth*, the directory is doubled by *copying it* and ‘adjusting’ the pointer to the split image page.
 - Use of the least significant bits enables efficient doubling via copying of directory!

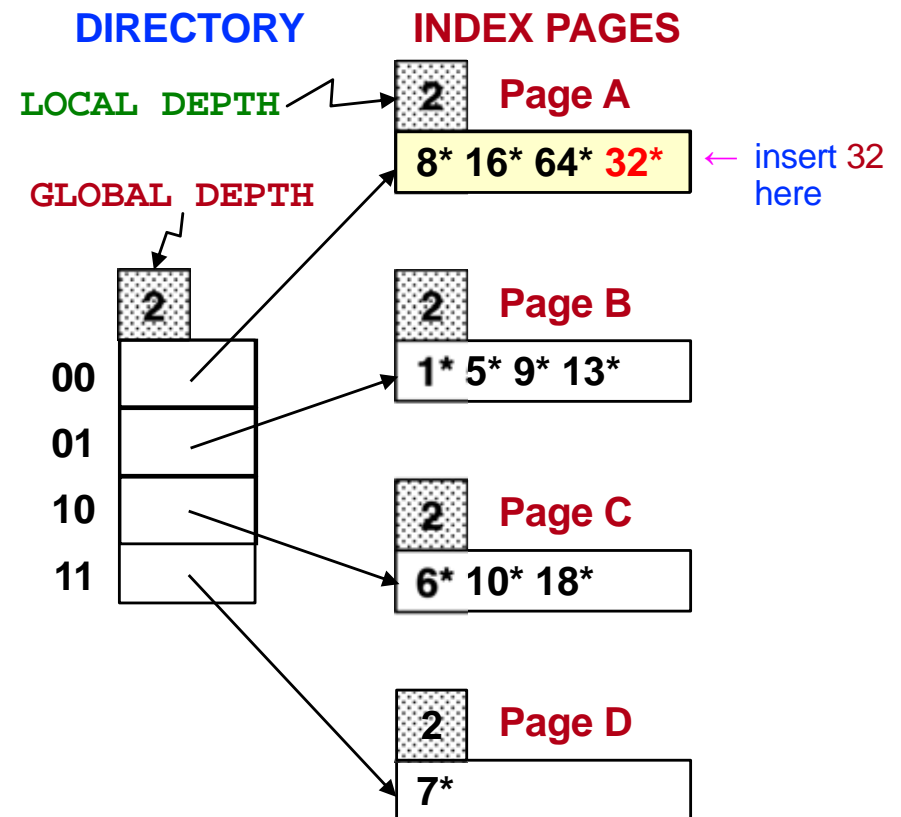
EXTENDABLE HASHING EXAMPLE

Consider insertions on the following hash index where the hash function is determined by the **least significant (right-most) bits**.

Insert: 18 (10)

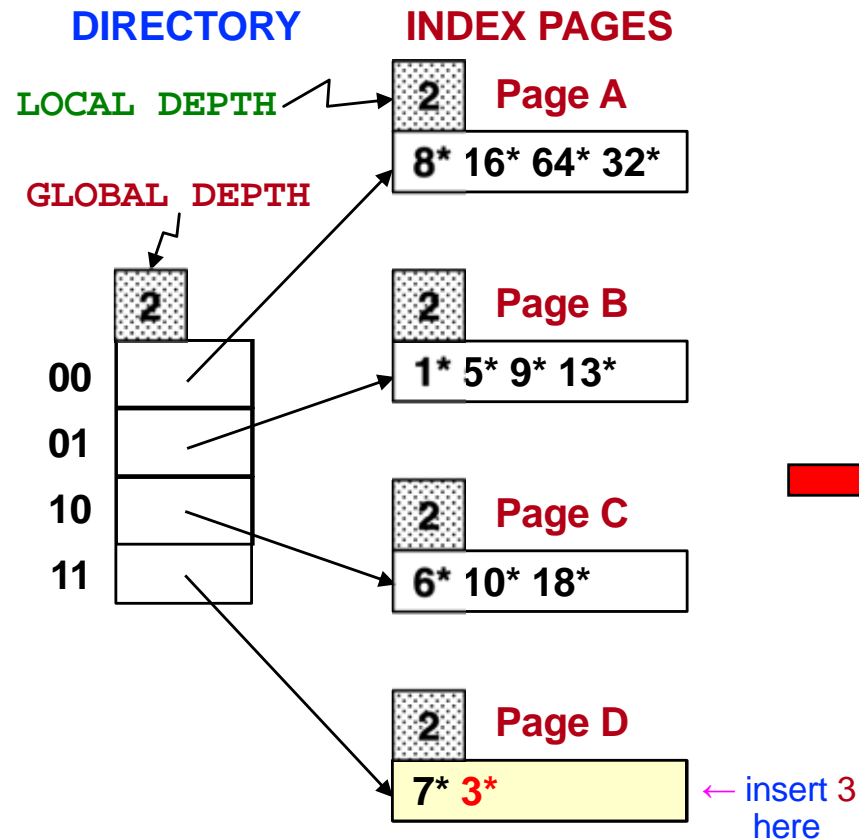


Insert: 32 (00)



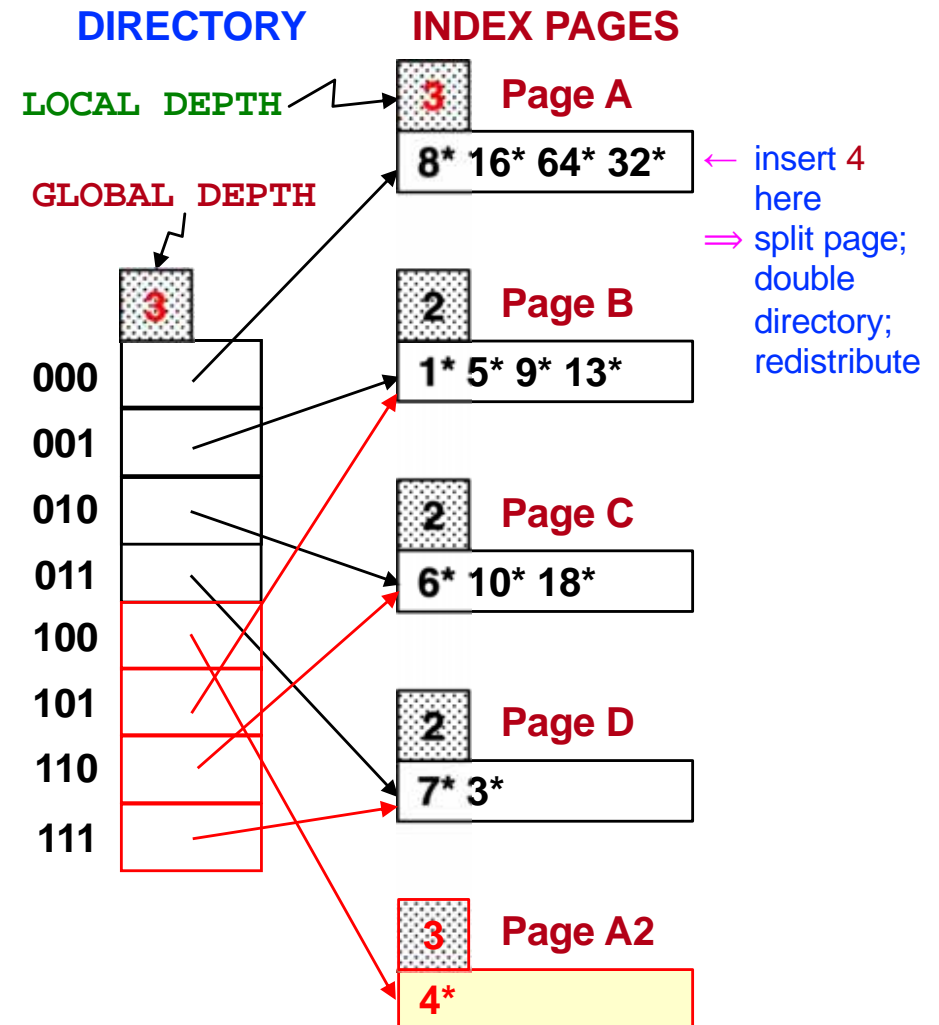
EXTENDABLE HASHING EXAMPLE (CONTD)

Insert: 3 (11)

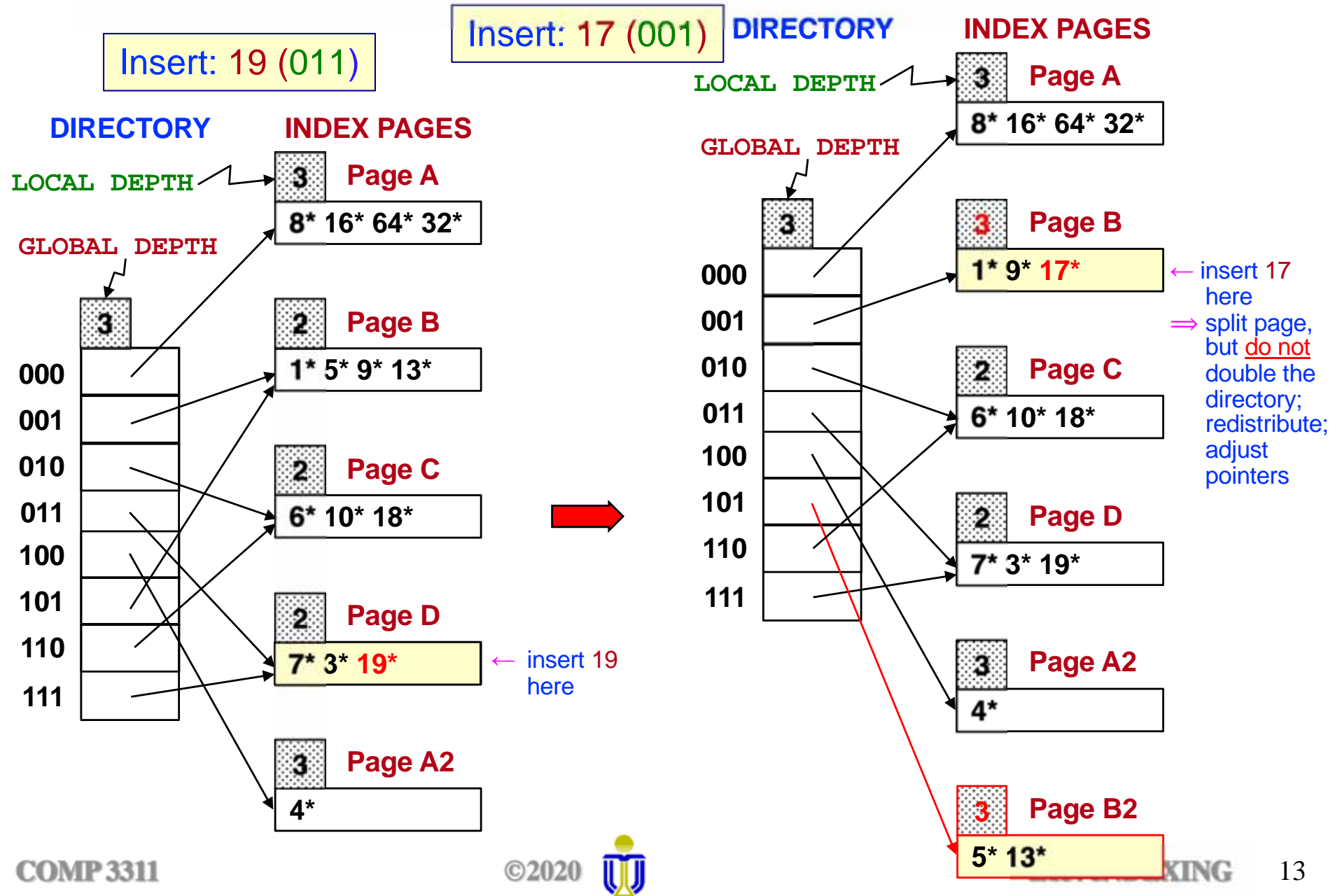


key value	4	8	16	32	64
binary value	100	000	000	000	000

Insert: 4 (100)



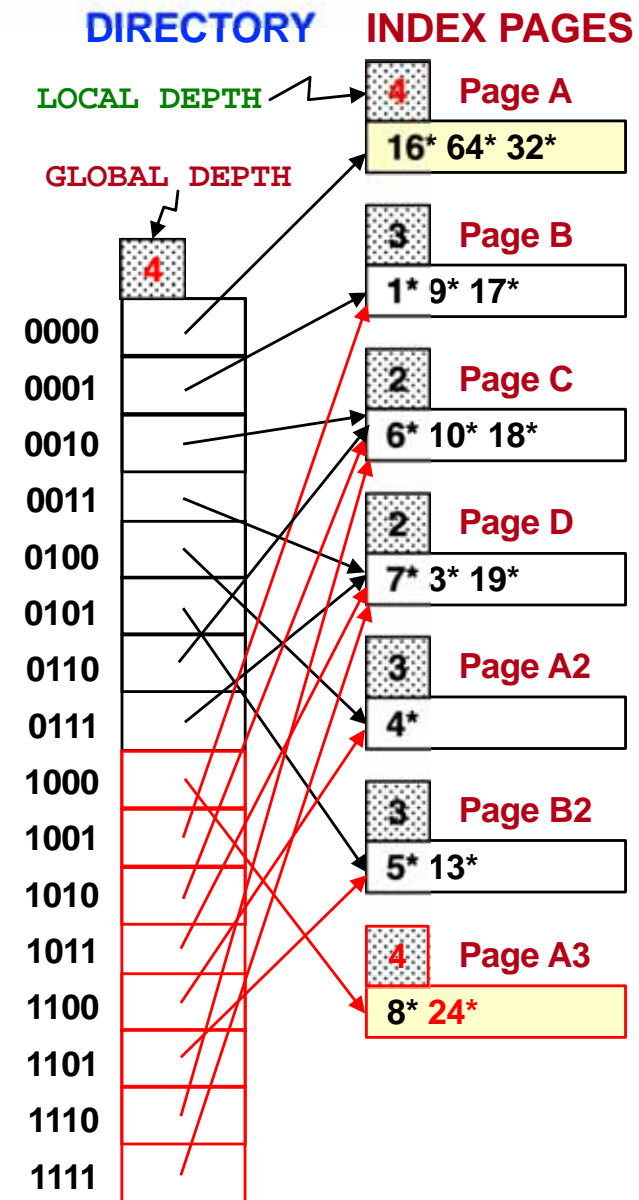
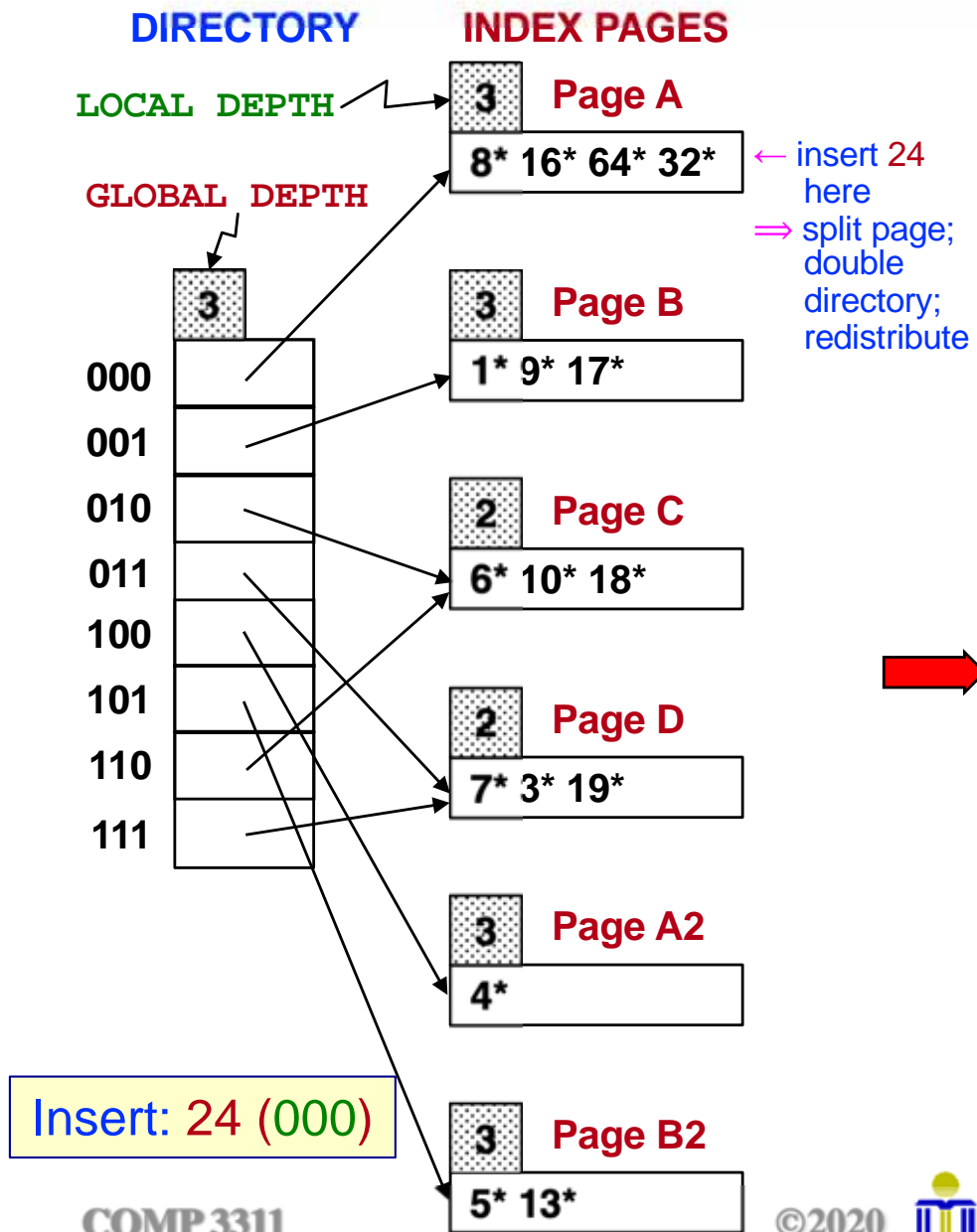
EXTENDABLE HASHING EXAMPLE (CONTD)



key value	8	16	24	32	64
binary value	1000	0000	1000	0000	0000

page size is 4

EXTENDABLE HASHING EXAMPLE (CONTD)



EXTENDABLE HASHING: OBSERVATIONS

- If the **directory fits in memory**, **equality search** can be answered with **one disk access**; else two disk accesses are needed.
 - For a 100MB file with 100 bytes/record and 4K pages containing 1,000,000 records (as data records) and 25,000 directory entries, chances are high that the directory will fit in memory.
 - The directory grows in spurts and, if the distribution of hash values is skewed, the directory can grow large.
 - Multiple entries with the same hash value cause overflows!

Deletion

If removal of a data record makes a page empty, it can be merged with its 'split image'.

If each directory element points to the same page as its split image, this can halve the directory.

BITMAP INDEX

- Bitmap indexes are a special type of index designed for **efficient querying on multiple search keys**.

 **A bitmap is simply an array of bits.**

- Records in a table are assumed to be numbered sequentially from, say, 0.
 - Given a number *n* it must be easy to retrieve record *n*.
- Bitmap indexes are applicable for **attributes that take on a relatively small number of distinct values**.
 - E.g. gender, country, state, ...
 - E.g. income-level (where income is broken up into a small number of categories such as 0-9999, 10000-19999, 20000-50000, 50000-infinity).

BITMAP INDEX (cont'd)

- In its simplest form, a bitmap index on an attribute has **a bitmap for each value of the attribute**.

✎ A bitmap has as many bits as there are records.

✎ In a bitmap for a value **v**, the bit for a record is **1** if the record has the value **v** for the attribute, and **0** otherwise.

- Queries are answered using bitmap operations.
 - **AND** \Rightarrow Intersection
 - **OR** \Rightarrow Union
 - **NOT** \Rightarrow Complementation
- Each operation takes **two bitmaps** of the **same size** and **applies the operation** on the corresponding bits **to get the result bitmap**.

BITMAP INDEX (cont'd)

Query: Find records for **males** with **income-level L1**.

male bit vector: 10010

income-level L1 bit vector: 10100

and the bit vectors together

10000 ← qualifying records

- **Counting** the number of matching records is even faster (especially useful for aggregation queries).

record number	name	gender	address	income-level	Bitmaps for gender	Bitmaps for income-level
		m			1 0 0 1 0	
		f			0 1 1 0 1	
0	John	m	Perryridge	L1		1 0 1 0 0
1	Diana	f	Brooklyn	L2		0 1 0 0 0
2	Mary	f	Jonestown	L1		0 0 0 0 1
3	Peter	m	Brooklyn	L4		0 0 0 1 0
4	Kathy	f	Perryridge	L3		0 0 0 0 0

Each bitmap has one bit for each record in the file.

BITMAP INDEX (cont'd)

- Bitmap indexes are **useful for queries on multiple attributes** but are not particularly useful for single attribute queries.
- Bitmap indexes are generally very small compared with the size of a table.
- Deletion needs to be handled properly.
 - Can use an **existence bitmap** to record whether there is a valid record at a given location.
 - An existence bitmap is needed for complementation.
 - $\text{not}(A=v): (\text{NOT } \text{bitmap-}A\text{-}v) \text{ AND } \text{ExistenceBitmap}$
- Bitmaps should be kept for **all values** of an attribute, **even null values**.
 - To correctly handle SQL null semantics for $\text{NOT}(A=v)$:
 - intersect previous result with $(\text{NOT } \text{bitmap-}A\text{-Null})$.

INDEX SELECTION CONSIDERATIONS

- **Types of accesses supported efficiently**
 - Hash indexes are in general good for equality selection queries, but do not support range searches.
 - Secondary indexes are not good for queries that retrieve many records as the same page may be retrieved multiple times.
- **Update time**
 - When a data file is modified, every index on the data file must be updated.
- **Space overhead**
 - The index should be, in general, much smaller than the data file.

INDEXING: SUMMARY

Indexing reduces the overhead of searching a table by trading space (storage overhead) for time (faster search).

Dense and sparse index

Dense: contain entries for every search-key value.

Sparse: contain entries for only some search-key values.

Clustering and non-clustering (secondary) index

Clustering: file is ordered on the search-key values.

Non-clustering: file is not ordered on the search-key values.

Indexing methods

B+-tree: use search-key value to search a tree-index.

Hash: apply a function to the search-key value to access a directory.

Bitmap: apply appropriate bitmap for search-key value.