# YIMENG LI

#### EDUCATION

2016-Present PhD, Computer Science

George Mason University, Fairfax, VA, USA

Research Interests: Robotics, Computer Vision

2016-2018 MS. Computer Science

George Mason University, Fairfax, VA, USA

2010-2014 **BE**, Software Engineering

East China Normal University, Shanghai, China

## EXPERIENCES

2016-Present Lab Research

Computer Vision and Robotics Lab

Department of Computer Science, George Mason University

2018 Summer Research Intern

AFRL Mathematical Modeling and Optimization Institute, FL

2016-2018 **Graduate Teaching Assistant** 

CS112: Introduction to Programming - Python

Department of Computer Science, George Mason University

2014-2016 Software Engineer

The 3rd Research Institute of China Ministry, Shanghai, China

2013-2014 Research Intern

The 3rd Research Institute of China Ministry, Shanghai, China

#### Research Projects

2018-Present Robot Navigation on Simulated Environments

Using deep learning techniques to train a robot to do short-

range and long-range visual navigation.

2019 Summer Guard Rail Detection on Building Images

> Doing guard rail detection on high-resolution images of buildings under construction. This project motivates from auto-

matic safety inspection for building construction.

2018 Summer Object Detection on Aerial Images

> Doing fine-grained object detection on xView dataset. Object classes include various engineering machines and multi-

functional buildings.

**Amazon Robotics Challenge** 2017 Summer

Part of the GMU-BGU team. Responsible for detecting both

the known and the unknown sets of objects.

# Paper

2020 **Y. Li**, J. Kosecka

"Learning View and Target Invariant Visual Servoing for Navigation" ICRA 2020

### Preprints

2020 G. Georgakis, **Y. Li**, J. Kosecka "Simultaneous Mapping and Target Driven Navigation" arXiv:1911.07980

# COMPUTER SKILLS

 $\begin{array}{ccc} \mathrm{PL} & \mathrm{C/C++,\,Python,\,Java} \\ \mathrm{OTHER} & \mathrm{OpenCV},\,\mathrm{PyTorch},\,\mathrm{Matlab} \end{array}$