## ECE4730J Advanced Embedded System

## LAB 2: PROGRAM PROFILING ON LINUX

October 11, 2021

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## Lab 1 Task 3. (Optional)



Figure 1. Setup the remote access to your Raspberry Pi.

1. No submission for the first exercise.

Figure 2. The list of the size of each program.

program	size
arr_search_static	607K
arr_search_dynamic	14K

Table 1. The list of the size of each program.

The statically compiled program is much larger than the dynamically compiled program because the statically compiled program includes all the library code in the executable file, while the dynamically compiled program places calls to the code of shared libraries during runtime.

Figure 3. time command.

The number of iterations used: 100000.

Note that there should be enough time interval between two measures of time, otherwise the measurement will be inaccurate.

The "real" execution time for the arr\_search\_dynamic binary: 1.042s.

The "real" execution time for the arr\_search\_static binary: 1.033s

The statically compiled program is slightly faster than the dynamically compiled program because the statically compiled program can directly execute the library code without calling to shared library. However, the difference is very small. If you repeat many times, you will find that sometimes they almost have the same execution time.

Figure 4. 1dd command.

They are different because 1dd is used to print shared object dependencies. The statically compiled program does not require shared objects (shared libraries), so it prompts "not a dynamic executable". On the contrary, the dynamically compiled program requires shared objects (shared libraries), so 1dd prints the shared objects (shared libraries) it used:

linux-vdso.so.1

 $\label{libm.so.6} $$ libm.so.6 =>/lib/aarch64-linux-gnu/libm.so.6 $$ libc.so.6 =>/lib/aarch64-linux-gnu/libc.so.6 $$ /lib/ld-linux-aarch64.so.1 $$$ 

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Figure 5. nm command (static).

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Figure 6. nm command (dynamic).

nm command is used to list symbols from object files. The statically compiled program has a lot of symbols, and all the symbols of library code are listed, such as malloc of stdlib.h and strchr of string.h, while the dynamically compiled program has relatively less symbols.

Figure 7. Compiling and loading programs by gdb.

Using -g option to compile our program by gcc we can use gdb to debug.

7. b command adds a breakpoint, where library\_calls is the function. r commands runs the program, and 2 is the number of iterations.

Figure 8. Executing the program in gdb.

c command continues to the next breakpoint, and we can see that the program stops again at the function library\_calls, which indicates that we are executing the second time.

9. We can see that the address of the variable  ${\tt values}$  is  $0{\tt xaaaaaaaab32a0}$ . 10.

Figure 9. Continue execution until the program execution exits.

Figure 10. Continue execution until the program execution exits.

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Values of values[0]: 0->1->0->6.58610278e-44->3.73740313e-41->1.02311141e-38->4.63080422e+27 Values of values[1]: 0->1.41421354
```