

Yimeng Li

Residence/domicile: Omaha, NE

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CS Ph.D. specializing in machine learning, robotics, and computer vision, with a proven track record of impactful research and publications.

Experienced Senior Software Engineer adept at developing large-scale systems.

Collaborative team player committed to fostering a respectful and innovative work environment.

Skills

- Proficient in Python, C++, Java, C, SQL
- Proficient with version control systems: Git
- Proficient of machine learning frameworks: PyTorch, Numpy, Pandas, Tensorflow, AWS, Pytorch3d, OpenCV, Scikit-learn, SciPy, Pandas, Keras, Numpy, Docker
- Proficient of machine learning models: CNNs, RNNs, GNNs, Transformers, GANs, Logistic regression, Ensemble learning, Random Forest, ANN, SVM, Naive Bayes, K-means clustering, and PCA.
- Familiar with full-stack development: HTML, CSS, JS, React

Work Experience

Senior Software Engineer

Schnackel Engineers

Jan 2024 - Present

Omaha, Nebraska

- Led the development of end-to-end algorithms to enhance CAD automation, incorporating extensive floating-point math and data structure manipulation for efficient solutions in C#.

Software Engineering Intern

United Imaging Intelligence

May 2021 - August 2021

Boston, Massachusetts

- Developed an end-to-end model to estimate 3D human joint locations in the world frame from images captured by cameras at four predefined viewpoints on the human36M dataset.

Research Intern

Honda Research Institute, US

June 2020 - August 2020

San Jose, California

- Conducted research on BEV object detection using RGB image and frontal depth image from stereo images on the KITTI dataset.
- Developed a novel approach that aimed at adapting to multiple 2D object detection inputs and different depth estimation methods for accurate BEV object detection in complex driving scenarios.

Research Intern

AFRL Mathematical Modeling and Optimization Institute

May 2018 - August 2018

Shalimar, Florida

- Conducted research on aerial object detection using Fast R-CNN in PyTorch, trained and fine-tuned models on the xView dataset.
- Optimized hyperparameters, performed data preprocessing and analyzed experimental results to achieve state-of-the-art performance.

Research Assistant to Prof. Jana Kosecka

Computer Vision and Robotics Lab

Department of Computer Science, George Mason University

September 2016 - Present

- Conducted in-depth research utilizing advanced deep-learning techniques to enable robots to navigate and interact with household objects in residential environments autonomously.

- Proposed and implemented a novel exploration approach using learning-augmented model-based planning for time-limited robotic exploration in previously unseen environments.
- Developed a framework utilizing unmanned aerial systems (UASs) for monitoring fall hazard prevention systems near unprotected edges and openings in high-rise buildings.

Teaching Assistant

Department of Computer Science

September 2016 - Present
George Mason University

- Instructed lab sessions for 'Intro to Python' and 'Intro to C' courses, guiding students in understanding programming concepts, debugging code, and completing assignments.
- Redesigned assignments for the 'Intro to AI' course, incorporating new concepts to enhance students' understanding of AI and setting up an auto-grading environment to streamline grading.
- Developed project assignments for image multi-class classification and object detection for the 'Deep Learning for Computer Vision' course, including creating the skeleton code framework and providing clear instructions to students.

Software Engineer

Third Research Institute of Ministry of Public

June 2014 - July 2016
Shanghai, China

- Designed and implemented an image classification system in C++ that selects candidate images from the TRECVID dataset, a widely used benchmark dataset for multimedia content retrieval.
- Developed the system to work on distributed systems, leveraging parallel processing and distributed computing techniques for efficient and scalable image classification.

Education

PhD in Computer Science

George Mason University, Fairfax, VA

2016 - 2023

Master of Science in Computer Science

George Mason University, Fairfax, VA

2016 - 2018

Bachelor of Engineering in Software Engineering

East China Normal University, Shanghai, China

2010 - 2014

Other Experience

Reviewer

2020 - Present

- Served as reviewer for journals: IEEE-Intelligent Systems, IEEE-RAL, IEEE-TITS
- Served as reviewer for conferences: ICRA, IROS, CVPR, ICCV, WACV, ACCV, PR

Personal

- Work Authorization: STEM OPT. Will need H1B sponsorship.
- Languages: English (Professional), Chinese (Native)

Publications

- Yimeng Li and Arnab Debnath and Gregory J. Stein and Jana Kosecka. *Learning-Augmented Model-Based Planning for Visual Exploration*. IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS), 2023
- Yimeng Li and Arnab Debnath and Gregory J. Stein and Jana Kosecka. *Comparison of Model Free and Model-Based Learning-Informed Planning for PointGoal Navigation*. CoRL 2022 Workshop on Learning, Perception, and Abstraction for Long-Horizon Planning, 2022.

- Yimeng Li and Jana Kosecka. *Uncertainty Aware Proposal Segmentation for Unknown Object Detection*. Proceedings of the IEEE/CVF Winter Conference on Applications of Computer Vision (WACV), 2022.
- Yimeng Li and Jana Kosecka. *Learning View and Target Invariant Visual Servoing for Navigation*. IEEE International Conference on Robotics and Automation (ICRA), 2020.