

# Yilun (Evelyn) Hao

yilunhao@stanford.edu | (858)-257-7293 | 51 Dudley Lane #218, Stanford, CA

## EDUCATION

**Stanford University**, Stanford, CA

Sep 2021 - Jun 2023(Expected)

Master of Science (GPA: 4.0/4.0) Major in Computer Science

Core courses: Machine Learning, Decision Making Uncertainty, Safe and Interactive Robotics

**University of California, San Diego**, La Jolla, CA

Aug 2017 - Jun 2021

Bachelor of Science (GPA: 3.9/4.0) Major in Computer Science Minor in Mathematics

Honors: Provost Honors, Magna Cum Laude

## PUBLICATIONS (\* denotes equal contribution)

- **Y. Hao\***, R. Wang\*, Z. Cao, Z. Wang, Y. Cui, Dorsa Sadigh, “Masked Imitation Learning: Discovering Environment-Invariant Modalities in Multimodal Demonstrations”, *IEEE Conference on Robotics and Automation (ICRA)*, 2023 (Submitted)
- **Y. Hao\***, R. Zhang\*, D. Bansal\*, A. Hiranaka, J. Gao, C. Wang, R. Martín-Martín, L. Fei-Fei, J. Wu, “A Dual Representation Framework for Robot Learning with Human Guidance”, *Proceedings of the 5th Conference on Robot Learning (CoRL)*, 2022
- Z. Wang\*, Z. Cao\*, **Y. Hao**, D. Sadigh, “Weakly Supervised Correspondence Learning”, *IEEE Conference on Robotics and Automation (ICRA)*, 2022
- Z. Cao, **Y. Hao**, M. Li, D. Sadigh “Learning Feasibility to Imitate Demonstrators with Different Dynamics”, *Proceedings of the 5th Conference on Robot Learning (CoRL)*, 2021
- J. Morris, **Y. Hao**, S. Gupta, B. Khaleghi, B. Aksanli, T. Rosing, “Stochastic-HD: Leveraging Stochastic Computing on the Hyper-Dimensional Computing Pipeline”, *Frontiers in Neuroscience*, 2022
- **Y. Hao**, S. Gupta, J. Morris, B. Khaleghi, B. Aksanli, and T. Rosing, “Stochastic-HD: Leveraging Stochastic Computing on Hyper-Dimensional Computing”, *IEEE International Conference on Computer Design (ICCD)*, 2021
- J. Morris, **Y. Hao**, S. Gupta, R. Ramkumar, J. Yu, M. Imani, B. Aksanli, T. Rosing, “Multi-label HD Classification in 3D Flash”, *IEEE/IFIP International Conference on VLSI and System-on-Chip (VLSI-SoC)*, 2020. (Invited Paper)
- J. Morris, R. Fernando, **Y. Hao**, M. Imani, B. Aksanli, T. Rosing, “Locality-based Encoder and Model Quantization for Efficient Hyper-Dimensional Computing”, *IEEE Transactions on Computer-Aided Design of Integrated Circuits and Systems*, 2020

## EXPERIENCE

**Stanford Vision and Learning Lab (SVL)**

Mar 2022 - Current

Research Assistant supervised by Prof. Fei-Fei Li and Prof. Jiajun Wu

Stanford University

- Designed and implemented human-in-the-loop RL and IRL algorithms that incorporate scene graph with human evaluative feedbacks and preferences, which significantly improve both task performance and learning speed

**Stanford Intelligent and Autonomous Systems Group (ILIAD)**

Apr 2021 - Current

Research Assistant supervised by Prof. Dorsa Sadigh

Stanford University

- Tackled robotics problems of 1) state over-specification of learning from multi-modality data, 2) learning from suboptimal demonstrations especially infeasible dynamics, and 3) corresponding learning

**System Energy Efficiency Lab (SEE Lab)**

Apr 2019 - Jun 2021

Research Assistant supervised by Prof. Tajana Rosing

University of California, San Diego

- Designed and implemented machine learning algorithms using Hyperdimensional (HD) Computing to raise both the accuracy and efficiency of single-label & multi-label & image classification problem

**Stanford University** | Course Assistant in Computer Science Dept.

Jan 2022 - Apr 2021

- Worked as course assistant for ‘Principles of Robot Autonomy II’

**University of California, San Diego** | Tutor in Computer Science Dept.

Jan 2021 - Jun 2021

- Worked as tutor for ‘Components and Design Techniques for Digital Systems’ and ‘Introduction to Machine Learning’

**Golf AI** | Software Engineer

Jul 2020 – Sep 2020

- Designed and implemented an upgraded User Interface of the GolfAI application using SwiftUI

**University of California, San Diego** | Grader in Mathematics Dept.

Sep 2018 - Jun 2019

- Graded students’ homework in Calculus class

## ACADEMIC SERVICES

- **Reviewer:** CoRL 2022, IEEE T-RO
- **Volunteer:** Bay Area Robotics Symposium 2021

## SKILLS

- **Programming:** Python, PyTorch, TensorFlow, C/C++, Java, Shell, MATLAB; Swift, Firebase; L<sup>A</sup>T<sub>E</sub>X
- **Robotics:** Mujoco, Pybullet, ROS, Franka Panda
- **Algorithms:** Machine Learning, Imitation Learning, Reinforcement Learning, Computer Vision