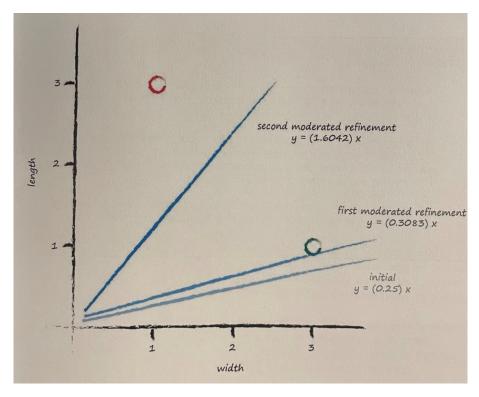
Make Your Own NN p1-p34

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$$t = (A + \Delta A)x$$
$$E = \Delta Ax$$

 $\Delta A = E/x$

t represents the correct desired value E represent the error, E=t-y we want to know how much to adjust A by to improve the slope of line so it is a better classifier, being informed by the error E

If we keep doing this, updating for each training data example, all we get is that the final update simply matches the last example closely. Therefore, we change it to

$$\Delta A = L * (E/x)$$
 where L represents learning rate

Let's run through again, we have an initial A=0.25. The first training example gives us y=0.25*3.0=0.75, note that the first point is (3,1) and desired y-value is 1.1. A desired value of 1.1 gives us an erroe of 0.35. The $\Delta A=L(E/x)=0.5*(0.35/3.0)=0.0583$. The update A is 0.25+0.0583=0.3083.

Trying out this new A on the training example at x = 3.0 gives y = 0.3083*3.0 = 0.9250. The line now falls on the wrong side of the training example because it is it is below 1.1 but it is not a bad result if you consider it a first refinement step of many to come. It did move in the right direction away from the initial line.

Let's press on to the second training data example at x = 1.0. Using A = 0.3083 we have y = 0.3083 * 1.0 = 0.3083. The desired value was 2.9, (1, 3) originally, so the error is 2.9 - 0.3083 = 2.5917. The $\Delta A = L(E/x) = 0.5 * (2.5917/1) = 1.2958$. The even newer A is now 0.3083 + 1.2958 = 1.6042.

Key Points

- \star We can use simple maths to understand the relationship between the output error of a linear classifier and the adjustable slop parameter. This is the same as knowing how much to adjust the slop to remove that output error.
- \star A problem with doing these adjustments naively, is that the model is updated to best match the last training example only, effectively ignoring all previous training examples. A good way to fix this is to moderate the updates with a learning rate so no single training example totally dominates the learning.
- \star Training examples form the real world can be noisy or contain errors. Moderating updates in this way helpfully limits the impact of these false example.