

«Constraint»
Obstacle detection distance
constraints
{rD > O}
Parameters
rD: robotDistance O: Obstacle

«Constraint»
Depth of Water
constraints
{Volume <= 65.8}
Parameters
volume : float

«Constraint»
Maximum weight of robot
constraints
{m*g == floatableRange}
Parameters
m: Mass g: gravitational acceleration

«Constraint»
Ultrasonic detection range
constraints
{d = 2 - 40}
Parameters
d: distance