YIHANG TAO

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EDUCATION

City University of Hong Kong

Hong Kong SAR

PhD in Computer Science

Sep. 2024 - Present

Supervisor: Prof. Yuguang "Michael" Fang JC STEM Lab of Smart City, WINET Laboratory

Shanghai Jiao Tong University

Shanghai, China

Master of Engineering in Electronic Information

Sep. 2021 - Apr. 2024

Outstanding Graduate (2024)

Southeast University

Nanjing, China

Bachelor of Engineering in Information Engineering

Sep. 2017 - Jul. 2021

GPA: 3.89/4.0

RESEARCH INTERESTS

Multi-agent collaborative perception, autonomous driving, AI security, foundation models for multi-agent systems, parameter-efficient fine-tuning.

PUBLICATIONS

Published & Accepted: (# Equal contribution, * Corresponding author)

- Z. Fang, J. Wang, Y. Ma, Y. Tao, Y. Deng, X. Chen, and Y. Fang. "R-ACP: Real-Time Adaptive Collaborative Perception Leveraging Robust Task-Oriented Communications," *IEEE Journal on Selected Areas in Communications* (JSAC), 2025.
- Y. Tao, S. Hu, Z. Fang, and Y. Fang. "Directed-CP: Directed Collaborative Perception for Connected and Autonomous Vehicles via Proactive Attention," *IEEE International Conference on Robotics and Automation (ICRA)*, Atlanta, USA, 2025.
- S. Hu#, Y. Tao#, G. Xu, Y. Deng, X. Chen, Y. Fang, and S. Kwong. "CP-Guard: Malicious Agent Detection and Defense in Collaborative Bird's Eye View Perception," *The 39th Annual AAAI Conference on Artificial Intelligence (AAAI)*, Philadelphia, USA, 2025. (Oral Presentation, <5%)
- Y. Tao, J. Wu, Q. Pan, A. K. Bashir, and M. Omar. "O-RAN-Based Digital Twin Function Virtualization for Sustainable IoV Service Response: An Asynchronous Hierarchical Reinforcement Learning Approach," *IEEE Transactions on Green Communications and Networking (TGCN)*, vol. 8, no. 3, pp. 1049-1060, Sep. 2024.
- Y. Tao, J. Wu, X. Lin, S. Mumtaz, and S. Cherkaoui. "Digital Twin and DRL-Driven Semantic Dissemination for 6G Autonomous Driving Service," *IEEE Global Communications Conference (GLOBECOM)*, Kuala Lumpur, Malaysia, Dec. 2023, pp. 2075-2080.
- **Y. Tao**, J. Wu, X. Lin, and W. Yang. "DRL-Driven Digital Twin Function Virtualization for Adaptive Service Response in 6G Networks," *IEEE Networking Letters (LNET)*, vol. 5, no. 2, pp. 125-129, Jun. 2023.

Preprints & Under Review:

Y. Tao#, S. Hu#, Y. Hu, H. An, H. Cao, and Y. Fang. "GCP: Guarded Collaborative Perception with Spatial-Temporal Aware Malicious Agent Detection," *arXiv* preprint *arXiv*:2501.02450, 2025.

Y. Tao, S. Hu, H. An, Z. Fang, H. Cao, and Y. Fang. "Adaptive Attack on Multi-Agent Collaborative Perception," *Under Review*, 2025.

S. Hu, **Y. Tao**, Z. Fang, G. Xu, Y. Deng, S. Kwong, and Y. Fang. "CP-Guard+: A New Paradigm for Malicious Agent Detection and Defense in Collaborative Perception," *arXiv preprint arXiv:2502.07807*, 2025.

HONORS & AWARDS

IEEE Robotics and Automation Society (RAS) Travel Grant for ICRA'25	Mar. 2025
Outstanding Graduate, Shanghai Jiao Tong University	May 2024
WEICHAI POWER Scholarship, Shanghai Jiao Tong University	Oct. 2023
Excellent League Member, Shanghai Jiao Tong University	Apr. 2022
National Student Research Training Program Excellence Award (Leader)	Oct. 2020
Excellence Prize, 2nd International Data Competition, IKCEST (top 3%)	Oct. 2020
Sun Qingyun Innovation Scholarship, Southeast University ($<$ 1% annually)	Jun. 2020
Finalist, 36th Mathematical Contest in Modeling (MCM), COMAP (top 1 %)	Apr. 2020
First Prize, 12th National Information Security Contest, China (top 8%)	Aug. 2019
First Prize, 15th Advanced Mathematics Competition, Jiangsu (top 10%)	Aug. 2018

ACADEMIC SERVICE

Program Committee Member:

ACM MM 2025, ICML 2025, ICLR 2025, AAAI 2025, ICRA 2025, IUI 2025, IJCNN 2025 IEEE ISBI 2025, IEEE ICC 2025, IEEE GLOBECOM 2023-2025, IEEE ICCC 2024

Journal Reviewer:

IEEE TITS, IEEE TCE, Pattern Recognition, Neural Networks, EAAI, IEEE JBHI, IEEE LNET

Session Chair:

IEEE GLOBECOM 2023, MWN Track, Semantic Communications Session

TECHNICAL SKILLS

Programming Languages: Python, MATLAB, C++, C#, JavaScript, Verilog HDL, Languages: Python, Matlab, C++, C#, Languages: Python, Python, Matlab, Python, Python,

Tools & Platforms: Git, Docker, Linux, CARLA Simulator, SUMO, ROS

Languages: English (IELTS 7.0), Chinese (Native)

PROJECT EXPERIENCE

Multi-Agent Collaborative Perception for Autonomous Driving	esen
) Institution and Supervisor: City University of Hong Kong, Prof. Yuguang Fang	
) Research Focus: Developing robust collaborative perception systems, designing defense mechanisms aga dversarial attacks, and deploying on real-world ROS and Jetson-based autonomous driving platforms;	ains
) Achievements: 3 first-author papers accepted/submitted to top venues (ICRA'25, AAAI'25), 1 RAS travel graduates and the submitted to top venues (ICRA'25, AAAI'25), 1 RAS travel graduates and the submitted to top venues (ICRA'25, AAAI'25), 1 RAS travel graduates and the submitted to top venues (ICRA'25, AAAI'25), 1 RAS travel graduates and the submitted to top venues (ICRA'25, AAAI'25), 1 RAS travel graduates are submitted to top venues (ICRA'25, AAAI'25), 1 RAS travel graduates are submitted to top venues (ICRA'25, AAAI'25), 1 RAS travel graduates are submitted to top venues (ICRA'25, AAAI'25), 1 RAS travel graduates are submitted to top venues (ICRA'25, AAAI'25), 1 RAS travel graduates are submitted to top venues (ICRA'25, AAAI'25), 1 RAS travel graduates are submitted to top venues (ICRA'25, AAAI'25), 1 RAS travel graduates are submitted to top venues (ICRA'25, AAAI'25), 1 RAS travel graduates are submitted to top venues (ICRA'25, AAAI'25), 1 RAS travel graduates are submitted to top venues (ICRA'25, AAAI'25), 1 RAS travel graduates are submitted to top venues (ICRA'25, AAAI'25), 1 RAS travel graduates are submitted to top venues (ICRA'25, AAAI'25), 1 RAS travel graduates are submitted to top venues (ICRA'25, AAAI'25), 1 RAS travel graduates are submitted to top venues (ICRA'25, AAAI'25), 1 RAS travel graduates are submitted to top venues are submi	ant.
Digital Twin and 6G Communications	2024
) Institution and Supervisor: Shanghai Jiao Tong University, Prof. Jun Wu	
Research Focus: Designing digital twin function virtualization for IoV services, developing DRL-based adaption	ptive
ervice response mechanisms, using Unity Software to connect with real-world elevator systems;	

Ultrasonic Anti-Recording Security System	2019 - 2020
1) Institution and Supervisor: Southeast University, Prof. Yubo Song	
2) Responsibility: Team leader. Designed ultrasonic anti-recording mechanism base	d on acoustic parametric array;
Implemented SM4-based spread spectrum and DDS waveform generation on STM3	32F407 microcontroller;
3) Achievements: First prize in National Information Security Contest, 1 patent (CN111064543A), Sun Qingyun
Innovation Scholarship.	