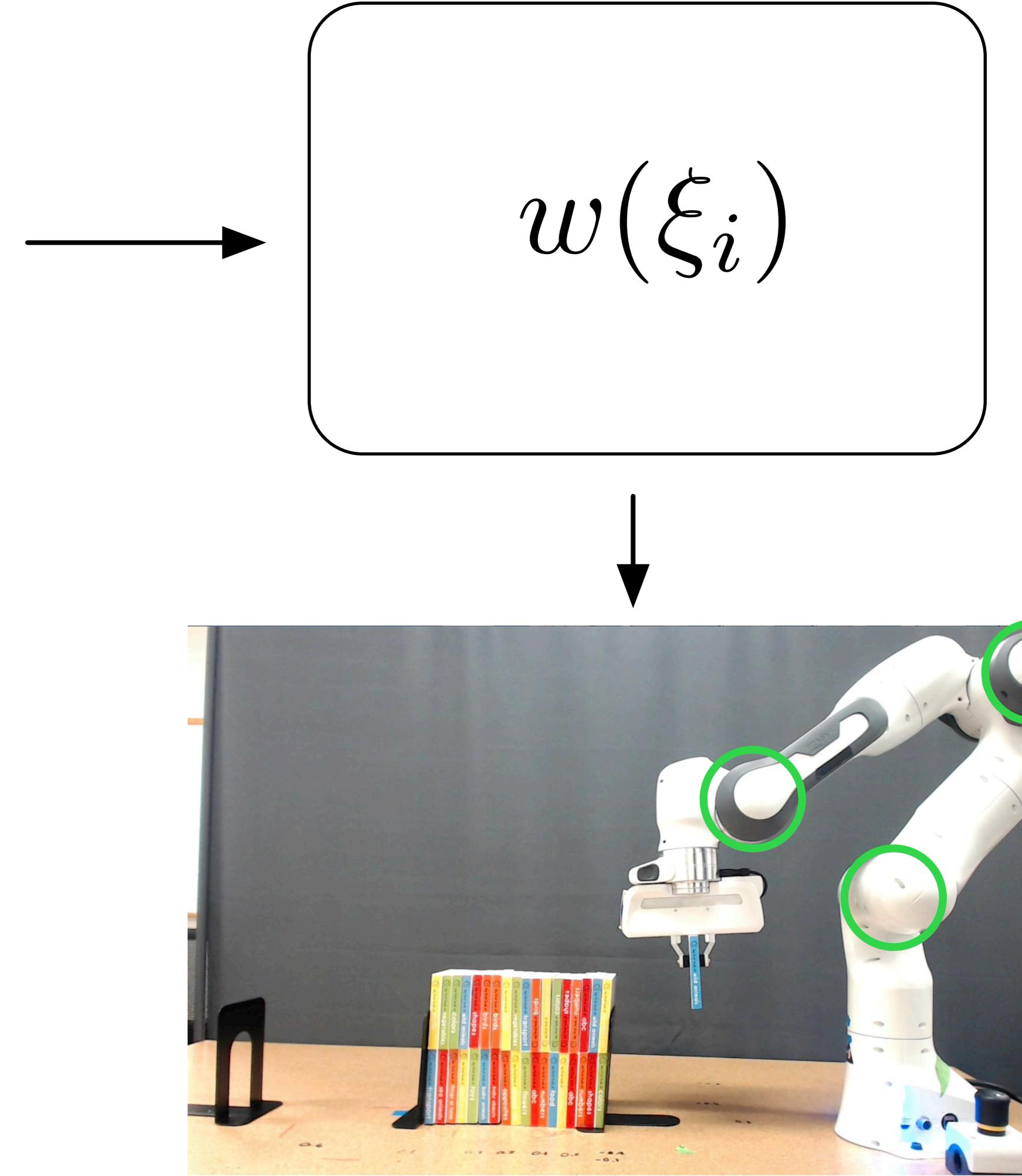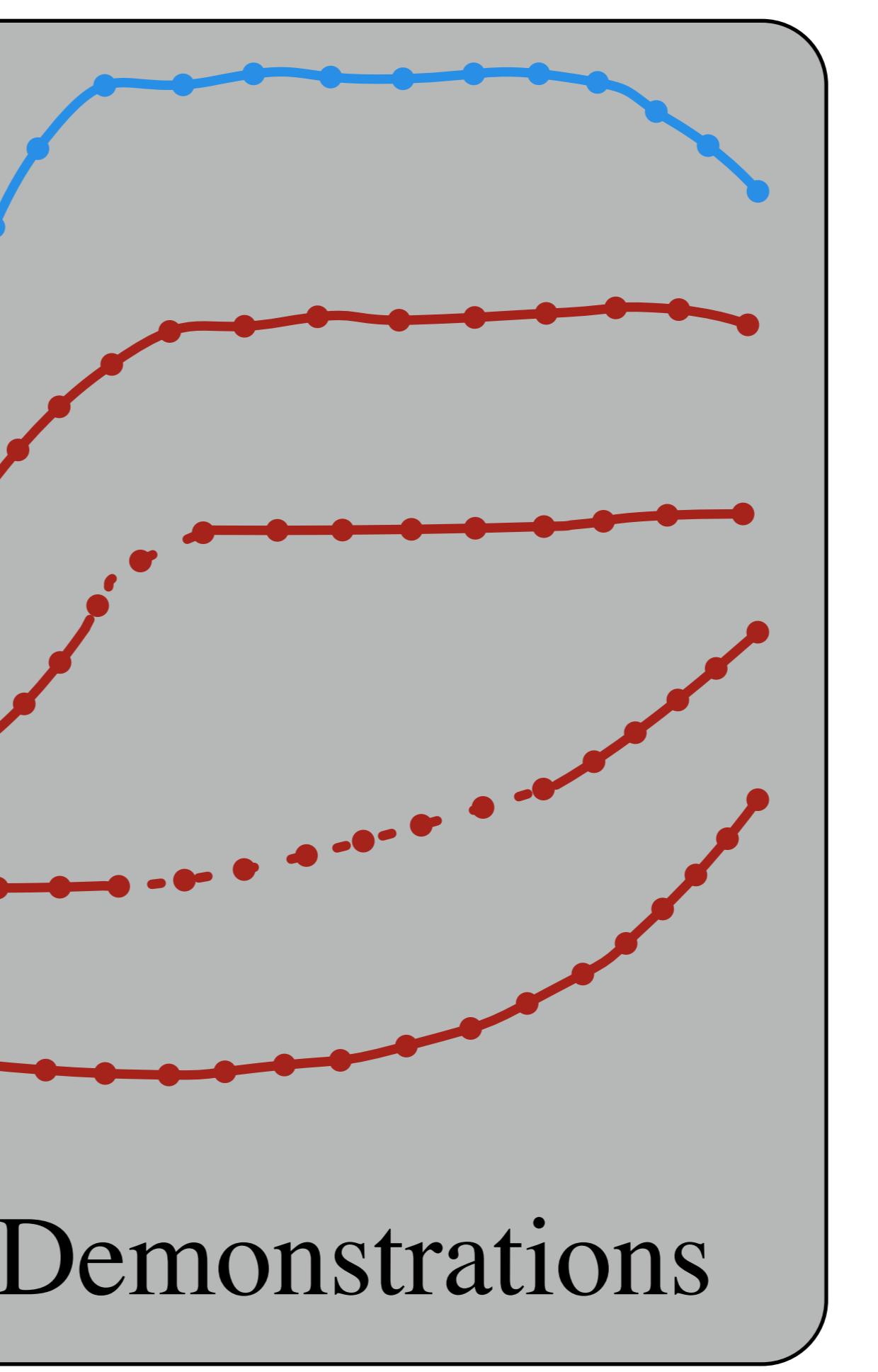$w(\xi_i)$

Demonstrations

7-DoF Robot Arm (Demonstrator)

3-DoF Robot Arm (Imitator)