

EECS 602 – Reinforcement Learning Theory

Homework 6

Due: 11:59 PM on Mar. 25

Bipedal Walker Problem - Twin Delayed DDPG (TD3) [50pts]

Please download the files `hw_6.ipynb` from Canvas. Train your model using Google Colab following the instructions in the file. **After completing the training, save your actor network as `actor.pth` (save the model's "state_dict"). Then upload `actor.pth` to Gradescope.** We will test your policy (actor) for 50 episodes on Gradescope.