

## Homework 5

This homework has two parts. In the first part, you will implement a multistep IMEX scheme based on the backward differentiation formula. In the second part, you will implement two new equation sets.

- **New timestepper:** You will implement a new multistep IMEX timestepper called `BDFExtrapolate`. I've written out the start of an `__init__` method and the call signature for the `_step` method in `timesteppers.py`. This timestepper will solve the equation

$$M \cdot \partial_t X + L \cdot X = F(X) \quad (1)$$

by approximating

$$\partial_t X^n \approx \sum_{i=0}^s a_i X^{n-i}, \quad (2)$$

$$L \cdot X \approx L \cdot X^n, \quad (3)$$

$$F(X)^n \approx \sum_{i=1}^s b_i F(X)^{n-i}. \quad (4)$$

This timestepping scheme calculates the future value of  $X$ , denoted by  $X^n$ , using the current value,  $X^{n-1}$ , and past values,  $X^{n-2}$ ,  $X^{n-3}$ , etc. The coefficients  $a_i$  and  $b_i$  can be found via Taylor expansion. The approximation of  $\partial_t X^n$  is the backwards differentiation formula that you worked out in homework 4. The approximation of  $F(X)^n$  is an extrapolation, because we only know  $F(X)^{n-1}$ ,  $F(X)^{n-2}$ , etc., but the  $F(X)^{n-i}$  for  $i \geq 1$  can be extrapolated to estimate  $F(X)^n$ .

As with the other multistep schemes we've used, you will need to take  $s$  timesteps before you can use the full scheme of order  $s$ . For the first  $s - 1$  timesteps, you should use the appropriate lower order schemes for the number of steps you have on hand. Assume the step size will stay constant.

- **Sound waves:** The perturbation equations for an ideal gas in one dimension are

$$\rho_0 \partial_t u' + \partial_x p' = 0, \quad (5)$$

$$\partial_t p' + \gamma p_0 \partial_x u' = 0. \quad (6)$$

Here  $u'$  and  $p'$  are the velocity and pressure perturbations,  $\rho_0$  and  $p_0$  are the background density and pressure, and  $\gamma$  is the ratio of specific heats (equal to  $5/3$  for a monatomic ideal gas). These equations admit sound waves which travel at the sound speed  $c_s^2 = \gamma p_0 / \rho_0$ .

You will implement an equation set to solve these equations for sound waves. In `equations.py` I've included the equation sets discussed in class, as well as the initialization call for the `SoundWave` class. This class will be given `numpy array`'s for  $u$  and  $p$ , as well as the first derivative operator (called `d`). In addition, it will be given  $\rho_0$  and  $\gamma p_0$ , which could be numbers, if those quantities are constant, or `numpy array`'s, if they are spatially dependent. Your job is to make a statevector `X`, matrices `L` and `M`, and function `F` for calculating RHS terms explicitly. These will be passed to IMEX timesteppers for time integration. I will be testing cases where  $\rho_0$  and  $\gamma p_0$  are constant, as well as cases where they are spatially varying.

- **Reaction-Diffusion:** We will solve the following one-dimensional reaction-diffusion equation

$$\partial_t c - D \nabla^2 c = c(c_{\text{target}} - c). \quad (7)$$

The left hand side of this equation is the diffusion equation; the right hand side represents an auto-catalytic “reaction” of some material with concentration  $c$ . There are two equilibrium configurations:  $c = 0$  and  $c = c_{\text{target}}$ . The first is unstable; the second stable. If you initialize with  $c$  zero everywhere, except near  $x_0$ , then the system will react to produce  $c$  until  $c = c_{\text{target}}$ . Then the diffusion of  $c$  about  $x_0$  will lead to a reaction front which propagates at a velocity  $\sim \sqrt{D/c_{\text{target}}}$ . In the case of combustion, this reaction front is called a flame.

As for the sound wave problem, you will implement these equations in `equations.py` as a new class `ReactionDiffusion`. I have written the initialization call, which is passed a `numpy array` for `c`, the second derivative operator (`d2`), the target value `c_target` (which could be either constant or a `numpy array` if spatially dependent), and the diffusivity  $D$ . As above, your code should specify the statevector `X`, matrices `M` and `L`, and function `F` for calculating terms explicitly. You should test cases where  $c_{\text{target}}$  is either constant, or spatially varying.