Matrix Completion Methods for Causal Panel Data Models

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Introduction

Today's Agenda; Keyword: Imputation

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Imputation

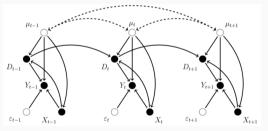
- As many panel data methods, we want to know ATT : $\mathbb{E}[Y_{it}(1) Y_{it}(0)|W_i = 1]$.
- Thus, it boils down to estimate (impute) the counterfactual $Y_{it}(0)$.
 - Horizontal: Under unconfoundedness, we can impute counterfactual PO using observed outcomes for control units.
 - Vertical: By SCM, we can also impute it using weighted average outcomes for control units with most predictive weights trained with pre-treatment datas.

$$\mathbf{Y} = \begin{pmatrix} \checkmark & \checkmark & \checkmark \\ \vdots & \vdots & \vdots \\ \checkmark & \checkmark & \checkmark \\ \vdots & \vdots & \vdots \\ \checkmark & \checkmark & ? \end{pmatrix}.$$

$$\mathbf{Y} = \begin{pmatrix} \checkmark & \checkmark & \dots & \checkmark & \ddots & \ddots \\ \checkmark & \checkmark & \dots & \checkmark & \ddots & \dots & \checkmark \\ \checkmark & \checkmark & \dots & \checkmark & ? & \dots & ? \end{pmatrix}$$

Xu (2024): Counterfactual estimation

- functional form: Y_{it}(0) = f(X_{it}) + h(U_{it}) + ε_{it}
 →No anticipation, carryover, feedback, LDV
- strict exogeneity: $\forall i, j \in \{1, \dots, N\}, \ \forall s, t \in \{1, \dots, T\}, \epsilon_{it} \perp \{D_{js}, \mathbf{X_{js}}, \mathbf{U_{js}}\}$



• low-dimensional decomposition: $h(\mathbf{U_{it}}) = \{L_{it}\}, \operatorname{rank}(\mathbf{L}_{N \times T}) \ll \min\{N, T\}$ \rightarrow The rank (= number of factors) is FIXED!!

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Set Up

Notation and Estimand

- Consider a setting with N units observed over T periods characterized by a binary treatment W_{it} and hence two POs $Y_{it}(1), Y_{it}(0)$.
 - $\mathbf{X} \in \mathbb{R}^{N \times P}$, $\mathbf{Z} \in \mathbb{R}^{T \times Q}$: observe (unit / time)-specific covariance matrix

• Estimand:
$$\mathbf{Y} = \{Y_{it}(0)^1\} = \begin{pmatrix} Y_{11}(0) & \cdots & Y_{1T}(0) \\ \vdots & \ddots & \vdots \\ Y_{N1}(0) & \cdots & Y_{NT}(0) \end{pmatrix} (\leftarrow \text{Matrix!!})$$

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$$W_{it} = \begin{cases} 1 & \text{if } (i,t) \in \mathcal{M} \\ 0 & \text{if } (i,t) \in \mathcal{O} \end{cases}$$

 $^{^{1}}$ 以降は簡単のため、 $Y_{it}(0) = Y_{it}$ とし、"(0)"を省略して表記する.

Patterns of data matrix

• Ordinary case (rich data wrt. units and times)

$$\mathbf{Y}_{N\times T} = \begin{pmatrix} \checkmark & \checkmark & \checkmark & \checkmark & \dots & \checkmark \\ \checkmark & \checkmark & \checkmark & \checkmark & \dots & \checkmark \\ \checkmark & \checkmark & \checkmark & \checkmark & \dots & \checkmark \\ \checkmark & \checkmark & \checkmark & ? & \dots & ? \\ \checkmark & \checkmark & \checkmark & ? & \dots & ? \\ \vdots & \vdots & \vdots & \vdots & \ddots & \vdots \\ \checkmark & \checkmark & \checkmark & ? & \dots & ? \end{pmatrix}$$

Staggered adoption

$$\mathbf{Y}_{N \times T} \\ = \begin{pmatrix} \checkmark & \checkmark & \checkmark & \ddots & \checkmark & \dots & \checkmark & \text{(never adopter)} \\ \checkmark & \checkmark & \checkmark & \checkmark & \dots & ? & \text{(late adopter)} \\ \checkmark & \checkmark & ? & ? & \dots & ? & \text{(medium adopter)} \\ \vdots & \vdots & \vdots & \vdots & \ddots & \vdots \\ \checkmark & ? & ? & ? & \dots & ? & \text{(early adopter)} \end{pmatrix}$$

Horizontal regression and unconfoundedness : thin matrix $(N\gg T)$

$$\mathbf{Y} = \left(\begin{array}{cccc} \checkmark & \checkmark & \checkmark \\ \vdots & \vdots & \vdots \\ \checkmark & \checkmark & \checkmark \\ \checkmark & \checkmark & ? \\ \vdots & \vdots & \vdots \\ \checkmark & \checkmark & ? \end{array} \right).$$

- 1. Regress the last period outcome on the lagged outcomes. (among untreated)
- 2. Predict the missing POs using the estimated regression.

$$\forall (i,T) \in \mathcal{M}, \ \hat{Y}_{iT} = \hat{\beta}_0 + \sum_{t=1}^{T-1} \hat{\beta}_t Y_{it}, \text{ where } \hat{\beta} = \arg\min_{\beta} \sum_{i:(i,T) \in \mathcal{O}} (Y_{iT} - \beta_0 - \sum_{t=1}^{T-1} \beta_t Y_{it})^2.$$

 \rightarrow Nonparametrically,

Vertical regression and synthesis control : fat matrix $(T \gg N)$

- 1. Regress the outcomes for treated unit prior to the treatment on the outcomes for the control units in the same periods.
- 2. Predct the missing POs using the estimated regression.

$$\forall (N,t) \in \mathcal{M}, \ \hat{Y}_{Nt} = \hat{\gamma}_0 + \sum_{i=1}^{N-1} \hat{\gamma}_i Y_{it}, \text{ where } \hat{\gamma} = \arg\min_{\gamma} \sum_{t:(N,t) \in \mathcal{O}} (Y_{Nt} - \gamma_0 - \sum_{i=1}^{N-1} \gamma_i Y_{it})^2.$$

- \rightarrow Vertical regression is generalization of ADH(2010) in that it relaxes two restrictions :
 - the coefficients $\hat{\gamma}$ are nonnegative. (Interpretability; What is a negative weight?)
 - the intercept in this regression is 0. (This is seen to be plausible in recent literatures.)

Matrix Completion

Model

• Under no covariates, we model the $N \times T$ matrix of complete matrix $\mathbf Y$ as

$$\mathbf{Y} = \mathbf{L}^* + \epsilon$$
, where $\mathbb{E}[\epsilon | \mathbf{L}^*] = 0$.

Assumption 1

- ϵ is independent of \mathbf{L}^*
- The element of ϵ are $\sigma sub Gaussian$ and independent each other. $\Leftrightarrow \forall t, \ \mathbb{E}[\exp(t\epsilon)] \leq \exp(\frac{\sigma^2 t^2}{2}).$
- The goal is to estimate the matrix L^* . (low-rank assumption)
 - \rightarrow Note that two types² of fixed effects are included.

²Interactive fixed effect も低ランクとしていいが, rank が明示的でないため具体的には考えない.

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for the Estimation Error

Theoritical Bounds

Two illustrations

References

References

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