

# Technical Solution

For The ICRA 2019 RoboMaster AI Chenllage

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## 1 Tasks previews

## **2 Hardware**

### **2.1 Overview**

### **2.2 Advantage and Disvantage**

### **2.3 Possible Problems**

### **2.4 Solution**

## **3 Software**

### **3.1 Enviroment**

As we know, a robot software system has two parts, the upper computer and the lower computer.

### **3.2 Overview**

### **3.3 Frame**

### **3.4 The Modules of Perception**

#### **3.4.1 Detection**

#### **3.4.2 Tracking and Hitting**

#### **3.4.3 Localization**

#### **3.4.4 Path planning**

## 4 Decision

### 4.1 Tasks of a robot

### 4.2 Tasks of Two robots

## References

- [1] Leslie Lamport, *LaTeX: a document preparation system*, Addison Wesley, Massachusetts, 2nd edition, 1994.