

Numerical Optimization in Robotics homework 1 Hints



主讲人 Jinqi Jiang

Bachelor in Control Science&Engineering Harbin Institute of Technology (HIT)



Gradient



$$f(x_1, x_2) = 100(x_1^2 - x_2)^2 + (x_1 - 1)^2$$

$$\nabla f(x_1, x_2) = \begin{bmatrix} 400x_1^3 - 400x_1x_2 + 2x_1 - 2\\ 200(x_2 - x_1^2) \end{bmatrix}$$

$$\nabla^2 f(x_1, x_2) = \begin{bmatrix} 1200x_1^2 - 400x_2 + 2 & -400x_1 \\ -400x_1 & 200 \end{bmatrix}$$

Algorithm

end



算法 1: Steepest Gradient Descent with Armijo Condition

```
k := 0, c := c_0, \mathbf{x} := \mathbf{x}_0, found := false;
while not found do
       \mathbf{g} := \nabla f(\mathbf{x});
       if ||\mathbf{g}|| < \epsilon then
              found := true;
       else
             \alpha := 1, \mathbf{x}_{new} := \mathbf{x} - \alpha \mathbf{g};
             while f(\mathbf{x}_{new}) > f(\mathbf{x}) - c\alpha \mathbf{g}^{\mathsf{T}} \mathbf{g} d\mathbf{o}
                 \alpha := \alpha/2, \mathbf{x}_{new} := \mathbf{x} - \alpha \mathbf{g};
              end
             \mathbf{x} := \mathbf{x}_{new}, k := k + 1;
       end
```

Suggestion



- You should try different parameters to find an optimal combination for your program to get a better performance.
- It is a great method to visiualize your function as well as the workflow of the optimization, then you will discover why the SGD method performance poor or Newton method can not handle the peoblem with some specific Initial value.
- The most important thing is that you have to check if your homework is submitted in the required format.

在线问答







感谢各位聆听 Thanks for Listening

