

Group theory and its application (in Physics)

0. Logistics:

1. 鼓楼线下: 房 A-202 (三) 14:00 - ~~16:00~~ ^{15:40}
A-201 (五)

2. ① 教室: 7F TJH212

② QQ: 7295 71175

③ yilu.me/teaching

3. 成绩: 40 + 60% ~10次

4. 教材参考:

① Greg Moore (Rutgers)

赵宇

<http://www.physics.rutgers.edu/~gmoore/618Spring2022/GroupTheory-Spring2022.html>

② Zee. GT in nutshell. PuP

Dresselhaus, GT. Springer

Ramond, GT, Cambridge UP.

③ 中文教材:

马中骥, 陶瑞宝

陈金全 《群表示论的新途径》

1. Introduction

19th Galois, "groupe" group

roots of polynomial $P(x)$

order ≤ 5 radical solutions

> 5 not necessarily

杨振宁 = 杨振宁 量子力学、对称性、守恒因子

20th

group \Leftrightarrow Symmetry



conservation

① General relativity $\text{Diff}(M)$

special relativity, $(t, x, y, z) \rightarrow t^2 - x^2 - y^2 - z^2$

$O(1, d)$ Lorentz group

② Lie algebra, Jacobi identity

$$[T^A, T^B] = i \epsilon^{ABC} T^C$$

$$[T^A, [T^B, T^C]] + [T^B, [T^C, T^A]] + [T^C, [T^A, T^B]] = 0$$



$SU(2)$



spin

$SO(3)$



rotation

$Sp(2n)$



$\{q_i, p_j\} = \delta_{ij}$

③ Standard model

electroweak $U(1) \times SU(2)$ strong $SU(3)$

4-dim

8-dim, 8-gluons

photon, $2 \times W$, Z

④ Condensed matter.

A. translation sym. ($T^n = \mathbb{I}$) \leftrightarrow momentum
B. rotation . 32 point group

A + B \rightarrow space group 17 wallpaper group 2D
230 in 3D

atomic spectra, lattice vibration, band structure

SC

2. Groups: Basic definitions & Examples

Definition : A group is a quartet $(G, \underline{m}, \underline{I}, e)$ where

1. G is a set.

2. $\underline{m}: \underline{G} \times \underline{G} \rightarrow \underline{G}$. multiplication map

3. $\underline{I}: G \rightarrow G$ inverse map

4. $e \in G$. identity element.

They satisfy conditions:

1 (associativity)

$$\underline{m}(\underline{m}(g_1, g_2), g_3) = \underline{m}(g_1, \underline{m}(g_2, g_3))$$

$$(g_1 g_2) \cdot g_3 = g_1 (g_2 g_3)$$

not associative : definition

$$e_i e_j = \begin{cases} e_i & i=j \\ e_j & j=i \\ -\delta_{ij} e_0 + \sum_{i,j,k} \epsilon_{ijk} e_k & \text{otherwise} \end{cases}$$

$$(e_i e_j) e_k = -e_i (e_j e_k)$$

2. (existence of e) $\exists e$ s.t. $\forall g$.

$$e \cdot g = g \cdot e = g$$

3. (existence of \underline{I}) $\forall g \in G$. $\exists \underline{I}(g) =: g^{-1}$ s.t.

$$g \cdot g^{-1} = g^{-1} \cdot g = e$$

Remarks.

$$1. \quad e, \quad \underline{1}_G, \quad g_0.$$

$$\underline{0}$$

2. related defs:

associativity, $\exists e$, $\exists g^{-1}$

semigroup / monoid.

unital monoid

group

3. topological group. if G is a topological space

\underline{m} , \underline{I} continuous

Lie group. G is a manifold

locally homeomorphic
to \mathbb{R}^n

$\underline{m}, \underline{I}$ real analytic in local coord.

$$4. G \Leftrightarrow (G, \underline{m}, \underline{I}, e)$$

Exercise.

a. e unique?

$$e_1 = e, e_2 = e$$

b. a^{-1} unique?

$$ab = ba = ac = ca = e$$

$$b = b(ac) = (ba)c = c$$

Examples:

1. $G = \mathbb{Z}, \mathbb{R}, \text{ or } \mathbb{C}$.

$$\begin{array}{l} \underline{m}(a,b) := a+b \\ e? \quad 0 \\ \underline{I}? \quad a \rightarrow -a \\ \text{closed?} \quad \checkmark \end{array}$$

$$\underline{m}(a,b) := ab$$

2. $G = \mathbb{R}^* := \mathbb{R} - \{0\}$

$$\mathbb{C}^* := \mathbb{C} - \{0\}$$

$$\mathbb{Z}^* := \mathbb{Z} - \{0\}$$

$$2 \rightarrow \frac{1}{2} \notin \mathbb{Z}$$

Definition (subgroup)

(G, m, I, e) a group. set $H \subset G$

m, I preserve H , i.e.

$$m: H \times H \rightarrow H$$

$$I: H \rightarrow H$$

(H, m, I, e) is a subgroup of (G, \dots)

proper subgroup $H \neq G$ $H \subsetneq G$

Exercise.

1. $\mathbb{Z} \subset \mathbb{R} \subset \mathbb{C}$. subgroups $m: "+"$

2. \mathbb{R}^* . $\xrightarrow[\quad 0 \quad]{R_{<0} \quad R_{>0}}$

$R_{<0}$ subgroup of \mathbb{R}^* ? \times

$R_{>0}$ \checkmark

3. $R_{<0}$: $\underline{m(a, b) = -ab}$

$$\begin{aligned} \parallel a \cdot (-1) &= a \quad \checkmark \\ \underline{a \cdot \frac{1}{a}} &= -1 \quad \checkmark \\ \underline{\quad} & \end{aligned}$$

4. $H_1 \subset G, H_2 \subset G$.

(a) $H_1 \cap H_2$ subgroup?

① $e \in H_1, e \in H_2 \quad e \in H_1 \cap H_2 \quad \checkmark$

$$\begin{array}{lll} \textcircled{2} \quad h \in H_1 \rightarrow h^{-1} \in H_1 & \rightarrow & h \in H_1 \cap H_2 \\ & & \downarrow \\ & & h^{-1} \in H_1 \cap H_2 \end{array}$$

$$(3) \quad \forall h, h_1 \in H_1 \cap H_2 \quad h, h_2 \in H_1 \rightarrow h_1 h_2 \in H_1 \cap H_2$$

$$h_1 h_2 \in H_2$$

(b) $H_1 \cup H_2$ subgroup?

if $\exists h_1 \in H_1 \notin H_2$

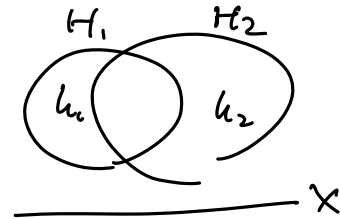
$\exists h_2 \in H_2 \notin H_1$

Contradiction \nearrow

$$h_3 = h_1 \cdot h_2 \in H_1 \cup H_2 \quad \text{wlog } \in H_1$$

$$h_1 = h_2^{-1} \cdot h_3 \in H_1$$

$\Rightarrow H_1 \subset H_2 \text{ or } H_2 \subset H_1$



Definition (order of a group) $|G|$ cardinality of G ,

finite group $|G| < \infty$

infinite group otherwise

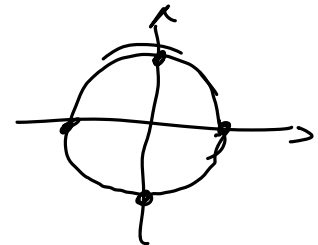
Example: n^{th} roots of unity

$$\mu_n = \{1, \omega, \dots, \omega^{n-1}\} \equiv \{z \in \mathbb{C} \mid z^n = 1\}$$

$$\omega = e^{2\pi i/n} \quad \text{for } n \in \mathbb{N}$$

$$|\mu_n| = n \rightarrow n = \infty \quad u(\phi) = e^{i\phi}$$

$$0 \leq \phi < 2\pi$$



$$\omega^i \omega^j = e^{i \frac{2\pi}{n} (i+j \bmod n)} \equiv \omega^k \quad k = (i+j) \bmod n$$

"equivalence" relation $\sim \quad \underline{k \sim k + n}$

Example: residue classes modulo N .

$$1 \leq j < N-1 \quad \bar{j} = [j] = \{ n \in \mathbb{Z} \mid j = n \bmod N \}$$

$$\underline{m}(\bar{r}_1, \bar{r}_2) := \overline{r_1 + r_2}$$

$$\mathbb{Z}_N, \text{ or } \mathbb{Z}/N\mathbb{Z}$$

$$P: x \rightarrow -x$$

$$P = \pm 1 \quad \mathbb{Z}_2$$

Definition: (direct product of groups) $G_1 \times G_2$, or $G_1 \otimes G_2$

$$\underline{m}_{G_1 \times G_2}((g_1, g_2), (g'_1, g'_2)) = (m_{G_1}(g_1, g'_1), m_{G_2}(g_2, g'_2))$$

$$\begin{pmatrix} g_1, g'_1 \in G_1 \\ g_2, g'_2 \in G_2 \end{pmatrix}$$

Example: Klein's Viergruppe (4-group) $\mathbb{Z}_2 \times \mathbb{Z}_2$

$$I = (1, 1), \quad a_1 = (-1, 1), \quad a_2 = (1, -1), \quad a_3 = (-1, -1)$$

So far, $a \cdot b = b \cdot a$.

Definitions (Abelian & non-Abelian groups)

$$\forall a, b \in G. \quad a \cdot b = b \cdot a \quad \text{Abelian}$$

$$\exists a, b \in G. \quad \text{s.t. } a \cdot b \neq b \cdot a \quad \text{non-Abelian}$$

$$\text{Abelian: } m(a, b) := \underline{a + b}$$

$$e = 0$$

Example . (The general linear group)

$M_n(K)$: all $\underbrace{\text{matrices}}_{n \times n}$ defined on field K
(\mathbb{R}, \mathbb{C})

$$GL(n, K) := \{ A \in M_n(K) \mid A \text{ non-singular} \}$$
$$= \text{invertible} =$$
$$\det A \neq 0$$

in general $AB \neq BA$ ($n \geq 2$)

Definition (center of a group) $Z(G)$

$$Z(G) := \{ z \in G \mid zg = gz, \forall g \in G \}$$

$\hookrightarrow Z(G)$ is an Abelian subgroup of G .

$$Z(GL(n, K)) = \{ \lambda \mathbf{1}_n, \lambda \in \underline{K^\times} \} \quad (\text{Moore notes p. 13})$$

Examples : standard matrix groups

1. Special linear group

$$SL(n, K) = \{ A \in GL(n, K) \mid \underline{\det A = 1} \}$$

2. (special) orthogonal groups

$$O(n, K) := \{ A \in GL(n, K) \mid \underline{AA^T = \mathbf{1}} \}$$

$$SO(n, K) := \{ A \in O(n, K) \mid \det A = 1 \}$$

$$AA^T = 1 \Leftrightarrow A^T A = 1$$

$$\hookrightarrow A^T = A^{-1} \rightarrow A^T A = 1$$

$$\det(AA^T) = (\det A)^2 = 1 \quad \det A = \pm 1$$

3. (special) unitary group

$$A^\dagger = (A^T)^*$$

$$U(n) = \{ A \in GL(n, \underline{\mathbb{C}}) \mid \underline{AA^\dagger} = 1 \}$$

$$SU(n) = \{ A \in U(n) \mid \det A = 1 \}$$

$$\det(AA^\dagger) = (\det A)(\det A^*) = 1$$

$$|\det A| = 1$$

def. by bilinear form: $\underbrace{AA^T}_{\dots} = 1$ generalized.

4 indefinite orthogonal group.

$$O(p, q) := \{ A \in GL(p+q, \underline{\mathbb{R}}) \mid A^T J_{p,q} A = J_{p,q} \}$$

$$J_{p,q} = \left(\begin{array}{c|c} -I_p & 0 \\ \hline 0 & I_q \end{array} \right)$$

Lorentz group $O(1, d)$ $d+1$ space-time

5 Symplectic group.

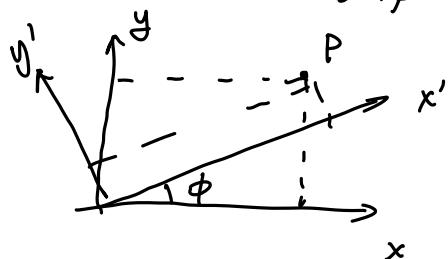
$$Sp(2n, k) := \{ A \in GL(2n, k) \mid A^T J A = J \}$$

$$J = \left(\begin{array}{c|c} 0 & I_n \\ \hline -I_n & 0 \end{array} \right) \quad \underline{J = J^* = -J^T = -J^{-1}}$$

Remarks :

1. $SO(2, \mathbb{R}) \ni g = \begin{pmatrix} a & b \\ -b & a \end{pmatrix} \quad a^2 + b^2 = 1$

$R(\phi_1) R(\phi_2) = R(\phi_1 + \phi_2) \Leftarrow R(\phi) = \begin{pmatrix} \cos \phi & \sin \phi \\ -\sin \phi & \cos \phi \end{pmatrix} \equiv e^{\phi J} \quad J = \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix}$



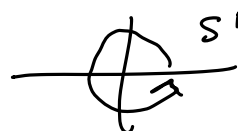
$$x' = \cos \phi x + \sin \phi y$$

$$y' = -\sin \phi x + \cos \phi y$$

2. $U(1) : z(\phi) = e^{i\phi} \quad z(\phi_1) z(\phi_2) = z(\phi_1 + \phi_2)$

$SO(2) \cong U(1)$

$\mu_N \cong \mathbb{Z}_N$



3. $SU(2) \quad g = \begin{pmatrix} z & -\omega^* \\ \omega & z^* \end{pmatrix} \quad (z)^2 + (\omega^2) = 1$

$$z = x_0 + i x_1$$

$$\omega = x_2 + i x_3$$

$$\sum_{i=0}^3 x_i^2 = 1 \quad \rightarrow S^3$$

4. $SU(3) \quad 8\text{-dim}$

" S^3 -bundle over S^5 "

5. $Sp(2n, \mathbb{K}) \quad A^T J A = J \quad (\det A)^2 = 1 \Rightarrow \det A = \pm 1$

"Pfaffian". $Pf(A^T J A) = (\det A) \cdot Pf(J) \Rightarrow \det A = 1$
"Pf(J)"

