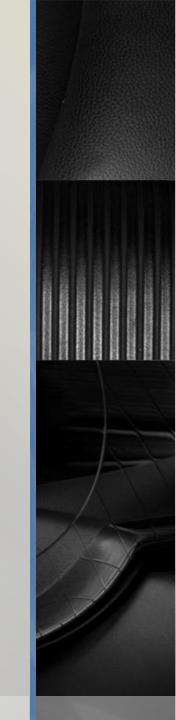
Web Based Graphics & Virtual Reality Systems
Programmable Shaders

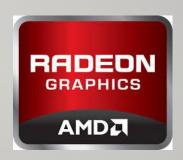


CPU and **GPU**

- The concept of GPU starts from early 2000
- Specially tailored for processing rendering tasks of graphics
- GPU become programmable in its rendering process
 - Shader will be introduced later in this lecture

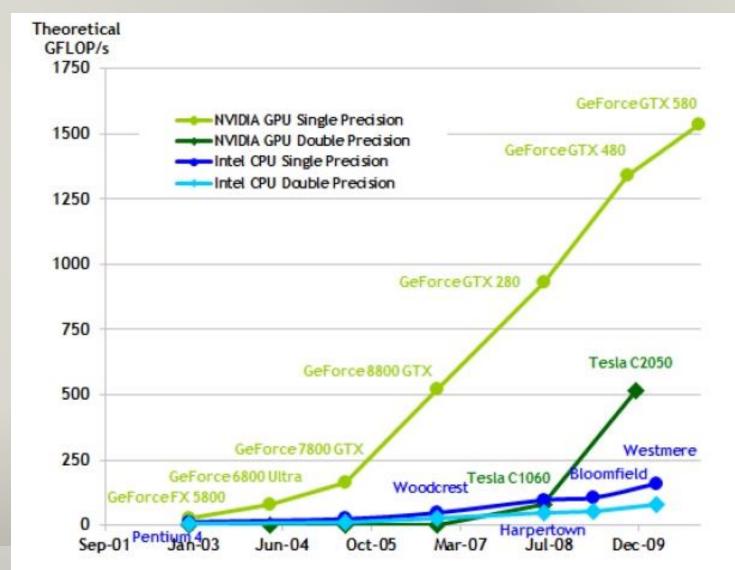
CPU and **GPU**

- Basic difference between CPU and GPU
 - Large number of parallel units in the pipeline
- This design is especially useful for graphics applications
 - Large number of vertices undergo similar or same transformation and operations
- Major GPU manufacturers
 - Nvidia : Geforce Series
 - AMD / ATI : Radeon Series
 - Intel





Computing Power of CPU and GPU



GFLOP:

FLoating-point
OPerations per
Second

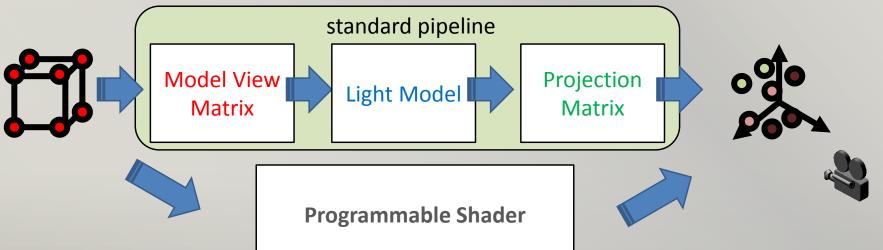
Computing Power of CPU and GPU

Compute

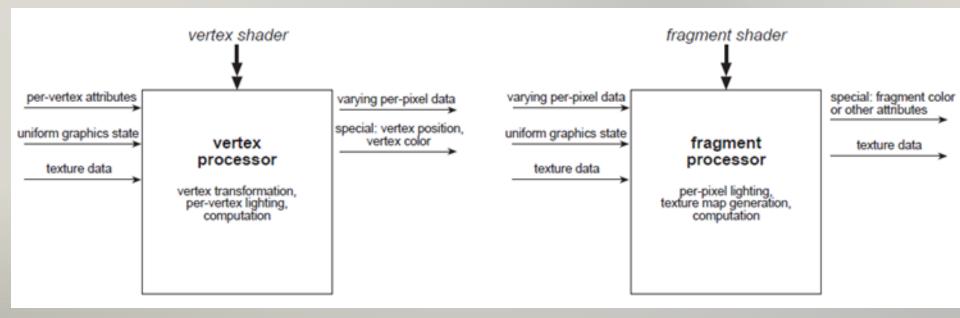
- Intel Core i7 4 cores 100 GFLOP
- NVIDIA GTX280 240 cores 1 TFLOP
- Memory Bandwidth
 - System Memory 60 GB/s
 - NVIDIA GTX680 200 GB/s
 - PCI-E Gen3 8 GB/s
- 2012 GPU peak FLOP about 10x CPU

- The standard rendering pipeline are being hard-wired in graphics hardware for years
- Until around 10 years before, the graphics hardware becomes programmable
- The small programs which can customize certain parts of the rendering pipeline are called "Shader"

- Instead of going through standard pipeline
- We can now write own programs to perform other processing steps wanted
- E.g. for vertex processing :

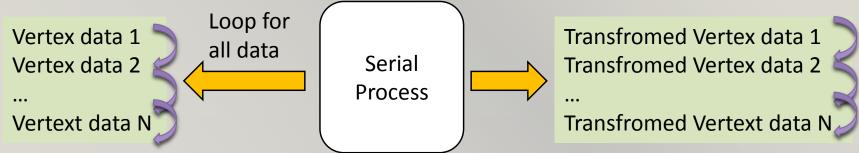


- Two major kinds of shaders are available:
 - Vertex shader (for vertex processing)
 - Fragment shader (for fragment processing)

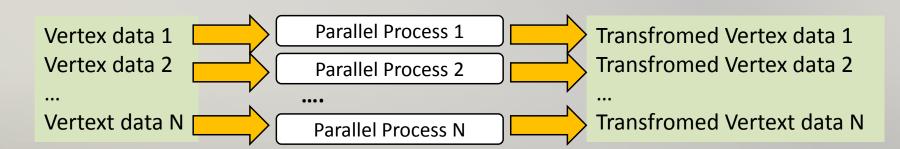


- ★GPU hardwares are designed to process a large number of vertices and fragments at the same time
- The major difference of GPU shaders to normal programs is that they are being processed in a <u>parallel</u> <u>manner</u>
- Serial program process all data one by one
- Parallel programs processes all data at the same time

Serial Processing

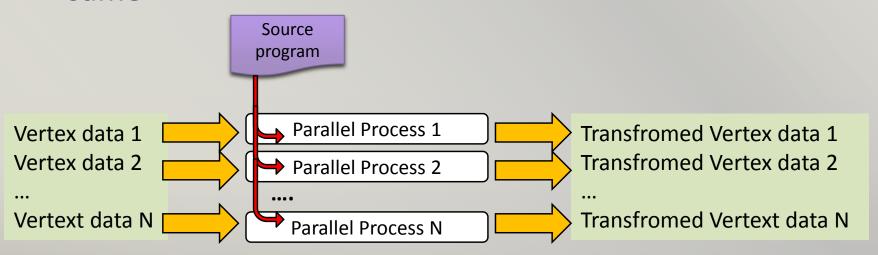


Parallel Processing



SIMD

- The parallel processing model in GPU is called SIMD (Single Instruction Multiple Data)
- SIMD architecture
 - Incoming data are different, but all program source are the same



- Although shader is run inside GPU, several languages are available for writing it
 - Cg (Nvidia)
 - GLSL (Open standard)
 - CUDA (Nvidia)
 - OpenCL (Open standard)





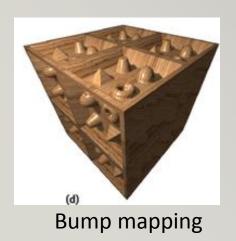


Shaders

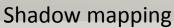
- Various kinds of shaders are available
 - Vertex Shader
 - Fragment Shader
 - Geometry Shader
- Responsible for handling different elements in corresponding part of the rendering pipeline

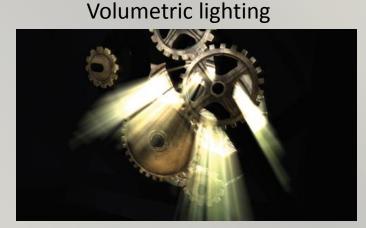
Applications of Shaders

 Special and advanced real-time effects can be done with the use of shaders











Skin rendering

Application: Physics Simulation

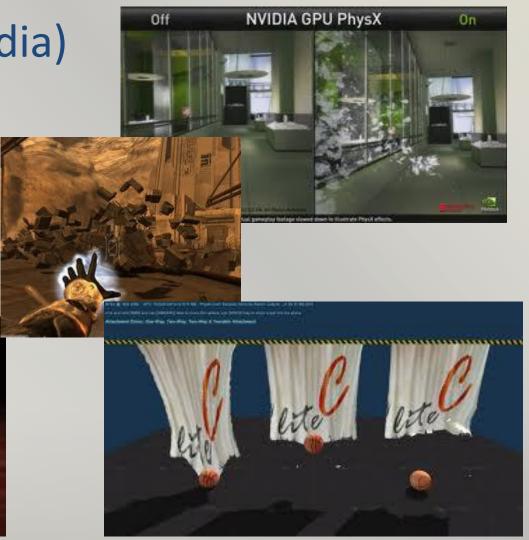
PhysX engine (Nvidia)

Rigid motions

Cloth simulation

Fluid dynamics





Application on Rendering Approaches

- Real-time non-photorealistic rendering
- Real-time Raytracing



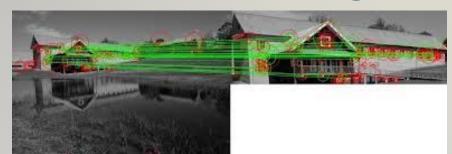
Nvdia GPU Raytracing



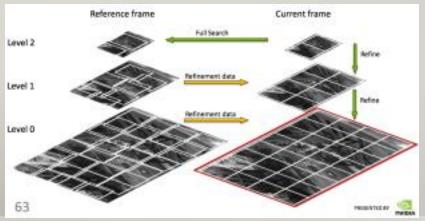
Toon Shaded Game

Application: Image and Video Processing

- Image Registration
- Motion Estimation



- Video Encoding and Compression
- Mainly to accelerate computational intensive tasks



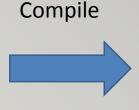


GPU Architecture: the basics

- CPU runs machine or assembly code of your compiled program
- GPU runs also assembly code, but from your compiled shader

```
sampler mySamp;
Texture2D<float3> myTex;
float3 lightDir;

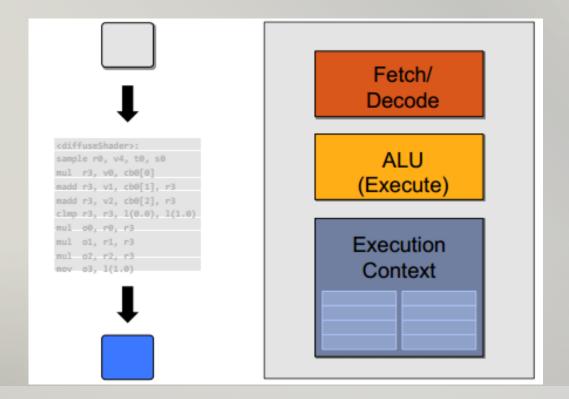
float4 diffuseShader(float3 norm, float2 uv)
{
   float3 kd;
   kd = myTex.Sample(mySamp, uv);
   kd *= clamp( dot(lightDir, norm), 0.0, 1.0);
   return float4(kd, 1.0);
}
```



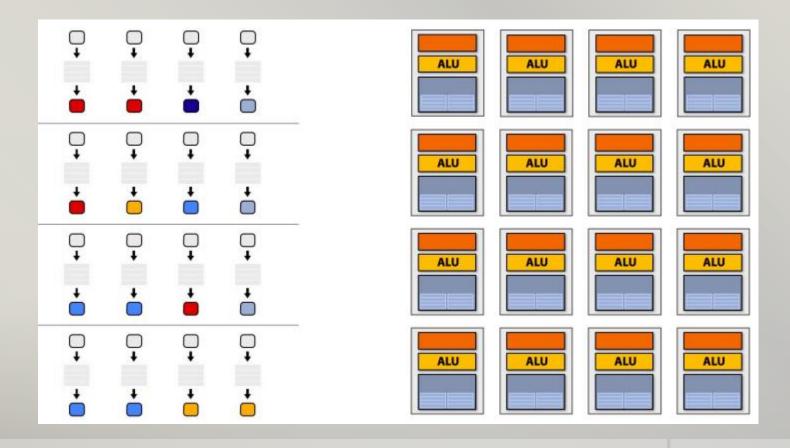
Assembly code

```
<diffuseShader>:
sample r0, v4, t0, s0
mul r3, v0, cb0[0]
madd r3, v1, cb0[1], r3
madd r3, v2, cb0[2], r3
clmp r3, r3, l(0.0), l(1.0)
mul o0, r0, r3
mul o1, r1, r3
mul o2, r2, r3
mov o3, l(1.0)
```

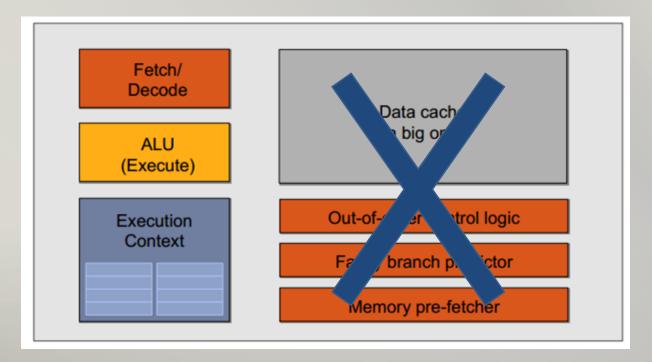
 Each GPU core runs the shader for a particular element (e.g fragment)



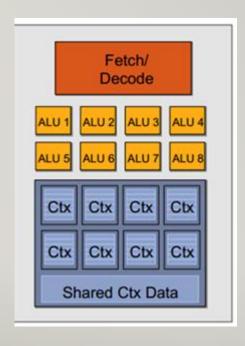
Multiple cores running in parallels

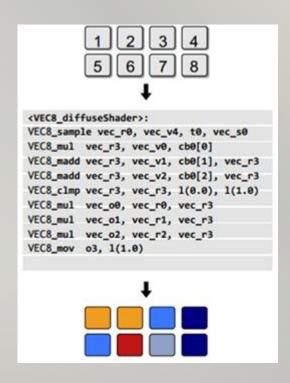


- Compare to a CPU-style core, GPU keeps a single core as simple as possible
 - Referred as "Slimmed down core"



- Tailor for SIMD processing
 - Combine fetch unit of several elements in one core

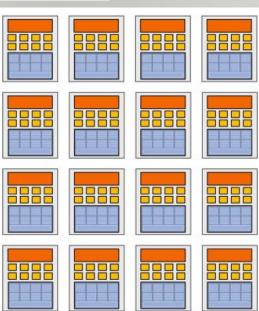




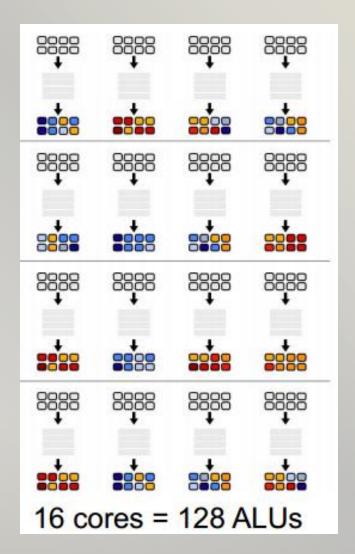
In practice, 16 to 64 fragments share an instruction stream



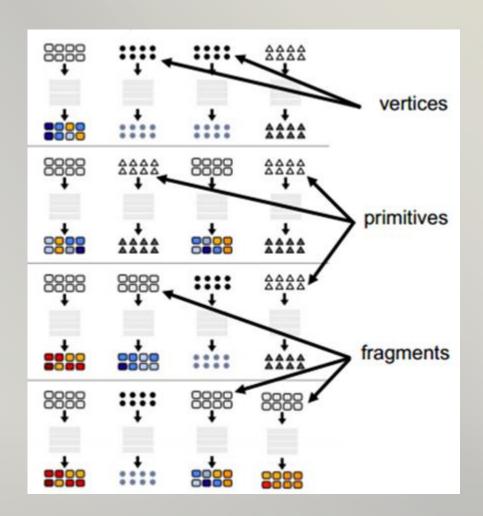
- Multiple cores runs in a GPU
 - Each of them can run same or different shader program



- Each core processes several elements simultaneously
 - Several ALU in one core

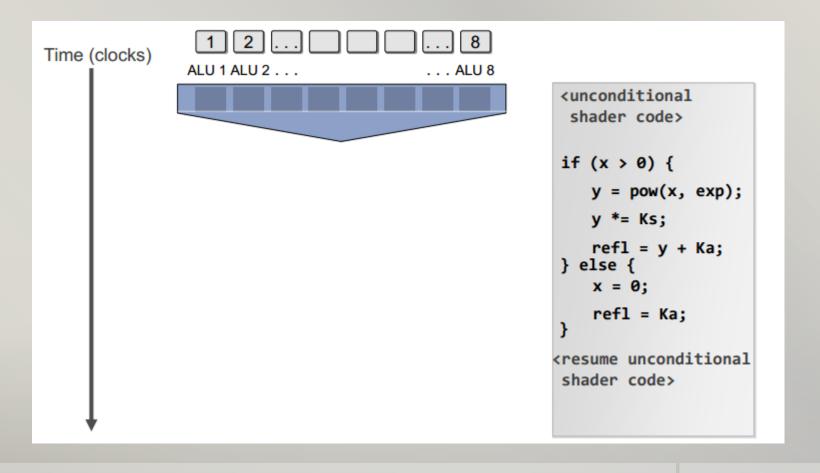


- Each core can process different elements including
 - Vertices
 - Triangles (primitives)
 - Fragments



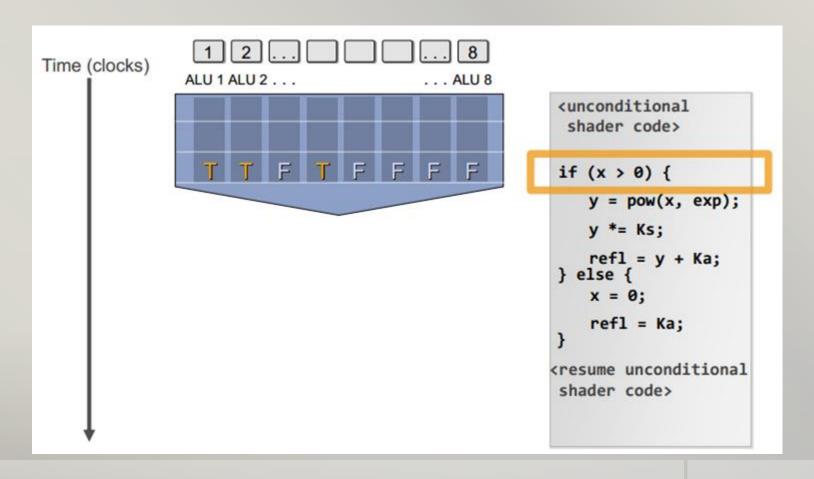
Problem of Branching in Core

However, not all element runs the same



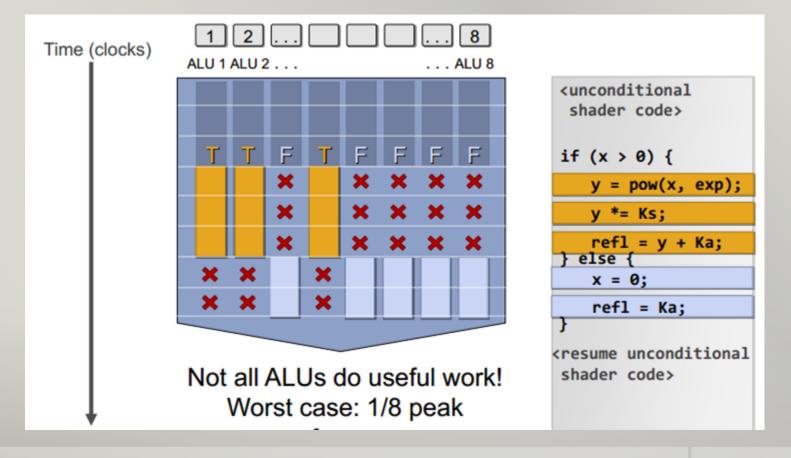
Problem of Branching in Core

An if-else will divide elements in 2 groups



Problem of Branching in Core

Cross represents ALU idle time

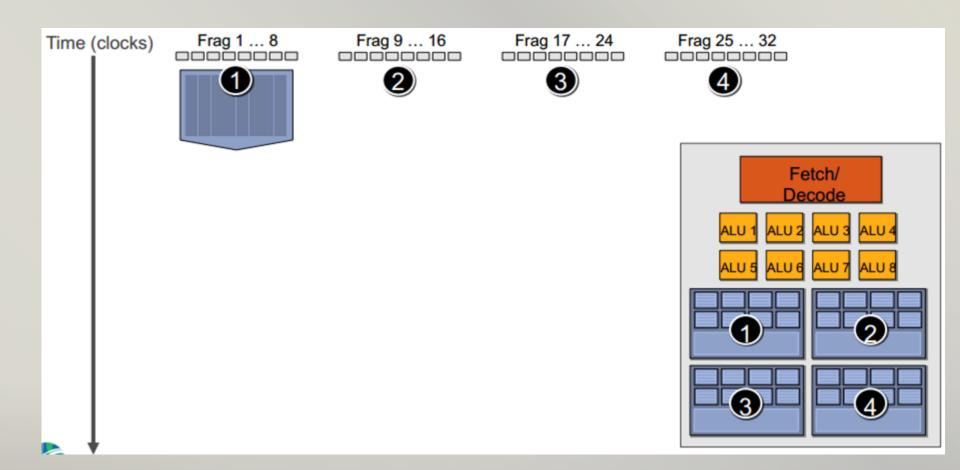


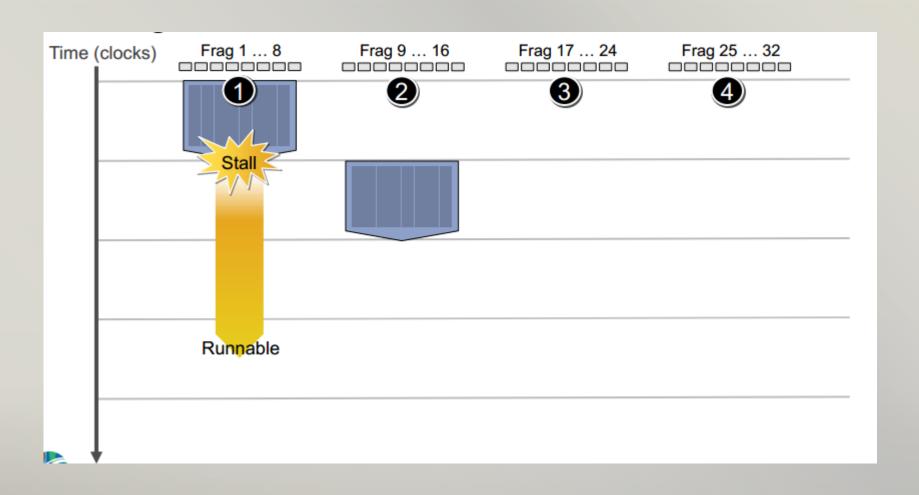
- Increase throughput with enlarged context
- Avoid latency stalls by interleaving execution of many groups of fragments
 - When one group stalls, work on another group

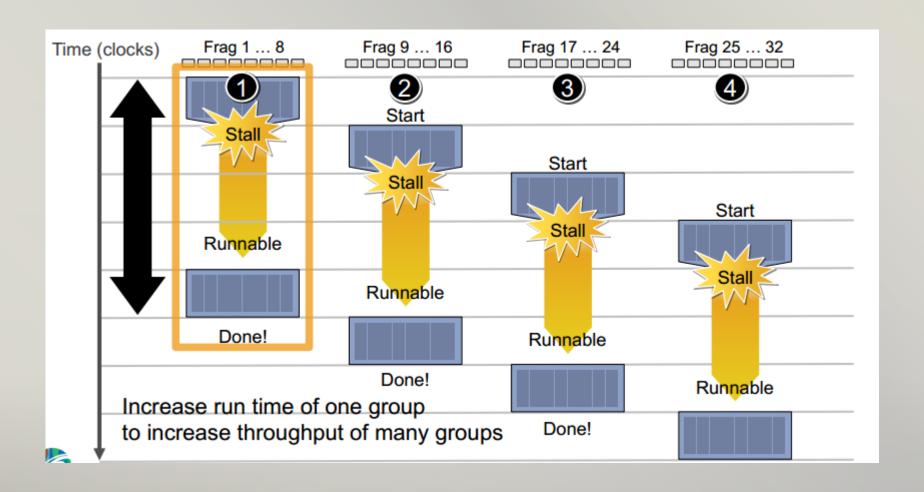
Summary: three key ideas

- 1. Use many "slimmed down cores" to run in parallel
- Pack cores full of ALUs (by sharing instruction stream across groups of fragments)
 - Option 1: Explicit SIMD vector instructions
 - Option 2: Implicit sharing managed by hardware
- Avoid latency stalls by interleaving execution of many groups of fragments
 - When one group stalls, work on another group

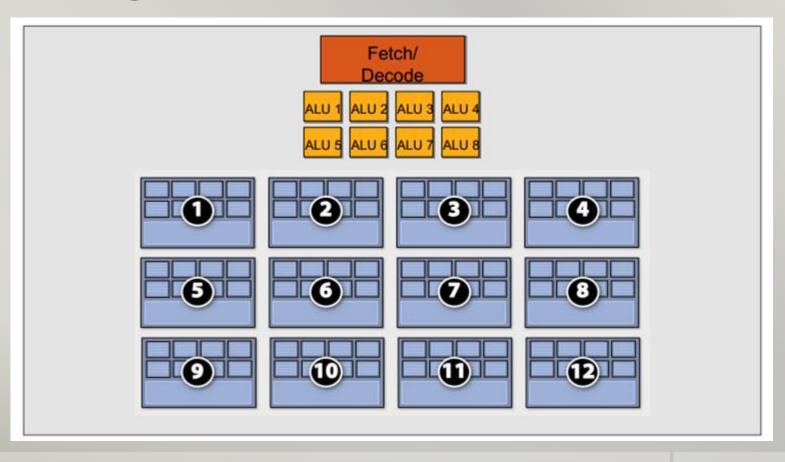








Storing context



An Example Chip

16 cores

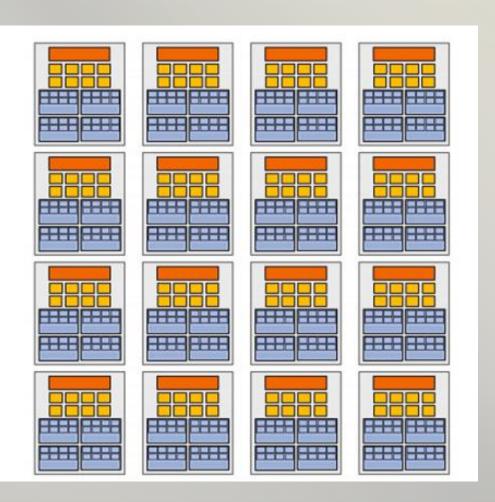
8 mul-add ALUs per core (128 total)

16 simultaneous instruction streams

64 concurrent (but interleaved) instruction streams

512 concurrent fragments

= 256 GFLOPs (@ 1GHz)



Shader Programming

- Setup of environment in the rendering engine (e.g. OpenGL)
 - Loading geometry, texture and other graphics elements into the engine (i.e. memory on GPU)
 - Loading shader program
 - Bind the shader program in rendering loop
- Shader program runs in parallel for all elements automatically during rendering
- The typical output is to frame buffer, but for GPGPU, we may have to dump output back to main memory

Shaders

- GLSL is used as example in the follow
- Shader object: an individual vertex, fragment, etc. shader
 - Are provided shader source code as a string
 - Are compiled
- Shader program: Multiple shader objects linked together
- Uniform variables: for passing in parameters to the shader program

Shader Objects

Compile a shader object:

```
const char *source = // ...
                                     Create a Shader Object and return its
GLint sourceLength = // ...
                                     handle
GLuint v = glCreateShader(GL VERTEX SHADER);
glShaderSource(v, 1, &source, &sourceLength);
                                              Provide the shader's
                                              source code as a string
glCompileShader(v);
                                  Compile the shader
glDeleteShader(v);
```

Shader Programs

Link a shader program:

Notice that the program had not yet applied to any of your rendered objects !!!

Using Shader Programs

Apply the Shader Program before any draw commands of OpenGL.

The same program can be applied on different drawing targets

```
GLuint p = g/CreateProgram();
// ...

glUseProgram(p);

glDraw*(); // * because there are lots of draw functions
// ...
```

Uniforms

```
GLuint p = glCreateProgram();
// ...
glLinkProgram(p);
```

Each *active* uniform variable has an integer index location (or handle).

```
GLuint m = glGetUniformLocation(p, "u_modelViewMatrix");
GLuint l = glGetUniformLocation(p, "u_lightMap");

// ...

glUseProgram(p);
mat4 matrix = // ...

glUniformMatrix4fv(m, 1, GL_FALSE, &matrix[0][0]);
glUniformli(l, 0);
```

Uniforms can be changed as often as needed before applying to drawing commands, but are constant during a draw call !!

Shader Programming

A Simple Example

Input: a teapot model

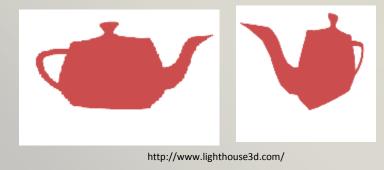


- Vertex Shader: Manipulate the vertices of the model so as to make it flatten
- Fragment Shader: a pass through or assigned certain color, e.g.

```
void main() {
   gl_FragColor = vec4(0.4,0.4,0.8,1.0);
}
```

The Flatten Shader

The Vertex Shader makes all input vertices with z = 0 (keeps x and y)



Actually making a cross-section at z=0

The Flatten Shader

 Another alternative is to assign z value with a sine function of coordinate x



It will produce a wavy flat teapot

```
void main(void) {
  vec4 v = vec4(gl_Vertex);
  v.z = sin(5.0*v.x )*0.25;

  gl_Position = gl_ModelViewProjectionMatrix * v;
}
```

Input: a teapot model

- Vertex Shader: Multiply vertex with modelview and projection matrices, and pass normal to fragment shader
- Fragment Shader: Apply a stepping function to map the renderred color

- The Vertex Shader
 - Passing normal vector to fragment shader
 - Values will be interpolated on each fragment

```
varying vec3 normal;
void main() {

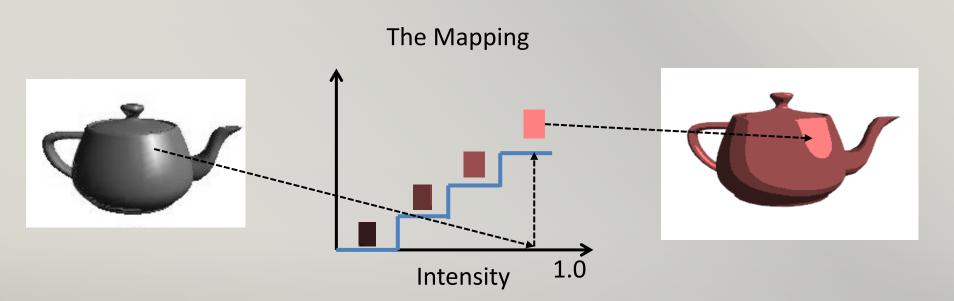
  vec4 v = vec4(gl_Vertex);
  gl_Position = gl_ModelViewProjectionMatrix * v;

  normal = gl_Normal;
}
```

- Based on per-fragment normal to compute shading
- Then, use shading intensity to map final color

```
uniform vec3 lightDir;
varying vec3 normal;
                                     Compute shading using Phong model
void main() {
  float intensity;
  vec4 color;
  intensity = dot(lightDir,normalize(normal));
  if (intensity > 0.95) color = vec4(1.0, 0.5, 0.5, 1.0);
  else
                                                           Smoothly changing
  if (intensity > 0.5) color = vec4(0.6, 0.3, 0.3, 1.0);
                                                           intensity is mapped to 4
  else
  if (intensity > 0.25) color = vec4(0.4, 0.2, 0.2, 1.0);
                                                           different colors
  else
    color = vec4(0.2, 0.1, 0.1, 1.0);
  gl FragColor = color; }
```

 The mapping is like a quantization to the shading intensity



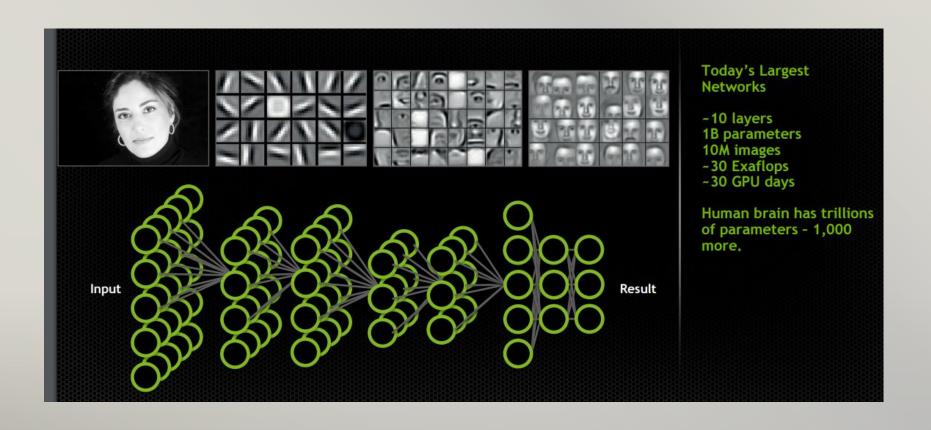
GPGPU

- General Purpose GPU
 - Not only for graphics related applications
 - Physics based simulation can also be regarded as a kind of GPGPU
- Recent examples: Bitcoin Miner using GPU



GPGPU

Recent examples: Deep learning



GPGPU

- We use GPU as a parallel processor
- A mapping between rendering pipeline and general purpose computation
 - Rendering pipeline

 Texture

 Data Buffer

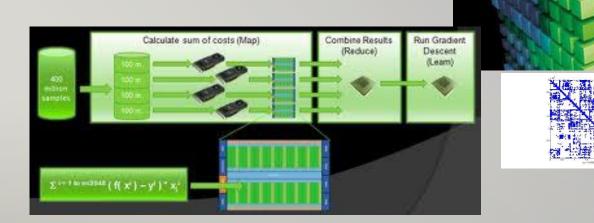
 Data Buffer

 Shader

 Parallel Program

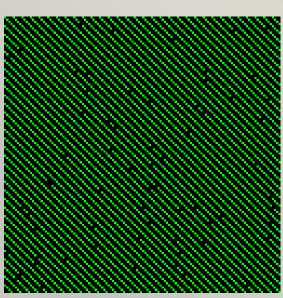
Application of GPGPU

- Accelerated Linear Algebra Computation
 - E.g. CUBLAS, cuSPARSE
- Massive Random Number Generation
- Machine Learning Algorithms
- Sorting

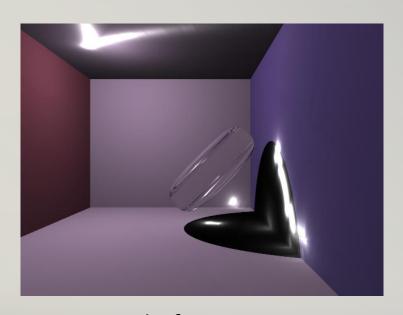


Pseudo-random number generator (PRNG)

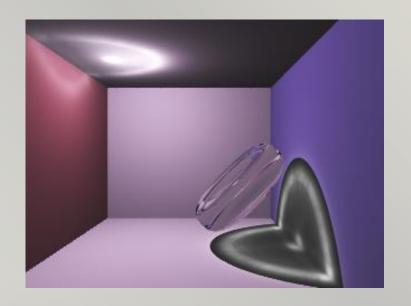
- Provide uniform random numbers
- Example : rand() in C
- Stochastic rendering algorithms
 - Photon-mapping
 - Distribution ray-tracing
- Poor randomness -> slow convergence



Pseudo-random number generator (PRNG)



Results from an LCG 10,000 photons



Control Image 10,000 photons

Some common PRNG

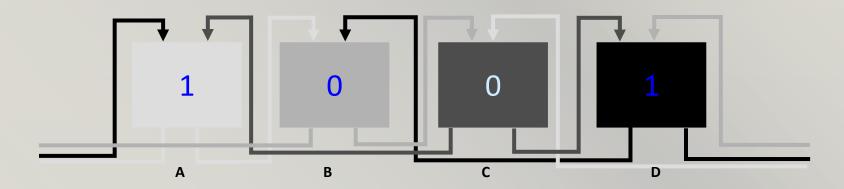
- linear congruential generator (LCG)
 - \blacksquare $R_{n+1} = aR_n + b \pmod{m}$
- lagged Fibonacci generator
 - \blacksquare R_n= R_{n-i} # R_{n+k} (mod m) (where # is a binary operator)
- High precision integer arithmetics
- Can't fit in the current GPU!
- GPU implementation is not available

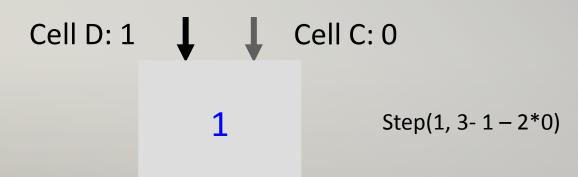
PRNG on GPU

- CA-based PRNG
- No high precision integer arithmetics
- Adoptable PRNG for different GPU
- PRNG Performance on different GPU
 - 7800 GTX and FX5900
- Why not find optimal PRNG automatically ?

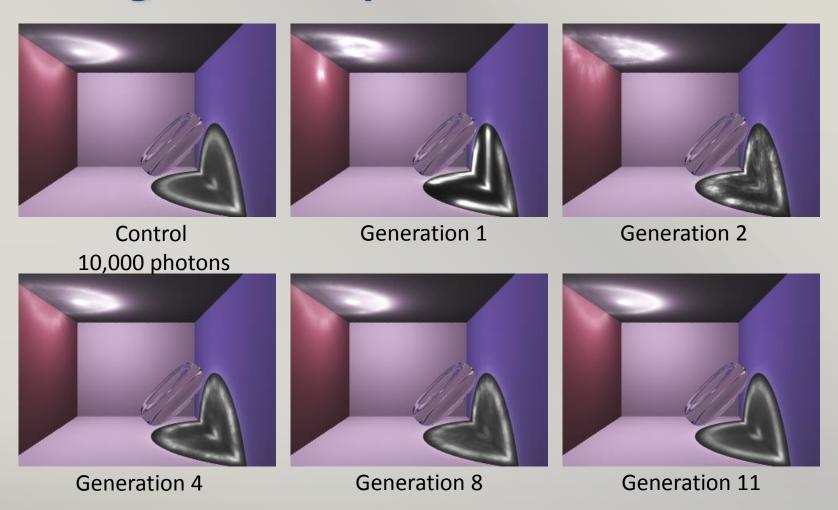
GPU Accelerated PRNG

- GPU : NO High precision integer arithmetic
- Most PRNG cannot fit in all GPU





Convergence of Optimization



Performance

- Performance compare with CPU
- 1,000 Parallel PRNG
- 13 times faster

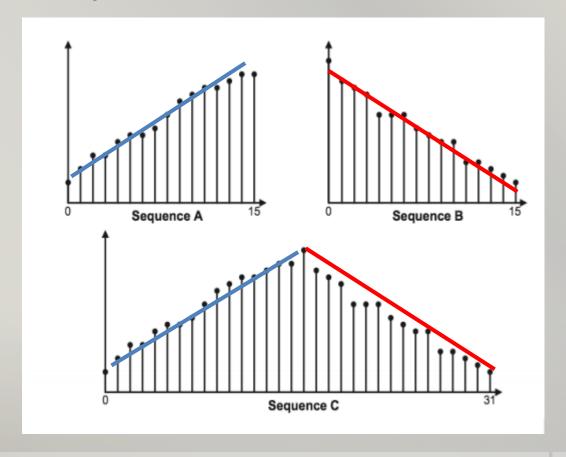
Random numbers generated	GPU CA-PRNG	Software CA- PRNG
10,000	0.004s	0.043s
100,000	0.031s	0.425s
1,000,000	0.31s	4.274s
10,000,000	3.098s	43.003s
100,000,000	31.875s	430s

Quicksort algorithm

- Divide and conquer approach (recursive)
 - Recursively divide the sequence into two based on a selected pivot value
- For n items, it has O(n log(n)) complexity on average and O(n²) in the worst case.
- But it is not very well fit for parallel processing
 - The two sequence are not balanced
 - Operation depends on the previous operations

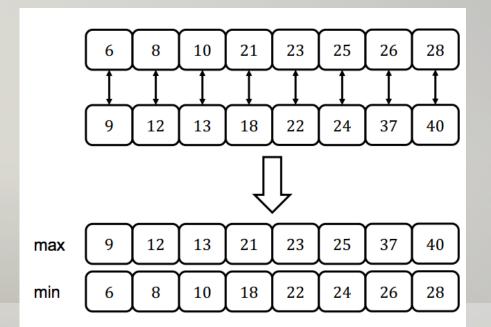
- Bitonic sort is a sort algorithm that works only with bitonic sequences of values
- A bitonic sequence is
 - A sequence a0, a1, ..., an is bitonic if and only if
 - There is an i, such that a0, ... ai is monotonically increasing and
 - ai, ... an is monotonically decreasing
- There is a cyclic shift of the sequence which makes the previous condition true

Bitonic sequences



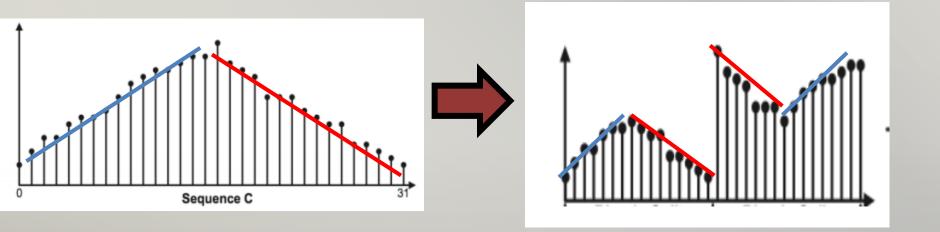
Bitonic Split

- This operation contains 2 Steps
 - Compare each element in the lower half of the sequence (0
 i) with the corresponding element in the upper half (i+ N/2)
 - If the element in the lower half is greater than the element in the upper half, swap the two elements



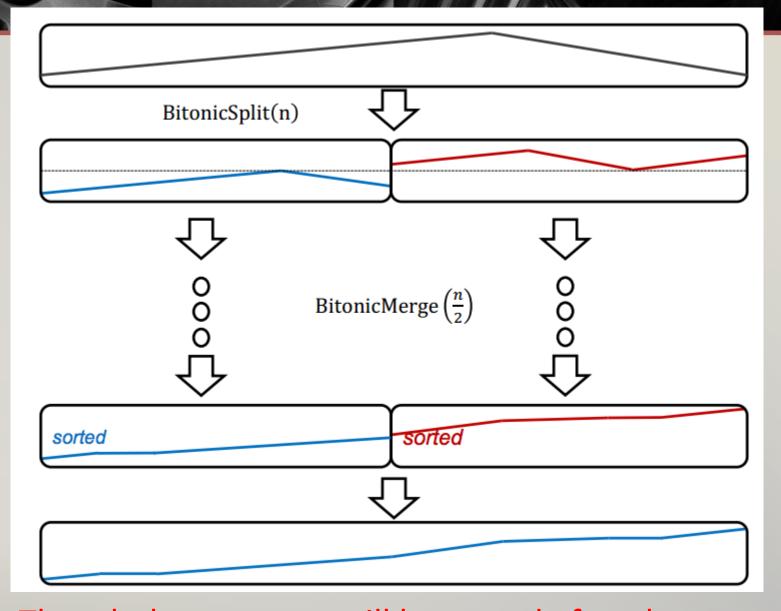
Bitonic Split

- If we apply the bitonic split to the sequence C, we obtain a sequence which is not bitonic
- But the two sequences are bitonic themselves



Bitonic Merge

- The bitonic merge consists in applying the bitonic split iteratively
- If a sequence contains N elements N=2k,
 the bitonic merge requires k steps
 - Each step is a bitonic split
 - Step i, splits N/i elements



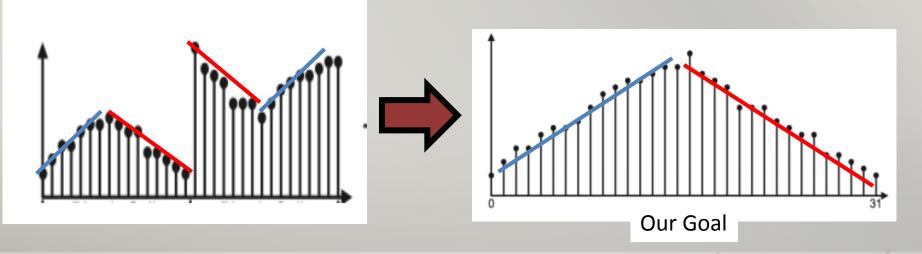
The whole sequence will be sorted after the bitonic merge operation!!

Bitonic Merge

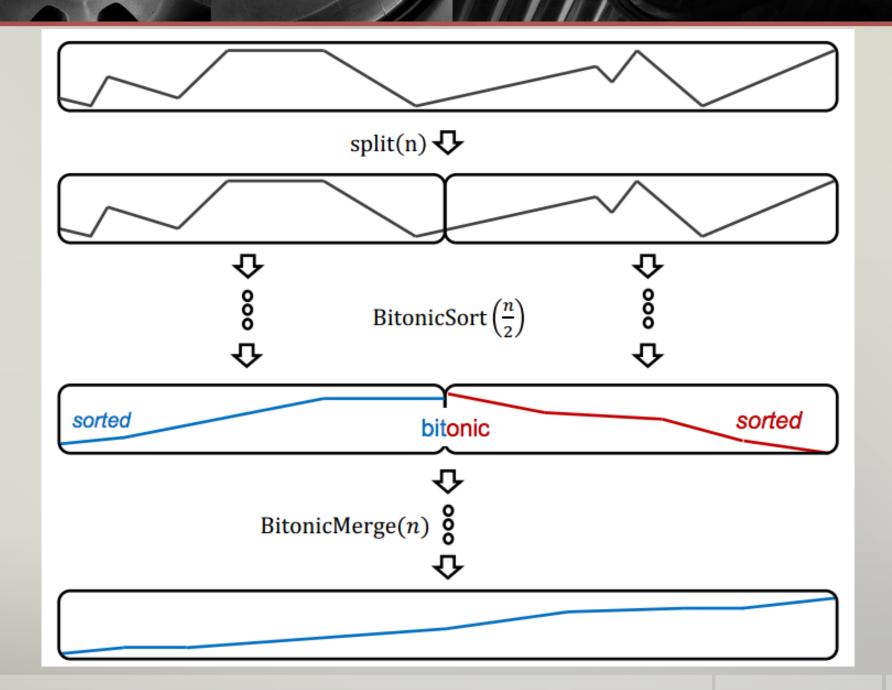
- If the sequence is bigger than N=2k but smaller than N=2k+1
 - We sort N=2k+1 elements, filling the extra values with the maximum possible value
- It is obvious that the algorithm can be parallelized easily
 - Each comparison in a pair of numbers within bitonic split is independent to each other

- But what if our sequence is not bitonic at the beginning? It is very likely to be...
- How about we first transform the sequence into a bitonic one?
- Split the sequence into two half each time
- Apply recursively on each half to construct a bitonic sequence

- Ultimately, we will split into a sequence of only two elements
 - Note that all two-elements sequence is already bitonic
- So, in each step, our objective is to
 - Combine two sequences with the first half being increasing and the upper half decreasing



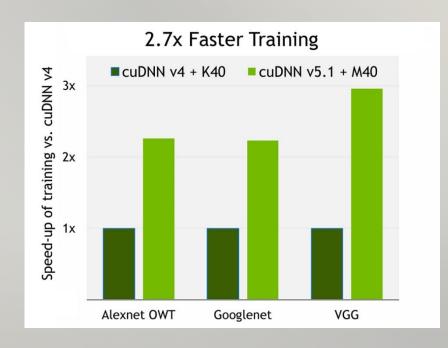
- In other words, we are doing two sortings
- 1. First half: sort in ascending order
- 2. Second half: sort in descending order
- So, we can apply a Bitonic sort (or bitonic merge)!
 - As each half now is bitonic itself



- Creating a bitonic sequence is actually sorting the data
 - Following a special order
- It is data independent
 - We can make a sorting network!
- So, very suitable for parallel processing

Deep Learning with GPU

- cuDNN
 - https://developer.nvidia.com/cudnn
- Many deep learning libraries support GPU
 - Caffe, Torch, Chainer
- DIGITS
 - For visualization
- (refers to notes from nVidia)



Summary

- We have discussed different topics related to GPU, e.g.
 - Difference between CPU and GPU
 - Strength and weakness of GPU
 - Graphics applications of GPU
 - Various types of Shaders
 - General Purpose GPU