



Analyzing Generalization of Neural Networks through Loss Path Kernels

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Outline

1. Introduction and motivation
2. Main results
3. Conclusion and future works

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1. Introduction and motivation

- Kernel machine and neural tangent kernel
- Generalization theory of neural networks
- Motivation of this work

2. Main results

- Loss path kernel and the equivalence between NN and KM
- Generalization bound for NN trained by gradient flow
- Case study and Application
 - Ultra-wide NN
 - Neural architecture search

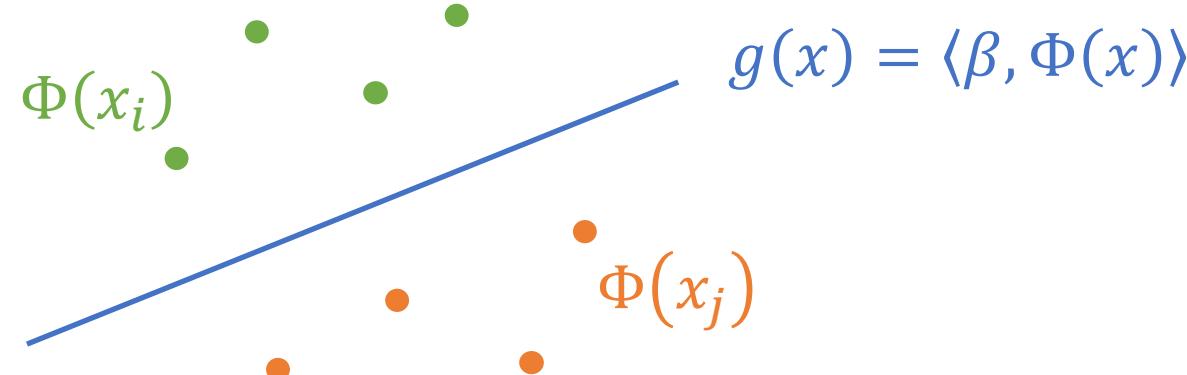
3. Conclusion and future works

Kernel Machine

- Kernel: $K(x, x') = \langle \Phi(x), \Phi(x') \rangle$, $\Phi: \mathcal{X} \rightarrow \mathcal{H}$ maps the data to a feature space.
- Kernel machine (KM): linear function in the feature space

$$g(x) = \langle \beta, \Phi(x) \rangle + b = \sum_{i=1}^n a_i K(x, x_i) + b, \text{ where } \beta = \sum_{i=1}^n a_i \Phi(x_i)$$

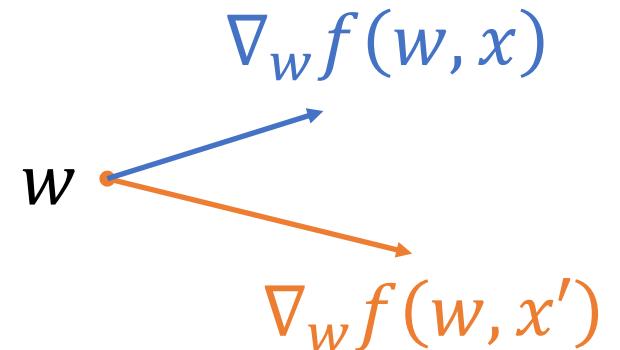
- RKHS norm of g : $\|\beta\| = \sqrt{\sum_{i=1}^n \sum_{j=1}^n a_i a_j K(x_i, x_j)}$



Neural tangent kernel

- Neural Tangent Kernel (NTK) (Jacot et al., 2018):

$$\widehat{\Theta}(w; x, x') = \langle \nabla_w f(w, x), \nabla_w f(w, x') \rangle$$



measures the similarity between data points x, x' by comparing their gradients

- Under certain conditions (e.g., infinite width limit), NTK at initialization w_0 converges to a deterministic limit and keeps constant during training:

$$\widehat{\Theta}(w_0; x, x') \rightarrow \Theta_\infty(x, x')$$

NTK at initialization Independent with w_0

Neural tangent kernel

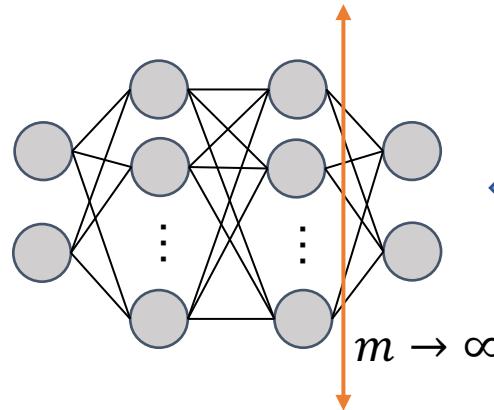
- Infinite-width NN trained by gradient descent with mean square loss \Leftrightarrow kernel regression with NTK [Jacot et al., 2018; Arora et al., 2019]

- Wide neural networks are linear in the parameter space [Lee et al., 2019]:

$$f(w_t, x) = f(w_0, x) + \langle \nabla_w f(w_0, x), w_t - w_0 \rangle + O\left(\frac{1}{\sqrt{m}}\right) \quad m: \text{width of NN}$$

- Infinite-width NN trained by with ℓ_2 regularized loss \Leftrightarrow ℓ_2 regularized KMs with NTK, e.g. SVM [Chen et al., 2021]

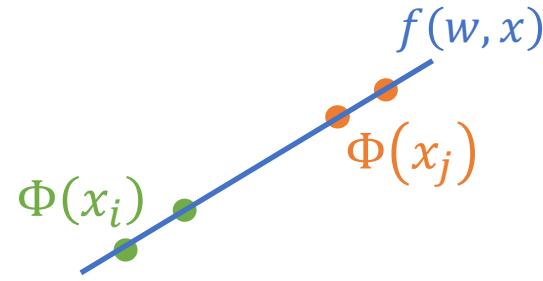
Neural tangent kernel



equivalent

kernel regression

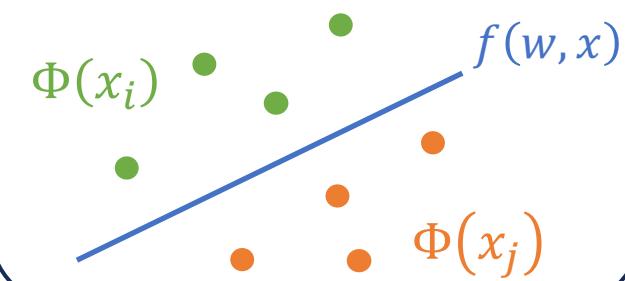
$$\mathcal{H}: \Phi(x) = \nabla_w f(w_0, x)$$



[Jacot et al., 2018; Arora et al., 2019; Lee et al., 2019]

SVM

$$\mathcal{H}: \Phi(x) = \nabla_w f(w_0, x)$$



[Chen et al., 2021]

These equivalences are useful for analyzing NNs

But only holds for infinite-width/ultra-wide NNs

Q1. Can we establish a connection or equivalence between general NNs (vs ultra-wide NNs) and KMs?

Generalization theory of neural networks

How do the neural networks (NN) generalize on test data?

generalization gap:

$$GAP = \mathbb{E}_{z \sim \mu} [\ell(w, z)] - \frac{1}{n} \sum_{i=1}^n \ell(w, z_i) \leq$$

$L_\mu(w)$: population loss

$L_S(w)$: training loss



Generalization theory: general NNs

1. VC dimension [Bartlett et al., 2019]

$$GAP \leq O\left(\sqrt{L \frac{\# \text{ of parameters}}{n} \log(n)}\right)$$

L : # of layers

n : # of samples

W_l : weight of layer l

2. Norm-based bounds [Bartlett et al., 2017; ...]

$$GAP \leq O\left(\frac{\prod_{l=1}^L \|W_l\|}{\sqrt{n}}\right)$$



- Do not explain the generalization ability of overparameterized NNs. [Belkin et al., 2019]
- Vacuous: too large to be useful

• Other bounds:

- PAC-Bayes bounds (mainly focus on stochastic NNs)
- Information-theoretical approach (expected bound)

Generalization theory: ultra-wide NNs

- Arora et al., 2019: for ultra-wide two-layer NN,

$$GAP \leq \sqrt{\frac{2 \mathbf{y}^\top (\mathbf{H}^\infty)^{-1} \mathbf{y}}{n}}$$

\mathbf{H}^∞ : NTK of the
first layer

- Cao & Gu, 2019: for ultra-wide L-layer NN,

 These bounds only hold for
ultra-wide NNs

$$GAP \leq \tilde{o}(L \cdot \sqrt{\frac{2 \mathbf{y}^\top (\Theta)^{-1} \mathbf{y}}{n}})$$

Q2. Can we establish tight (vs vacuous) generalization bounds for general NNs
(vs ultra-wide NNs)?

Motivation of this work

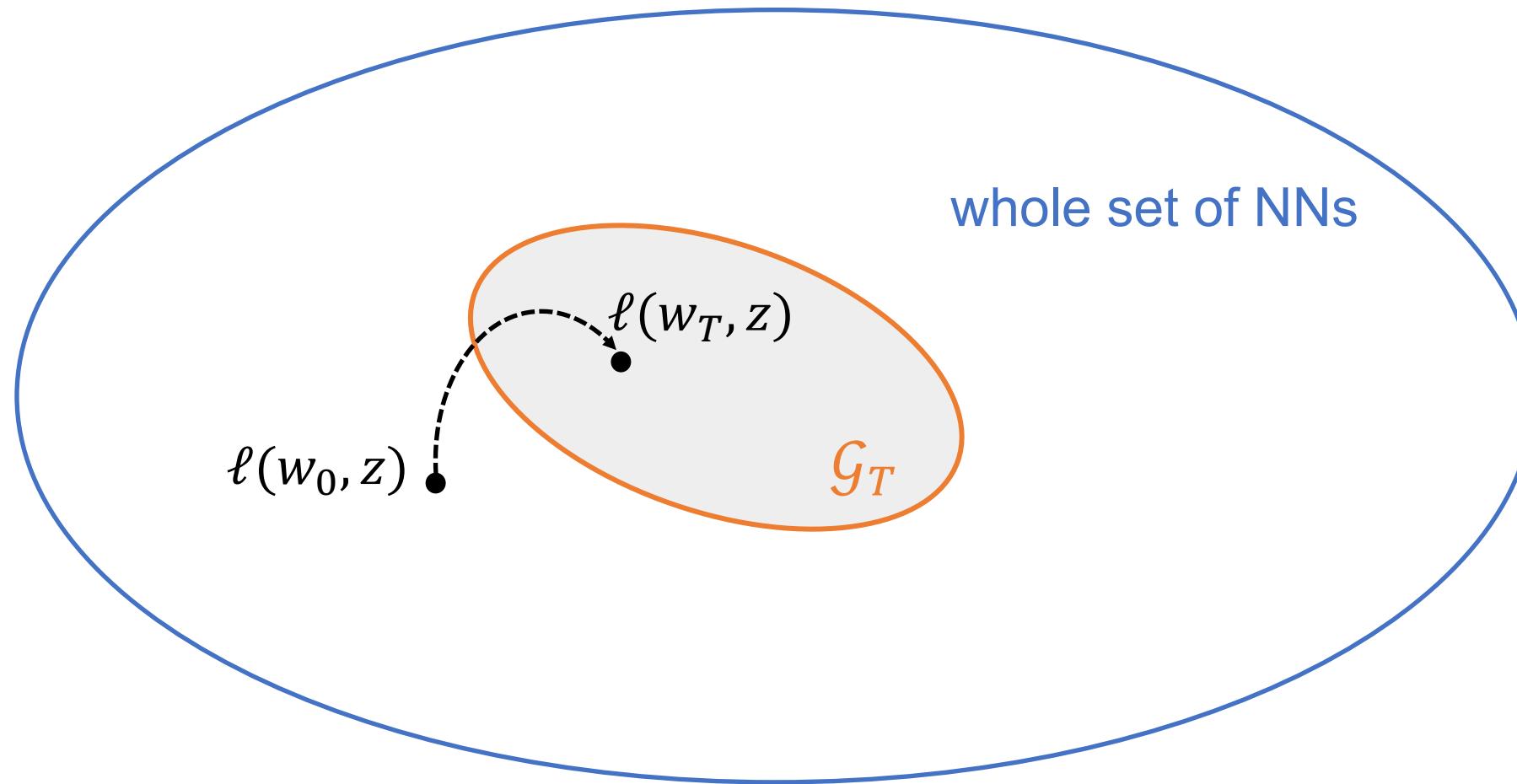
1. Can we establish a connection or equivalence between general NNs (vs ultra-wide NNs) and Kernel machines (KMs)? It can have many benefits:
 1. New understanding of NN trained with SGD
 2. Generalization bound for NNs from the perspective of kernel
 3. Analyze NN architectures from this equivalence
 4. Improve kernel method from the NN viewpoint
2. Can we establish tight (vs vacuous) generalization bounds for general NNs (vs ultra-wide NNs)?



Yes!

Intuition of our work

- The set of trained NNs \mathcal{G}_T can be much smaller than the whole set of NNs
- We characterize \mathcal{G}_T through a connection between NN and KM



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Loss Path Kernel

Loss Tangent Kernel (LTK):

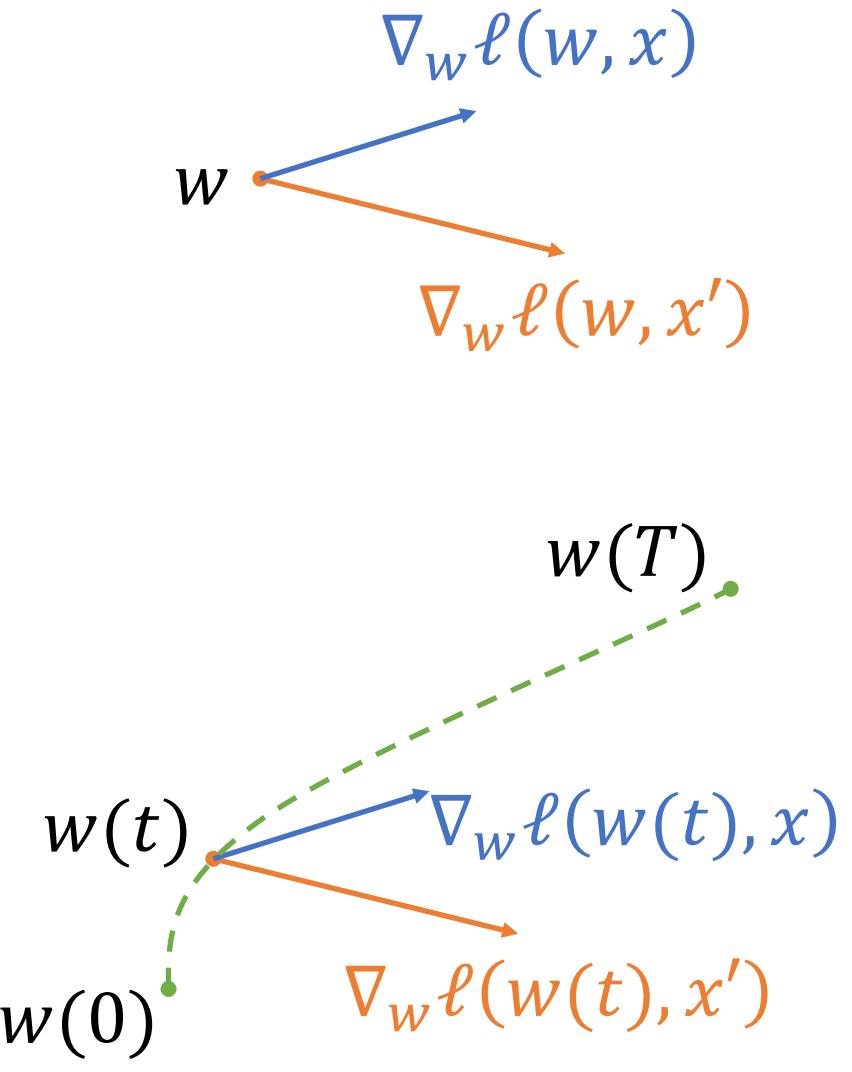
$$\bar{K}(w; z, z') = \langle \nabla_w \ell(w, x), \nabla_w \ell(w, x') \rangle$$

Compare with NTK:

$$\hat{\Theta}(w; x, x') = \langle \nabla_w f(w, x), \nabla_w f(w, x') \rangle$$

Loss Path Kernel (LPK):

$$\begin{aligned} K_T(z, z'; S) &= \int_0^T \bar{K}(w(t); z, z') dt \\ &= \int_0^T \langle \nabla_w \ell(w, x), \nabla_w \ell(w, x') \rangle dt \end{aligned}$$



Equivalence between neural network and kernel machine

With gradient flow (gradient descent with infinitesimal step size):

$$\frac{w(t+1) - w(t)}{\eta} = -\nabla_w L_S(w(t)) \xrightarrow{\eta \rightarrow 0} \frac{dw(t)}{dt} = -\nabla_w L_S(w(t))$$

We can derive equivalence:

$$\ell(w_T, z) = \sum_{i=1}^n -\frac{1}{n} K_T(z, z_i; S) + \ell(w_0, z)$$

Loss function at time T

Kernel machine with LPK

Loss function at initialization

Very general equivalence!

Equivalence between neural network and kernel machine

Stochastic gradient flow (SGD with infinitesimal step size):

$$\frac{w(t+1) - w(t)}{\eta} = -\nabla_w L_{S_t}(w(t)) \xrightarrow{\eta \rightarrow 0} \frac{dw(t)}{dt} = -\nabla_w L_{S_t}(w(t))$$

$S_t \subseteq \{1, \dots, n\}$ is the indices of batch data, m : batch size

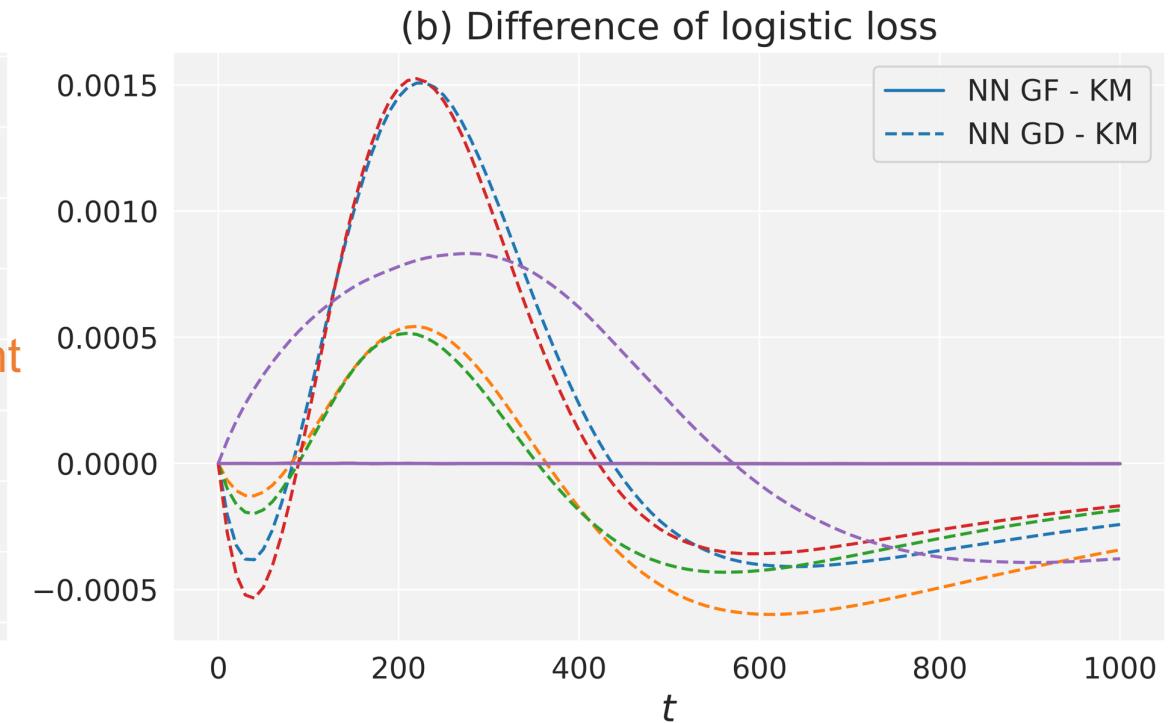
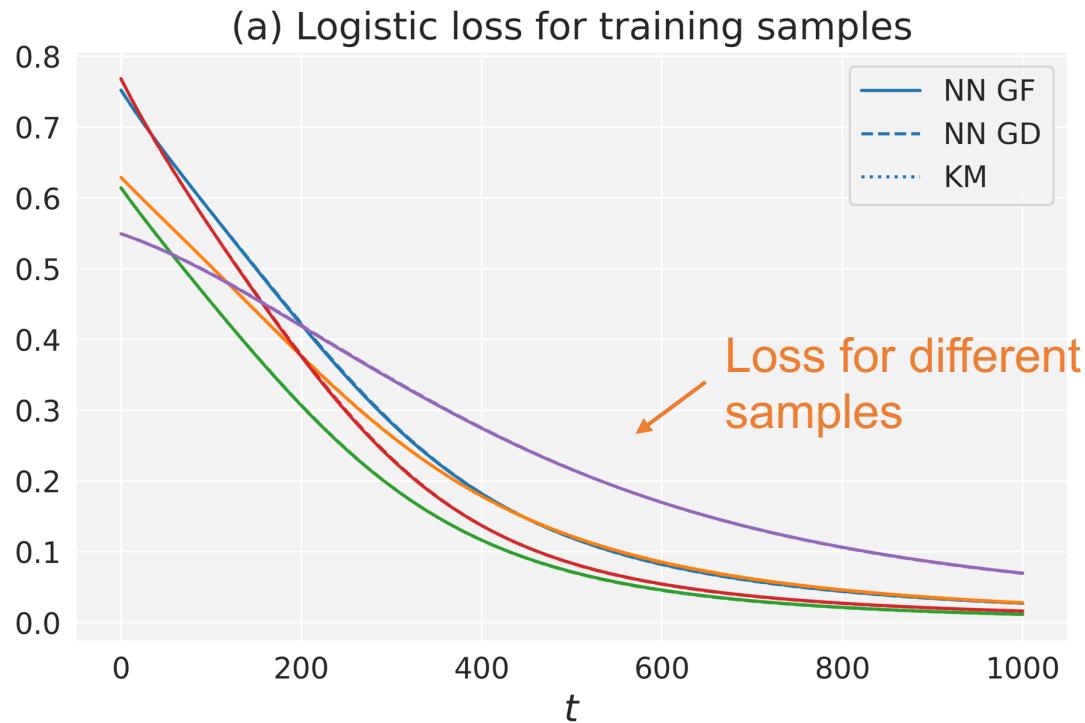
Equivalence:

Sum of KMs with LPK

$$\ell(w_T, z) = \sum_{t=1}^{T-1} \sum_{i \in S_t} -\frac{1}{m} K_T(z, z_i; S) + \ell(w_0, z)$$

Generalization bound for NN trained by gradient flow

Verify the equivalence



- NN trained by gradient flow (GF) overlaps with the KM
- NN trained by gradient descent (GD) is also close with the KM

Generalization bound for NN trained by gradient flow

Different training set induces distinct LPK. Set of LPKs with constrained RKHS norm:

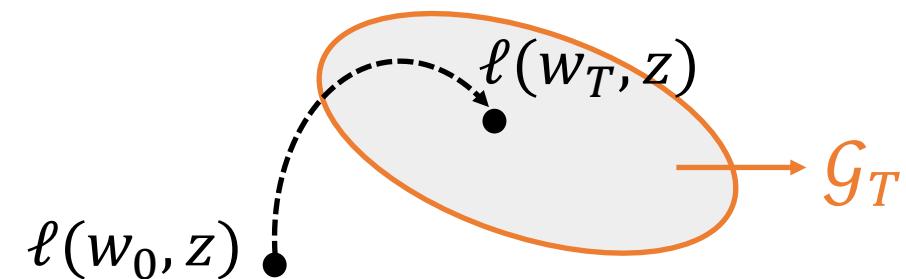
$$\mathcal{K}_T = \left\{ K_T(\cdot, \cdot; S') : S' \in \text{supp}(\mu^{\otimes n}), \frac{1}{n^2} \sum_{i,j} K_T(z_i', z_j'; S') \leq B^2 \right\}$$

$$S = \{z_i\}_{i=1}^n, \quad S' = \{z'_i\}_{i=1}^n$$

Set of NNs trained to time T :

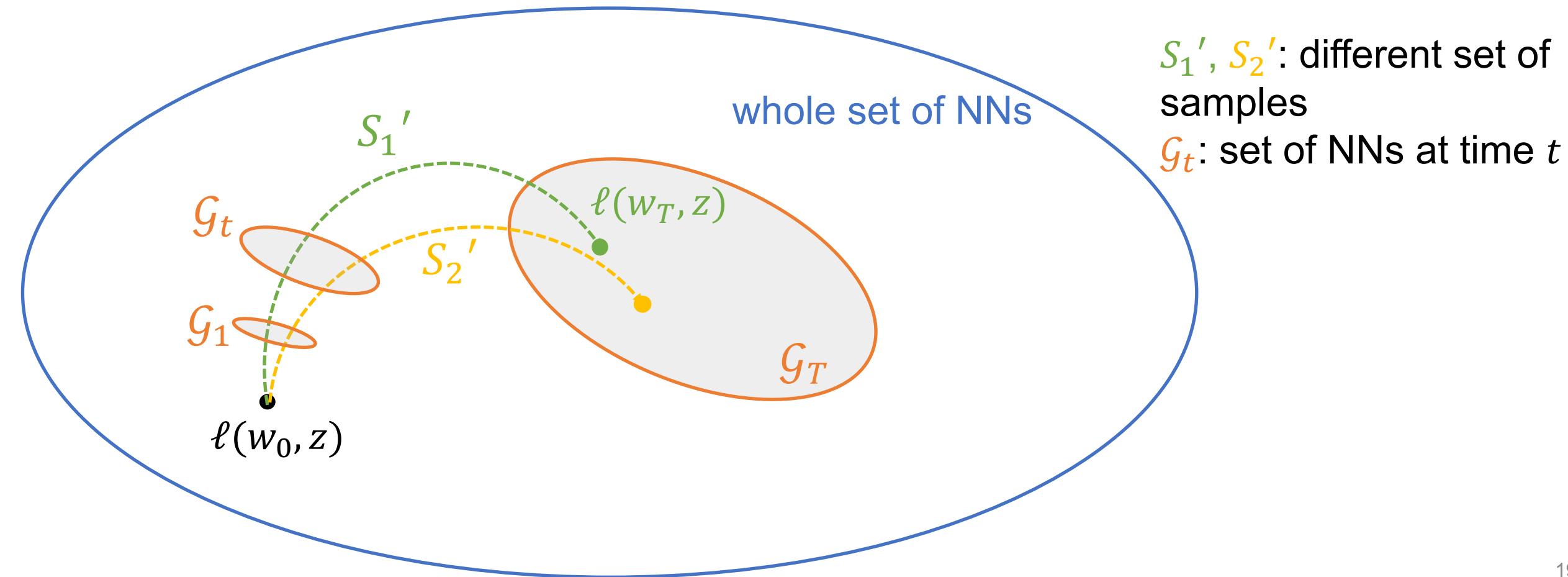
$$\mathcal{G}_T = \left\{ g(z) = \sum_{i=1}^n -\frac{1}{n} K(z, z_i'; S') + \ell(w_0, z) : K(\cdot, \cdot; S') \in \mathcal{K}_T \right\}$$

$\ell(w_T, z)$ trained from S'



Intuition of our work

- The set of trained NNs \mathcal{G}_T can be much smaller than the whole set of NNs
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Generalization bound for NN trained by gradient flow

Compute the Rademacher complexity of \mathcal{G}_T ,

$$GAP \leq 2 \min(U_1, U_2)$$

$$U_1 = \frac{B}{n} \sqrt{\sup_{K \in \mathcal{K}_T} \sum_{i=1}^n K(z_i, z_i; S') + \sum_{i \neq j} \Delta(z_i, z_j)}$$

maximum magnitude of the loss gradient in \mathcal{K}_T evaluated with S throughout the training trajectory.

$$\Delta(z_i, z_j) = \frac{1}{2} [\sup_{K \in \mathcal{K}_T} K(z_i, z_j; S') - \inf_{K \in \mathcal{K}_T} K(z_i, z_j; S')]$$

range of variation of LPK in \mathcal{K}_T

Can be estimated with training samples

Generalization bound for NN trained by gradient flow

Compute the Rademacher complexity of \mathcal{G}_T ,

$$GAP \leq 2 \min(U_1, U_2)$$

$$U_1 = \frac{B}{n} \sqrt{\sup_{K \in \mathcal{K}_T} \sum_{i=1}^n K(z_i, z_i; S') + \sum_{i \neq j} \Delta(z_i, z_j)}$$

Similar with the bound of KM but with an additional supremum over \mathcal{K}_T

Due to the set of kernels \mathcal{K}_T

Compare with the bound of KM with a fixed kernel K

$$GAP \leq \frac{B}{n} \sqrt{\sum_{i=1}^n K(x_i, x_i)}$$

[Bartlett, P. L. and Mendelson, S. 2002]

- Our bound holds for general NNs
- When $|\mathcal{K}_T| = 1$, our bound recovers KM's bound

Generalization bound for NN trained by gradient flow

Analyze the covering number of \mathcal{G}_T ,

$$GAP \leq 2 \min(U_1, U_2)$$

$$U_2 = \inf_{\epsilon > 0} \left(\frac{\epsilon}{n} + \sqrt{\frac{2 \ln \mathcal{N}(\mathcal{G}_T^S, \epsilon, \|\cdot\|_1)}{n}} \right)$$

$\mathcal{G}_T^S = \{g(\mathbf{z}) = (g(z_1), \dots, g(z_n)) : g \in \mathcal{G}_T\}$,
 $\mathcal{N}(\mathcal{G}_T^S, \epsilon, \|\cdot\|_1)$ is the covering number of \mathcal{G}_T^S .

If the variation of the loss dynamics of gradient flow with different training data is small, U_2 will be small.

- Can be estimated with training samples
- Can get similar bounds as U_1, U_2 for stochastic gradient flow
- U_1, U_2 can be used to analyze specific cases

Generalization bound for NN trained by gradient flow

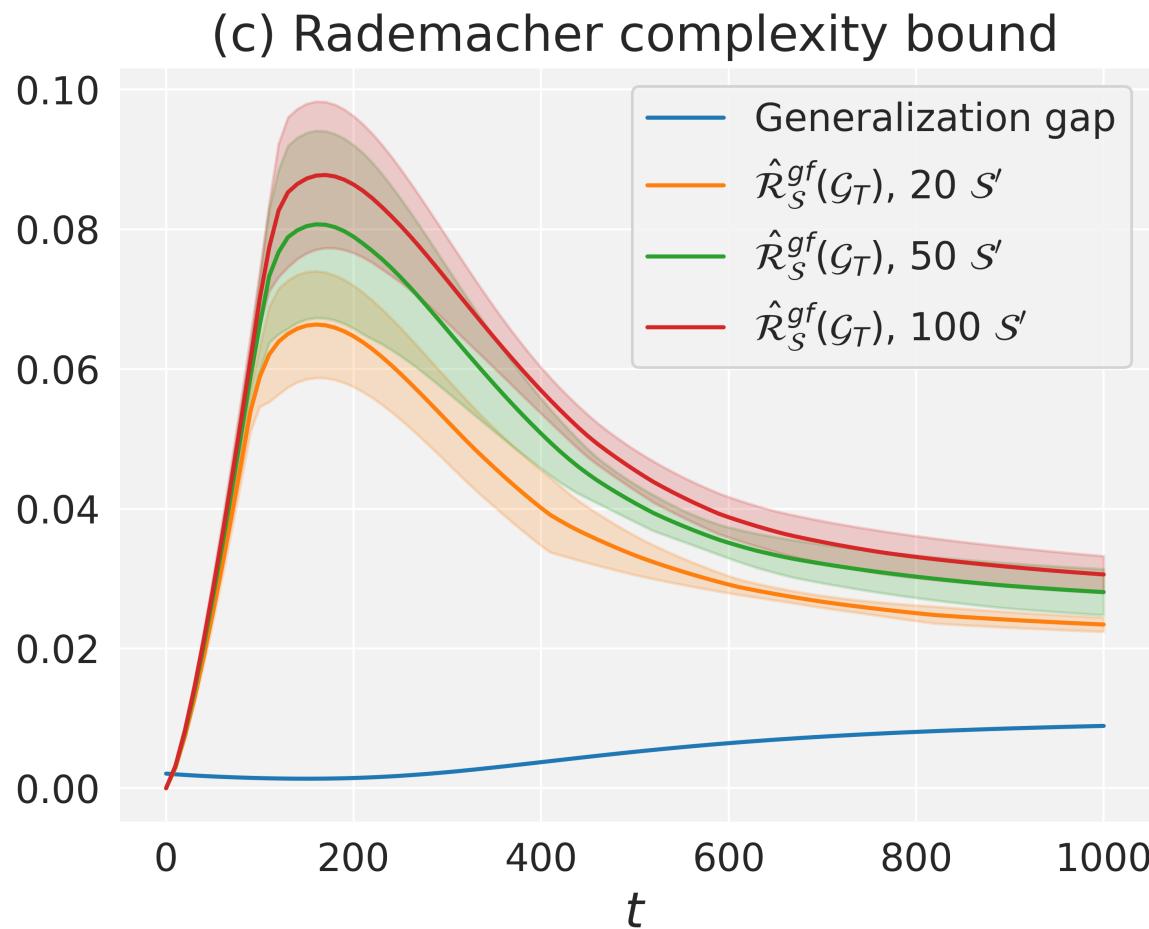
Compare with previous NTK-based bounds

	Arora et al.	Cao & Gu	Ours
Bound	$\sqrt{\frac{2\mathbf{Y}^\top(\mathbf{H}^\infty)^{-1}\mathbf{Y}}{n}}$	$\tilde{O}(L \cdot \sqrt{\frac{\mathbf{Y}^\top(\Theta)^{-1}\mathbf{Y}}{n}})$	Theorem 3, Theorem 5
Model	Ultra-wide two-layer FCNN	Ultra-wide FCNN	General continuously differentiable NN
Data	i.i.d. data with $\ \mathbf{x}\ = 1$	i.i.d. data with $\ \mathbf{x}\ = 1$	i.i.d. data
Loss	Square loss	Logistic loss	Continuously differentiable & bounded loss
During training	No	No	Yes
Multi-outputs	No	No	Yes
Training algorithm	GD	SGD	(Stochastic) gradient flow

Much more general results!

Generalization bound for NN trained by gradient flow

Experiment of two-layer NN



Compare with

VC dimension bound: 55957.3

Norm-based bound: 140.7

NTK-based bound (ultra-wide NN): 1.44

Tight bound!

Case study: Ultra-wide NN

For an infinite-width NN with constant NTK $\Theta(x, x')$

$$GAP \leq \frac{\rho B \sqrt{T}}{n} \sqrt{\sum_{i,j} |\Theta(x_i, x_j)|}$$

ρ : Lipschitz constant of $\ell(f, y)$

Compare with $\tilde{\mathcal{O}}(L \cdot \sqrt{\frac{2 \mathbf{y}^\top (\Theta)^{-1} \mathbf{y}}{n}})$ [Cao & Gu, 2019],

1. no dependence on the number of layers L
2. holds for NNs with multiple outputs.

- U_1, U_2 can also be used to analyze stable algorithms, norm-constraint NNs

Application: Neural architecture search

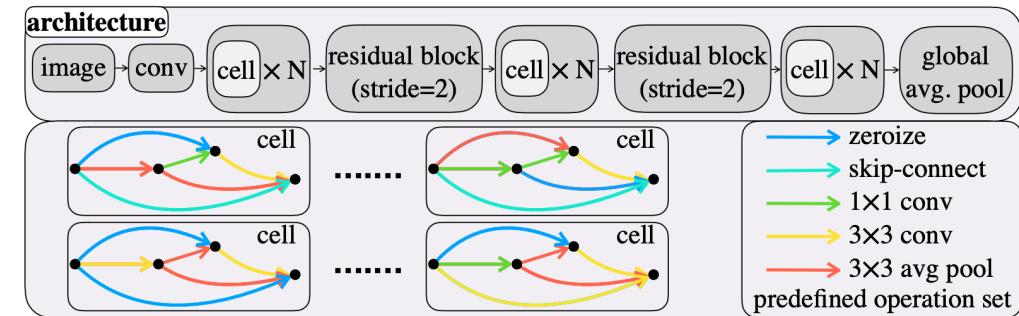
Use the bound to estimate the test loss and design minimum-training NAS algorithms:

$$\text{Gene}(w, S) = L_S(w) + 2U_{sgd}$$

U_{sgd} : simplified from the bound of stochastic gradient flow

Algorithm	CIFAR-10		CIFAR-100	
	Accuracy	Best	Accuracy	Best
Baselines				
TENAS [13]	93.08±0.15	93.25	70.37±2.40	73.16
RS + LGA ₃ [39]	93.64		69.77	
Ours				
RS + Gene(w, S) ₁	93.68±0.12	93.84	72.02±1.43	73.15
RS + Gene(w, S) ₂	93.79 ±0.18	94.02	72.76 ±0.33	73.15
Optimal	94.37		73.51	

NAS-Bench-201



“RS”: randomly sample 100 architectures and select the one with the best metric value

Gene(w, S)₁: Gene(w, S) at epoch 1

“Optimal”: the best test accuracy achievable in NAS-Bench-201 search space

“Best”: best accuracy over the four runs

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Conclusion

Our theory has several benefits:

1

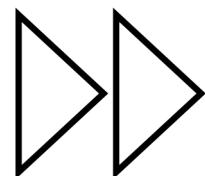
**New equivalence
between NN and KM**



- New kernel LPK
- Much more general equivalence

2

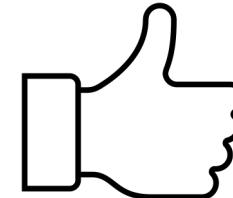
**Generalization
bound for NN**



- Holds for general NNs
- Tighter bounds!

3

**Useful in theory
and practice**



- Better bound for ultra-wide NNs
- Minimum-training NAS algorithms

Future works

What's next?

1

**Generalization bounds
for other optimization
algorithms.**

- SGD with momentum
- Adam

2

**Study different NN
architectures**

- Full-connected NN
- CNN
- Resnet

3

**Extend the results
to obtain expected
bounds.**



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