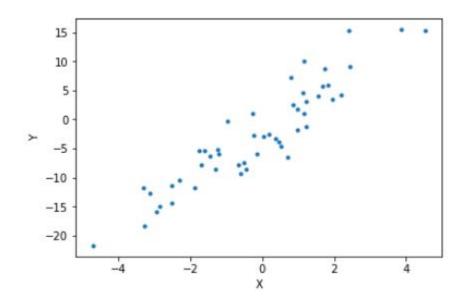
Backprop

Outline

- Simple example (OLS regression)
- Chain rule
- Backprop
- Deriving gradients for a neural network

Simple Regression

$$\hat{Y} = \beta_0 + \beta_1 X$$



Yes, we know how to estimate the coefficients of this model analytically. But we'll use this as a simple example of how to minimize a Loss function through gradient descent.

Squared Error Loss

$$L = \sum_{i} (y_i - \hat{y}_i)^2$$
$$= \sum_{i} (y_i - (\beta_0 + \beta_1 x_i))^2$$

$$\theta = \{\beta_0, \beta_1\}$$

$$\min_{\beta_0, \beta_1} L : \nabla_{\theta} L = 0$$

$$\frac{\partial L}{\partial \beta_0} = \frac{\partial}{\partial \beta_0} \sum_{i} (y_i - (\beta_0 + \beta_1 x_i))^2$$

$$= \sum_{i} \frac{\partial}{\partial \beta_0} (y_i - (\beta_0 + \beta_1 x_i))^2$$

$$= 2 \sum_{i} (y_i - (\beta_0 + \beta_1 x_i)) \frac{\partial}{\partial \beta_0} (y_i - (\beta_0 + \beta_1 x_i))$$

$$= 2 \sum_{i} (y_i - (\beta_0 + \beta_1 x_i))(-1)$$

$$= -2 \sum_{i} (y_i - (\beta_0 + \beta_1 x_i))$$

$$= -2 \sum_{i} e_i$$

$$\frac{\partial L}{\partial \beta_1} = \frac{\partial}{\partial \beta_1} \sum_{i} (y_i - (\beta_0 + \beta_1 x_i))^2$$

$$= \sum_{i} \frac{\partial}{\partial \beta_1} (y_i - (\beta_0 + \beta_1 x_i))^2$$

$$= 2 \sum_{i} (y_i - (\beta_0 + \beta_1 x_i)) \frac{\partial}{\partial \beta_1} (y_i - (\beta_0 + \beta_1 x_i))$$

$$= 2 \sum_{i} (y_i - (\beta_0 + \beta_1 x_i))(-x_i)$$

$$= -2 \sum_{i} x_i (y_i - (\beta_0 + \beta_1 x_i))$$

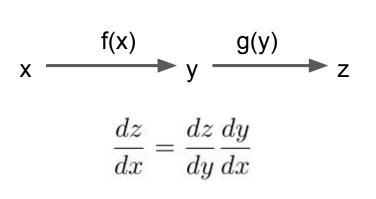
$$= -2 \sum_{i} e_i x_i$$

$$L = \sum_{i} (y_i - (\beta_0 + \beta_1 x_i))^2$$
$$\nabla_{\theta} L = \{-2 \sum_{i} e_i, -2 \sum_{i} e_i x_i\}$$

Exercise: Use the accompanying notebook to estimate regression coefficients using gradient descent.

- For our simple regression model, calculating the gradient was simple enough algebra. This is because the model is so simple.
- For neural network models, the model outputs tend to be a sum of several composed functions. Computing the gradient is still straightforward, but requires a little more thought and book-keeping.

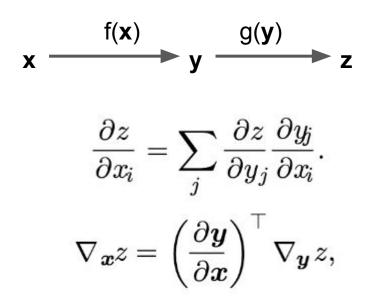
Computing derivatives of composed functions

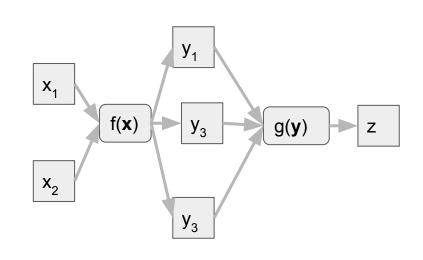


$$y = x^2$$
$$z = \sin(y)$$

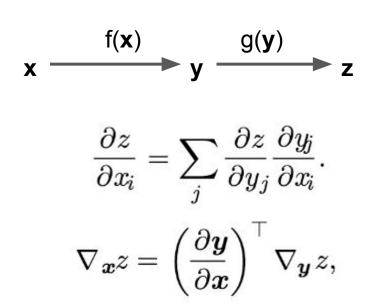
$$\frac{dz}{dx} = \frac{dz}{dy} \frac{dy}{dx}$$
$$= \cos(y)2x$$

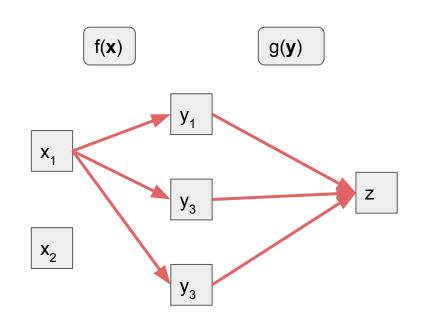
Generalize to vector-valued functions



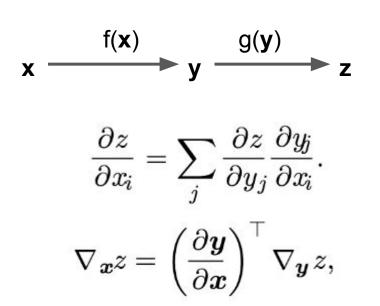


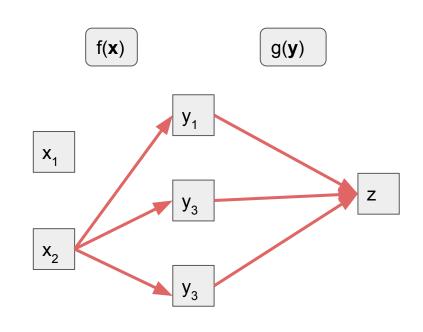
Generalize to vector-valued functions





Generalize to vector-valued functions





Backpropagation

After the forward computation, compute the gradient on the output layer:

$$\boldsymbol{g} \leftarrow \nabla_{\hat{\boldsymbol{y}}} J = \nabla_{\hat{\boldsymbol{y}}} L(\hat{\boldsymbol{y}}, \boldsymbol{y})$$

for k = l, l - 1, ..., 1 do

Convert the gradient on the layer's output into a gradient into the prenonlinearity activation (element-wise multiplication if f is element-wise):

$$\boldsymbol{g} \leftarrow \nabla_{\boldsymbol{a}^{(k)}} J = \boldsymbol{g} \odot f'(\boldsymbol{a}^{(k)})$$

Compute gradients on weights and biases (including the regularization term, where needed):

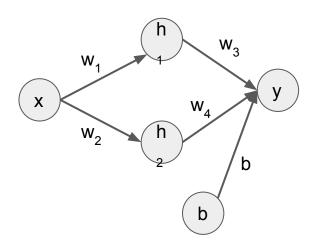
$$\nabla_{\boldsymbol{b}^{(k)}} J = \boldsymbol{g} + \lambda \nabla_{\boldsymbol{b}^{(k)}} \Omega(\theta)$$

$$\nabla_{\boldsymbol{W}^{(k)}}J = \boldsymbol{g}\;\boldsymbol{h}^{(k-1)\top} + \lambda \nabla_{\boldsymbol{W}^{(k)}}\Omega(\boldsymbol{\theta})$$

Propagate the gradients w.r.t. the next lower-level hidden layer's activations:

$$oldsymbol{g} \leftarrow
abla_{oldsymbol{h}^{(k-1)}} J = oldsymbol{W}^{(k) op} \ oldsymbol{g}$$

end for



$$L = \frac{1}{2} (y_i - \hat{y}(x_i))^2$$

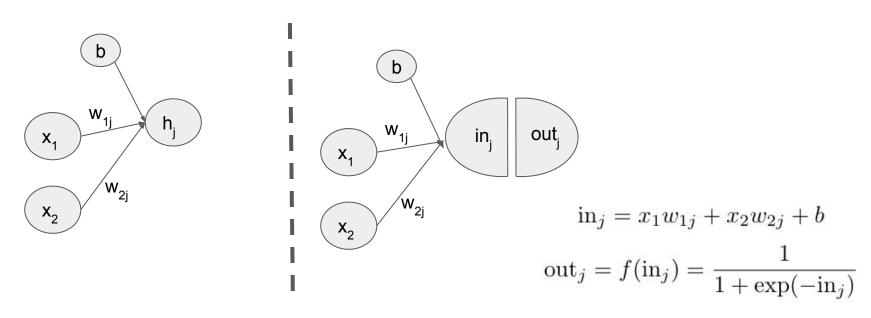
$$\theta = \{w_1, w_2, w_3, w_4, b\}$$

$$\nabla_{\theta} = \{\frac{\partial L}{\partial w_1}, \frac{\partial L}{\partial w_2}, \frac{\partial L}{\partial w_3}, \frac{\partial L}{\partial w_4}, \frac{\partial L}{\partial b}\}$$

We'll use sigmoid activation

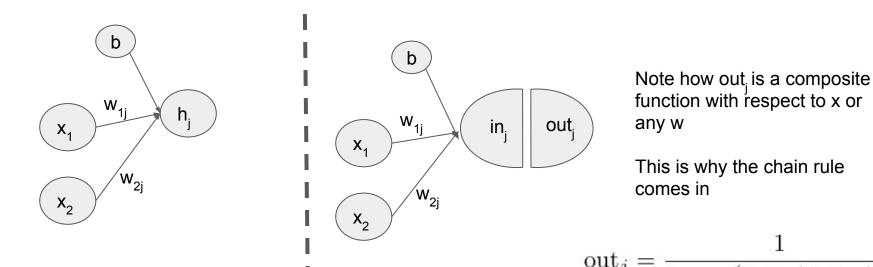
Aside - Notational Convenience

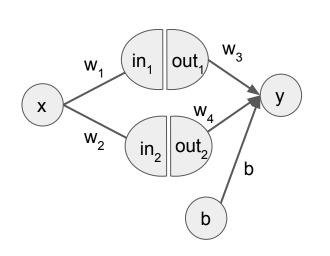
When deriving gradients, we will use a more explicit representation of hidden units, one that allows us to represent (and name) every transformation that occurs.



Aside - Notational Convenience

When deriving gradients, we will use a more explicit representation of hidden units, one that allows us to represent (and name) every transformation that occurs.



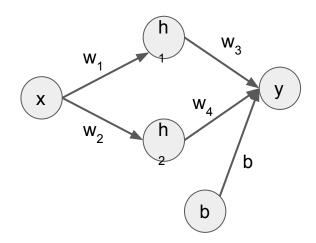


This notation makes it clear how we will compute derivatives of composite functions. Some useful properties:

(1)
$$\frac{d\operatorname{out}_j}{d\operatorname{in}_j} = \frac{d}{dx}f(x) = \frac{d}{dx}\sigma(x) = \sigma(x)(1 - \sigma(x))$$

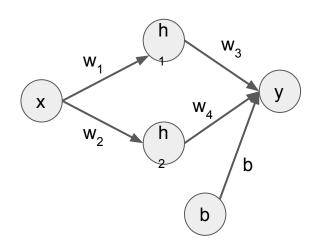
(2)
$$\frac{d \text{in}_j}{d w_k} = \frac{d}{d w_k} [b + w_1 x_1 + w_2 x_2] = x_k$$

(3)
$$\frac{d\operatorname{out}_{j}}{dw_{k}} = \frac{d\operatorname{out}_{j}}{d\operatorname{in}_{j}} \frac{d\operatorname{in}_{j}}{dw_{k}}$$
$$= \sigma(\operatorname{in}_{j})(1 - \sigma(\operatorname{in}_{j}))x_{k}$$



With these preliminaries, let's restate our goals

- Construct a loss function
- Derive the gradient vector for that loss function
- Use gradient descent to optimize that loss function

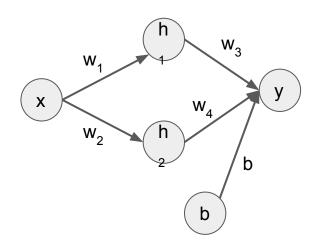


Construct a loss function

$$L = \frac{1}{2} (y_i - \hat{y}(x_i))^2$$

$$\theta = \{w_1, w_2, w_3, w_4, b\}$$

$$\nabla_{\theta} = \{\frac{\partial L}{\partial w_1}, \frac{\partial L}{\partial w_2}, \frac{\partial L}{\partial w_3}, \frac{\partial L}{\partial w_4}, \frac{\partial L}{\partial b}\}$$



$$\frac{\partial L}{\partial w_3} = \frac{\partial L}{\partial \hat{y}} \frac{\partial \hat{y}}{\partial w_3}$$

$$= \frac{\partial L}{\partial \hat{y}} \frac{\partial}{\partial w_3} (w_3 \text{out}_1 + w_4 \text{out}_2 + b)$$

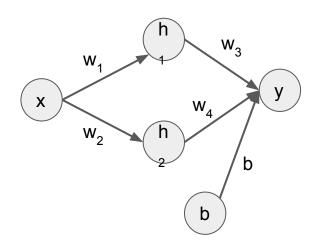
$$= \frac{\partial L}{\partial \hat{y}} \text{out}_1$$

$$= \text{out}_1 \frac{\partial}{\partial \hat{y}} (\frac{1}{2} (y_i - \hat{y}(x_i))^2)$$

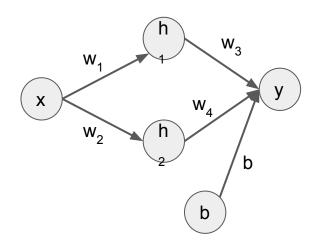
$$= \text{out}_1 (y_i - \hat{y}(x_i)) (0 - 1)$$

$$= -\text{out}_1 (y_i - \hat{y}(x_i))$$

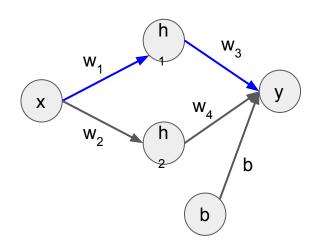
$$\frac{\partial L}{\partial w_3} = -\text{out}_1 e_i$$



$$\frac{\partial L}{\partial w_4} = -\text{out}_2 e_3$$



$$\begin{split} \frac{\partial L}{\partial b} &= \frac{\partial L}{\partial \hat{y}} \frac{\partial \hat{y}}{\partial b} \\ &= -(y_i - \hat{y}(x_i)) \frac{\partial}{\partial b} \hat{y} \\ &= -e_i \frac{\partial}{\partial b} (w_3 \text{out}_1 + w_4 \text{out}_2 + b) \\ &= -e_i \end{split}$$



$$\frac{\partial L}{\partial w_1} = \frac{\partial L}{\partial \hat{y}} \frac{\partial \hat{y}}{\partial \text{out}_1} \frac{d \text{out}_1}{d \text{in}_1} \frac{\partial \text{in}_1}{\partial w_1}$$

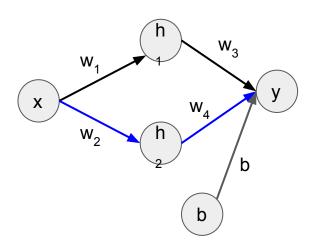
$$\frac{\partial L}{\partial \hat{y}} = -(y_i - \hat{y}(x_i))$$

$$\frac{\partial \hat{y}}{\partial \text{out}_1} = w_3$$

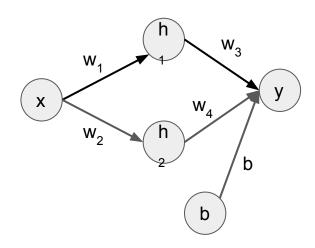
$$\frac{d \text{out}_1}{d \text{in}_1} = \sigma(\text{in}_1)(1 - \sigma(\text{in}_1))$$

$$\frac{\partial \text{in}_1}{\partial w_1} = \frac{d}{d w_1}(xw_1) = x$$

$$\frac{\partial L}{\partial w_1} = -x_i e_i w_3 \sigma(\text{in}_1)(1 - \sigma(\text{in}_1))$$

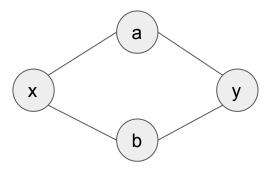


$$\frac{\partial L}{\partial w_2} = -x_i e_i w_4 \sigma(\text{in}_2) (1 - \sigma(\text{in}_2))$$



$$\nabla_{\theta} = \begin{bmatrix} -x_i e_i w_3 \sigma(\text{in}_1) (1 - \sigma(\text{in}_1)) \\ -x_i e_i w_4 \sigma(\text{in}_2) (1 - \sigma(\text{in}_2)) \\ -\text{out}_1 e_i \\ -\text{out}_2 e_i \\ -e_i \end{bmatrix}$$

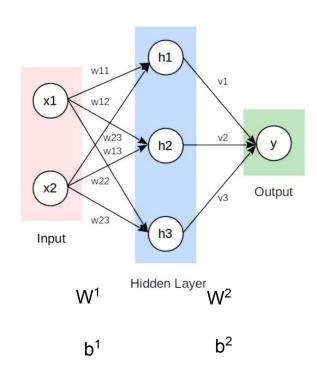
Chain Rule - Sum over paths



$$\frac{dy}{dx} = \frac{dy}{da}\frac{da}{dx} + \frac{dy}{db}\frac{db}{dx}$$

- To compute the total contribution of one variable to another, we must sum over all paths in the computation graph that connect the two
- We didn't encounter this in our previous examples, but is important to keep in mind with deeper networks

- Each layer has a weight matrix W and a bias vector b.
- The layer is typically associated with a single type of activation function.
- Borrowing from Nielsen, we'll use a notational convention
 - The error due to unit j from layer I
 - \circ δ^{I}



- Starting from the output layer
- The error due to unit j in the output layer

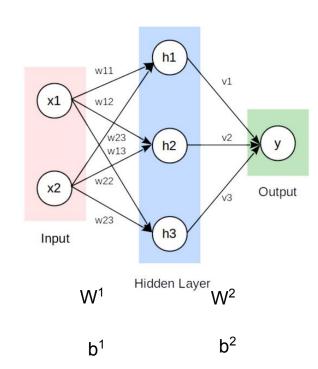
$$\delta_j^L = \frac{\partial C}{\partial a_j^L} \sigma'(z_j^L).$$

In vector form

$$\delta^L = \nabla_a C \odot \sigma'(z^L).$$

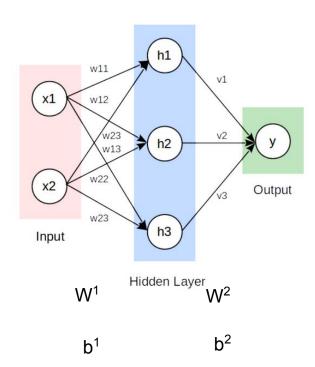
 For example, squared error Loss function, this should look familiar

$$\delta^L = (a^L - y) \odot \sigma'(z^L)$$



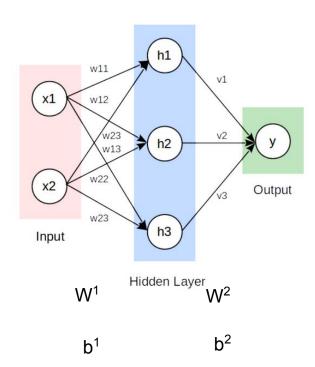
- Then recurse from right to left.
- We want expressions relating the weights in each layer and the error in the adjacent (to the right) layer

$$\delta^l = ((w^{l+1})^T \delta^{l+1}) \odot \sigma'(z^l)$$



- Now we have the ingredient for out partial derivatives
- For bias weights (for any layer):

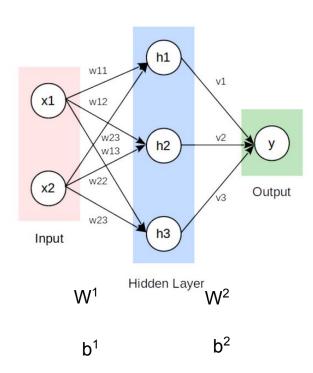
$$\frac{\partial C}{\partial b_i^l} = \delta_j^l$$



- Now we have the ingredient for out partial derivatives
- For connection weights (for any layer):

$$\frac{\partial C}{\partial w_{ik}^l} = a_k^{l-1} \delta_j^l$$

$$\frac{\partial C}{\partial w} = a_{\rm in} \delta_{\rm out}$$



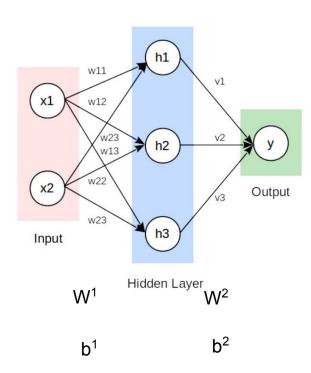
- Now we have the ingredient for out partial derivatives
- For connection weights (for any layer):

the amount of input)

$$\frac{\partial C}{\partial w_{jk}^l} = a_k^{l-1} \delta_j^l$$

$$\frac{\partial C}{\partial w} = a_{\rm in} \delta_{\rm out}$$
 How much the output of this unit changes, as changes when the its input changes (ie.

changes



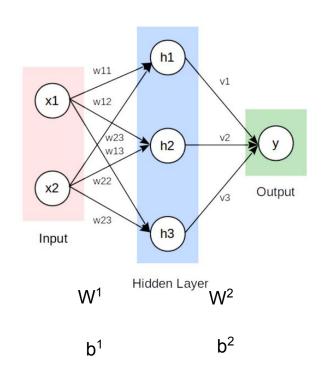
Summary: the equations of backpropagation

$$\delta^L = \nabla_a C \odot \sigma'(z^L) \tag{BP1}$$

$$\delta^l = ((w^{l+1})^T \delta^{l+1}) \odot \sigma'(z^l)$$
 (BP2)

$$\frac{\partial C}{\partial b_j^l} = \delta_j^l$$
 (BP3)
$$\frac{\partial C}{\partial w_{jk}^l} = a_k^{l-1} \delta_j^l$$
 (BP4)

$$\frac{\partial C}{\partial w_{ik}^l} = a_k^{l-1} \delta_j^l \tag{BP4}$$



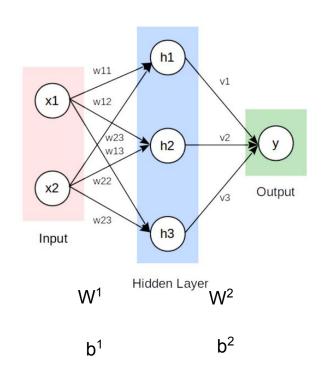
Summary: the equations of backpropagation

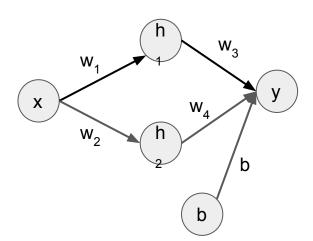
$$\delta^L = \nabla_a C \odot \sigma'(z^L) \tag{BP1}$$

$$\delta^l = ((w^{l+1})^T \delta^{l+1}) \odot \sigma'(z^l)$$
 (BP2)

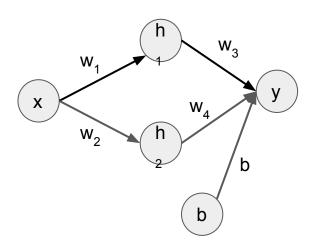
$$\frac{\partial C}{\partial b_j^l} = \delta_j^l$$
 (BP3)
$$\frac{\partial C}{\partial w_{jk}^l} = a_k^{l-1} \delta_j^l$$
 (BP4)

$$\frac{\partial C}{\partial w_{ik}^l} = a_k^{l-1} \delta_j^l \tag{BP4}$$





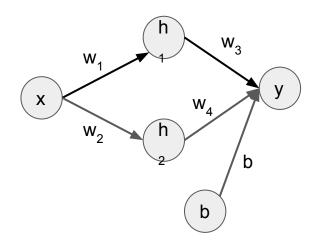
• W¹, W², b



1. Bias

$$\delta^{L} = \frac{\partial C}{\partial \hat{y}} = \frac{\partial}{\partial \hat{y}} \frac{1}{2} (y_i - \hat{y}_i)^2 = (y_i - \hat{y}_i) = e_i$$
$$\frac{\partial C}{\partial b_j^l} = \delta_j^l$$

$$\frac{\partial C}{\partial b} = e_i$$

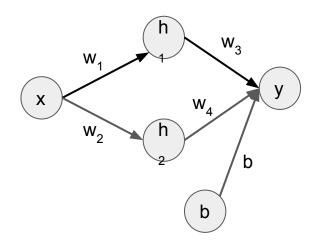


• 2. Output layer weights W²

$$\frac{\partial C}{\partial W^2} = a^{l-1} \delta^L$$

$$= \begin{bmatrix} \text{out}_1 \\ \text{out}_2 \end{bmatrix} \cdot e_i$$

$$= \begin{bmatrix} \text{out}_1 e_i \\ \text{out}_2 e_i \end{bmatrix}$$



• 3. Hidden layer weights W¹

$$\frac{\partial C}{\partial W^l} = a^{l-1}\delta^l$$

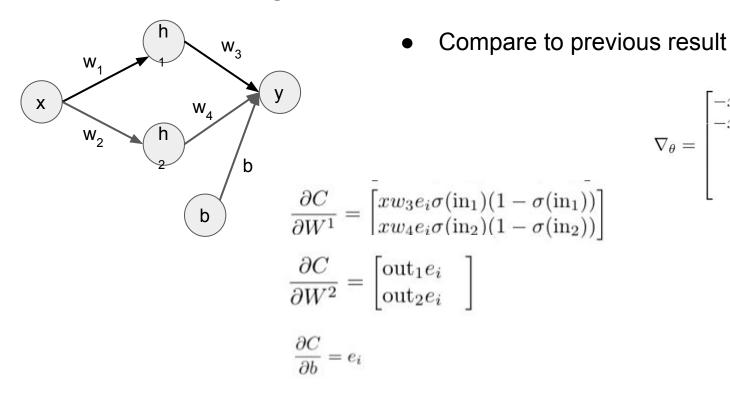
$$a^0 = x$$

$$\delta^1 = (W^2\delta^L) \odot \sigma'(\text{in}_j)$$

$$= \begin{bmatrix} w_3 \\ w_4 \end{bmatrix}^T \cdot e_i \odot [\sigma(\text{in}_j)(1 - \sigma(\text{in}_j))]$$

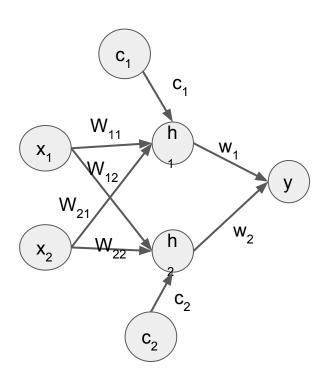
$$= \begin{bmatrix} w_3 e_i \sigma(\text{in}_1)(1 - \sigma(\text{in}_1)) \\ w_4 e_i \sigma(\text{in}_2)(1 - \sigma(\text{in}_2)) \end{bmatrix}$$

$$\frac{\partial C}{\partial W^1} = \begin{bmatrix} xw_3 e_i \sigma(\text{in}_1)(1 - \sigma(\text{in}_1)) \\ xw_4 e_i \sigma(\text{in}_2)(1 - \sigma(\text{in}_2)) \end{bmatrix}$$



 $\nabla_{\theta} = \begin{bmatrix} -x_i e_i w_3 \sigma(\text{in}_1) (1 - \sigma(\text{in}_1)) \\ -x_i e_i w_4 \sigma(\text{in}_2) (1 - \sigma(\text{in}_2)) \\ -\text{out}_1 e_i \\ -\text{out}_2 e_i \end{bmatrix}$

Exercise - Classification Network

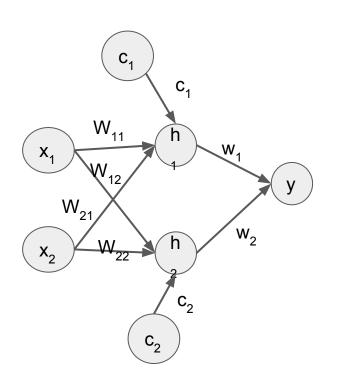


Recall this example from the book (XOR), where we have 2-D input data and need to classify them with with an obviously non-linear decision boundary.

This model has 8 free parameters. Assume ReLu activations in the hidden layer and a sigmoid output for the classifier. Loss function will be binary cross-entropy.

- Derive the gradients for the free parameters in the model
- Use gradient descent to fit our model to the 4 datapoint dataset.
- 3. Do your estimated weights match up with the ones in the book? Do they need to?

Exercise - Classification Network



Helpful hint -

$$L = -y_i \log(\hat{y}_i) - (1 - y_i) \log(1 - \hat{y}_i)$$

$$\frac{dL}{d\hat{y}} = \frac{d}{d\hat{y}} (-y_i \log(\hat{y}_i) - (1 - y_i) \log(1 - \hat{y}_i))$$

$$= -\left(\frac{d(-y_i \log(\hat{y}_i))}{d\hat{y}} + \frac{d((1 - y_i) \log(1 - \hat{y}_i))}{d\hat{y}}\right)$$

$$= -\left(\frac{y_i}{\hat{y}_i} - \frac{1 - y_i}{1 - \hat{y}_i}\right)$$

Exercise - Classification

 $\frac{\partial L}{\partial w_1} = \frac{dL}{d\hat{y}} \text{out}_1$ $\frac{\partial L}{\partial w_2} = \frac{dL}{d\hat{y}} \text{out}_2$

 $\frac{\partial}{\partial c_1} = \frac{\partial}{\partial \hat{y}} \frac{\partial}{\partial \text{out}_1} \frac{\partial}{\partial \text{in}_1} \frac{\partial}{\partial c_1}$ $\partial L = dL \quad \partial \hat{y} \quad dout_2 \partial in_2$ $\overline{\partial c_2} = \overline{d\hat{y}} \, \overline{\partial \text{out}_2} \, d\text{in}_2 \, \partial c_2$ $\partial L = dL \quad \partial \hat{y} \quad dout_1 \quad \partial in_1$ $\overline{\partial W_{11}} - \overline{d\hat{y}} \, \overline{\partial \text{out}_1} \, d\text{in}_1 \, \partial W_{11}$ $\partial L = dL \quad \partial \hat{y} \quad dout_1 \quad \partial in_1$ $\partial W_{21} = d\hat{y} \partial \text{out}_1 d\text{in}_1 \partial W_{21}$ $\partial L \qquad dL \quad \partial \hat{y} \quad dout_2 \quad \partial in_2$ $\frac{\partial W_{12}}{\partial W_{12}} - \frac{\partial \hat{y}}{\partial \text{out}_2} \frac{\partial \text{out}_2}{\partial \text{out}_2} \frac{\partial W_{12}}{\partial W_{12}}$ $\partial L = dL \quad \partial \hat{y} \quad dout_2 \quad \partial in_2$ ∂W_{22} $d\hat{y} \partial \text{out}_2 din_2 \partial W_{22}$

 $\partial L = dL \quad \partial \hat{y} \quad dout_1 \partial in_1$