

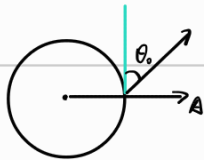
§1.

轨道方程有:

$$\dot{E} = \frac{mc^2}{2} \left( \left( \frac{du}{d\phi} \right)^2 + u^2 \right) + V(u)$$

$$E + C = \frac{\dot{\phi}}{u} \text{ 为守恒量}$$

$$\text{在万有引力中 } V(u) = -GMmu$$



$$\text{即有 } \frac{du}{d\phi} = \sqrt{\frac{2}{mc^2} (\dot{E} + GMmu) - u^2}$$

$$d\phi = \frac{du}{\sqrt{\frac{2}{mc^2} (\dot{E} + GMmu) - u^2}}$$

两边积分有

$$\phi - \phi_0 = \int_{\frac{1}{R}}^u \frac{du}{\sqrt{-\left(u - \frac{GM}{c^2}\right)^2 + \left(\frac{GM}{c^2}\right)^2 + \frac{2\dot{E}}{mc^2}}}$$

$$\text{设 } A^2 = \frac{GM^2}{c^4} + \frac{2\dot{E}}{mc^2} \quad B = \frac{GM}{c^2}$$

$$\text{即有 } \phi = \int_{\frac{1}{R}}^u \frac{du}{\sqrt{A^2 - (u-B)^2}} = \int_{\frac{1}{R}-B}^{\frac{u-B}{A}} \frac{ds}{\sqrt{A^2 - s^2}}$$

$$= \arcsin \frac{s}{A} \Big|_{\frac{1}{R}-B}^{\frac{u-B}{A}} = \arcsin \frac{u-B}{A} - \varphi_0$$

$$\varphi_0 = \arcsin \left( \frac{\frac{1}{R} - B}{A} \right)$$

$$\cos(\phi + \varphi_0 - \frac{\pi}{2}) = \frac{u-B}{A} \quad u = A \cos(\phi + \varphi_0 - \frac{\pi}{2}) + B$$

$$\text{轨道方程 } r = \frac{1}{B + A \cos(\phi + \varphi_0 - \frac{\pi}{2})}$$

$$C = R \cdot \frac{1}{\sqrt{2}} V = R \cdot \frac{1}{\sqrt{2}} \sqrt{\frac{GM}{R}} = \sqrt{\frac{GMR}{8}}$$

$$\dot{E} = \frac{1}{2} m V^2 - \frac{GMm}{R} = \frac{GMm}{8R} - \frac{GMm}{R} = -\frac{7GMm}{8R}$$

$$B = \frac{GM}{c^2} = \frac{8}{R}$$

$$A = \frac{\sqrt{2}}{R} \quad \text{因此有 } r = \frac{1}{\frac{8}{R} + \frac{\sqrt{2}}{R} \cos(\phi + \varphi_0 - \frac{\pi}{2})}$$

$$\text{整理得 } r = \frac{\frac{R}{8}}{1 + \frac{\sqrt{2}}{8} \cos(\phi + \varphi_0 - \frac{\pi}{2})}$$

$$\text{其中 } \varphi_0 = -\arcsin \frac{7}{5\sqrt{2}} \quad \text{化简得即}$$

$$r = \frac{R}{8 - 5 \sin \phi - 7 \cos \phi}$$

§2. 飞离地球后. 设  $V_1$  和  $V_{11}$ . 有  $\frac{1}{2} m V_1^2 = \frac{1}{2} m V_3^2 - \frac{GMm}{R_E} \quad V_1 = \sqrt{V_3^2 - \frac{2GM}{R_E}}$ 

$$V_{11} = \sqrt{\frac{GM_S}{R_S}}$$

$$V_3 = \sqrt{\left(3 - 2\sqrt{2}\right) \frac{GM_S}{R_S} + \frac{2GM_E}{R_E}} \Rightarrow V_1 = \sqrt{\left(3 - 2\sqrt{2}\right) \frac{GM_S}{R_S}}$$

$$\dot{E} = \frac{1}{2} m (4 - 2\sqrt{2}) \frac{GM_S}{R_S} - \frac{GM_S m}{R_S} = (1 - \sqrt{2}) \frac{GM_S m}{R_S}$$

$$L = m R_S V_{11} \quad C = V_{11} R_S = \sqrt{GM_S R_S}$$

$$B = \frac{GM_S}{c^2} = \frac{1}{R_S} \quad A = \sqrt{B^2 + \frac{2\dot{E}}{mc^2}} = \sqrt{\frac{1}{R_S^2} + \frac{(2 - 2\sqrt{2}) m \frac{GM_S}{R_S}}{m GM_S R_S}} = \sqrt{\frac{1}{R_S^2} + (2 - 2\sqrt{2}) \frac{1}{R_S^2}}$$

$$= \frac{1}{R_S} \sqrt{3 - 2\sqrt{2}} = \frac{(\sqrt{2} - 1)}{R_S}$$

$$\text{所以轨道方程为 } r = \frac{1}{\frac{1}{R_S} (1 + (\sqrt{2} - 1) \cos(\varphi \pm \varphi_0))}$$

$$= \frac{R_S}{1 + (\sqrt{2} - 1) \cos(\varphi \pm \varphi_0)} \quad \varphi_0 = \frac{\pi}{2}$$

$$\text{即 } r = \frac{R_S}{1 + (\sqrt{2} - 1) \sin \varphi}$$

§3.

设飞出地球后, 相对地球切向速度

$v_{11}$  径向速度  $v_{\perp}$  故有

$$C = (v_{11} + v_{\perp})R. \quad E = \frac{1}{2}m(v_{\perp}^2 + (v_{11} + v_{\perp})^2) - m v_{\perp}^2$$

$$= \frac{1}{2}m(v_{\perp}^2 + v_{11}^2 + 2v_{11}v_{\perp} - v_{\perp}^2)$$

$$B = \frac{GM}{C^2} = \frac{v_{\perp}^2 R}{(v_{11} + v_{\perp})^2 R^2} = \frac{1}{R} \left( \frac{v_{\perp}}{v_{11} + v_{\perp}} \right)^2$$

$$A^2 = B^2 + \frac{2E}{mc^2} = \frac{1}{R^2} \left( \frac{v_{\perp}}{v_{11} + v_{\perp}} \right)^4 + \frac{m(v_{\perp}^2 + v_{11}^2 + 2v_{11}v_{\perp} - v_{\perp}^2)}{m(v_{11} + v_{\perp})^2 R^2}$$

$$A = \frac{1}{R(v_{11} + v_{\perp})} \sqrt{v_{\perp}^2 + v_{11}^2 + 2v_{11}v_{\perp} - v_{\perp}^2 + \frac{v_{\perp}^4}{(v_{11} + v_{\perp})^2}}$$

$$\text{又由 } r_{\min} = \frac{1}{B + A}$$

$$= \frac{v_{\perp}^2}{(v_{11} + v_{\perp})^2} + \frac{1}{(v_{11} + v_{\perp})^2} \sqrt{(v_{11} + v_{\perp})^2 (v_{\perp}^2 + v_{11}^2 + 2v_{11}v_{\perp} - v_{\perp}^2) + v_{\perp}^4}$$

$$\text{设 } v_{11} = v \cos \theta. \quad v_{\perp} = v \sin \theta$$

$$R(v_{11} + v_{\perp})^2$$

$$r_{\min} = \frac{v^2}{v^2 + \sqrt{(v + v \cos \theta)^2 (v^2 + 2v v \cos \theta - v^2) + v^4}}$$

$$\text{设 } \frac{v}{v_1} = \eta. \quad \text{故有}$$

$$R(1 + \eta \cos \theta)^2$$

$$r_{\min} = \frac{1}{1 + \sqrt{(1 + \eta \cos \theta)^2 (\eta^2 + 2\eta \cos \theta - 1) + 1}} = 0.7R.$$

要发射, 即  $\theta = \pi$  此时, 沿切向向后发射.

因此, 轨道形状确定.

$$\text{发射后轨道能量为 } E = -\frac{GM_S m}{1.7R}$$

脱离地球引力后, 发射后动能为 (太阳系下)

$$\frac{1}{2}m v_s^2 = E + \frac{GM_S m}{R} \Rightarrow v_s^2 = \frac{2E}{m} + \frac{2GM_S}{R}$$

地球上, 脱离后速度可以表示为  $v_{min} = v_0 - v_s$

即, 地球上发射速度为

$$\frac{1}{2}m v_f^2 - \frac{GM_E m}{r} = \frac{1}{2}m v_{min}^2$$

$$v_f = \sqrt{v_{min}^2 + \frac{2GM_E}{r}} = \sqrt{\left( \sqrt{\frac{GM_S}{R}} \sqrt{\frac{2E}{m} + \frac{2GM_S}{R}} \right)^2 + \frac{2GM_E}{r}}$$

$$= \sqrt{\left( \sqrt{\frac{GM_S}{R}} + \left( \frac{2GM_S}{R} - \frac{2GM_S}{1.7R} \right) - 2\sqrt{2 - \frac{2.0}{1.7}} \right) \frac{GM}{R}} + \frac{2GM_E}{r}$$

$$= \sqrt{\frac{GM_S}{R} \left( 1 + 2 - \frac{2.0}{1.7} - 2\sqrt{2 - \frac{2.0}{1.7}} \right) + \frac{2GM_E}{r}}$$

$$v_f = \sqrt{\frac{2GM_E}{r} + \frac{GM_S}{R} \left( \frac{31}{17} - 2\sqrt{\frac{14}{17}} \right)} \text{ 为最小发射速度}$$

代入数据得  $v_f = 11.512 \text{ km/s}$

§4. 自由度为 3.  $\theta, \varphi, x$ .

$$T = \frac{1}{2}m \dot{x}^2 + \frac{1}{2}m x^2 \dot{\theta}^2 + \frac{1}{2}M(l-x)^2 \dot{\varphi}^2 + \frac{1}{2}M \dot{x}^2$$

广义坐标:  $\begin{cases} \dot{\varphi} = 0. \\ x^2 \dot{\theta} = C_0. \end{cases}$

$$\Rightarrow \frac{d}{dt} = \frac{d}{d\theta} \frac{d\theta}{dt} = \frac{d}{d\theta} \cdot \frac{C_0}{x^2}$$

$$\text{能量守恒, } \frac{1}{2}m \dot{x}^2 + \frac{1}{2}M \dot{x}^2 + \frac{1}{2}m x^2 \dot{\theta}^2 = C_1$$

$$\text{得 } \frac{1}{2}(M+m) \left( \frac{dx}{d\theta} \frac{C_0}{x^2} \right)^2 + \frac{1}{2}m x^2 \left( \frac{C_0}{x^2} \right)^2 = C_1$$

$$\frac{1}{2}(M+m) \frac{C_0^2}{x^4} \left( \frac{dx}{d\theta} \right)^2 = C_1 - \frac{1}{2}m \frac{C_0^2}{x^2} \Leftrightarrow \left( \frac{dx}{d\theta} \right)^2 = \frac{2x^4}{C_0^2(M+m)} \left( C_1 - \frac{1}{2}m \frac{C_0^2}{x^2} \right)$$

$$\frac{dx}{d\theta} = \frac{x^2}{C_0} \sqrt{\frac{2}{M+m} \left( C_1 - \frac{1}{2}m \frac{C_0^2}{x^2} \right)} \Leftrightarrow \frac{d\theta}{dx} = \frac{C_0}{x^2 \sqrt{\frac{2}{M+m} \left( C_1 - \frac{1}{2}m \frac{C_0^2}{x^2} \right)}}$$

$$-\frac{dx}{\sqrt{\frac{2}{m+m}(r, -\frac{1}{2}\frac{mC_0^2}{x^2})}} = \frac{d\theta}{C_0} \quad \text{or} \quad \frac{dx}{\sqrt{1 - \frac{1}{2}\frac{mC_0^2}{C_1 x^2}}} = -\sqrt{\frac{2C_1}{m+m}} \frac{d\theta}{C_0}$$

$$\text{let } u = \frac{1}{x}. \quad \text{or} \quad \frac{du}{\sqrt{1 - Au^2}} = -k d\theta \quad A = \frac{1}{2}\frac{mC_0^2}{C_1} \quad k = \sqrt{\frac{2C_1}{m+m}} \frac{1}{C_0}$$

$$\text{let } \sqrt{A}u = \cos\varphi. \quad \frac{\frac{1}{\sqrt{A}} d\cos\varphi}{\sin\varphi} = \pm k d\theta$$

$$d\theta = \pm \frac{1}{k\sqrt{A}} d\varphi \quad \theta + \theta_0 = \pm \frac{1}{k\sqrt{A}} \arccos \sqrt{A}u$$

$$\sqrt{A}u = \cos[k\sqrt{A}(\theta + \theta_0)]. \quad r = \frac{\sqrt{A}}{\cos[k\sqrt{A}(\theta + \theta_0)]}$$

$$\text{or } r = \sqrt{\frac{1}{2}\frac{mC_0^2}{C_1}} \sec\left[\sqrt{\frac{1}{2}\frac{mC_0^2}{C_1}} \sqrt{\frac{2C_1}{m+m}}(\theta + \theta_0)\right]$$

$$C_0 = r_0 v_0 \quad C_1 = \frac{1}{2}mv_0^2$$

$$r = \sqrt{\frac{\frac{1}{2}mv_0^2 r_0^2}{\frac{1}{2}mv_0^2}} \sec\left[\sqrt{\frac{m}{m+m}}(\theta + \theta_0)\right]$$

$$= r_0 \sec\left[\sqrt{\frac{m}{m+m}}(\theta + \theta_0)\right] \quad \text{if } \theta_0 = 0.$$

$$\text{or } r = r_0 \sec\left(\sqrt{\frac{m}{m+m}}\theta\right).$$

85.  $E_{\text{eff}} = V(r) + \frac{J^2}{2mr^2} \quad m\ddot{r} = -\frac{\partial E_{\text{eff}}}{\partial r} = -\frac{k}{r^2} e^{-r/a} - \frac{J^2}{mr^3}$

$$\text{or } m\ddot{\epsilon} + \frac{J^2}{m(r_0 + \epsilon)^3} = F(r_0 + \epsilon)$$

$$m\dot{\epsilon} + \frac{J^2}{mr_0^3}\left(1 - \frac{3\epsilon}{r_0}\right) = F(r_0) + F'(r_0)\epsilon$$

$$m\dot{\epsilon} - \left(\frac{3J^2}{mr_0^4} + F'(r_0)\right)\epsilon = 0.$$

$$3F(r_0) + r_0 F'(r_0) < 0 \text{ 时稳定.}$$

$$\text{or } -\frac{3k}{r_0^2} e^{-\frac{r_0}{a}} + r_0 \left( \frac{2k}{r_0^2} e^{-\frac{r_0}{a}} - \frac{k}{r_0^2} e^{-\frac{r_0}{a}} \left( \frac{1}{a} \right) \right) < 0$$

$$\text{or } -\frac{3k}{r_0^2} e^{-\frac{r_0}{a}} + \frac{2k}{r_0^2} e^{-\frac{r_0}{a}} + \frac{k}{ar_0} e^{-\frac{r_0}{a}} < 0.$$

$$\text{or } \frac{k}{r_0} \left( -\frac{1}{r_0} + \frac{1}{a} \right) < 0 \quad \text{or } r_0 < a \text{ 时轨道是稳定的.}$$

86. 地球半径  $a$

$$\begin{cases} \frac{1}{2} m v_0^2 = \frac{1}{2} m v^2 - \frac{GMm}{a} \\ b v_0 = v a \end{cases} \Rightarrow \begin{cases} v_0^2 = \frac{v^2 b^2}{a^2} - \frac{2GM}{a} \\ v_0^2 + u^2 = \frac{v^2 b^2}{a^2} \end{cases}$$

即卫星轨道半径  $b = \frac{a}{v_0} \sqrt{v_0^2 + u^2}$  其中  $u$  为卫星速度。

截面积为  $S = \pi b^2 = \pi a^2 \left(1 + \frac{u^2}{v_0^2}\right)$