CatBoost: unbiased boosting with categorical features

Liudmila Prokhorenkova, Gleb Gusev, Aleksandr Vorobev, Anna Veronika Dorogush, Andrey Gulin

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- Gradient Boosting
- Target Statistics(TS)
- Ordered Boosting
- 4 CatBoost

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Boosting

Given $\mathcal{D} = \{(x_k, y_k)\}_{k=1...n}$, where $x_k = (x_k^1, \ldots, x_k^m)$ is a data point with m features and y_k is the target, we want to learn a model $F : \mathbb{R}^m \to \mathbb{R}$ that minimizes the expected loss function $\mathcal{L}(F) := \mathbb{E}[L(y, F(x))]$.

- Using a sequence of weak models to produce a strong model
- Approximate F iteratively. We build a sequence of models F^t (t = 0, 1, ...) s.t.

$$F^t = F^{t-1} + \alpha h^t$$

 $h: \mathbb{R}^m \to \mathbb{R}$ is a function/base predictor chosen from a family of functions H.

Gradient Boosting

- $L^{t}(y, F^{t}(x)) := \frac{1}{2} \sum_{k=1}^{n} (y_{k} F^{t}(x_{k}))^{2}$
- $\frac{\partial L^t(y,F^t(x))}{\partial F^t(x)} = y F^t(x)$ the **residual**



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• In practice, ht's are decision trees (CART for Gradient Boosting)



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- Categorical Variables has a discrete set of values(categories) that are not comparable to each other.
 E.g. Gender, Major, User ID
- High dimensionality → target statistics(TS)
- A Typical TS is the expected target value conditioned on the category.

$$\hat{x}_k^i \approx \mathbb{E}[y \mid x^i = x_k^i]$$

• This changes a categorical feature to numerical feature that is easier for a decision tree to use.

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Solution Attempt: Greedy TS

- For a category *i*, use the average target value of all samples within this category to estimate TS.
- Add smoothing:

$$\hat{x}_k^i := \frac{\sum_{j=1}^n \mathbb{1}_{\{x_j^i = x_k^i\}} \cdot y_j + ap}{\sum_{j=1}^n \mathbb{1}_{\{x_j^i = x_k^i\}} + a}$$

where a > 0 is a hyperparameter and p is the prior probability. $p = \frac{1}{n} \sum_{k=1}^{n} y_k$

Target Leakage & Conditional Shift

- Target leakage: we use y_k (target/the ground-truth label) to compute a feature that is used in a model to predict y.
 - "leaking answers to testtakers" when training
 - BUT, no access to answer when testing
- Conditional shift: Train $\hat{x}_{k}^{i}|y_{k} \Rightarrow \text{Test } \hat{x}^{i}|y$

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- 2 Problems:
 - 1. \hat{x}_k^i is a **biased** estimator of $\mathbb{E}[y \mid x^i = x_k^i]$
 - 2. overfitting, poor generalization

Solutions

• Holdout TS: Partition the training set into 2 parts $\mathcal{D} = \mathcal{D}_0 \cup \mathcal{D}_1$. One for calculating the TS and the other for training.

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• Holdout TS: Partition the training set into 2 parts $\mathcal{D} = \mathcal{D}_0 \cup \mathcal{D}_1$. One for calculating the TS and the other for training.

Inefficient data usage

- Ordered TS: No using y_k for \hat{x}_k^i
 - (randomly) order the data
 - compute TS only using the preceding examples

Let σ be a random permutation of the indices $1, \ldots, n$. For the k-th training example, use $\mathcal{D}_k = \{x_i : \sigma(i) < \sigma(k)\}$ for computing TS.

For a testing example, use \mathcal{D} .

This ensures $\mathbb{E}[\hat{x}_{k}^{i}|y_{k}] = \mathbb{E}[\hat{x}^{i}|y]$



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Prediction Shift & Ordered Boosting

- Similar Problem when doing gradient boosting: $h^t(x_k, y_k) \approx -g^t(x_k, y_k)$ is computed using x_k
- Train $g^t(x_k, y_k) \mid x_k \Rightarrow \text{Test } g^t(x, y) \mid x$
- Ordered boosting:

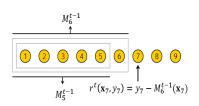


Figure 1: Ordered boosting principle, examples are ordered according to σ .

Algorithm 1: Ordered boosting

return M_n

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CatBoost

• CatBoost: using *ordering principle* when (1) dealing with categorical features and (2) computing gradient in boosting

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Algorithm 2: Building a tree in CatBoost
input : M, \{(\mathbf{x}_i, y_i)\}_{i=1}^n, \alpha, L, \{\sigma_i\}_{i=1}^s, Mode
grad \leftarrow CalcGradient(L, M, y);
r \leftarrow random(1, s); // sample an index for the permutation
if Mode = Plain then
 | G ← (grad<sub>r</sub>(i) for i = 1..n);
if Mode = Ordered then
 G ← (grad_{r,\sigma_r(i)-1}(i) \text{ for } i = 1..n);
T \leftarrow \text{empty tree};
foreach step of top-down procedure do // choose the optimal tree structures
     foreach candidate split c do
          T_c \leftarrow \text{add split } c \text{ to } T;
          if Mode = Plain then
               \Delta(i) \leftarrow \text{avg}(qrad_r(p) \text{ for }
                p: leaf_r(p) = leaf_r(i)) for i = 1..n;
          if Mode = Ordered then
               \Delta(i) \leftarrow \operatorname{avg}(\operatorname{grad}_{r,\sigma_{-}(i)-1}(p)) for
                p : lea f_r(p) = lea f_r(i), \sigma_r(p) < \sigma_r(i))
                for i = 1..n:
         loss(T_c) \leftarrow cos(\Delta, G)
     T \leftarrow \arg \min_{T} (loss(T_c))
if Mode = Plain then
     M_{r'}(i) \leftarrow M_{r'}(i) - \alpha \operatorname{avg}(\operatorname{grad}_{r'}(p)) for
      p: leaf_{r'}(p) = leaf_{r'}(i)) \text{ for } r' = 1..s, i = 1..n;
if Mode = Ordered then // update the predictions
     M_{r',j}(i) \leftarrow M_{r',j}(i) - \alpha \operatorname{avg}(\operatorname{grad}_{r',j}(p)) for
      p : leaf_{r'}(p) = leaf_{r'}(i), \sigma_{r'}(p) \leq j for r' = 1...s,
      i = 1..n, i \ge \sigma_{r'}(i) - 1;
return T, M
```

Thank You!

