

Recap  $GL(n, k)$

$$Sp(2n, k) \Rightarrow \{p^i, p_i\} \\ \Rightarrow \{Q^i, P_i\}$$

$$\begin{pmatrix} Q^1 \\ Q^2 \\ \vdots \\ Q^n \\ P_1 \\ \vdots \\ P_n \end{pmatrix} = A \begin{pmatrix} q^1 \\ \vdots \\ q^n \\ p_1 \\ \vdots \\ p_n \end{pmatrix}$$

$$A \in Sp(2n, \mathbb{R})$$

$$X \subset G \quad \langle X \rangle = G \quad |X| < \infty \quad \text{"finitely generated"}$$

$$G = \langle g_1, \dots, g_n \mid R_1, \dots, R_r \rangle$$

$$\mathbb{Z}_n, \mu_n \quad \langle A \mid A^n = 1 \rangle$$

$$\mathbb{Z}_2 \otimes \mathbb{Z}_2 \quad \langle A, B \mid A^2 = B^2 = (AB)^2 = 1 \rangle$$

$$D_n \quad \langle A, B \mid A^n = B^2 = (AB)^2 = 1 \rangle$$

$$D_{2^n} \cong \mathbb{Z}_2 \otimes \mathbb{Z}_2$$

Quaternion group.  $i^2 = j^2 = k^2 = -1$

$$ij = -ji = k \quad \dots$$

$$Q = \{\pm 1, \pm i, \pm j, \pm k\} = \langle x, y \mid x^4 = 1, x^2 = y^2, y^2 x y = x^3 \rangle \\ = \langle i, j \rangle$$

Pauli matrices.  $\sigma^1 = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$   $\sigma^2 = \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix}$   $\sigma^3 = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$

$$\underline{i} = -i\sigma^1, \underline{j} = -i\sigma^2, \underline{k} = -i\sigma^3$$

$$Q = \{ \pm 1, \pm i\sigma^1, \pm i\sigma^2, \pm i\sigma^3 \} \cong \langle -i\sigma^1, -i\sigma^2 \rangle$$

Pauli group

$$P_1 = \{ \pm 1, \pm i, \dots \} \cong \langle \sigma^1, \sigma^2, \sigma^3 \rangle$$

( $P_1 = 16$ )

$$X = \sigma^1, \quad Z = \sigma^3.$$

$$|0\rangle = \begin{pmatrix} 1 \\ 0 \end{pmatrix}$$

$$X|0\rangle = |1\rangle$$

$$|1\rangle = \begin{pmatrix} 0 \\ 1 \end{pmatrix}$$

$$X|1\rangle = |0\rangle$$

bit flip

$$Z|0\rangle = |0\rangle$$

$$Z|1\rangle = -|1\rangle$$

phase flip

$$P_1 \rightarrow n\text{-qubit} \quad P_n = (P_1)^n$$

$$V_S = \{ |\varphi\rangle : S|\varphi\rangle = |\varphi\rangle, \forall S \in S \}$$

3-qubit bit-flip code

$$S = \langle Z_1 Z_2, Z_2 Z_3 \rangle$$

$$V_S = \{ |000\rangle, |111\rangle \}$$

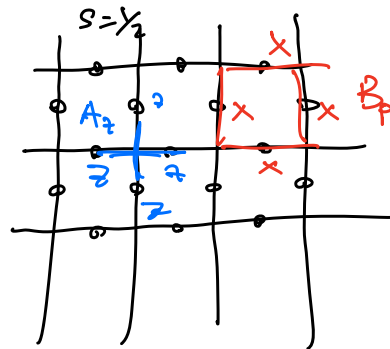
$z_1 z_2$	$z_1 z_2$	$\rightarrow$
$+1$	$+1$	$\checkmark$
$+1$	$-1$	3 - flip
$-1$	$+1$	1
$-1$	$-1$	2

Toric code

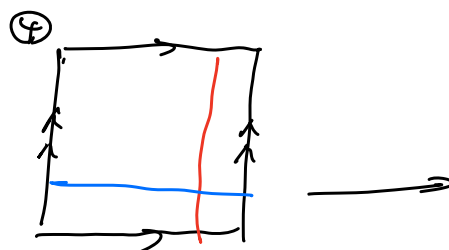
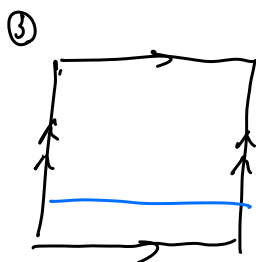
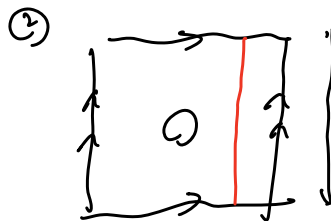
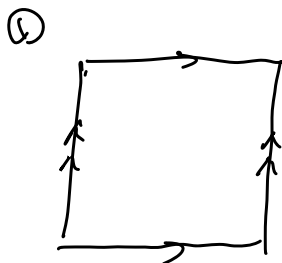
$$\left| \begin{array}{l} A_v = \prod_j z_j \\ B_p = \prod_j x_j \end{array} \right|$$

$$H = -\sum_v A_v - \sum_p B_p$$

$$|GS\rangle = \sum | \text{closed loops} \rangle$$



$\mathbb{Z}_2 \times \mathbb{Z}_2$



## 3. Homomorphism &amp; Isomorphism.

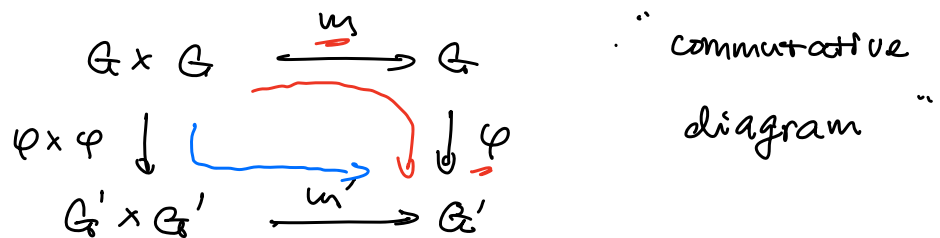
Definition. Let  $(G, \underline{m}, \underline{I}, e)$  and  $(G', \underline{m}', \underline{I}', e')$  be two groups.

Homomorphism.  $\varphi : G \rightarrow G'$  . s.t.  $\forall g_1, g_2 \in G$

$$\varphi(\underline{m}(g_1, g_2)) = \underline{m}'(\varphi(g_1), \varphi(g_2))$$

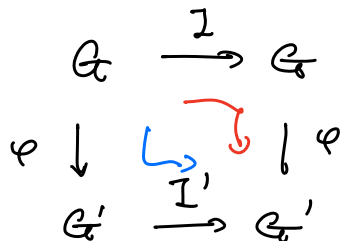
a mapping preserving the group law.

$$\varphi(g_1 \cdot g_2) = \varphi(g_1) \cdot \varphi(g_2)$$



$$\varphi(e) = \varphi(e \cdot e) = \varphi(e) \varphi(e) \Rightarrow \varphi(e) = e'$$

$$\underline{e'} = \varphi(e) = \varphi(g \cdot g^{-1}) = \underline{\varphi(g) \cdot \varphi(g^{-1})} \Rightarrow \underline{\varphi(g)} = \underline{\varphi(g)^{-1}}$$



(2)

$$(1) \quad \underline{\varphi(g) = e' \text{ iff } g = e} \quad \varphi \text{ injective}$$

or

$$\underline{\varphi(g_1) = \varphi(g_2) \Rightarrow g_1 = g_2}$$

$$\exists g_1, g_2 \in G \quad g_1 \neq g_2$$

$$\underline{e' = \varphi(g_1) \cdot \varphi(g_2)^{-1} = \varphi(g_1 \cdot g_2^{-1}) = \varphi(g_3 \neq e)}$$

$$(2) \quad \forall g' \in G' \quad \exists g \in G \text{ s.t. } \varphi(g) = g' \quad \varphi \text{ is } \underline{\text{surjective}}$$

(3) (Def)  $\varphi$  is an isomorphism if (1) & (2)  
(bijective)

$$G \xrightleftharpoons[\varphi^{-1}]{\varphi} G' \quad \begin{array}{l} \varphi \text{ isomorphism} \\ \varphi^{-1} \text{ isomorphism} \end{array}$$

$$\forall g'_1, g'_2 \in G' \quad \varphi^{-1}(g'_1 \cdot g'_2) = \varphi^{-1}(g'_1) \cdot \varphi^{-1}(g'_2) \quad ? \checkmark$$

$$\exists g_1, g_2 \in G \text{ s.t. } \varphi(g_1) = g'_1, \quad \varphi(g_2) = g'_2.$$

$$\varphi(g_1) \cdot \varphi(g_2) = \varphi(g_1 g_2)$$

$$\varphi^{-1}(\varphi(g_1) \cdot \varphi(g_2)) = g_1 g_2 = \varphi^{-1}(g'_1) \cdot \varphi^{-1}(g'_2)$$

Isomorphic groups are the same.

$$4. \text{ (Def) } \varphi \text{ an isomorphism } \underline{G \xrightarrow{\varphi} G}$$

$$\varphi : \underline{\text{automorphism}}$$

## Definition (kernel & Image)

Let  $\varphi$  be an homomorphism

$$\varphi : G \rightarrow H$$

(a) kernel of  $\varphi$

$$K = \ker \varphi := \{ g \in G : \varphi(g) = \underline{1_H} \}$$

(b) image of  $\varphi$ :

$$\begin{aligned} \operatorname{im} \varphi &:= \{ h \in H : h = \varphi(g) \text{ for some } g \in G \} \\ &= \varphi(G) \end{aligned}$$

## Remarks

(a)  $\varphi(G)$   $\subset H$  is a subgroup.

$$\textcircled{1} \varphi(\underline{1_G}) = \underline{1_H} \quad \checkmark$$

$$\textcircled{2} \forall h_1 = \varphi(g_1), h_2 = \varphi(g_2)$$

$$h_1 \cdot h_2 = \varphi(g_1) \varphi(g_2) = \varphi(g_1 g_2) \in \varphi(G) \quad \checkmark$$

$$\textcircled{3} h_1 = \varphi(g_1) \quad \checkmark$$

$$1 = \varphi(g_1) \varphi(g_1^{-1}) = h_1 h_2 \quad h_2 = \varphi(g_1^{-1}) \in \varphi(G)$$

⊕

(b)  $K \subset G$  is a subgroup

①  $\varphi(1_G) = 1_K \quad 1_G \in K$  ✓

②  $\forall g_1, g_2 \in K \quad \underbrace{\varphi(g_1)} \cdot \underbrace{\varphi(g_2)} = \underbrace{\varphi(g_1 g_2)} = 1_K$   
 $g_1 g_2 \in K$  ✓

③  $\underbrace{\varphi(g_1)}_1 \cdot \underbrace{\varphi(g_1^{-1})}_1 = \varphi(1_G) = \underline{1_H} \quad (g_1 \in K)$   
 $g_1^{-1} \in K$  ✓

(c)  $\varphi$  isomorphism.  $G \xrightarrow{\varphi} \underline{H}$

$K = \{1\}$

$\text{im } \varphi = H$

Example :  $\mu_N$  &  $\mathbb{Z}_N$

$\mu_N = \{1, \omega, \omega^2, \dots, \omega^{N-1}\}$   $\omega = e^{i \frac{2\pi}{N}}$

$\mathbb{Z}_N = \{\bar{0}, \bar{1}, \dots, \overline{N-1}\}$   $\bar{i} = i + \mathbb{Z} \cdot N$   
 $(0 \leq i < N)$

$\varphi: \mathbb{Z}_N \rightarrow \mu_N$

$\boxed{\varphi(\bar{r} = r + N\mathbb{Z}) := e^{i \frac{2\pi}{N} r}}$

①  $\varphi(\bar{r}_1 + \bar{r}_2) = \varphi(\bar{r}_1) \cdot \varphi(\bar{r}_2)$

$e^{i \frac{2\pi}{N} (r_1 + r_2)} = e^{i \frac{2\pi}{N} r_1} \cdot e^{i \frac{2\pi}{N} r_2}$  *homom.*

②  $\varphi(\bar{r}) = 1 \Rightarrow \bar{r} = \bar{0}$  *injective*

$$\textcircled{2} \quad \forall \omega^j \in \mu_n, \exists \varphi(\bar{r}_j) = \omega^j$$

surjective

⑤

① + ② + ③ :  $\varphi$  is an isomorphism

Example

$$\mu_n \rightarrow \mu_n$$

$$P_k : \mu_k \rightarrow \mu_k$$

$$P_k(z) = z^k$$

$$(z_1, z_2)^k = z_1^k z_2^k$$

$$P_k(z_1, z_2) = P_k(z_1) \cdot P_k(z_2) \quad \checkmark$$

$$\mathbb{Z}_n \rightarrow \mathbb{Z}_n$$

$$m_k : \mathbb{Z}_n \rightarrow \mathbb{Z}_n$$

$$m_k(\bar{r}) = \overline{mr}$$

is  $P_k$  or  $m_k$  an isomorphism?

$$\gcd(k, n) = 1$$

$$\textcircled{1} \quad \mu_3 \cong \mathbb{Z}_3 \quad k=2$$

$$\bar{0} \rightarrow \bar{0}$$

$$\bar{1} \rightarrow \bar{2}$$

$$\bar{2} \rightarrow \bar{1}$$

$$\gcd(2, 3) = 1$$

$$\textcircled{2} \quad P_2 \not\cong \mu_4, \quad m_2 \not\cong \mathbb{Z}_4$$

$$\gcd(2, 4) = 2 \neq 1$$

$$\begin{array}{ccc} \bar{0} & \rightarrow & \bar{0} \\ \bar{1} & \rightarrow & \bar{2} \\ \bar{2} & \rightarrow & \bar{0} \\ \bar{3} & \rightarrow & \bar{2} \end{array}$$

$$\ker(m_2) = \{\bar{0}, \bar{2}\}$$

$$\text{Im}(m_2) = \{\bar{0}, \bar{2}\}$$

$\mathbb{Z}_2$



$\varphi(\bar{r}) = e^{i \frac{2\pi}{N} \cdot r}$

$$\begin{array}{ccc}
 \mathbb{Z}_N & \xrightarrow{m_k} & \mathbb{Z}_N \\
 \varphi \downarrow & \searrow & \downarrow \varphi \\
 \mu_N & \xrightarrow{p_k} & \mu_N
 \end{array}$$

$\varphi \circ m_k = p_k \circ \varphi$   
 $p_k = \varphi \circ m_k \circ \varphi^{-1}$

diagram commutes iff  $k_1 = k_2 \pmod{N}$

Example  $\varphi: U(1) \rightarrow SU(2)$   
 $\varphi(z) = \begin{pmatrix} z^N & 0 \\ 0 & z^{-N} \end{pmatrix} \in SU(2)$   $\det \varphi(z) = 1$   
 $\ker(\varphi) = \langle z \mid z^N = 1 \rangle \cong \mu_N$

Example  $\pi: SU(2) \rightarrow SO(3)$   $\vec{x} \in \mathbb{R}^3$   
 $\vec{x} \cdot \vec{\sigma} = \sum x_i \sigma_i$   
 $\forall u \in SU(2), \exists \pi(u) \in SO(3) \text{ s.t.}$   
 $u \vec{x} \cdot \vec{\sigma} u^\dagger = (\pi(u) \cdot \vec{x}) \cdot \vec{\sigma}$   $\text{def } \vec{y} \cdot \vec{\sigma} = -\vec{y}^2$   
 $= \sum_{ij} (\pi(u)_{ij} x_j) \sigma_i$   $\vec{x}^2 = \vec{y}^2$

$$(\Leftrightarrow) u \sigma_i u^\dagger = \sum_j \pi(u)_{ji} \sigma_j$$

$$(u_1 u_2) \sigma_i (u_1 u_2)^\dagger = u_1 (u_2 \sigma_i u_2^\dagger) u_1^\dagger$$

$SU(2), SO(3)$  double cover

$$\pi(u) = \pi(-u)$$

$$\begin{aligned}
 &= u_1 \left( \sum_j \sigma_j \pi(u_2)_{ji} \right) u_1^\dagger \\
 &= \sum_j \pi_{ji}(u_2) (u_1 \sigma_j u_1^\dagger) \\
 &= \sum_{j,k} \pi_{ji}(u_2) \pi_{kj}(u_1) \sigma_k \\
 &= \sum_k \pi_{ki}(u_1 u_2) \sigma_k
 \end{aligned}$$

$$\pi(u_1) \cdot \pi(u_2) = \pi(u_1 u_2) \quad \checkmark$$

③

$$\pi(u) \in SO(3) \quad ?$$

$$① \quad \pi(u) \in O(3)$$

$$\text{LHS} \quad \det(u \cdot \vec{x} \cdot \vec{\sigma} \cdot u^\dagger) = \det(\vec{x} \cdot \vec{\sigma}) = \det \begin{pmatrix} x_3 & x_1 - ix_2 \\ x_1 + ix_2 & -x_3 \end{pmatrix}$$

$$\text{RHS} \quad (\pi(u) \cdot \vec{x}) \cdot \vec{\sigma} = \vec{y} \cdot \vec{\sigma} \quad \det(\cdot) = -\vec{y}^2 = -\vec{x}^2$$

$$\vec{x}^2 = \vec{y}^2 \quad \text{norm preserving}$$

$$\pi(u) \in O(3) \quad \checkmark$$

$$② \quad u = \underline{1}, \quad \pi(u) = \underline{1} \quad \pi(u) \in SO(3)$$

$$2i = \text{tr}(\sigma_1 \sigma_2 \sigma_3) \quad u^\dagger u$$

$$= \text{tr}(u \sigma_1 u^\dagger u \sigma_2 u^\dagger u \sigma_3 u^\dagger)$$

$$= \sum \pi(u)_{i1} \pi(u)_{j2} \pi(u)_{k3} \text{tr}(\sigma_i \sigma_j \sigma_k)$$

$$= \sum_{i,j,k} \epsilon^{ijk} \pi(u)_{i1} \pi(u)_{j2} \pi(u)_{k3}$$

$$\det(\pi(u)) = 1$$

Definition: A matrix representation of a group  $G$  is a homomorphism

$$T: \underline{G} \rightarrow \underline{GL(n, k)} \quad (k = \mathbb{R}, \mathbb{C})$$

$$g \mapsto T(g)$$

The set of matrices in  $GL(n, k)$  can be

thought as invertible linear transformations

on a  $n$ -dim. vector space  $V$  with  
a given basis set  $b = \{ \hat{e}_1, \hat{e}_2, \dots, \hat{e}_n \}$

$$(\underline{GL(V)} \cong \underline{GL(n, k)})$$

$$T(g_1) \cdot T(g_2) = T(g_1 g_2) \quad ?$$

$$T(g) \hat{e}_i = \sum_j \hat{e}_j T(g)_{ji}$$

$$(T(g_1) \cdot T(g_2)) \hat{e}_i = T' \left( \sum_j \hat{e}_j T^2_{ji} \right) \quad (T^i := T(g_i))$$

$$= \sum_j T^2_{ji} (T' \hat{e}_j)$$

$$= \sum_{jk} T^2_{ji} T'_{kj} \hat{e}_k$$

$$= \sum_k \hat{e}_k \sum_j (T'_{kj} T^2_{ji})$$

$$= \sum_k \hat{e}_k \underline{(T' T^2)_{ki}}$$

$$= \sum_k \hat{e}_k \underline{[T(g_1 g_2)]_{ki}}$$

$$\boxed{T(g_1) \cdot T(g_2) = T(g_1 g_2)} \quad \checkmark$$

basis dependent,  $\hat{e}_i = \sum_{j=1}^n S_{ji} \hat{e}'_j$

$$\underline{T'(g)} = \underline{S} \underline{T(g)} \underline{S}^{-1}$$

Definition (equivalent representation).  $T, T'$

are  $n$ -dim matrix. rep. of  $G$ .

$T \cong T'$  (equivalent) if  $\exists S \in GL(n, k)$ , s.t.



"faithful representation": injective

$A \cong B = \mathbb{I}_n$  "not faithful"