The Termination Problem of Equality Saturation is Undecidable

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In this note, we study the decidability of the termination of equality saturation and related problems.

Background

Term rewriting

A term rewriting system (TRS) R consists of a set of rewrite rules. R defines a rewrite relation \to_R . We omit the subscript R when it's clear from the context. Let \to^* be the transitive closure of binary relation \to . We define $(\leftarrow_R) = (\to_R)^{-1}$, $(\leftrightarrow) = \to_R \cup \leftarrow_R$, and $(\approx) = \leftrightarrow_R^*$. \approx is an equivalence relation.

A normal form is a term that cannot be rewritten any further. We say n is a normal form of t if t can be reduced to n. A TRS R is terminating if there is no infinite rewriting chain $t_1 \to_R t_2 \dots$ A TRS R is confluent if for all $t, t_1, t_2, t_1 \leftarrow_R^* t \to_R^* t_2$ implies there exists a t' such that $t_1 \to_R^* t' \leftarrow_R^* t_2$. We call a confluent and terminating TRS convergent. Every term in a terminating TRS has at least one normal form, every term in a confluent TRS has at most one normal form, and every term in a convergent TRS has exactly one normal form.

We call a term rewriting system left-linear (resp. right-linear) if variables in the left-hand side (resp. right-hand side) of each rewrite rule occur only once. For example, $R_1 = \{f(x,y) \to g(x)\}$ is left-linear, while $R_2 = \{f(x,x) \to g(x)\}$ is not left-linear. A TRS is linear if it's left-linear and right linear.

Finite tree automata

A finite tree automaton (FTA) is a tuple $\mathcal{A}=(Q,F,Q_f,\Delta)$, where Q is a set of states, F is a set of function symbols, $Q_f\subseteq Q$ is a set of final states, and Δ is a set of transitions of the form $f(q_1,\ldots,q_n)\to q$ where $q,q_1,\ldots,q_n\in Q$. A term t is accepted by a state by \mathcal{A} if it can be rewritten to a final state $q_f\in Q_f$ of \mathcal{A} , i.e., $t\to^*q_f\in Q_f$. Since Q and F can be determined by Δ , we omit them and use (Q_f,Δ) to denote a FTA for brevity. Let $\mathcal{L}(\mathcal{A})$ be the set of terms accepted by FTA \mathcal{A} . A language L is called regular if it is accepted by some FTA $(\exists \mathcal{A}, L=\mathcal{L}(\mathcal{A}))$.

Regular languages and FTAs are closed under union, intersection, and complement. Moreover, it is possible to define a tree automaton that accepts any term: define

$$\mathcal{A}_* = (\{q_*\}, \{f(q_*|_{i=1\dots n}) \to q_* \mid n\text{-ary symbol } f \in F\})$$

for a fresh state q_* .

Given a left-linear term-rewriting system R, the set of normal forms of R is regular. The set of normal forms of R is the complement of the set of rewritable terms, i.e., terms whose subterm match some left-hand side patterns of R. We give such a construction below. The construction here requires left linearity to ensure that each "hole" in the left-hand side patterns can pick terms independently. For example, the set of rewritable terms of rule $f(x,x) \to x$ is not regular.

Procedure termsMatchingPattern(p)

Input: A linear pattern p.

Output: An FTA \mathcal{A} satisfying $\mathcal{L}(\mathcal{A})$ contains all terms matching the given pattern.

begin

 $2. \qquad q_f \leftarrow \textit{mkFreshState}();$

```
3.
           case p of
  4.
               f(p_1,\ldots,p_k) \Rightarrow
                    (q_i, \Delta_i) \leftarrow termsMatchingPattern(p_i) for i = 1, ..., k;
  5.
                    q \leftarrow mkFreshState():
  6.
                    \Delta \leftarrow \{f(q_1, \dots, q_k) \to q\} \cup \bigcup_{i=1}^k \Delta_i;
  7.
  8.
                    return (q, \Delta);
  9.
               x \Rightarrow \mathbf{return} \ A_{\star};
end
Procedure subtermsMatchingPattern(p)
Input: A linear pattern p.
Output: An FTA \mathcal{A} satisfying \mathcal{L}(\mathcal{A}) contains all terms containing the given pattern.
begin
  2.
           q_f \leftarrow mkFreshState();
          (q_p, \Delta) \leftarrow termsMatchingPattern(p);
  3.
           \Delta \leftarrow \Delta \cup \{q_p \rightarrow q_f\};
  4.
```

for each many gymb

5. **for each** n-ary symbol f **where** n > 0 **do**

6. **for** i = 1, ..., n **do**

7. $\Delta \leftarrow \Delta \cup \{f(q_*|_{j=1,\dots,i-1}, q_f, q_*|_{j=i+1,\dots,n}) \to q_f\};$

8. **return** (q_f, Δ) ;

end

Procedure normalForms(R)

Input: A left-linear TRS R.

Output: An FTA \mathcal{A} satisfying $\mathcal{L}(\mathcal{A})$ is the set of normal forms of R.

begin

 $1. \ \ \mathbf{return} \ \overline{\bigcup_{lhs \rightarrow rhs \ \in \ R} \ subtermsMatchingPattern(lhs)};$

end

E-graphs and equality saturation

We call an FTA deterministic if for every term t,

$$t \to^* q_1 \wedge t \to^* q_2 \to q_1 = q_2.$$

We call an FTA reachable its every state accepts some term. An e-graph G is a deterministic and reachable FTA (Q_f, Δ) with $|Q_f| = 1$. Moreover, G induces a relation \approx_G defined as follows: if for two terms t_1 and t_2 there exists a state q in G such that $t_1 \to^* q \leftarrow^* t_2$, $t_1 \approx t_2$. \approx_G is symmetric and reflexive. Moreover, if $t_1 \to^* q \leftarrow^* t_2$ and $t_2 \to^* q' \leftarrow^* t_3$, since an E-graph is deterministic, $t_1 \to^* q = q' \leftarrow^* t_3$, so \approx_G is also transitive.

Turing machines

A Turing machine $\mathcal{M}=(Q,\Sigma,\Pi,\Delta,q_0,\beta)$ consists of a set of states Q, the input and the tape alphabet Σ and Π (with $\Sigma\subseteq\Pi$), a set of transitions Δ , an initial state $q_0\in Q$, and a special blanket symbol $\beta\in\Pi$. Each transition in Δ is a quintuple in $Q\times\Pi\times\Pi\times\{L,R\}\times Q$. For example, transition q_iabRq_j means if the current state is q_i and the symbol being scanned is a, then replace a with b, move the head to the right, and transit to state q_j . We assume the Turing machine is two-way infinite, so that the head can move in both directions indefinitely. Each

configuration of \mathcal{M} can be represented as $\triangleright uq_iav \triangleleft$, where $\triangleright, \triangleleft$ are left and right end markers, u is the string to the left of the read/write head, q_i is the current state, a is the symbol being scanned, and v is the string to the right. We say $w_1 \vdash_{\mathcal{M}} w_2$ if configuration w_1 can transit to configuration w_2 in a Turing machine \mathcal{M} , and we omit \mathcal{M} when it's clear from the context.

Termination of Equality Saturation

Theorem 1. The following problem is R.E.-complete:

Instance: a set of rewrite rules R, a term t.

Question: does EqSat terminate with R and t?

Proof. First, this problem is in R.E. since we can simply run EqSat with R and t to test whether it terminates. To show this problem is R.E.-hard, we reduce the termination problem of Turing machines to the termination of EqSat. We use the technique by (Narendran, Ó'Dúnlaing, and Rolletschek 1985). In particular, for each Turing machine \mathcal{M} , we produce a string rewriting system R such that the equivalence closure of R, $(\approx_R) = (R \cup R^{-1})^*$, satisfies that each equivalence class of \approx_R corresponds to a trace of the Turing machine. As a result, the Turing machine halts iff its trace is finite iff the corresponding equivalence class in R is finite iff EqSat terminates.

In this proof, we consider a degenerate form of EqSat that works with *string* rewriting systems instead of term rewriting systems. Every string corresponds to a term, and every string rewrite rule corresponds to a rewrite rule. For example, the string uvw corresponds to a term $u(v(w(\epsilon)))$, where $u(\cdot), v(\cdot), w(\cdot)$ are unary functions and ϵ is a constant, and a string rewrite rule $uvw \to vuw$ corresponds to a (linear) term rewriting rule $u(v(w(x))) \to v(u(w(x)))$ where x is a variable.

It is useful to define several sets of symbols for our construction. For each Turing machine \mathcal{M} , we define $\overline{Q}=\{\overline{q}\mid q\in Q\}$. We also define $\overline{\Sigma},\overline{\Pi}$ in a similar way. In our encoding, we use \overline{Q} to denote states where the symbol being scanned is to the left of the state, and we use $\overline{\Sigma}$ and $\overline{\Pi}$ to denote alphabets that are to the left of the states. Moreover, we introduce two sets of "dummy" symbols L_z and R_z for z ranges over $Q\times(\{\lhd\}\cup\Pi)$ and $(\{\rhd\}\cup\overline{\Pi})\times\overline{Q}$. Let D_L and D_R be the set of all L_z and R_z respectively. We use these dummy symbols to make the string rewriting system that we will later define Church-Rosser.

The rewriting system we are going to define works over the set of strings $CONFIG = \triangleright (\overline{\Pi} \cup D_L)^*(Q \cup \overline{Q})(\Pi \cup D_R)^* \lhd$. Strings in CONFIG is in a many-to-one mapping, denoted as π , to configurations of a Turing machine. $\pi(w)$ converts each \overline{aq}_i to q_ia , removes dummy symbols L_z and R_z , and replace \overline{a} with a. For example $\pi(\triangleright L_{q_0,a}\overline{b}L_{q_1,b}\overline{cq_3}dR_{q_i,\lhd}\lhd) = \triangleright bq_3cd\lhd$

Now, the transitions in \mathcal{M} , we define our string rewriting system R as follows.

transitions in \mathcal{M}	rewrites in R
$\overline{q_i ab R q_j}$	$q_i a \rightarrow_R L_{q_i a} \bar{b} q_j$
, and the second	$\overline{aq}_i ightarrow_R L_{\overline{a}q_i}^{\scriptscriptstyle T} ar{b} q_j^{\scriptscriptstyle T}$
$q_i eta b R q_j$	$q_i \lhd \to_R L_{q_i \lhd} \bar{b} q_j \lhd$
	$ ho \overline{q}_i ightarrow_R ho \overline{L}_{ ho \overline{q}_i} \overline{b} q_j$
$q_i ab L q_j$	$q_i a ightarrow_R \overline{q}_j b R_{q_i a}$
	$\overline{aq}_i ightarrow_R \overline{q}_j^{} b R_{\overline{aq}_i}^{}$
$q_i eta b L q_j$	$q_i \lhd \to_R \overline{q}_j b R_{q_i} \lhd \lhd$
	$ ho \overline{q}_i ightarrow_R ho \overline{q}_j b R_{ ho \overline{q}_i}$

Moreover, for each z, we have the following two additional (sets of) auxiliary rewrite rules

$$q_i R_z \to_R L_z L_z q_i$$

$$L_z \overline{q}_i \to_R \overline{q}_i R_z R_z$$

for any z.

To explain what these two rules do, let us define two types of strings. Type-A strings are strings where the symbol being scanned is to the immediate right of q_i or to the immediate left of $\overline{q_i}$. In other words, we call a string s

a type-A string if s contains $q_i a$ or $\overline{aq_i}$. Type-B strings are strings that are not type-A: they are strings where there are dummy symbols in between the state and the symbol being scanned. The rewrite rules above convert any type-B strings into type-A in a finite number of steps.

Now, we observe that R has several properties:

- 1. Reverse convergence: the critical pair lemma implies that if a rewriting system is terminating and all its critical pairs are convergent, it is convergent. Define $\leftarrow_R = (\rightarrow_R)^{-1}$. \leftarrow_R is terminating since rewrite rules in \leftarrow_R decreases the sizes of terms (that is, rewrite rules in \rightarrow_R increases the sizes of terms), and \leftarrow_R has no critical pairs. Therefore, \leftarrow_R is convergent.
- 2. For each type-A string w, then either
 - there exists no w' with $w \to_R w'$ and $\pi(w)$ is a halting configuration;
 - there exists a unique w' such that $w \to_R w'$ and $\pi(w) \vdash \pi(w')$.
- 3. For each type-B string w, there exists a unique w' such that $w \to_R w'$, and $\pi(w) = \pi(w')$. Moreover, if $w_0 \to_R w_1 \to_R \dots$ is a sequence of type-B strings, the sequence must be bounded in length, since the state symbols q_i and \overline{q}_i move towards one end according to the auxillary rules above.
- 4. By 2 and 3, $w \to_R w_1$ and $w \to_R w_2$ implies $w_1 = w_2$. In other words, \to_R is a function.

These observations allows us to prove the following lemma

Lemma 2. Let $w_0 = \triangleright q_0 s \triangleleft$ be an initial configuration. w_0 is obviously in *CONFIG*. Moreover, given a Turing machine \mathcal{M} , construct a string rewriting system R as above. \mathcal{M} halts on w_0 if and only if $[w_0]_R$, the equivalence class of w_0 in R, is finite.

Proof. Consider $S: w_0 \to_R w_1 \to_R \dots$, a sequence of *CONFIG* starting with w_0 . By the above observations, S must have a subsequence of type-A strings $w_0 \to_R^* w_{a_1} \to_R^* w_{a_2} \to_R^* \dots$ with

$$\pi(w_0) = \ldots = \pi(w_{a_1-1}) \vdash \pi(w_{a_1}) = \ldots = \pi(w_{a_2-1}) \vdash \pi(w_{a_2}) = \ldots.$$

An overview of the trace $w_0, w_{a_1}, w_{a_2}, \dots$ and its properties is shown below:

Rw	w_0	\rightarrow_R	$\underbrace{w_1 \to_R \dots \to_R w_{a_1-1}}_{}$	\rightarrow_R	w_{a_1}	$\underbrace{w_{a_1+1} \to_R \dots \to_R w_{a_2-1}}_{}$	\rightarrow_R	w_{a_2}	
Type	A		$\stackrel{ ext{finite}}{ ext{B} \dots ext{B}}$		A	$\stackrel{ ext{finite}}{ ext{B} \dots ext{B}}$		A	
Config	$\pi(w_0)$	=	$\pi(w_1) = \ldots = \pi(w_{a_1-1})$	$\vdash_{\mathcal{M}}$	$\pi(w_{a_1})$	$\pi(w_{a_1+1}) = \ldots = \pi(w_{a_2-1})$	$\vdash_{\mathcal{M}}$	$\pi(w_{a_2})$	

Now we prove the claim:

• \Leftarrow : Suppose $[w_0]_R$ is finite. We show that there exists a *finite* sequence S of $w_0 \to_R w_1 \to_R \dots \to_R w_n$ such that there is no w' such that $w_n \to_R w'$. If this is not the case, then an infinite rewriting sequence $w_0 \to_R w_1 \to \dots$ must exist. Because $[w_0]_R$ is finite, for the sequence to be infinite, there must exist distinct i, j such that $w_i = w_j$ in the sequence. However, this is impossible, because \to_R always increases the sizes of terms.

By our observation above, if there is no such w' that $w_n \to_R w'$ in sequence S, it has to be the case that w_n is type-A and $\pi(w)$ is a halting configuration.

Now, take the subsequence of S that contains every type-A string:

$$w_0 \to_R^* w_{a_1} \to_R^* \ldots \to_R^* w_{a_k} = w_n.$$

We have $\pi(w_{a_i}) \vdash \pi(w_{a_{i+1}})$ for all i and $\pi(w_{a_k})$ is a halting configuration. This implies a finite trace of the Turing machine:

$$w_0 \vdash \pi(w_{a_1}) \vdash \ldots \vdash \pi(w_{a_n}).$$

Since we only consider deterministic Turing machines, the Turing machine halts on w_0 .

• \Rightarrow : Suppose otherwise \mathcal{M} halts on w_0 and $[w_0]_R$ is infinite.

By definition, w_0 is a normal form with respect to \leftarrow_R , and because \leftarrow_R is convergent, if there exists a w such that $w \approx_R w_0$, then $w_0 \to_R^* w$. The fact that $[w_0]_R$ is infinite implies w_0 can be rewritten to infinitely many

strings w. Because \to_R satisfies the functional dependency, it has to be the case that there exists an infinite rewriting sequence: $S: w_0 \to_R w_1 \to_R \dots$ Taking the subsequence of S consisting of every type-A strings:

$$w_0 \to_R^* w_{a_1} \to_R^* \dots$$

This implies an infinite trace of the Turing machine:

$$w_0 \vdash \pi(w_{a_1}) \vdash \dots,$$

which is a contradiction.

We are ready to prove the undecidability of the termination problem of EqSat:

Given a Turing machine \mathcal{M} . We construct the following two-tape Turing machine \mathcal{M}' :

 \mathcal{M}' alternates between the following two steps:

- 1. Simulate one transition of \mathcal{M} on its first tape.
- 2. Read the string on its second tape as a number, compute the next prime number, and write it to the second tape.

 \mathcal{M}' halts when the simulation of \mathcal{M} reaches an accepting state.

It is known that a two-tape Turing machine can be simulated using a standard Turing machine, so we assume \mathcal{M}' is a standard Turing machine and takes input string (s_1, s_2) , where s_1 is the input on its first tape and s_2 is the input on its second tape. Let R' be the string rewriting system derived from \mathcal{M}' using the encoding we introduced in the lemma.

Given a string s, let w be the initial configuration $\triangleright q_0(s,2) \triangleleft$. The following conditions are equivalent to each other:

- 1. \mathcal{M} halts on input s.
- 2. \mathcal{M}' halts on input (s, 2).
- 3. $[w]_{R'}$ is finite.
- 4. $[w]_{R'}$ is regular.

Note that (3) implies (4) trivially, and (4) implies (3) because if $[w]_{R'}$ is infinite, it must not be regular since the trace of \mathcal{M}' computes every prime number.

Now run EqSat with initial string w and rewriting system $\leftrightarrow_{R'}$. EqSat terminates if and only if \mathcal{M} halts on s:

- \Rightarrow : Suppose EqSat terminates with output E-graph G. Strings equivalent to w in G is exactly the equivalence class of w, i.e., $[w]_G = [w]_{R'}$. Moreover, every e-class in an E-graph represents a regular language, so $[w]_G$ is regular. Therefore, $[w]_G$ is finite.
- \Leftarrow : Suppose \mathcal{M} halts on s. This implies $[w]_{R'}$ is finite. Because EqSat monotonically enlarges the set of represented terms, it has to stop in a finite number of iterations.

Because the halting problem of a Turing machine is undecidable, the termination problem of EqSat is undecidable as well. \blacksquare

Theorem 3. The following problem is undecidable.

Instance: a set of rewrite rules R, a term w.

Problem: Is $[w]_R$ regular?

Proof.

To show the undecidability, we reduce the halting problem of Turing machines to this problem. As shown in Theorem 1, given a Turing machine \mathcal{M} , \mathcal{M} halts on an input s if and only if $[w]_{R'}$ is regular for $w = \triangleright q_0(s, 2) \triangleleft$.

For a particular kind of rewrite systems, we show this regularity problem is R.E.-complete.

Theorem 4. The following problem is R.E.-complete.

Instance: a set of linear, convergent rewrite rules R, a term w.

Problem: Is $[w]_R$ regular?

Proof.

As we show in Theorem 1, the regularity of \leftarrow_R is undecidable. Note that \leftarrow_R , the inverse of \rightarrow_R defined in Theorem 1, is convergent. Moreover, because every string rewriting system is a linear term rewriting system and therefore a left-linear term rewriting system, \leftarrow_R is left-linear. Therefore, the regularity of left-linear, convergent term rewriting systems is undecidable. Additionally, we show the regularity problem is in R.E. by showing a semi-decision procedure for it.

Procedure equivClassOf(R, w)

Input: a left-linear, convergent term rewriting system R, a term w.

Output: an E-graph that represents $[w]_R$ if exists.

begin

- 1. for each E-graph G such that $w \in \mathcal{L}(G)$ do
- 2. if $G = runEqSatOneIter(G, \leftrightarrow_R)$ then
- 3. if $\mathcal{L}(G) \cap normalForms(R) = \{w\}$ then
- 4. return G;

end

We show the correctness of our algorithm in two steps.

• We show that if an e-graph G is returned, $\mathcal{L}(G) = [w]_R$: First, if $G = runEqSatOneIter(G, \leftrightarrow_R)$, we have, for any term t,

$$t \in \mathcal{L}(G) \Rightarrow [t]_R \subseteq \mathcal{L}(G).$$
 (1)

Suppose this is not the case. There must exist term u, v where $u \leftrightarrow_R v, u \in \mathcal{L}(G)$, and $v \in \mathcal{L}(G)$, and running one iteration of equality saturation will further enlarge the e-graph, which is a contradiction. Therefore, since $w \in \mathcal{L}(G)$, $[w]_R \subseteq \mathcal{L}(G)$.

Second, we show $\mathcal{L}(G) \subseteq [w]_R$. Suppose this is not the case. There exists a term $u \in \mathcal{L}(G)$ that is in a different equivalence class than $[w]_R$. By (1), $[u]_R \subseteq \mathcal{L}(G)$. Because R is convergent, $[u]_R$ has a normal form n_u that is contained in $\mathcal{L}(G)$, but line 3 ensures that $\mathcal{L}(G)$ has one normal form which is w, a contradiction.

• On the other hand, if there exists an e-graph G such that $\mathcal{L}(G) = [w]_R$. This case is straightforward: if $\mathcal{L}(G) = [w]_R$, G is "saturated" with regard to \leftrightarrow_R . Moreover, since R is convergent, $[w]_R$ has only one normal form which is w.

References

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