

05

COMPUTATIONAL DESIGN

Cheese Stairs

By Python, Rhinoceros and Grasshopper

Task:

*The Lab of Constructioning Bridges
and Roads of Southeast University*
is now waiting to be **REFORMED.**

Condition:

1. **No Electricity;**
2. **No Pipe;**
3. **No Construction Machine;**

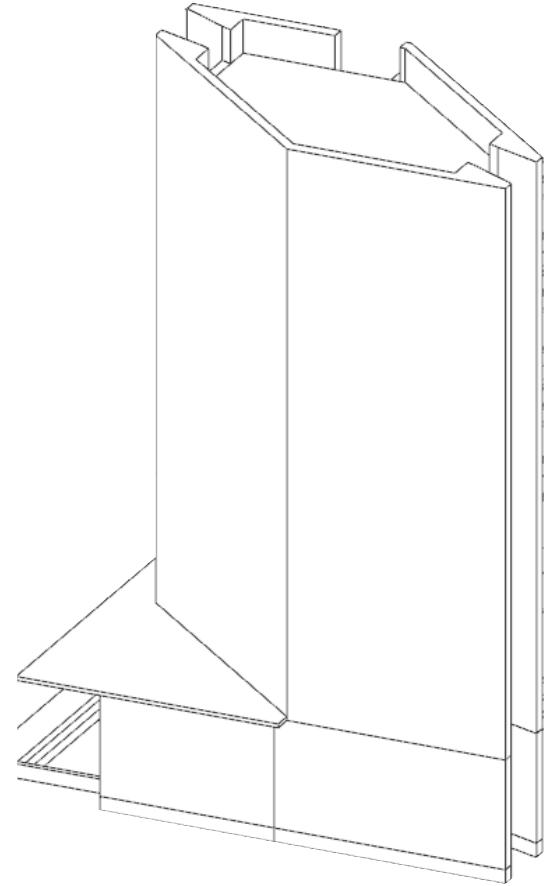
How? Here's our answer.



Conditions

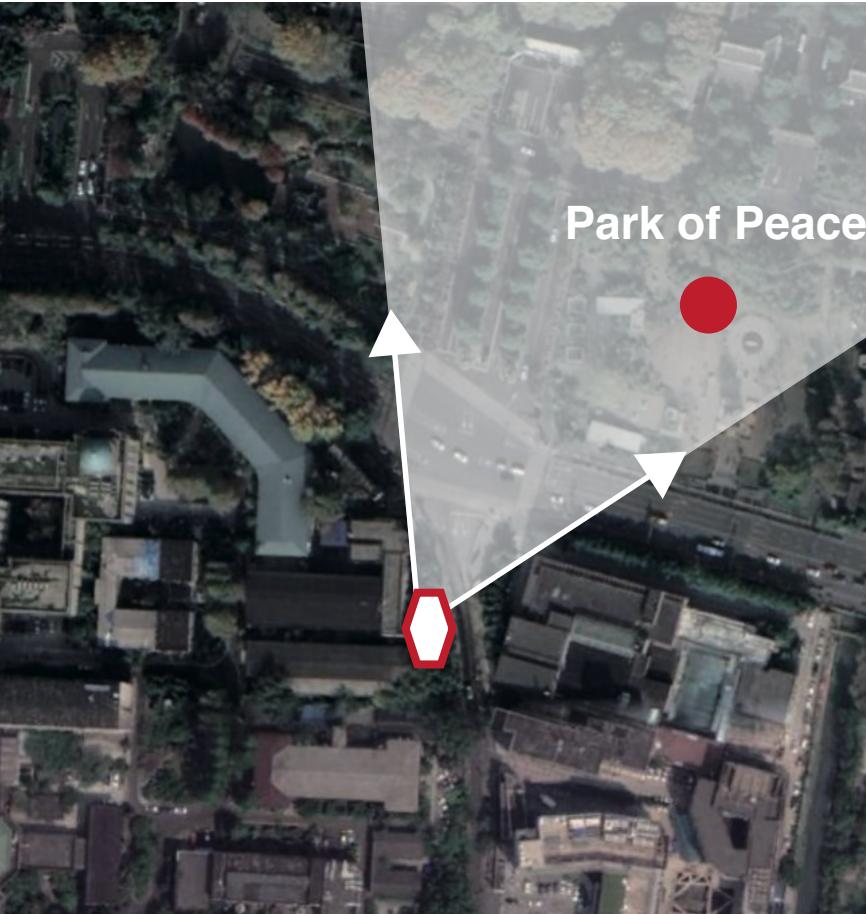
History

Lab of Constructioning Bridges and Roads, built in 1978. The original stairs is diamond-shaped to approach with the street.



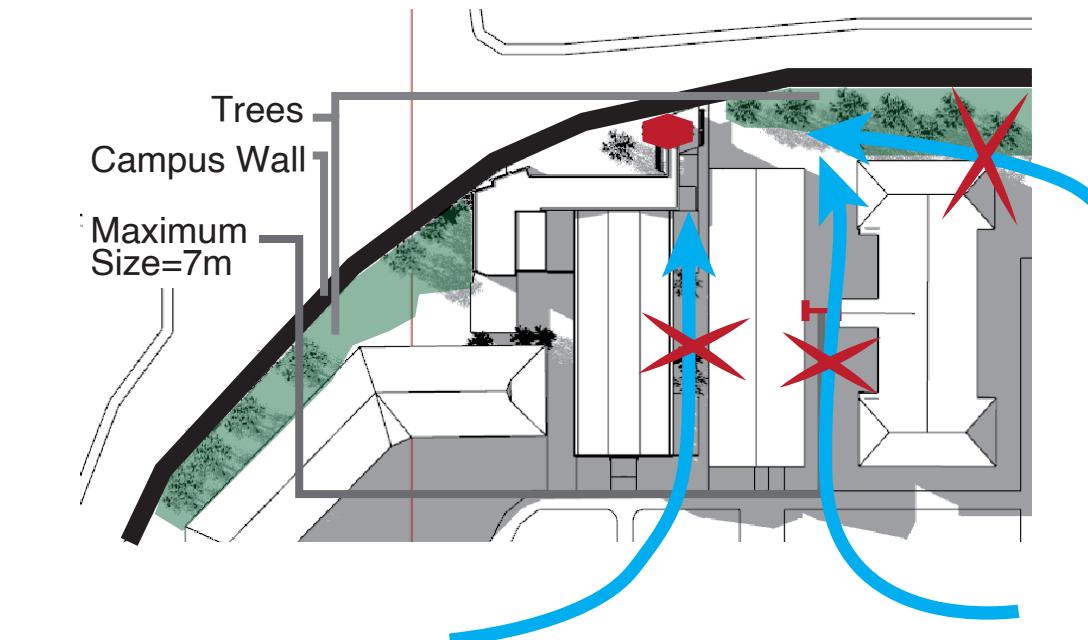
Site & Vision

It's been the focus of the crossing ever since. At the same time, It provided the best view to the Park of Peace crossroads.



Why no construction machines?

The campus building has a history for more than 50 years averagely, and the roads to the site is no wider than 7m. For teachers and students there, save the noises for them would be a better choice.



Why no water and electricity?

Due to the situation of the building, it's hard to attach wires and electronics to the stairs.

Solution: Prefabrication

In order to build without machines, the only way to build is to “build elsewhere, import to site”: Prefabrication.

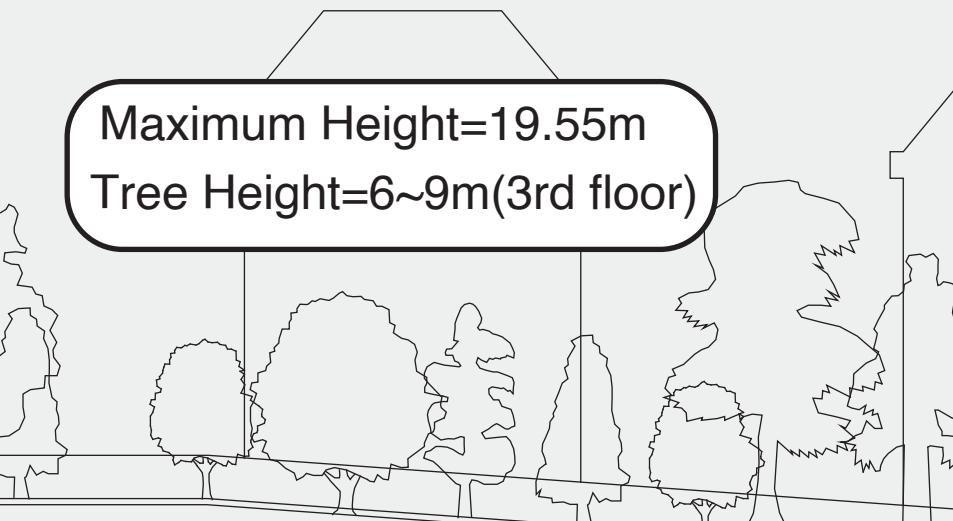
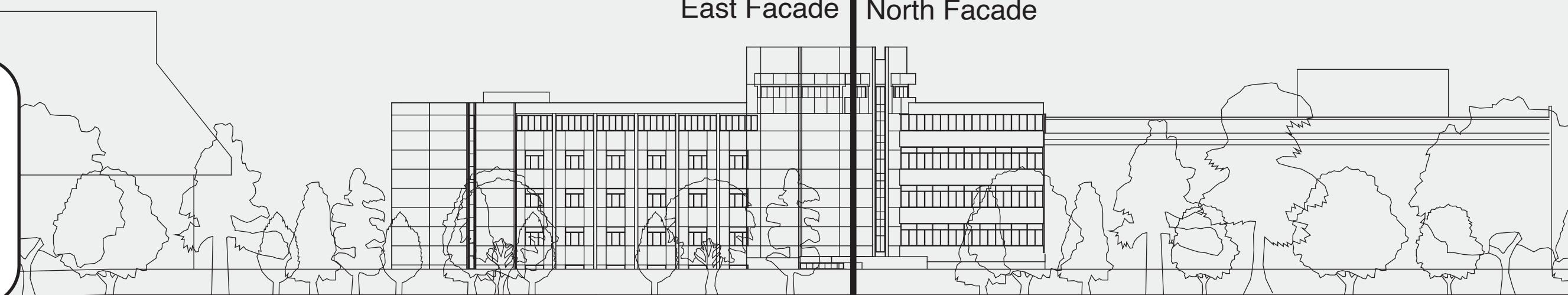
By 3D printing elements in the factory with its least size at no more than 2m, they can be transported by trucks.

Once moved to site, elements are put together and worked on connections.

Theoretically the assembling takes just 2 days in silent.

Campus Look

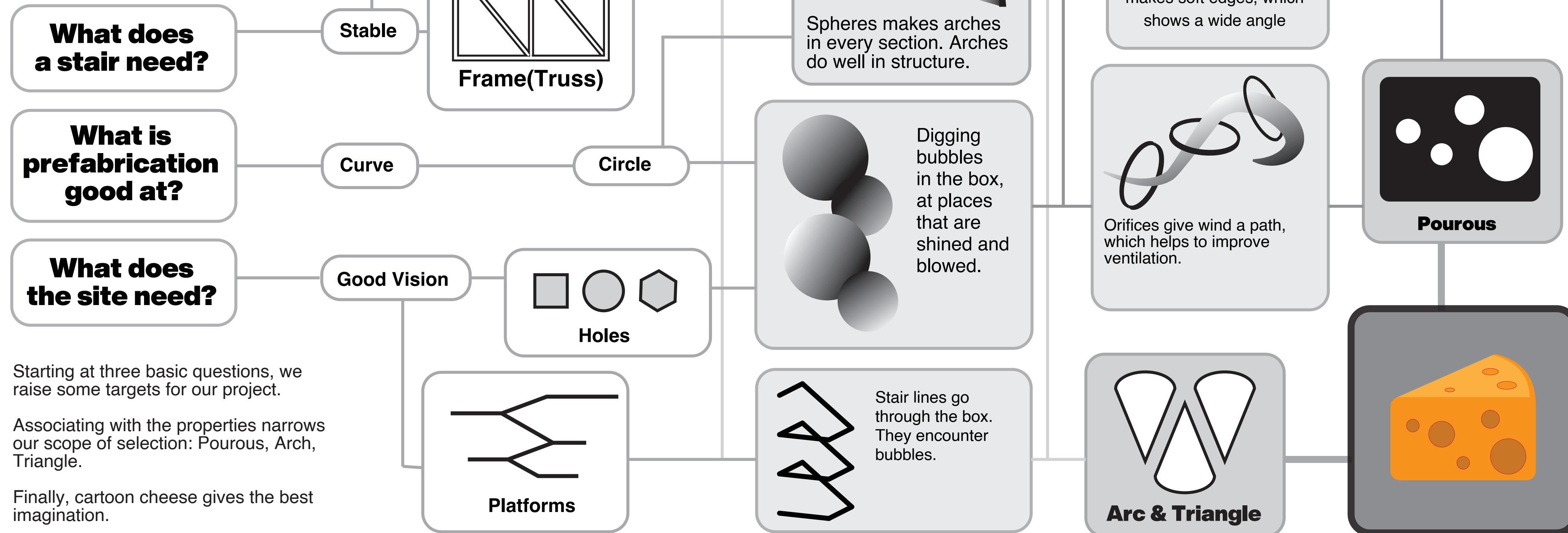
6(3.35)	Roof
5(3.15m)	Warehouse
4(3.15m)	Classroom
3(3.15m)	Labs
2(3.15m)	Labs
1(3.6m)	Entrance (walled)



Choosing Cheese

After establishing prefabrication as the way to build, the new question is the shape to use.

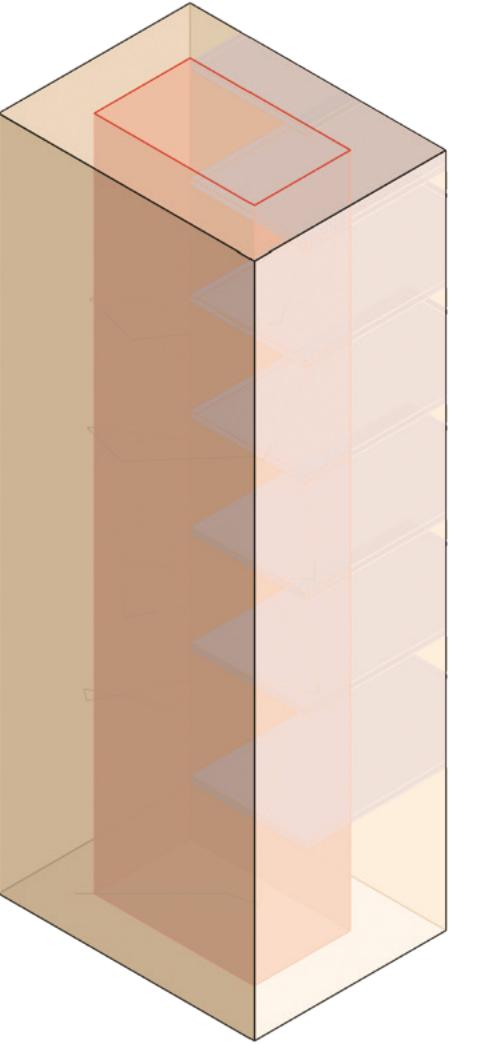
However, the best option can be simple. Here's the logic chain.



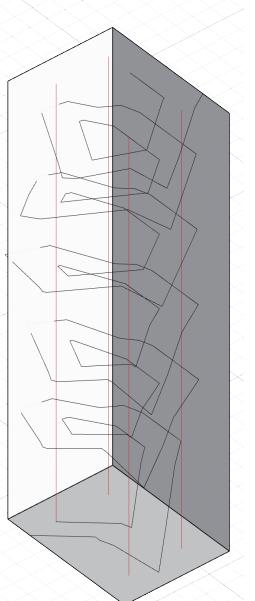
Generating Cheese

We use **Rhinoceros** and **Grasshopper** to Generate the Cheese Stair, vision and ventilation are optimized.

Here's how.



A. Boundingbox
Original defined space.



Root Path

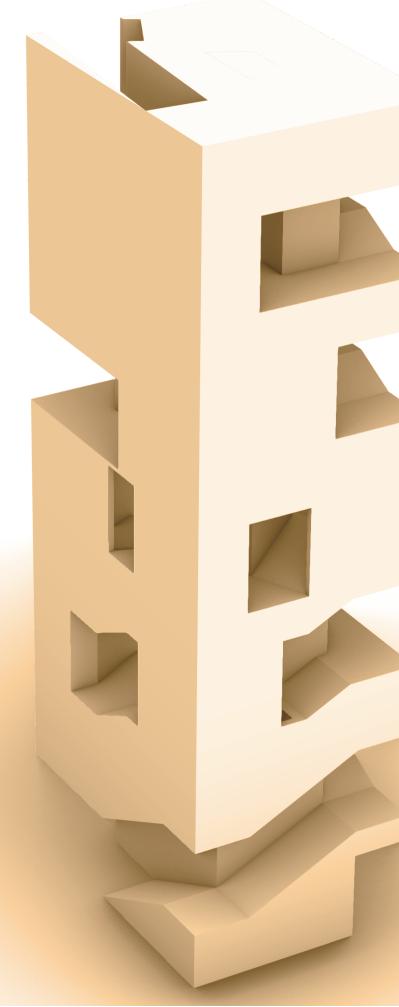
MINUS



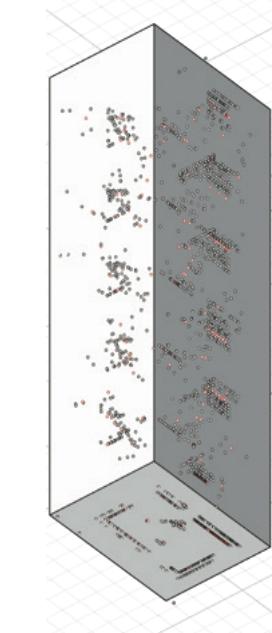
B. Space for stairs
Random path with no offense to structure and remain balance.

```
def spc_nts(pointn,pointm,m):
    pntmnh=rs.PointCoordinates(pointm)
    pntmnh=rs.PointCoordinates(pointn)
    pointm_newheight=rs.AddPoint(pntmnh.X,pntmnh.Y,pntmnh.Z)
    length=rs.Distance(pointn,pointm_newheight)
    stairs=length/q
    if m<5:
        height_of_next_layer=ha*(m+1)
    else:
        height_of_next_layer=ha*m+hb*1
    ntg=(height_of_next_layer-pntmnh.Z)/p
    if stairs>ms:
        return False,ntg
    if pntmnh.Z+p*stairs>height_of_next_layer:
        return False,ntg
    if pntmnh.Z+p*stairs<=height_of_next_layer:
        return True,ntg
def spc_ubl(pointn,pointm,m):
    pntmnh=rs.PointCoordinates(pointm)
    pntmnh=rs.PointCoordinates(pointn)
    pointm_newheight=rs.AddPoint(pntmnh.X,pntmnh.Y,pntmnh.Z)
    length=rs.Distance(pointn,pointm_newheight)
    stairs=length/q
    if m<5:
        height_of_next_layer=ha*(m+1)
    else:
        height_of_next_layer=ha*m+hb*1
    ntg=(height_of_next_layer-pntmnh.Z)/p
    if pntmnh.Z+p*stairs<height_of_next_layer:
        return False,ntg
    if pntmnh.Z+p*stairs>=height_of_next_layer:
        return True,ntg
    if pntmnh.Z+p*stairs>=height_of_next_layer:
        return True,ntg
    if pntmnh.Z+p*stairs>=height_of_next_layer:
        return True,ntg
def ghtp(lastpoint,start,end,floor,iflast,ifflat):
    newpoint=ppfl(start,end)
    lstpnt=rs.PointCoordinates(lastpoint)
    newpoint=ghtpnt(newpoint,lstpnt.Z)
    spc_judge,ntg=spc_nts(lastpoint,newpoint,floor)
    count=0
    while(spc_judge==False):
        count+=1
        newpoint=ppfl(start,end)
        newpoint=ghtpnt(newpoint,lstpnt.Z)
        if count>10:
            newpoint=ghtpnt(end,lstpnt.Z)
            spc_judge=True
        if iflat or ntg==0:
            linen=rs.AddLine(lastpoint,newpoint)
            midpoint=pspf1(lastpoint,newpoint,0.5)
            linen=rs.AddLine(lastpoint,midpoint)
            linen=rs.AddLine(midpoint,newpoint)
        else:
            spc_judge,ntg=spc_ubl(lastpoint,newpoint,floor)
            if iflast or spc_judge:
                ratio=ntg*q/rs.Distance(lastpoint,newpoint)
                spc_judge,ntg=spc_tm(lastpoint,newpoint,floor)
                count=0
            while(spc_judge==False):
                count+=1
                newpoint=ppfl(start,end)
                spc_judge,ntg=spc_tm(lastpoint,newpoint,floor)
                if count>10:
                    newpoint=ghtpnt(end,lstpnt.Z)
                    spc_judge=True
                linen,linem,ending=iafd(lastpoint,newpoint,ntg)
            else:
                linen,linem,ending=iafd(lastpoint,newpoint)
                newpoint=ending
            return linen,linem,newpoint

```



C. Basic Entity
Volume of common stairs and space to pass.



Center

MINUS

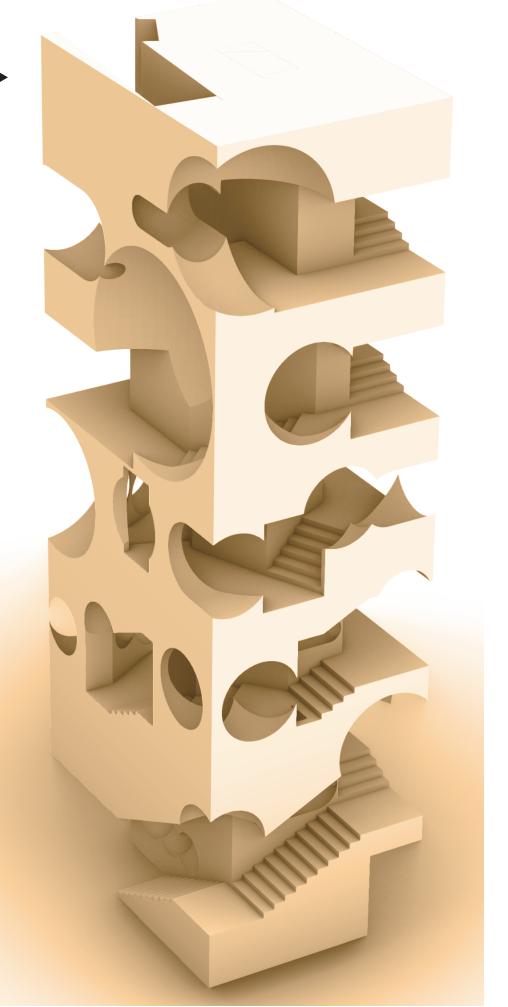


D. Bubble
Aimed spheres for optimizing physical factors for stairs

```
for j in range(M):
    height_of_next_layer=ha*(j+1)
if j==0:
    for i in range(3):
        if i==0:
            linen,linem,pointm=ghtp(zsi,sppua,zxi,j,False,False)
        if i==1:
            linen,linem,pointm=ghtp(pointm,zxi,sppub,j,False,True)
        if i==2:
            linen,linem,pointm=ghtp(pointm,ec,sppuc,j,True,False)
            new_sppuc=rs.AddPoint(a-d,c+1,height_of_next_layer)
            if not rs.PointCompare(pointm,new_sppuc):
                llhl.append(rs.AddLine(pointm,new_sppuc))
                pointm=rs.AddPoint(a-d,c+1,height_of_next_layer)
                llhl.append(linem)
                llhl.append(linem)
                llhl.append(rs.AddLine((a-d,c+1,height_of_next_layer),
                (a-d,e,height_of_next_layer)))
            elif j in [1,2,3,4,5]:
                height_of_next_layer=ha*j+hb
            for i in range(5):
                if i==0:
                    linen,linem,pointm=ghtp(pointm,ee,ysi,j,False,True)
                if i==1:
                    linen,linem,pointm=ghtp(pointm,sppda,zsi,j,False,False)
                if i==2:
                    linen,linem,pointm=ghtp(pointm,zsi,sppdb,j,False,True)
                if i==3:
                    linen,linem,pointm=ghtp(pointm,xzi,sppdc,j,False,False)
                if i==4:
                    linen,linem,pointm=ghtp(pointm,yxi,ec,j,True,False)
                    new_ec=rs.AddPoint(a-d,c,height_of_next_layer)
                    if not rs.PointCompare(pointm,new_ec):
                        llhl.append(rs.AddLine(pointm,new_ec))
                        pointm=rs.AddPoint(a-d,c,height_of_next_layer)
                        llhl.append(linem)
                        llhl.append(linem)
                        llhl.append(rs.AddLine((a-d,c,height_of_next_layer),
                        (a-d,e,height_of_next_layer)))
                llhl=rs.JoinCurves(llhl,False)
                newcurve=rs.OffsetCurve(llhl[0],zx,d,hv,1)

pts=[]
for i in range(1):
    if Line1:
        points=rs.DivideCurve(Line1,25)
        for pt in points:
            rs.AddPoint(pt)
            pts.append(pt)
    if Line2:
        points=rs.DivideCurve(Line2,25)
        for pt in points:
            rs.AddPoint(pt)
            pts.append(pt)
balls=[]
for i in range(1):
    for pt in pts:
        radius=random.random()+0.5
        center=rs.AddPoint(pt)
        ball=rs.AddSphere(center,radius)
        balls.append(ball)
z0=0.5*random.random()+1
for i in range(1):
    for balls in balls:
        rs.MoveObjects(balls,(0,0,z0))

def aptfm(list,floor):
    m=floor
    if m<5:
        height_of_next_layer=ha*(m+1)
    else:
        height_of_next_layer=ha*m+hb*1
    ree=rs.AddPoint(a-d,e,height_of_next_layer)
    rec=rs.AddPoint(a-d,c,height_of_next_layer)
    rpt=rs.AddLine(ree,rec)
    return list.append(rpt)
def iafd(pointn,pointm):
    pntmnh=rs.PointCoordinates(pointm)
    pntmnh=rs.PointCoordinates(pointn)
    pointm_newheight=rs.AddPoint(pntmnh.X,pntmnh.Y,pntmnh.Z)
    length=rs.Distance(pointn,pointm_newheight)
    stairs=length/q
    inclined_length=stairs*q
    ratio=inclined_length/length
    pointq=rs.AddPoint(pntmnh.X+(pntmnh.X-pntmnh.X)*ratio,pntmnh.Y+(pntmnh.Y-pntmnh.Y)*ratio,pntmnh.Z+stairs*p)
    pointm=rs.AddPoint(pntmnh.X,pntmnh.Y,pntmnh.Z+stairs*p)
    linen=rs.AddLine(pointn,pointq)
    linem=rs.AddLine(pointq,pointm)
    ending=pointm
    return linen,linem,ending
```



E. Outcome

Making Cheese

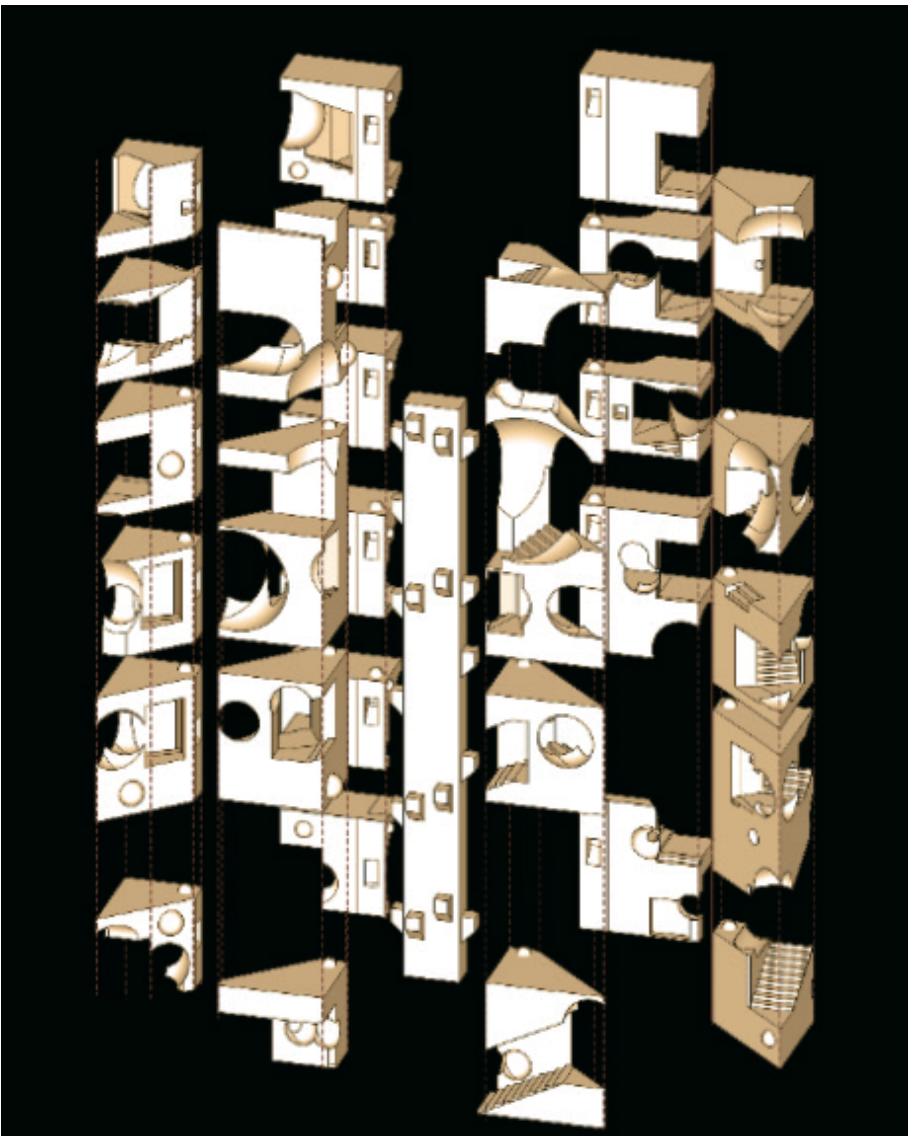
After shapes are done, it's time to dive into the details. The questions are:

- How to construct?
- How to attach?
- How to assemble?

A. Assembling

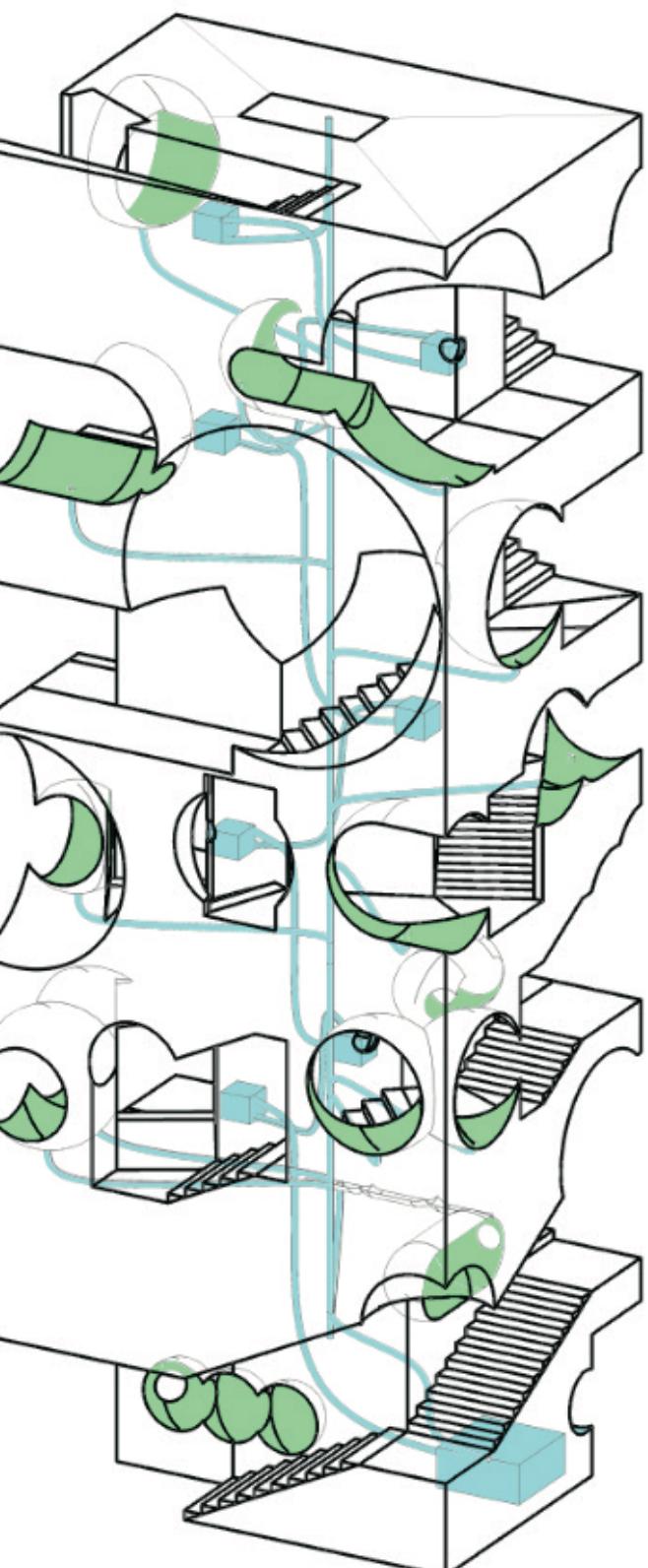
By dividing the shape into 30 parts along the arches, stucture stays strong and portable.

With a small iron frame stem, the elements can be attached.



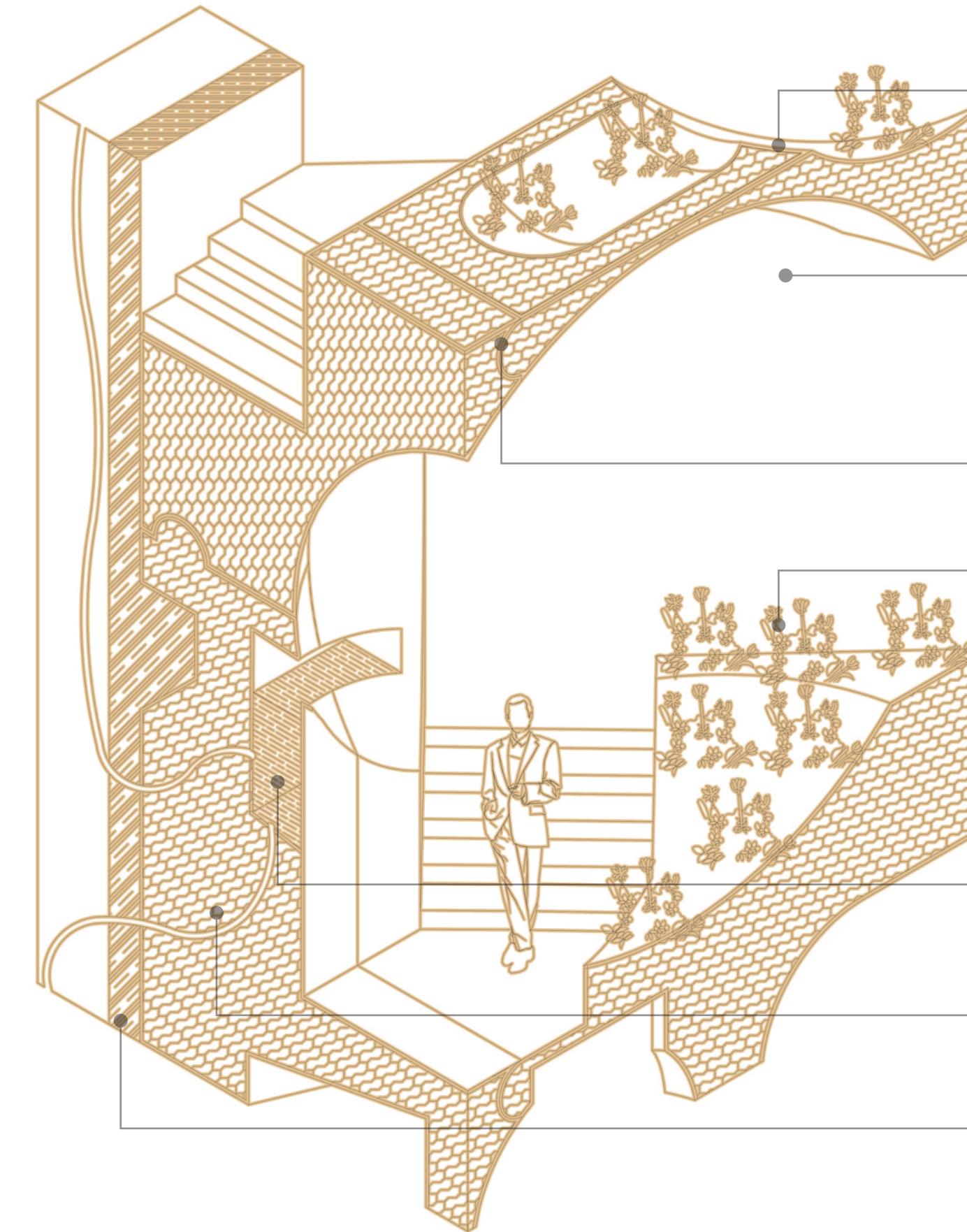
B. Draining & Irrigating

The lower parts of the spheres naturally collect water. Through the tubes, irrigating water balances with the height.



C. Tectonics

Elements each have its own bulges and pits to connect, and space for a concrete wall as to strengthen the stairs.



Spherical Stucture

Makes arches in every section, stand stable

Light & Ventilation

Provided by bubble spaces

Telescopic Seam

Plant Area

Collects precipitation, provides landscape

Rabbet

Drainage Tube

Loading Wall

Concrete. Concealed. Coherent.

Outcomes of Cheese



▲ Platform

This pic shows a good vision from the platform between 3th and 4th floor.
It is bright enough to close lights.

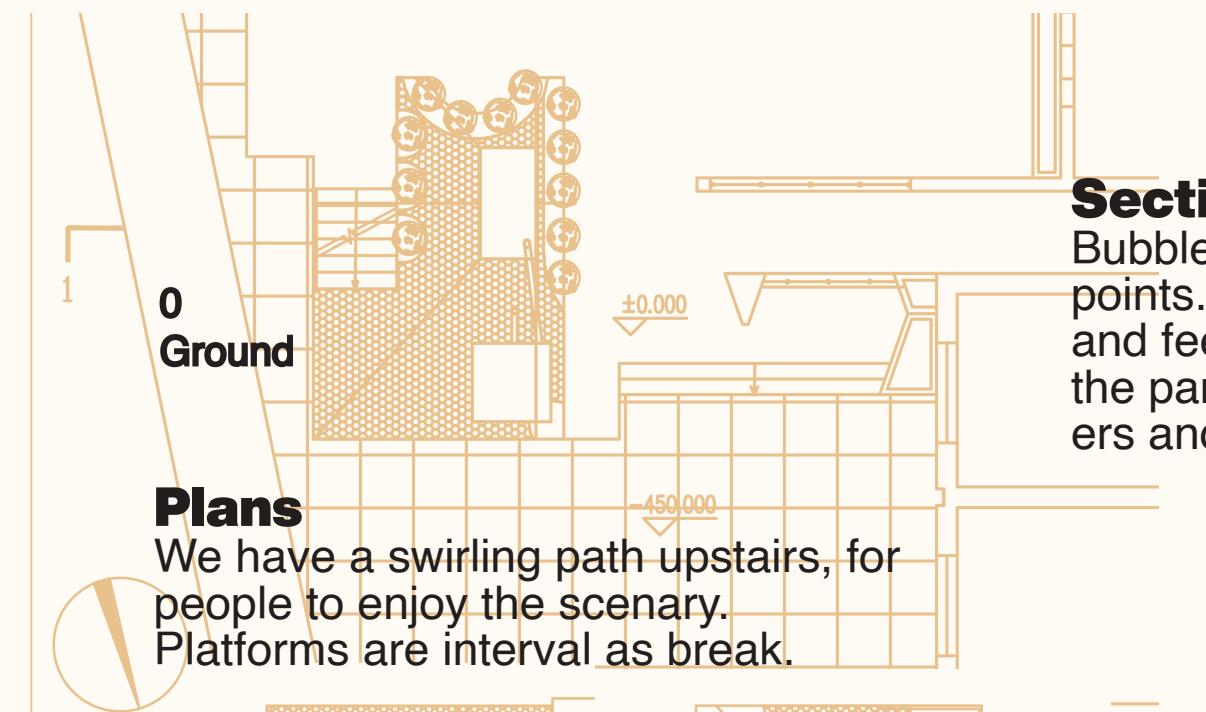


▲ Entrance

It shows the entrance as a good site for wind blowing.

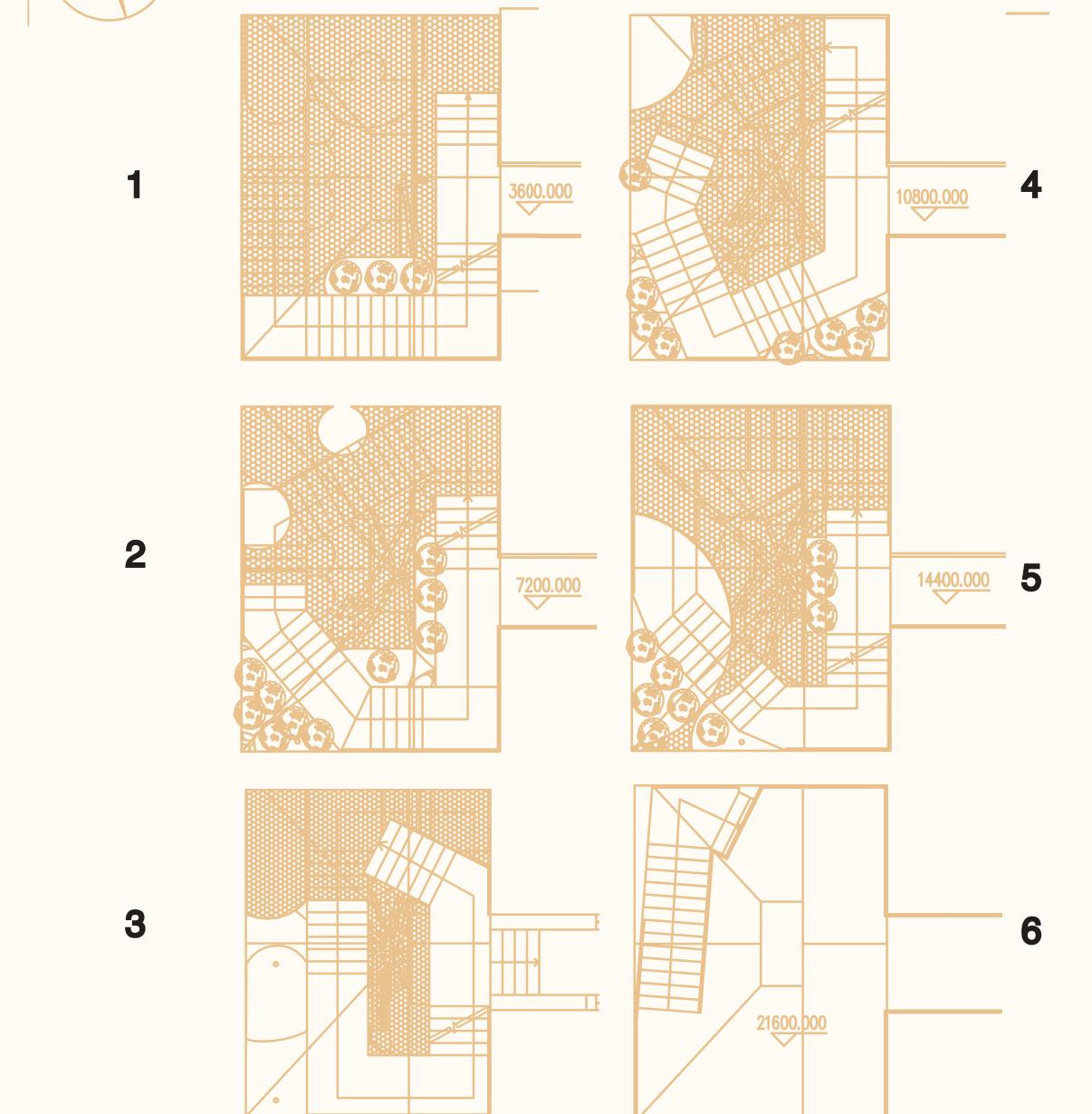
North Facade ▶

The bubbles shows a distinguished face toward vehicles passing by and the park .

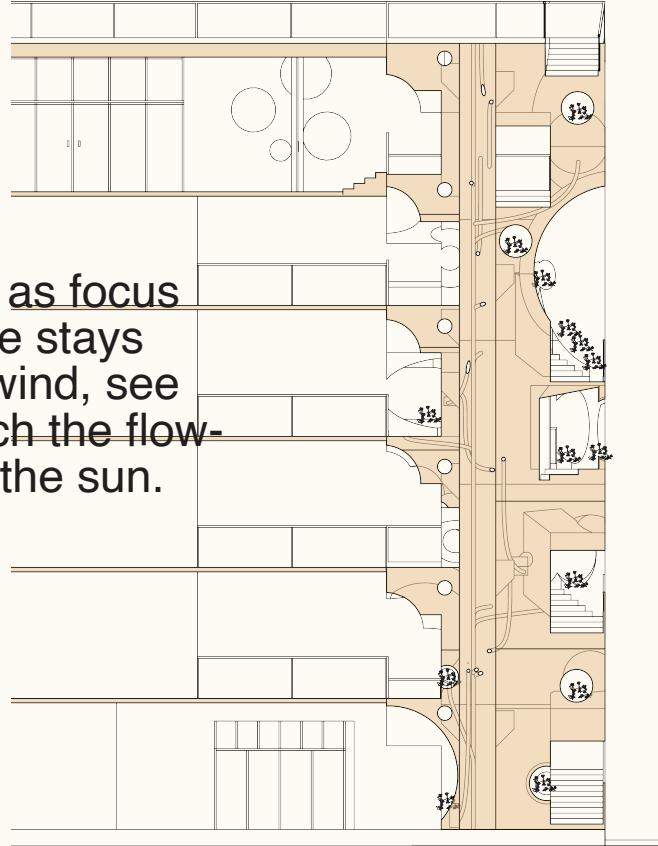


Plans

We have a swirling path upstairs, for people to enjoy the scenery.
Platforms are interval as break.



1:100 Model



Section

Bubbles play as focus points. People stays and feel the wind, see the park, touch the flowers and bath the sun.