

$$1. (a) H(j\omega) = \frac{2j\omega + 1}{-j\omega^3 - 5\omega^2 + 8j\omega + 4} = \frac{-2\omega + j}{(\omega - 2j)^2(\omega - j)} = \frac{2j\omega + 1}{(j\omega + 2)^2(j\omega + 1)}$$

$$G(v) = \frac{2v+1}{(v+2)^2(v+1)} = \frac{A_{11}}{v+2} + \frac{A_{12}}{(v+2)^2} + \frac{A_{21}}{v+1}$$

$$A_{11} = \frac{d}{dv} [(v+2)^2 G(v)] \Big|_{v=-2} = \frac{d}{dv} \left(\frac{2v+1}{v+1} \right) \Big|_{v=-2} = \frac{d}{dv} \left(2 - \frac{1}{v+1} \right) \Big|_{v=-2}$$

$$= \frac{d}{dv} \left(-\frac{1}{v+1} \right) \Big|_{v=-2} = \frac{1}{(v+1)^2} \Big|_{v=-2} = 1$$

$$A_{12} = [(v+2)^2 G(v)] \Big|_{v=-2} = \frac{2v+1}{v+1} \Big|_{v=-2} = 3$$

$$A_{21} = [(v+1) G(v)] \Big|_{v=-1} = \frac{2v+1}{(v+2)^2} \Big|_{v=-1} = -1$$

$$H(j\omega) = \frac{1}{j\omega+2} + \frac{3}{(j\omega+2)^2} - \frac{1}{j\omega+1}$$

MATLAB code:

Input: Coefficients of numerator and denominator polynomial

Output: Residues of PFE, poles of PFE, and direct term

```
1 b = [2 1];
2 a = [1 5 8 4];
3 [r, p, k] = residue(b, a)
```

Output:

```
r =
    1.0000
    3.0000
   -1.0000
```

```
p =
   -2.0000
   -2.0000
   -1.0000
```

```
k =
    []
```

In the case of repeated poles, r is ordered in A_{1k} first,

Hence, MATLAB gives $\frac{1}{j\omega+2} + \frac{3}{(j\omega+2)^2} - \frac{1}{j\omega+1}$

which is exactly our result.



$$(b) e^{-at} u(t) \leftrightarrow \frac{1}{j\omega + a}$$

$$te^{-at} u(t) \leftrightarrow \frac{1}{(j\omega + a)^2}$$

$$H(j\omega) = \frac{1}{j\omega + 2} + \frac{3}{(j\omega + 1)^2} - \frac{1}{j\omega + 1}$$

Do Fourier Transform, the unit impulse response $h(t)$ of this system is

$$h(t) = e^{-2t} u(t) + 3te^{-2t} u(t) - e^{-t} u(t)$$

$$= \boxed{(e^{-2t} + 3te^{-2t} - e^{-t}) u(t)}$$

MATLAB plot

$$\text{plot}((\exp(-2*t)) + 3*t*\exp(-2*t) - \exp(-t))*\text{heaviside}(t), [2, 8])$$

Graph see attached pages.

Use MATLAB impulse to generate a same plot Graph see attached pages

By comparing the two graphs, we can verify our results.

$$2. (a) x(t) = \cos \omega_0 t$$

$$x_s(t) = x(t)p(t) = x(t) \sum_{n=-\infty}^{\infty} \delta(t - nT) = \sum_{n=-\infty}^{\infty} x(nT) \delta(t - nT)$$

$$X_p(\omega) = \frac{1}{T} X(\omega) * p(\omega) = \frac{1}{T} \sum_{k=-\infty}^{\infty} X(\omega - k\omega_s)$$

$$\cos \omega_0 t \leftrightarrow \pi \delta(\omega - \omega_0) + \pi \delta(\omega + \omega_0)$$

$$X(\omega - k\omega_s) = \pi \delta(\omega - \omega_0 - k\omega_s) + \pi \delta(\omega + \omega_0 - k\omega_s) \quad \omega_s = \frac{2\pi}{T} = 6\pi$$

$$= \pi \delta(\omega - \omega_0 - k\omega_s) + \pi \delta(\omega + \omega_0 - k\omega_s)$$

$$X_p(\omega) = \frac{1}{T} \sum_{k=-\infty}^{\infty} \left(\pi \delta(\omega - \omega_0 - k\omega_s) + \pi \delta(\omega + \omega_0 - k\omega_s) \right)$$

The sketches are included in attached pages.

(b) For $\omega_0 = \pi$ and 5π $X_p(\omega)$ identical

By Sampling theorem, $\omega_s \geq 2\omega_{\max} \Rightarrow \omega_{\max} < 3\pi$

Thus, for $\omega_0 = 3\pi$ and 5π we will NOT be able to recover the input sinusoidal signal after lowpass filtering $X_p(\omega)$.

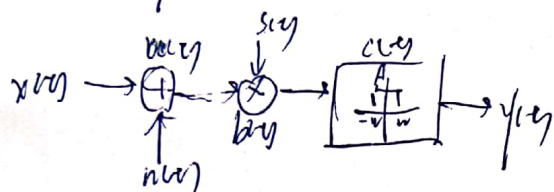


3. Denote the response of the unknown deterministic system as $P(\omega)$.
 Then $Q(\omega) = P(\omega) X_p(\omega)$. $\cos \omega t$ can be seen as a function of ω . too
 No matter what is $P(\omega)$ since $X_p(t)$ is a train of impulses is periodic as a function of ω
 $Q(\omega)$ is ~~constant~~ ^{for t} and $Q(\omega)$ should also be ~~a train of impulses~~ periodic
 ~~$P(\omega) \cdot \delta(\omega - n\omega_s) = P(n\omega_s) \delta(\omega - n\omega_s)$~~

However, ω_s (b) are not like this,

so the following two plots ω_s (b) ~~is~~ ^{is} ~~not~~ ^{not} possible for the variation of Q as a function of ω , but (c) is possible

4. Derive the systems as follows

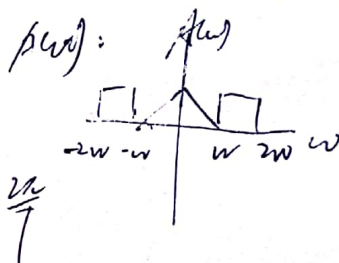
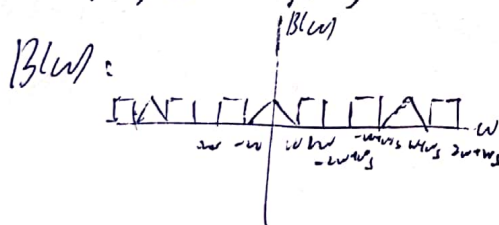


then $a(t) = x(t) + n(t)$
 $b(t) = a(t) \cdot s(t)$

$$s(t) = \sum_{n=-\infty}^{+\infty} \delta(t - nT)$$

$$B(\omega) = \frac{1}{T} \sum_{n=-\infty}^{+\infty} A(\omega - n\omega_s), \quad \omega_s = \frac{2\pi}{T}$$

$$Y(\omega) = B(\omega) C(\omega) = X(\omega)$$



We have

$$-2\omega_s + \omega_s \geq \omega_s$$

$$\Rightarrow \omega_s = \frac{2\pi}{T} \geq 3\omega$$

Suppose the amplitude of $X(\omega)$ and $P(\omega)$ is A_0 , $T \leq \frac{2\pi}{3\omega}$

then

$$\frac{A}{T} = A_0 \quad A \leq \frac{2\pi A_0}{3\omega}$$

Thus the maximum values for T is $\frac{2\pi}{3\omega}$

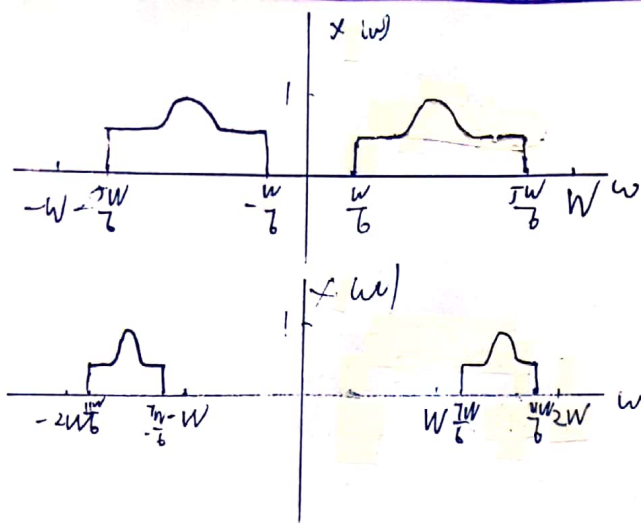
for A is $\frac{2\pi A_0}{3\omega}$

5. $\omega_{\max} = \frac{5\pi}{6}$ $\omega_s = \frac{2\pi}{T} = 2\omega$ $\omega_s > 2\omega_{\max}$, so $X(\omega)$ can simply be identical to $X_r(\omega)$

Alternatively, $X(\omega)$ can also be just one side part of $X_r(\omega)$

The sketches are:





6. (a) $x(t) = x_1(t - \frac{T}{2}) + x_2(t)$

Doing Fourier transform

$$X(\omega) = X_1(\omega) e^{-j\omega \frac{T}{2}} + X_2(\omega), \quad x_1(\omega) = 0 \text{ for } |\omega| > 2W \text{ and } x_2(\omega) = 0 \text{ for } |\omega| > W$$

So the ranges for ω_c is ~~$|\omega_c| \leq 2W$~~ $|\omega_c| \geq 2W$ and $|\omega_c| \leq \frac{2T}{T} - 2W$

$$X_p(\omega) = \frac{1}{T} \sum_{n=-\infty}^{\infty} X(\omega - n\omega_c)$$

-then

$$A = \frac{T}{T}$$

$$\begin{aligned} -2W + \frac{2T}{T} &\geq 2W \\ \frac{2T}{T} &\geq 4W \\ T &\leq \frac{2W}{W} \end{aligned}$$

Thus, the maximum value of T is $\frac{2}{2W}$
the maximum value of A is $\frac{2}{2W}$

(b) $x(t) = x_1(t) * x_2(t)$

$$X(\omega) = \frac{1}{2} X_1(\omega) * X_2(\omega)$$

By the property of convolution the range for ω_c is ~~$|\omega_c| \geq 3W$~~ $|\omega_c| \geq 3W$ and $|\omega_c| \leq \frac{2T}{T} - 3W$

$$\frac{A}{T} = 1 \quad A = \frac{T}{T}$$

$$\begin{aligned} -3W + \frac{2T}{T} &\geq 3W \\ \frac{2T}{T} &\geq 6W \\ T &\leq \frac{2}{3W} \end{aligned}$$

The maximum value of T is $\frac{2}{3W}$, the maximum value of A is $\frac{2}{3W}$

(c)

$$x(t) = \frac{d x_1(t)}{dt}$$

$$X(\omega) = j\omega X_1(\omega)$$

$$\frac{A}{T} = 1 \quad A = \frac{T}{T}$$

The range for ω_c is ~~$|\omega_c| \geq W$~~ $|\omega_c| \geq W$ and $|\omega_c| \leq \frac{2T}{T} - W$

$$\begin{aligned} -W + \frac{2T}{T} &\geq W \\ \frac{2T}{T} &\geq 2W \\ T &\leq \frac{2}{W} \end{aligned}$$

The maximum value of T is $\frac{2}{W}$ the maximum value of A is $\frac{2}{W}$



$$(d) \quad x(t) = x_2(t) \cos(2\pi W t)$$

Fourier transform.

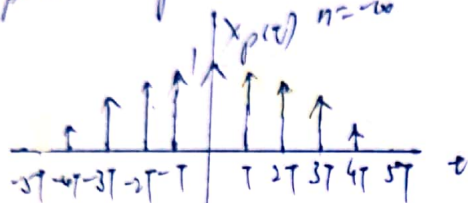
$$X(\omega) = \frac{X_2(\omega - 2W) + X_2(\omega + 2W)}{2}$$

The range of useful frequency ω_c is

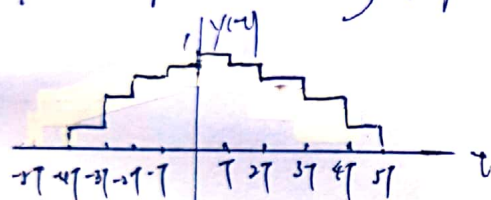
$$\boxed{\begin{array}{l} \pm W \text{ and } \pm 3W \\ |\omega| \leq \frac{\omega_c}{2} \end{array}}$$

No applicable T and A values such that $x_r(t) = x(t)$

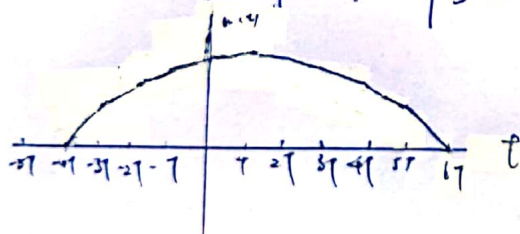
$$7. \quad x_p(t) = x(t) p(t) = x(t) \sum_{n=-\infty}^{\infty} \delta(t - nT)$$



$$y(t) = x_p(t) * h(t) = \int_{-\infty}^{\infty} x_p(t) h(t-\tau) d\tau$$



$$w(t) = y(t) * \frac{1}{T} h(t) = \frac{1}{T} \int_{-\infty}^{\infty} y(\tau) h(t-\tau) d\tau$$



$$8. \quad z(t) = y(t) \cos(\omega_d t)$$

$$y(t) = x(t) \cos(\omega_c t)$$

$$w(t) = x(t) \cos(\omega_c t) \cos(\omega_d t)$$

$$= \frac{1}{2} x(t) (\cos((\omega_c + \omega_d)t) + \cos((\omega_c - \omega_d)t))$$

$$= \frac{1}{2} x(t) (\cos((\omega_c + \omega_d)t) + \cos(\omega t))$$

Since $\omega_H + \omega_L < \omega_c < 2\omega_c + \omega_H - \omega_L$

and $\frac{1}{2} x(t) \cos((\omega_c + \omega_d)t)$ is in $\omega_c + \omega_d - \omega_H \leq |\omega| \leq \omega_c + \omega_d + \omega_H$

However, after filtering the spectrum $\omega \leq \omega_c < 2\omega_c + \omega_H - \omega_L = \omega_c + \omega_H - \omega_L$

So this part is eliminated, $w(t) = \frac{1}{2} x(t) \cos(\omega t)$

Thus, the output of the lowpass filter in the demodulator is proportional to $x(t) \cos(\omega t)$

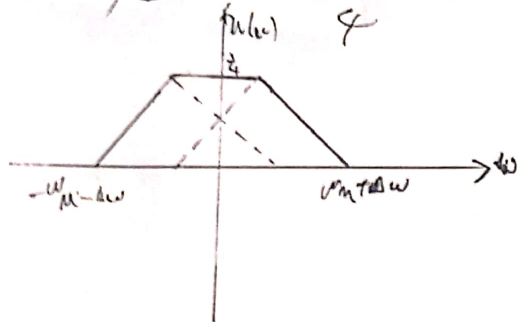


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$$(b) \quad w(t) = \frac{1}{2} x(t) \cos(\omega_0 t)$$

Fourier transform:

$$W(\omega) = \frac{X(\omega - \omega_0) + X(\omega + \omega_0)}{2}$$



$$9. \quad x(t) = \text{sinc}\left(\frac{t}{\tau}\right)$$

$$\frac{1}{2} x(t) = \frac{1}{2} \text{sinc}\left(\frac{t}{\tau}\right) \quad \omega_0 = 2$$

$$\frac{1}{2} X(\omega) = \text{rect}\left(\frac{\omega}{2}\right)$$

$$X(\omega) = 2 \text{rect}\left(\frac{\omega}{2}\right)$$

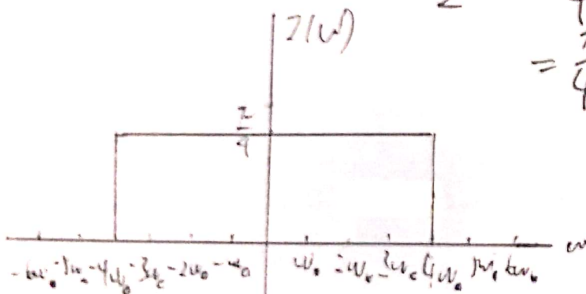
$$y(t) = x(t) \cos(\omega_0 t)$$

$$Y(\omega) = \frac{X(\omega - \omega_0) + X(\omega + \omega_0)}{2} = \frac{2}{2} \left(\text{rect}\left(\frac{\omega - \omega_0}{2}\right) + \text{rect}\left(\frac{\omega + \omega_0}{2}\right) \right)$$

$$z(t) = y(t) \cos(\omega_0 t)$$

$$Z(\omega) = \frac{Y(\omega - \omega_0) + Y(\omega + \omega_0)}{2} = \frac{2}{4} \left(\text{rect}\left(\frac{\omega - \omega_0}{2} - \omega_0\right) + \text{rect}\left(\frac{\omega - \omega_0}{2} + \omega_0\right) + \text{rect}\left(\frac{\omega + \omega_0}{2} - \omega_0\right) + \text{rect}\left(\frac{\omega + \omega_0}{2} + \omega_0\right) \right)$$

$$= \frac{1}{2} \left(\text{rect}\left(\frac{\omega - 3\omega_0}{2}\right) + \text{rect}\left(\frac{\omega - \omega_0}{2}\right) + \text{rect}\left(\frac{\omega + \omega_0}{2}\right) + \text{rect}\left(\frac{\omega + 3\omega_0}{2}\right) \right)$$

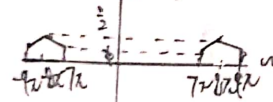
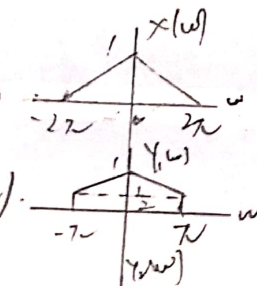


$$/ a. \quad x(t) = \left(1 - \left|\frac{t}{\tau}\right|\right) \text{rect}\left(\frac{t}{\tau}\right) \quad \text{Sketch of } x(t):$$

$$y_1(t) = x(t) H(t) \quad \text{Sketch of } y_1(t):$$

$$y_2(t) = y_1(t) \cos(2\pi t) \quad Y_2(\omega) = \frac{Y_1(\omega - 2) + Y_1(\omega + 2)}{2}$$

Sketch of $Y_2(\omega)$:

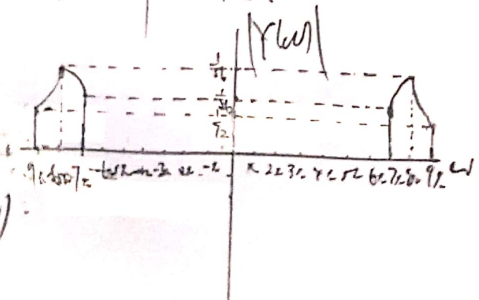


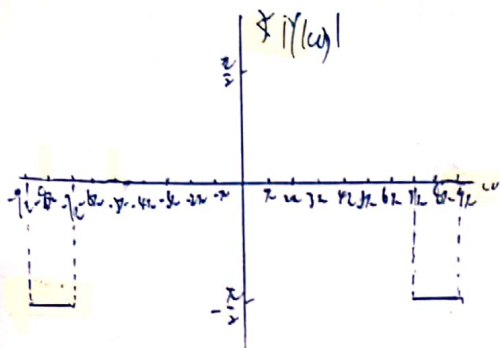
Passing through an integrator system:

$$Y(\omega) = \frac{1}{j\omega} Y_2(\omega) + \pi Y_2(0) \delta(\omega) = \frac{1}{j\omega} Y_2(\omega)$$

$$= \frac{1}{2j\omega} (Y_1(\omega - 2) + Y_1(\omega + 2))$$

Sketch of $Y(\omega)$:
(continued)





11(a) The maximum absolute value of $x(t) = \cos \omega_m t$ is 1, so
the modulation index $m = 1$

$$y(t) = (A + x(t)) \cos(\omega_c t + \theta_c)$$

$$= [A + \cos(\omega_m t)] \cos(\omega_c t + \theta_c)$$

$$= A \cos(\omega_c t + \theta_c) + \cos(\omega_m t) \cos(\omega_c t + \theta_c)$$

$$= A \cos(\omega_c t + \theta_c) + \frac{1}{2} \cos\left(\frac{\omega_c + \omega_m}{2} t + \theta_c\right) + \frac{1}{2} \cos\left(\frac{\omega_c - \omega_m}{2} t + \theta_c\right)$$

Consider the power of a sinusoid of frequency ω_0 ,

$$P = \frac{1}{T} \int_0^T \cos^2(\omega_0 t) dt$$

$$= \frac{\omega_0}{2\pi} \int_0^{2\pi/\omega_0} \frac{1 + \cos(2\omega_0 t)}{2} dt$$

$$= \frac{\omega_0}{2\pi} \cdot \frac{1}{2} \cdot \frac{2\pi}{\omega_0} + \frac{\omega_0}{2\pi} \cdot \frac{1}{2} \cdot \frac{\sin(2\omega_0 t)}{2\omega_0} \Big|_0^{2\pi/\omega_0}$$

$$= \frac{1}{2}$$

$$P_y = \frac{1}{T} \int_0^T y^2(t) dt$$

$$= \frac{A^2}{2} + \frac{1}{4} + \frac{1}{4} = \frac{A^2}{2} + \frac{1}{2} = \frac{1}{2m^2} + \frac{1}{4}$$

$$P_y = \frac{1}{2m^2} + \frac{1}{4}$$

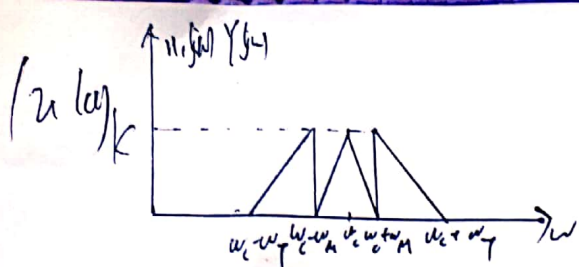
(b) Derive the efficiency as ϵ , then $\epsilon = \frac{\frac{1}{2}}{\frac{1}{2}(\frac{1}{m^2} + \frac{1}{2})} = \frac{m^2}{m^2 + 2}$

Thus the efficiency of the modulated signal as a function of the modulation index m is

$$\boxed{\frac{m^2}{m^2 + 2}}$$

the sketch see the attached page.



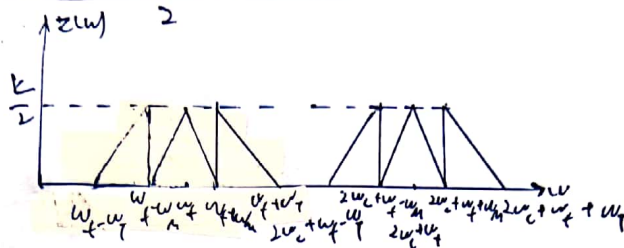


Denote $y_2(j\omega) = H_1(j\omega) Y(j\omega)$

then $z(t) = y_2(t) \cos(\omega_c t + \phi)$

F.T. $Z(j\omega) = \frac{Y_2(j(\omega + \omega_c + \omega_f)) + Y_2(j(\omega - \omega_c - \omega_f))}{2}$

Sketch of $Z(j\omega)$:
for $\omega > 0$



(b)

$2\omega_c + \omega_f - \omega_f \geq \omega_f + \omega_m$

$\omega_c + 2\omega_f - \omega_m \geq \omega_c + \omega_f$

\Rightarrow

$$\begin{aligned} \omega_f &\geq \omega_m \\ \omega_f &\leq 2\omega_c - \omega_m \\ \omega_f &\leq 2\omega_c - \omega_m \end{aligned}$$

(c)

$$\begin{aligned} \alpha &= \frac{2}{k} \\ \alpha &= \omega_f - \omega_m \\ \beta &= \omega_f + \omega_m \end{aligned}$$



VE216

Introduction to Signals and Systems

HOMEWORK 5 ATTACHED PAGES

April 24, 2020

Yihua Liu 518021910998

1. (b) The graph of my answer as a function of t is

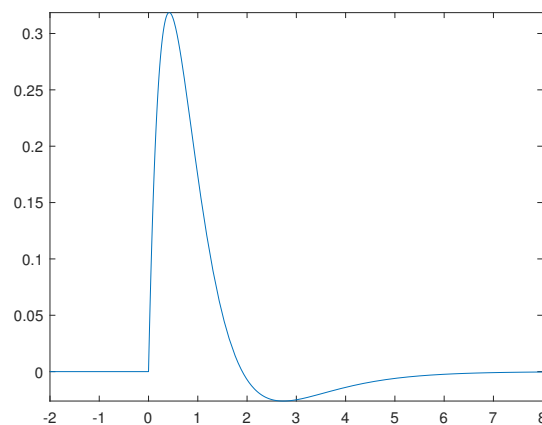


Figure 1. 1(b)-1.

The graph generated by MATLAB impulse is

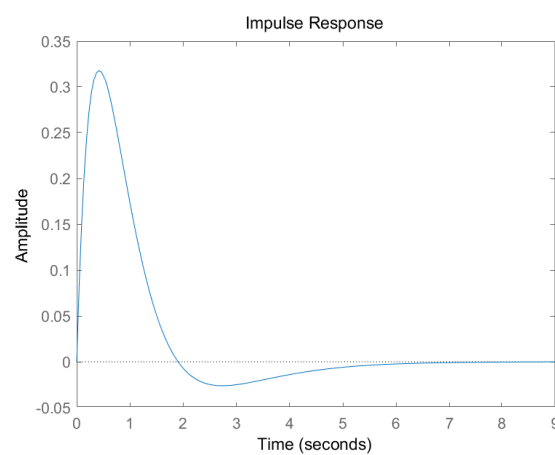


Figure 2. 1(b)-2.

2. (a) The sketches of $X_p(\omega)$ for $-9\pi \leq \omega \leq 9\pi$ for $\omega_0 = \pi$, 2π , 3π , and 5π are respectively

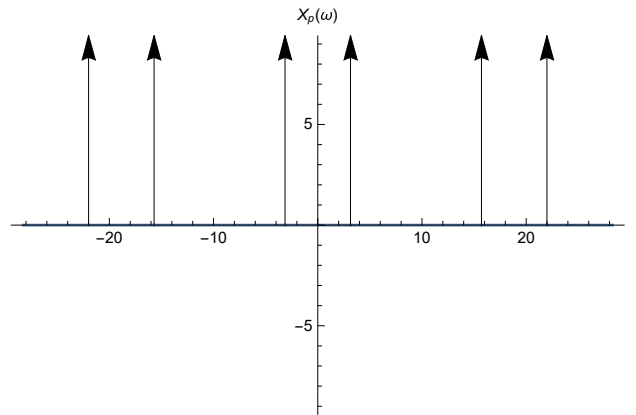


Figure 3. 2(a)i.

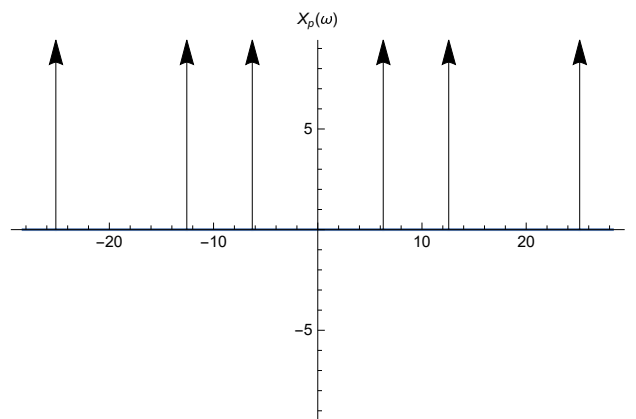


Figure 4. 2(a)ii.

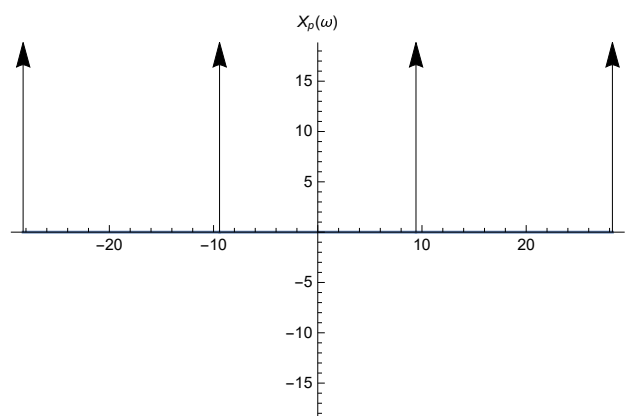


Figure 5. 2(a)iii.

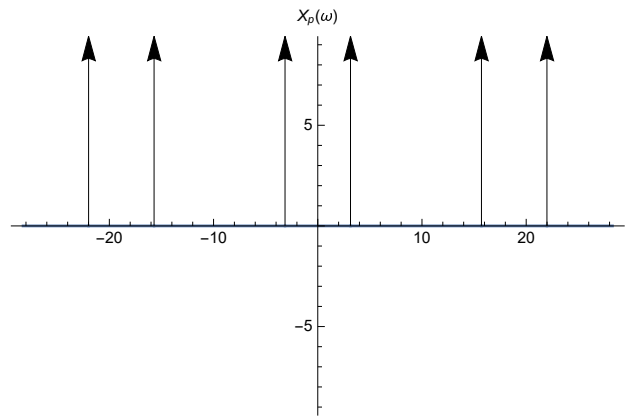


Figure 6. 2(a)iv.

11. (b) The sketch of the efficiency of the modulated signal as a function of the modulated index m is

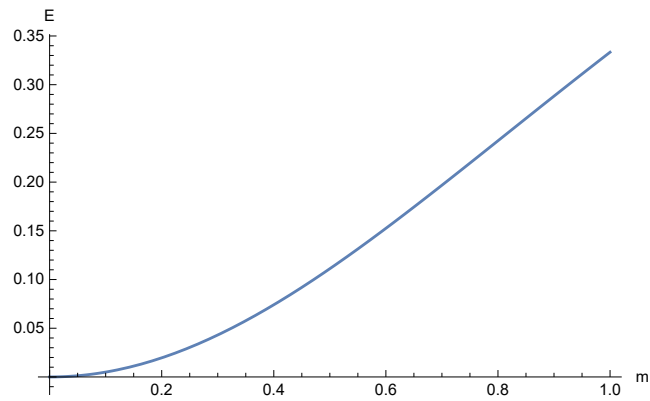


Figure 7. 11(b).