

Understanding Longitudinal Modified Treatment Policies in `lmt`

Dynamic Treatment Strategies Based on Propensity Score Thresholds

Based on Díaz et al. (2021)

August 7, 2025

Outline

- 1 Introduction
- 2 Modified Treatment Policies
- 3 How Imtp Works
- 4 The Weight Mechanism
- 5 Implementation
- 6 Common Misconceptions
- 7 Summary

The Research Question

Clinical Scenario

How do we estimate the effect of a dynamic treatment strategy where:

- Treatment continues as long as the cumulative propensity score remains above a threshold α
- We have longitudinal data with time-varying confounders
- Outcome: probability of surviving event-free

Example

- $A_1 = 1$ if $g_1(1|L_1) > \alpha$
- $A_2 = 1$ if $g_1 \times g_2 > \alpha$ (but which policy?)
- In our code: $Y_t = 1$ means event occurred (note the coding!)
- Estimate: $P(Y_3 = 0) = P(\text{no event by time 3})$ under the policy

What are Modified Treatment Policies?

Definition (Modified Treatment Policy)

An intervention where the post-intervention treatment can depend on:

- The natural (observed) value of treatment
- The patient's history
- A random component

$$A_t^d = d(A_t, H_t, \epsilon_t)$$

Examples

- Static: $d(a_t, h_t) = 1$ (always treat)
- Dynamic: $d(a_t, h_t) = \mathbb{I}(L_t > c)$ (treat if covariate exceeds threshold)
- Modified: $d(a_t, h_t) = \min(a_t + \delta, u_{\max})$ (increase dose by δ)

Two Fundamentally Different Policies

Policy 1: Sequential Adherence

"Treat at time 2 if currently on treatment AND cumulative propensity $> \alpha$ "

```
return(ifelse(  
  data$A1 * g1 * g2 > alpha,  
  1,  
  data$A2  
)
```

- More conservative
- Respects treatment continuity
- Realistic for clinical protocols

Policy 2: Cumulative Propensity

Treat at time 2 if cumulative propensity $> \alpha$ regardless of current treatment

```
return(ifelse(  
  g1 * g2 > alpha,  
  1,  
  data$A2  
)
```

- More aggressive
- Based purely on propensity
- Theoretical optimal

Example: When Policies Differ

Consider a patient with:

- $g_1 = 0.4 > \alpha = 0.3$ (high propensity at time 1)
- Observed $A_1 = 0$ (not treated despite high propensity)
- $g_2 = 0.8$
- $g_1 \times g_2 = 0.32 > \alpha$

Policy 1

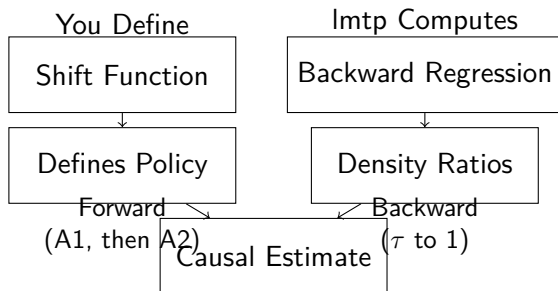
$$A_1 \times g_1 \times g_2 = 0 \times 0.32 = 0$$
$$0 < 0.3 \Rightarrow A_2 = \text{natural value}$$

Policy 2

$$g_1 \times g_2 = 0.32$$
$$0.32 > 0.3 \Rightarrow A_2 = 1$$

Key insight: These define different causal questions!

The Imtp Framework



Backward Sequential Regression (Our Setting)

The Sequential Regression Process

Starting from the end and working backward:

$$q_{\tau+1} = Y_{\tau+1} \text{ (final outcome)} \quad (1)$$

$$q_t(a_t, h_t) = \mathbb{E}[R_{t+1} \times q_{t+1}(A_{t+1}^d, H_{t+1}) | R_t = 1, A_t = a_t, H_t = h_t] \quad (2)$$

- R_t : at-risk indicator (no event by time t)
- $Y_t = 1$: event occurred (our coding)
- Regression only uses observations still at risk
- Final estimate: $\theta = 1 - \mathbb{E}[q_1(A_1^d, L_1)]$ estimates $P(Y_3 = 0)$

Important: Outcome Coding

In our R code, $Y_t = 1$ means event **occurred**. The `lmt` package handles this internally when `outcome_type = "survival"`. Different papers use different codings!

Understanding Different Outcome Codings

Our R Code

- $Y_t = 1$: Event **occurred** by time t
- $Y_t = 0$: Event **not occurred**
- Estimating: $P(Y_3 = 0)$ (survival)
- No competing risks

Sequential regression:

$$q_t = \mathbb{E}[R_{t+1} \times q_{t+1} | \dots]$$

Simple and clean!

Díaz et al. Papers

- $Y_t = 1$: Event **not occurred**
- $Y_t = 0$: Event **occurred**
- With competing risks:
 - $Z_t = 0$: No competing event
 - $Z_t = 1$: Competing event occurred

Their formula:

$$\phi_t = \mathbb{E}[R_{t+1}\{R_{t+2}\phi_{t+2} + Z_{t+1}\} | \dots]$$

The " $+Z_{t+1}$ " makes sense with their coding!

Key insight: Different coding conventions lead to different formulas, but both estimate the same thing: survival probability under the LMTP!

Why the Competing Risks Formula Works

Understanding the Díaz et al. Formula

$$\phi_t = \mathbb{E}[R_{t+1}\{R_{t+2}\phi_{t+2} + Z_{t+1}\}|\cdots]$$

With their coding ($Y_t = 1$ means no event, $Z_t = 1$ means no competing event):

- **If $R_{t+1} = 0$:** Person had an event by $t + 1$, contributes 0
- **If $R_{t+1} = 1$:** Person is still at risk at $t + 1$
 - **If $Z_{t+1} = 1$:** Competing event occurred \rightarrow contributes $1 \times 1 = 1$
 - **If $Z_{t+1} = 0$:** No competing event \rightarrow continues recursion

The Beauty of the Formula

The " $+Z_{t+1}$ " term elegantly handles competing risks:

- When competing event occurs: $Z_{t+1} = 1$, stops recursion
- When no competing event: $Z_{t+1} = 0$, but $R_{t+2} = 0$ if main event occurs
- The formula naturally tracks both types of events!

Density Ratios and Compatibility

The Key Mechanism

$$w_t = \frac{g^d(a_t|h_t)}{g(a_t|h_t)}$$

where:

- $g^d(a_t|h_t)$: density under your intervention
- $g(a_t|h_t)$: observed density

Key Insight

$g^d(a_t|h_t)$ can be **ZERO** when history is incompatible with the policy!

How Weights Enforce Compatibility

For a deterministic policy "treat if $g_1 > \alpha$ ":

Scenario	$g^d(a h)$	$g(a h)$	Weight
$g_1 > \alpha, A_1 = 1$	1	g_1	$1/g_1 > 1$
$g_1 > \alpha, A_1 = 0$	0	$1 - g_1$	0
$g_1 \leq \alpha, \text{ any } A_1$	$g(a h)$	$g(a h)$	1

Result

- Compatible observations: weighted appropriately
- Incompatible observations: **zero weight**
- Natural values: unit weight

Example: Weight Calculation

Patient with $g_1 = 0.4 > \alpha = 0.3$ but observed $A_1 = 0$:

- 1 Policy requires: $A_1 = 1$ (since $g_1 > \alpha$)
- 2 But observed: $A_1 = 0$
- 3 Density under policy: $g^d(0|h_1) = 0$ (impossible!)
- 4 Observed density: $g(0|h_1) = 1 - 0.4 = 0.6$
- 5 Weight: $w_1 = 0/0.6 = 0$

Consequence

This patient contributes **nothing** to the estimate because their history is incompatible with the policy being evaluated!

R Implementation

```
# Important: In our data generation, Y=1 means event OCCURRED
# Y2 = as.numeric(U.Yt2 > plogis((L1+(A1*2))))
# Y3 = ifelse(Y2==0, as.numeric(U.Yt3+1 < plogis(...)), 1)

# Define shift function for Policy 2
dynamic_threshold_shift <- function(data, trt) {
  # Compute propensity scores
  fit1 <- glm(A1 ~ L1, data = data, family = binomial())
  g1 <- predict(fit1, type = "response")

  if (trt == "A1") {
    return(ifelse(g1 > alpha, 1, data$A1))
  } else if (trt == "A2") {
    fit2 <- glm(A2 ~ L1 + A1 + L2, data = data,
               family = binomial())
    g2 <- predict(fit2, type = "response")

    # Policy 2: Cumulative propensity
    return(ifelse(g1 * g2 > alpha, 1, data$A2))
  }
}

# Run lmtp - it handles our Y coding when outcome_type = "survival"
# Estimates P(Y3 = 0) = P(no event by time 3)
result <- lmtp_tmle(
  data = data,
  trt = c("A1", "A2"),
  outcome = c("Y2", "Y3"),
  shift = dynamic_threshold_shift,
  outcome_type = "survival"
)
```

What the Shift Function Does NOT Do

Common Misconception

"The shift function assumes previous histories satisfy the protocol"

Reality

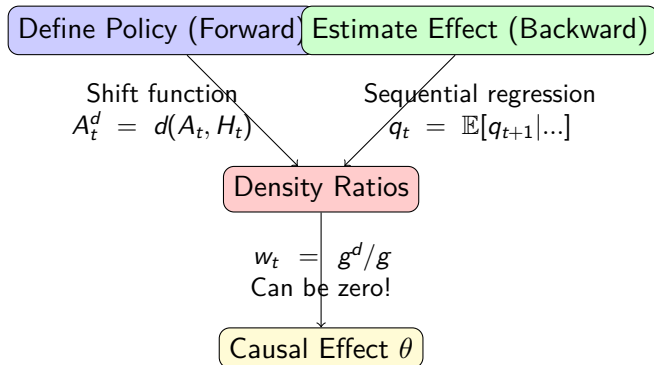
The shift function **defines a policy**, it doesn't make assumptions!

- The shift function is called with **observed data**
- It defines what treatment **should be** under your policy
- The weighting mechanism handles incompatible histories
- Zero weights effectively filter out incompatible observations

Key Takeaways

- ➊ **Shift functions define policies**, not assumptions about data
- ➋ **Two distinct policies** answer different causal questions:
 - Sequential adherence: realistic, conservative
 - Cumulative propensity: theoretical, aggressive
- ➌ **Imtp elegantly handles incompatibility**:
 - Density ratios can be zero
 - Incompatible histories get zero weight
 - Correct counterfactual estimation
- ➍ **Outcome coding matters!**
 - Our code: $Y = 1$ means event occurred
 - Some papers: $Y = 1$ means event NOT occurred
 - Different codings \rightarrow different formulas
 - Imtp's `outcome_type = "survival"` handles this
- ➎ **Backward sequential regression** is flexible for:
 - Different outcome codings
 - Competing risks (when present)
 - Time-varying confounders

The Complete Picture



Practical Guidelines

When to Use Policy 1 (Sequential Adherence)

- Clinical protocols require treatment continuity
- Stopping and restarting treatment is problematic
- You want to respect observed treatment patterns

When to Use Policy 2 (Cumulative Propensity)

- You want the theoretically optimal policy
- Treatment can be started/stopped freely
- You're interested in propensity-based decisions

Remember

Different policies answer different causal questions!

Questions?

References

- Díaz et al. (2021). Nonparametric causal effects based on longitudinal modified treatment policies. JASA.
- Díaz et al. (2024). Causal survival analysis under competing risks using longitudinal modified treatment policies. Lifetime Data Analysis.
- Williams & Díaz (2023). Imtp: An R Package for Estimating the Causal Effects of Modified Treatment Policies. Observational Studies.

Key Insight from This Talk

Understanding outcome coding is crucial! Always check whether $Y = 1$ means event occurred or event-free. This affects the formulas but not the underlying concepts.