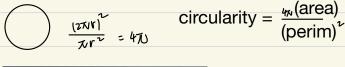
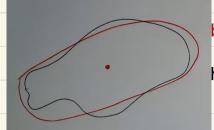
boundary and region description; filtering shape, texture, matlab: regionprops



- perimeter
- area
- diameter
- bounding box

compactness: (perimeter)^v

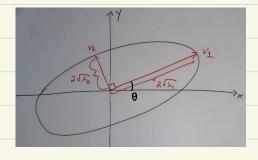




best fit ellipse

how to get this ellipse

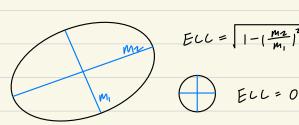
2) (λι. Vι), (λ. V.) eigenvals/vectors



v1: direction of major axis v2: direction of minor axis

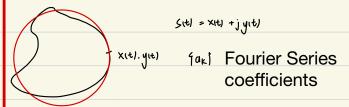
ع (ع آلم) length of major axis 2 (2) length of minor axis

eccentricity

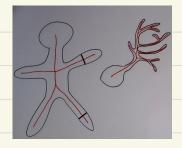


topology: Euler number = (# of connect component) - (# holes)





PCA: principal component analysis training shape



estimation:

- 1) successive erosions
- 2) distance transform

definition: points that have more than one nearest neighbor

remember that underlying intensity/colour inside each binary block

The texture can also be filtered

- flat, noisy, stripey statistics on hist of intensity in blob:
- mean intensity
- second moment (variance) => contrast flat => var = 0noisy => var = high
- third moment (skewness)
- entropy (how random) none of these reflect spatial distribution of intensity

Gray-level co-occurence matrix (GLCM)



1) specify an operator Q (spatial relationship b/w 2 pixels) eg."1 pixel to right" if N gray levels, make N*N matrix

P(pixel 1, pixel 2) = $(\rho 1, \rho 2)$ according to Q

will have k pixels (# of possible pixel pairs according to Q) in practice, # gray levels is quantized (eg. 8 or 16)