

4.1 (a) RC $\frac{dV_{out}(t)}{dt} + V_{out}(t) = V_{in}(t)$

Let $V_{out}(t) = y_{step}(t)$, $V_{in}(t) = u(t)$

$$y_{step}(t) = (1 - e^{-t/\tau_c})u(t) = \begin{cases} 1 - e^{-t/\tau_c} & t \geq 0 \\ 0 & t < 0 \end{cases}$$

$t \geq 0$ RC $\frac{1}{\tau_c} e^{-t/\tau_c} + 1 - e^{-t/\tau_c} = 1$

$t < 0$ $0 = 0$

thus, the solution corresponding to $V_{in}(t) = u(t)$ is the step response

(b) $y_{step} = (1 - e^{-t/\tau_c})u(t)$

Plot see attached pages

Q.2 Using (3.8.9) $\frac{dy_{step}(t)}{dt} = \frac{d}{dt} \int_{-\infty}^t h(\tau) d\tau = h(t)$

$$\frac{dy_{step}(t)}{dt} = \frac{d}{dt} (1 - e^{-t/\tau_c})u(t) = \delta(t) (1 - e^{-t/\tau_c}) + \frac{1}{\tau_c} e^{-t/\tau_c} u(t)$$

Since $u(t) e^{t/\tau_c} = 0$

$$h(t) = \frac{1}{\tau_c} e^{-t/\tau_c} u(t)$$

Q.3 (a) Using time-invariance with the step response

$$y_{step} = (1 - e^{-t/\tau_c})u(t)$$

The output of $u(t) - u(t-\delta)$ is

$$(1 - e^{-t/\tau_c})u(t) - (1 - e^{-(t-\delta)/\tau_c})u(t-\delta)$$

Using linearity

The output of $V_{in}(t)$ is

$$V_{out}(t) = y_{b,d}(t) = \frac{b}{\Delta} [(1 - e^{-t/\tau_c})u(t) - (1 - e^{-(t-\delta)/\tau_c})u(t-\delta)]$$

4b) When $b=1$

$$\lim_{\Delta \rightarrow 0} y_{b,\Delta}(t) = \lim_{\Delta \rightarrow 0} \frac{1}{\Delta} [(1 - e^{-(t-\Delta)/RC}) u(t-\Delta) - (1 - e^{-(t-0)/RC}) u(t-0)]$$

Using L'Hopital's rule

$$\begin{aligned} &= \lim_{\Delta \rightarrow 0} \left(-\frac{1}{RC} e^{-(t-\Delta)/RC} u(t-\Delta) - (-1 - e^{-(t-0)/RC}) \delta(t-0) \right) \\ &= -\frac{1}{RC} e^{-t/RC} u(t) - (1 - e^{-t/RC}) \delta(t) \\ &= -\frac{1}{RC} e^{-t/RC} u(t) \end{aligned}$$

$$\begin{aligned} \text{(c)(i)} y_{b,\Delta}(t) &= \frac{10^{-4}}{10^{-3}} [(1 - e^{-1000t}) u(t) - (1 - e^{-1000(t-10^{-3})}) u(t-10^{-3})] \\ &= \frac{1}{10} [(1 - e^{-1000t}) u(t) - (1 - e^{-1000(t-10^{-3})}) u(t-10^{-3})] \end{aligned}$$

$$\text{(ii)} y_{b,\Delta}(t) = \frac{1}{5} [(1 - e^{-1000t}) u(t) - (1 - e^{-1000(t-0.5 \times 10^{-3})}) u(t-0.5 \times 10^{-3})]$$

$$\text{(iii)} y_{b,\Delta}(t) = (1 - e^{-1000t}) u(t) - (1 - e^{-1000(t-0.1 \times 10^{-3})}) u(t-0.1 \times 10^{-3})$$

MATLAB plots see attached pages

$$h(t) = \frac{1}{RC} e^{-t/RC} u(t) = 1000 e^{-1000t} u(t)$$

$$b h(t) = [a^{-1} h(t)] = \frac{1}{10} e^{-1000t} u(t)$$

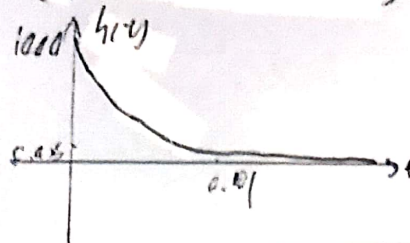
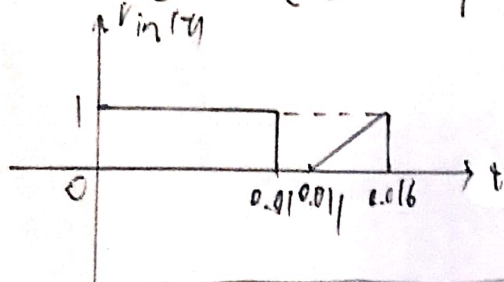
It can be observed from the three plots that

the plots for cases (i) - (iii) approach the plot of $b h(t)$ as Δ decreases.

From the three graphs we can verify our answers for parts (i) - (iii) are correct by the partial results provided in hint.

$$\begin{aligned} \text{Q.4} \quad V_{out} &= V_{in} (V * h(t)) \\ &= \int_{-\infty}^{\infty} [u(\tau) - u(\tau - 0.01)] + 200(\tau - 0.011) [u(\tau - 0.011) - u(\tau - 0.016)] \\ &\quad \cdot 1000 e^{-1000(t-\tau)} u(t-\tau) d\tau \\ &= \int_0^{0.01} 1000 e^{-1000(t-\tau)} u(t-\tau) d\tau + \int_{0.011}^{0.016} 2 \times 10^5 e^{-1000(t-\tau)} u(t-\tau) (\tau - 0.011) d\tau \\ &= \int_{t-0.01}^t 1000 e^{-1000\tau} d\tau + \int_{t-0.016}^{t-0.011} 2 \times 10^5 e^{-1000\tau} (\tau - 0.011) d\tau \\ &= -e^{-1000\tau} \Big|_{t-0.01}^t - (t-\tau-0.011) 200 e^{-1000\tau} \Big|_{t-0.016}^{t-0.011} \\ &= e^{-1000(t-0.01)} - e^{-1000t} + 0.8 \times e^{-1000(t-0.016)} - 0.2 \times e^{-1000(t-0.011)} \end{aligned}$$

$$V_{out} = e^{-1000t} (e^{10} - 1 + 0.8e^{16} - 0.2e^{11})$$



$$V_{out} = (e^{10} e^{-1000t} - 1) u(t - 0.01) + (1 - e^{-1000t}) u(t) \\ + (0.8e^{-1000(t-0.01)} - 0.4e^{-1000(t-0.011)} - 200(t-0.012)) u(t - 0.016) \\ + (200(t-0.012) + 0.2e^{-1000(t-0.011)}) u(t - 0.011)$$

$$0 \leq t < 0.01 \quad \text{conv} = \int_0^t 1000 e^{-1000\tau} d\tau = 1 - e^{-1000t}$$

$$0.01 \leq t < 0.011 \quad \text{conv} = \int_{t-0.01}^t 1000 e^{-1000\tau} d\tau = e^{10} e^{-1000t} - e^{-10000}$$

$$0.011 \leq t < 0.016 \quad \text{conv} = \int_{t-0.01}^t 1000 e^{-1000\tau} d\tau + 200 \int_{0.011}^t \tau u(\tau - 0.011) / 0.001 e^{-1000(t-\tau)} d\tau \\ = e^{-1000t} (e^{10} - 1) + 200 (t - 0.012) e^{-1000(t-0.011)} \\ = e^{-1000t} (e^{10} - 1) + 200(t - 0.012) + 0.2e^{-1000(t-0.011)}$$

$t \geq 0.016$

$$\text{conv} = \int_{t-0.01}^t 1000 e^{-1000\tau} d\tau + 200 \int_{0.011}^{0.016} (\tau - 0.011) 1000 e^{-1000(t-\tau)} d\tau$$

$$= e^{-1000t} (e^{10} - 1) + 200 (t - 0.012) e^{-1000(t-0.011)} \Big|_{0.011}^{0.016}$$

$$= e^{-1000t} (e^{10} - 1) + 200 \times (-0.001) e^{-1000(t-0.011)} + 200 \times 0.004 e^{-1000(t-0.016)}$$

$$= e^{-1000t} (e^{10} - 1) + (0.8e^{16} - 0.2e^{11}) e^{-1000t}$$

We can verify the correctness of our answer with the provided partial results.

$$V_{out}(9ms) = 1 - e^{-1000 \times 0.009} = 0.865V, V_{out}(12ms) = e^{-1000 \times 0.012} (e^{10} - 1) + 0.2e^{-1000 \times 0.001} = 0.21V$$

4.5 Using the phasor circuit analysis (learned in vtus)

$$V_{out}(18ms) = e^{-1000 \times 0.018} (e^{10} - 1 + 0.8e^{16} - 0.2e^{11}) = 0.11V$$

$$\frac{V_{out}}{\frac{1}{j\omega C}} = \frac{V_{in}}{R + \frac{1}{j\omega C}}$$

$$\text{Frequency transfer function } H(j\omega) = \frac{V_{out}}{V_{in}} = \frac{\frac{1}{j\omega C}}{R + \frac{1}{j\omega C}} = \left[\frac{1}{j\omega RC + 1} \right]$$

4. b $H(j2\pi f_c) = \frac{1}{j2\pi f_c RC + 1}$

$$|H(j2\pi f_c)| = \left| \frac{1}{j2\pi f_c RC + 1} \right| = \frac{1}{\sqrt{4\pi^2 f_c^2 R^2 C^2 + 1}} = \frac{1}{\sqrt{4\pi^2 \times 10^{-6} f_c^2 + 1}}$$

$f_c (Hz)$	$ H(j2\pi f_c) $	$\angle (H(j2\pi f_c))$ (deg)	τ_d (ms)
50	0.9540	-17.4406	0.9689
200	0.6227	-51.4881	0.7151
500	0.3033	-72.3432	0.4019
1k	0.1572	-80.9569	0.2249
5k	0.0318	-88.1768	0.0490

$$\angle (H(j2\pi f_c)) = -\arctan(2\pi f_c RC) = -\arctan(2\pi \times 10^{-3} f_c) \quad (\text{in degree})$$

$$\tau_d = \frac{-\angle H(j2\pi f_c)}{2\pi f_c} = \frac{\arctan(2\pi \times 10^{-3} f_c)}{2\pi f_c} = \frac{\arctan(2\pi \times 10^{-3} f_c)}{2\pi f_c} \quad (\text{in radian})$$

VE216

Introduction to Signals and Systems

PRELAB 1 ATTACHED PAGES

June 6, 2020

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4.1 (b)

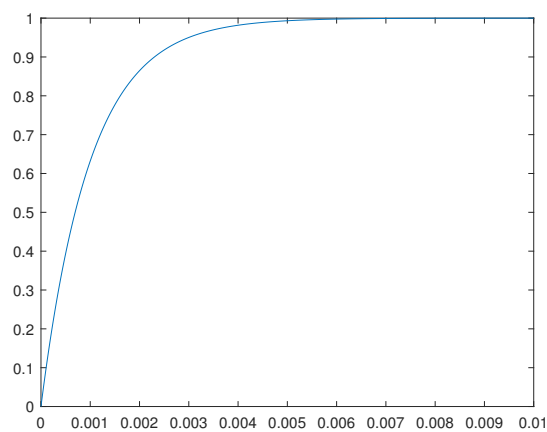


Figure 1. 4.1(b).

MATLAB Code:

```
1 t=linspace(0,0.01,1000);  
2 y=(1-exp(-1000*t)).*heaviside(t);  
3 plot(t,y);  
4 axis([0 0.01 0 1]);
```

4.3 (c) (i)

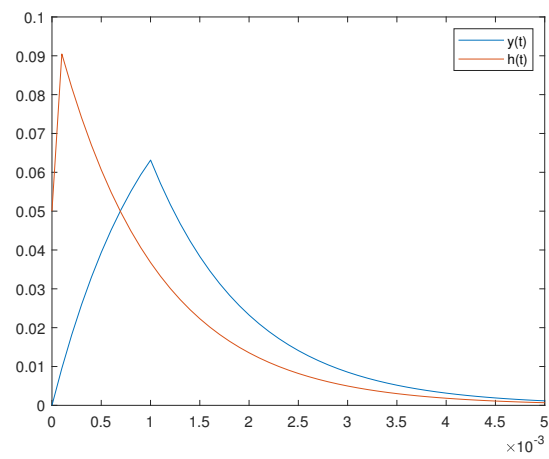


Figure 2. 4.3(c)(i).

(ii)

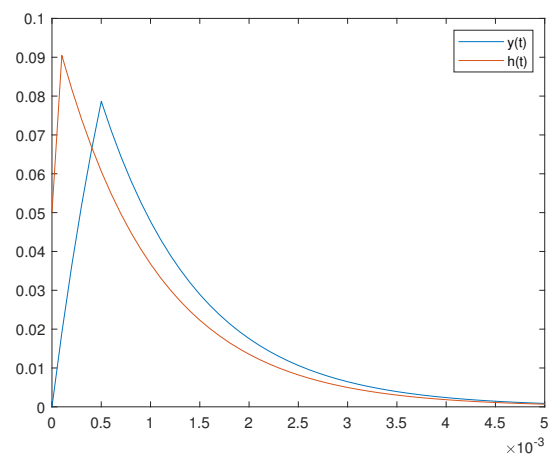


Figure 3. 4.3(c)(ii).

(iii)

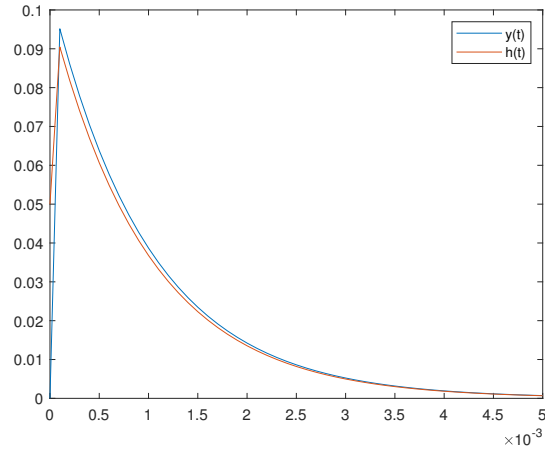


Figure 4. 4.3(c)(iii).

MATLAB Code:

```

1  t=linspace(0,0.1,1000);
2  h=0.1*exp(-1000*t).*heaviside(t);
3  y=0.1*((1-exp(-1000*t)).*heaviside(t)-(1-exp(-1000*(t-10^(-3))).*
   heaviside(t-10^(-3))));
4  plot(t,y,t,h);
5  axis([0 0.005 0 0.1]);
6  legend('y(t)','h(t)');
7  y=0.2*((1-exp(-1000*t)).*heaviside(t)-(1-exp(-1000*(t-0.5*10^(-3))).*
   heaviside(t-0.5*10^(-3))));
8  plot(t,y,t,h);
9  axis([0 0.005 0 0.1]);
10 legend('y(t)','h(t)');
11 y=(1-exp(-1000*t)).*heaviside(t)-(1-exp(-1000*(t-0.1*10^(-3))).*
   heaviside(t-0.1*10^(-3)));
12 plot(t,y,t,h);
13 axis([0 0.005 0 0.1]);
14 legend('y(t)','h(t)');

```