

«Constraint»
Obstacle detection distance
constraints
{d > O}
Parameters
d: distance O: Obstacle

«Constraint»
Depth of Water
constraints
{V <= 65.8}
Parameters
v: volume

«Constraint»
Maximum weight of robot
constraints
{m*g == floatableRange}
Parameters
m: Mass g: gravitational acceleration

«Constraint»
Ultrasonic detection range
constraints
{d = 2 - 40}
Parameters
d: distance