

## DETERMINING NOISE FROM DETERMINISTIC FORCES

Consider the following deterministic equations

$$(1) \quad dX_\alpha = V_\alpha dt$$

and

$$(2) \quad dV_\alpha = -U_\alpha dt - \nabla \phi(\mathbf{X}) dt.$$

We assume that  $U_\alpha$  are generated by hydrodynamic interactions which do not however affect the equilibrium Gibbs Boltzmann distribution which is

$$(3) \quad P_{eq}(\mathbf{X}, \mathbf{V}) = \frac{1}{\bar{Z}} \exp\left(-\frac{\beta \mathbf{V}^2}{2} - \beta \phi(\mathbf{X})\right)$$

The Fokker Planck equation at finite temperature which introduces white noise and possibly temperature dependent drifts is  $\phi(\mathbf{X})$  is

$$(4) \quad \frac{\partial P}{\partial t} = \frac{\partial}{\partial V_\alpha} \left[ T \gamma_{\alpha\beta} \frac{\partial P}{\partial V_\beta} + U_\alpha P + \frac{\partial \phi}{\partial X_\alpha} P \right] - \frac{\partial}{\partial X_\alpha} V_\alpha P$$

We obtain the GB distribution for the steady state if

$$(5) \quad U_\alpha = \gamma_{\alpha\beta} V_\beta$$

We have for small velocities that

$$(6) \quad U_\alpha = \lambda_{\alpha\beta}(\mathbf{X}) V_\beta + \Lambda_{\alpha\beta\gamma} V_\beta V_\gamma,$$

and so we find

$$(7) \quad \gamma_{\alpha\beta} V_\beta = \lambda_{\alpha\beta}(\mathbf{X}) V_\beta + \Lambda_{\alpha\beta\gamma}(\mathbf{X}) V_\beta V_\gamma$$

Written this way the term  $\lambda_{\alpha\beta}(\mathbf{X})$  is just the friction tensor in the absence of any elastic effects. We can thus write

$$(8) \quad \gamma_{\alpha\beta} = \lambda_{\alpha\beta} + \gamma_{2\alpha\beta}$$

and we write

$$(9) \quad \gamma_{2\alpha\beta} = \Gamma_{\alpha\beta\gamma} V_\gamma$$

and

$$(10) \quad \Gamma_{\alpha\beta\gamma} V_\beta V_\gamma = \Lambda_{\alpha\beta\gamma} V_\beta V_\gamma,$$

where we without loss of generality take  $\Lambda_{\alpha\beta\gamma} = \Lambda_{\alpha\gamma\beta}$ . This then gives

$$(11) \quad \Gamma_{\alpha\beta\gamma} + \Gamma_{\alpha\gamma\beta} = 2\Lambda_{\alpha\beta\gamma}.$$

We have to solve this system with the constraint that  $\Gamma_{\alpha\beta\gamma}V_\gamma = \Gamma_{\beta\alpha\gamma}V_\gamma$ . In Thomas' problem we have

$$(12) \quad U_z = \xi \frac{V_z}{Z^{\frac{3}{2}}} + \frac{21\kappa\xi}{4} \frac{V_z^2}{Z^{\frac{9}{2}}} - \frac{\kappa\xi}{4} \frac{V_x^2}{Z^{\frac{7}{2}}}$$

and

$$(13) \quad U_x = 2\xi\epsilon \frac{V_x}{3Z^{\frac{1}{2}}} + \frac{19\kappa\xi\epsilon}{24} \frac{V_z V_x}{Z^{\frac{7}{2}}}$$

Form this we find that

$$(14) \quad \begin{aligned} \sum_{\alpha\beta} \Lambda_{z\alpha\beta} V_\alpha V_\beta &= \frac{21\kappa\xi}{4} \frac{V_z^2}{Z^{\frac{9}{2}}} - \frac{\kappa\xi}{4} \frac{V_x^2}{Z^{\frac{7}{2}}} \\ \sum_{\alpha\beta} \Lambda_{x\alpha\beta} V_\alpha V_\beta &= \frac{19\kappa\xi\epsilon}{24} \frac{V_z V_x}{Z^{\frac{7}{2}}} \end{aligned}$$

This gives the set of equations

$$(15) \quad \Gamma_{zzz} = \frac{21\kappa\xi}{4Z^{\frac{9}{2}}}$$

$$(16) \quad \Gamma_{zxx} = -\frac{\kappa\xi}{4Z^{\frac{7}{2}}}$$

$$(17) \quad \Gamma_{zzx} + \Gamma_{zzx} = 0$$

$$(18) \quad \Gamma_{xzz} = 0$$

$$(19) \quad \Gamma_{xxx} = 0$$

$$(20) \quad \Gamma_{xxz} + \Gamma_{xzx} = \frac{19\kappa\xi\epsilon}{24Z^{\frac{7}{2}}}.$$

The symmetry  $\Gamma_{\alpha\beta\gamma} = \Gamma_{\beta\alpha\gamma}$  now gives

$$(21) \quad \Gamma_{xxz} = \frac{19\kappa\xi\epsilon}{24Z^{\frac{7}{2}}} - \Gamma_{xzx} = \frac{19\kappa\xi\epsilon}{24Z^{\frac{7}{2}}} - \Gamma_{zxx} = \frac{\kappa\xi}{Z^{\frac{7}{2}}} \left( \frac{19\epsilon}{24} + \frac{1}{4} \right),$$

as well as

$$(22) \quad \Gamma_{zxx} = \Gamma_{zzx} = 0$$

The Langevin equation corresponding to this is, using the Ito convention,

$$(23) \quad \frac{dV_\alpha}{dt} = -U_\alpha - \frac{\partial\phi(\mathbf{X})}{\partial X_\alpha} + T \frac{\partial\gamma_{\alpha\beta}}{\partial V_\beta} + \eta_\alpha(t)$$

which can be written as

$$(24) \quad \frac{dV_\alpha}{dt} = -U_\alpha - \frac{\partial\phi(\mathbf{X})}{\partial X_\alpha} + T\Gamma_{\alpha\beta\gamma} + \eta_\alpha(t),$$

where we use the Einstein summation convention and the noise correlator is given by

$$(25) \quad \langle \eta_\alpha(t) \eta_\beta(t') \rangle = 2T\gamma_{\alpha\beta}\delta(t-t') = 2T[\lambda_{\alpha\beta}(\mathbf{X}) + \Gamma_{\alpha\beta\gamma}(\mathbf{X})V_\gamma]\delta(t-t').$$

Putting this together we find

$$\begin{aligned}
 \frac{dV_z}{dt} &= -V'(Z) - \xi \frac{V_z}{Z^{\frac{3}{2}}} - \frac{21\kappa\xi}{4} \frac{V_z^2}{Z^{\frac{9}{2}}} + \frac{\kappa\xi}{4} \frac{V_x^2}{Z^{\frac{7}{2}}} + T\left[\frac{21\kappa\xi}{4Z^{\frac{9}{2}}} - \frac{\kappa\xi}{4Z^{\frac{7}{2}}}\right] + \eta_z(t) \\
 (26) \quad \frac{dV_x}{dt} &= -2\xi\epsilon \frac{V_x}{3Z^{\frac{1}{2}}} - \frac{19\kappa\xi\epsilon}{24} \frac{V_z V_x}{Z^{\frac{7}{2}}} + \eta_x(t)
 \end{aligned}$$