



1

解

$$\begin{aligned}\frac{dp}{dt} &= \frac{d}{dt} \int_V \rho \vec{x}' dV' \\ &= \int_V \frac{d\rho \vec{x}'}{dt} dV' \\ &= \int_V \left(\frac{\partial \rho \vec{x}'}{\partial t} + \frac{\partial \rho \vec{x}'}{\partial \vec{x}'} \frac{d\vec{x}'}{dt} \right) dV' \\ &= \int_V \frac{\partial \rho}{\partial t} \vec{x}' dV' \\ &= - \int_V \nabla' \cdot \vec{j} \vec{x}' dV'\end{aligned}$$

又因为

$$\begin{aligned}\nabla' \cdot (\vec{x}' \vec{j}) &= \partial_i x'_j j_i \\ &= x'_j \partial_i j_i + j_i \partial_i x'_j \\ &= x'_j \partial_i j_i + j_i \delta_{ij} \\ &= x'_j \partial_i j_i + j_j \\ &= (\nabla' \cdot \vec{j}) \vec{x}' + \vec{j}\end{aligned}$$

故

$$\begin{aligned}- \int_V \nabla' \cdot \vec{j} \vec{x}' dV' &= \int_V \vec{j} dV' - \int_V \nabla' \cdot (\vec{x}' \vec{j}) dV' \\ &= \int_V \vec{j} dV' - \int_{\partial V} \vec{x}' \vec{j} \cdot d\vec{S}\end{aligned}$$

又体系电荷守恒, 故在 ∂V 上 $\vec{j} \cdot d\vec{S} = 0$, 故

$$\nabla' \cdot (\vec{x}' \vec{j}) = \int_V \vec{j} dV'$$

2

解

$$\begin{aligned}\nabla \times \vec{A} &= \nabla \left(\frac{1}{r^3} \right) \times (\vec{m} \times \vec{r}) + \frac{1}{r^3} \nabla \times (\vec{m} \times \vec{r}) \\ &= \frac{-3\vec{r}}{r^5} \times (\vec{m} \times \vec{r}) + \frac{1}{r^3} [(\vec{r} \cdot \nabla) \vec{m} + (\nabla \cdot \vec{r}) \vec{m} - (\vec{m} \cdot \nabla) \vec{r} - (\nabla \cdot \vec{m}) \vec{r}] \\ &= \frac{-3[r^2 \vec{m} - (\vec{r} \cdot \vec{m}) \vec{r}]}{r^5} + \frac{2\vec{m}}{r^3} \\ &= \frac{-3r^2 \vec{m}}{r^3} + \frac{3(\vec{r} \cdot \vec{m}) \vec{r}}{r^5} + \frac{2\vec{m}}{r^3}\end{aligned}$$



$$= \frac{3(\vec{r} \cdot \vec{m})\vec{r}}{r^5} - \frac{\vec{m}}{r^3}$$

$$\begin{aligned}\nabla\varphi &= \frac{1}{r^3}\nabla(\vec{m} \cdot \vec{r}) + (\vec{m} \cdot \vec{r})\nabla\frac{1}{r^3} \\ &= \frac{1}{r^3}[\vec{m} \times (\nabla \times \vec{r}) + (\vec{m} \cdot \nabla)\vec{r} + \vec{r} \times (\nabla \times \vec{m}) + (\vec{r} \cdot \nabla)\vec{m}] - \frac{3(\vec{m} \cdot \vec{r})\vec{r}}{r^5} \\ &= \frac{\vec{m}}{r^3} - \frac{3(\vec{r} \cdot \vec{m})\vec{r}}{r^5}\end{aligned}$$

故

$$\nabla \times \vec{A} = -\nabla\varphi$$

4
解

$$\begin{aligned}\vec{F}_{12} &= \frac{\mu_0}{4\pi} \oint_{(L_1)} \oint_{(L_2)} \frac{I_1 I_2 d\vec{l}_1 \times (d\vec{l}_2 \times \hat{\mathbf{r}}_{12})}{r_{12}^2} \\ &= \frac{\mu_0}{4\pi} \oint_{(L_1)} \oint_{(L_2)} \frac{I_1 I_2 [(d\vec{l}_1 \cdot \hat{\mathbf{r}}_{12}) d\vec{l}_2 - (d\vec{l}_1 \cdot d\vec{l}_2) \hat{\mathbf{r}}_{12}]}{r_{12}^2} \\ &= -\frac{\mu_0}{4\pi} \oint_{(L_1)} \oint_{(L_2)} \frac{I_1 I_2 (d\vec{l}_1 \cdot d\vec{l}_2) \hat{\mathbf{r}}_{12}}{r_{12}^2}\end{aligned}$$

又因为被积函数连续, 故积分可交换顺序, 即

$$\vec{F}_{12} = -\frac{\mu_0}{4\pi} \oint_{(L_2)} \oint_{(L_1)} \frac{I_1 I_2 (d\vec{l}_1 \cdot d\vec{l}_2) \hat{\mathbf{r}}_{12}}{r_{12}^2}$$

同理

$$\vec{F}_{21} = -\frac{\mu_0}{4\pi} \oint_{(L_2)} \oint_{(L_1)} \frac{I_1 I_2 (d\vec{l}_1 \cdot d\vec{l}_2) \hat{\mathbf{r}}_{21}}{r_{21}^2}$$

又因为 $\hat{\mathbf{r}}_{21} = -\hat{\mathbf{r}}_{12}$, 故

$$\vec{F}_{12} = -\vec{F}_{21}$$

3

解 设抛物线方程为 $y = ax^2 (z = 0)$, 则其焦点为 $(0, \frac{1}{4a}, 0)$ 。在其上一点 $(x, ax^2, 0)$ 的电流元为 $I d\vec{l} = (I dx, I 2ax dx, 0)$ 。故其焦点处的磁感应强度为

$$\vec{B} = \int \frac{\mu_0}{4\pi} \frac{I d\vec{l} \times \vec{r}}{r^3}$$



$$\begin{aligned}
 &= - \int_{-\infty}^{\infty} \frac{\mu_0 I}{4\pi} \frac{ax^2 + \frac{1}{4a}}{\sqrt{x^2 + (ax^2 - \frac{1}{4a})^2}}^3 dx \vec{e}_z \\
 &= - \frac{\mu_0 I}{4\pi} 4a\pi \vec{e}_z \\
 &= -a\mu_0 I \vec{e}_z
 \end{aligned}$$

4

解 因为所有场量均只与 z, t 相关, 故麦克斯韦方程组可简化为

$$\begin{aligned}
 \frac{\partial E_z}{\partial z} &= 0 \\
 \frac{\partial E_y}{\partial z} \vec{e}_x - \frac{\partial E_x}{\partial z} \vec{e}_y &= \frac{\partial \vec{B}}{\partial t} \\
 -\frac{\partial B_y}{\partial z} \vec{e}_x + \frac{\partial B_x}{\partial z} \vec{e}_y &= \mu_0 \epsilon_0 \frac{\partial \vec{E}}{\partial t} \\
 \frac{\partial B_z}{\partial z} &= 0
 \end{aligned}$$

因为 $\frac{\partial E_z}{\partial z} = 0, \frac{\partial B_z}{\partial z} = 0$ 故 E_z 为常数, 同理 B_z 为常数, 不妨将 E_z, B_z 均取为 0。故可得到两组独立方程

$$\begin{cases} \frac{\partial E_y}{\partial z} = \frac{\partial B_x}{\partial t} \\ \frac{\partial B_x}{\partial z} = \mu_0 \epsilon_0 \frac{\partial E_y}{\partial t} \end{cases} \quad \begin{cases} -\frac{\partial E_x}{\partial z} = \frac{\partial B_y}{\partial t} \\ -\frac{\partial B_y}{\partial z} = \mu_0 \epsilon_0 \frac{\partial E_x}{\partial t} \end{cases}$$

消去第一组方程中的 B_x 可得到

$$\mu_0 \epsilon_0 \frac{\partial^2 E_y}{\partial t^2} = \frac{\partial^2 E_y}{\partial z^2}$$

此是一波动方程, 可解出 E_y , 再代入原式, 可解出 B_x 。此是一组解。同理第二组方程可解出第二组解 (E_x, B_y) 。故整个方程组的解由这两组独立的解组成。

4

解

$$\begin{aligned}
 \nabla \cdot \vec{E}' &= \cos \theta \nabla \cdot \vec{E} + c \sin \theta \nabla \cdot \vec{B} \\
 &= 0 \\
 \nabla \times \vec{E}' &= \cos \theta \nabla \times \vec{E} + c \sin \theta \nabla \times \vec{B} \\
 &= -\cos \theta \frac{\partial \vec{B}}{\partial t} + c \mu_0 \epsilon_0 \sin \theta \frac{\partial \vec{E}}{\partial t}
 \end{aligned}$$



$$\begin{aligned}
 &= -\frac{\partial}{\partial t}(\cos \theta \vec{B} - c\mu_0\varepsilon_0 \sin \theta \vec{E}) \\
 &= -\frac{\partial}{\partial t}(\cos \theta \vec{B} - \sqrt{\mu_0\varepsilon_0} \sin \theta \vec{E}) \\
 &= -\frac{\partial}{\partial t}(\cos \theta \vec{B} - \frac{1}{c} \sin \theta \vec{E}) \\
 &= -\frac{\partial \vec{B}'}{\partial t} \\
 \nabla \cdot \vec{B}' &= \frac{-\sin \theta}{c} \nabla \cdot \vec{E} + \cos \theta \nabla \cdot \vec{B} \\
 &= 0 \\
 \nabla \times \vec{B}' &= \frac{-\sin \theta}{c} \nabla \times \vec{E} + \cos \theta \nabla \times \vec{B} \\
 &= \frac{\sin \theta}{c} \frac{\partial \vec{B}}{\partial t} + \cos \theta \mu_0\varepsilon_0 \frac{\partial \vec{E}}{\partial t} \\
 &= \mu_0\varepsilon_0 \frac{\partial}{\partial t} \left(\frac{\sin \theta}{\mu_0\varepsilon_0 c} \vec{B} + \cos \theta \vec{E} \right) \\
 &= \mu_0\varepsilon_0 \frac{\partial}{\partial t} \left(\frac{\sin \theta}{\sqrt{\mu_0\varepsilon_0}} \vec{B} + \cos \theta \vec{E} \right) \\
 &= \mu_0\varepsilon_0 \frac{\partial}{\partial t} (c \sin \theta \vec{B} + \cos \theta \vec{E}) \\
 &= \mu_0\varepsilon_0 \frac{\partial \vec{E}'}{\partial t}
 \end{aligned}$$

4

解

$$\begin{aligned}
 \vec{B} &= \nabla \times \vec{A} \\
 &= \left(\nabla \frac{1}{r(r - \vec{r} \cdot \vec{n})} \right) \times (\vec{r} \times \vec{n}) + \frac{1}{r(r - \vec{r} \cdot \vec{n})} \nabla \times (\vec{r} \times \vec{n}) \\
 &= \left(\nabla \frac{1}{r^2} \frac{1}{1 - \cos \theta} \right) \times (\vec{r} \times \vec{n}) - \frac{2\vec{n}}{r(r - \vec{r} \cdot \vec{n})} \\
 \nabla \frac{1}{r^2} \frac{1}{1 - \cos \theta} &= \frac{1}{1 - \cos \theta} \nabla \frac{1}{r^2} + \frac{1}{r^2} \nabla \frac{1}{1 - \cos \theta} \\
 &= \frac{1}{1 - \cos \theta} \frac{-2\vec{r}}{r^4} + \frac{1}{r^2} \frac{1}{(1 - \cos \theta)^2} \nabla \cos \theta \\
 &= \frac{-2\vec{r}}{r^3(r - \vec{r} \cdot \vec{n})} + \frac{1}{(r - \vec{r} \cdot \vec{n})^2} \nabla \frac{\vec{r} \cdot \vec{n}}{r} \\
 \nabla \frac{\vec{r} \cdot \vec{n}}{r} &= \frac{1}{r} \nabla (\vec{r} \cdot \vec{n}) + (\vec{r} \cdot \vec{n}) \nabla \frac{1}{r} \\
 &= \frac{1}{r} [\vec{n} \times (\nabla \times \vec{r}) + (\vec{n} \cdot \nabla) \vec{r} + \vec{r} \times (\nabla \times \vec{n}) + (\vec{r} \cdot \nabla) \vec{n}] - (\vec{r} \cdot \vec{n}) \frac{\vec{r}}{r^3}
 \end{aligned}$$



$$= \frac{\vec{n}}{r} - \frac{(\vec{r} \cdot \vec{n})\vec{r}}{r^3}$$

故

$$\begin{aligned} \vec{B} &= (\nabla \frac{1}{r^2} \frac{1}{1 - \cos \theta}) \times (\vec{r} \times \vec{n}) - \frac{2\vec{n}}{r(r - \vec{r} \cdot \vec{n})} \\ &= (\frac{-2\vec{r}}{r^3(r - \vec{r} \cdot \vec{n})} + \frac{1}{(r - \vec{r} \cdot \vec{n})^2} \nabla \frac{\vec{r} \cdot \vec{n}}{r}) \times (\vec{r} \times \vec{n}) - \frac{2\vec{n}}{r(r - \vec{r} \cdot \vec{n})} \\ &= (\frac{-2\vec{r}}{r^3(r - \vec{r} \cdot \vec{n})} + \frac{1}{(r - \vec{r} \cdot \vec{n})^2} (\frac{\vec{n}}{r} - \frac{(\vec{r} \cdot \vec{n})\vec{r}}{r^3})) \times (\vec{r} \times \vec{n}) - \frac{2\vec{n}}{r(r - \vec{r} \cdot \vec{n})} \\ &= \frac{(\vec{r} \cdot \vec{n} - 2r)\vec{r} + r^2\vec{n}}{r^3(r - \vec{r} \cdot \vec{n})^2} \times (\vec{r} \times \vec{n}) - \frac{2\vec{n}}{r(r - \vec{r} \cdot \vec{n})} \end{aligned}$$