

# Support Vector Machines

(ISLR 9.1-9.4)

Yingbo Li

Southern Methodist University

STAT 4399

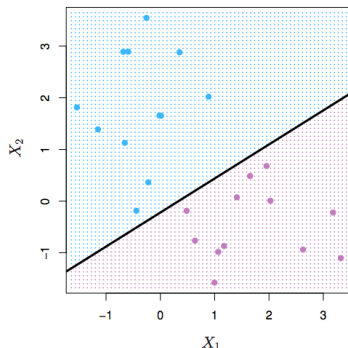
# Outline

- 1 Maximal Margin Classifier
- 2 Support Vector Classifier
- 3 Support Vector Machine

# Support Vector Machines

Here we approach the two-class classification problem in a direct way:

*We try and find a plane that separates the classes in predictor space.*



If we cannot, we get creative in two ways:

- Soften what we mean by “separates”, and
- Enrich and enlarge the predictor space so that separation is possible.

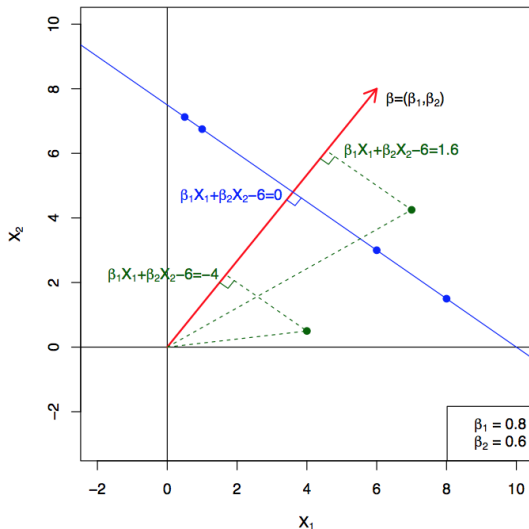
# Hyperplane

- A *hyperplane* in  $\mathbb{R}^p$  is a flat affine subspace of dimension  $p - 1$ .
- Equation for a hyperplane:

$$\beta_0 + \beta_1 X_1 + \beta_2 X_2 + \cdots + \beta_p X_p = 0$$

- ▶ If  $\beta_0 = 0$ , the hyperplane goes through the origin, otherwise not.
  - ▶ The vector  $\beta = (\beta_1, \beta_2, \dots, \beta_p)$  points in a direction orthogonal to the surface of a hyperplane.
  - ▶ In  $p = 2$  dimensions, a hyperplane is a line.
- Let  $f(X) = \beta_0 + \beta_1 X_1 + \beta_2 X_2 + \cdots + \beta_p X_p$ .
  - ▶ If  $f(X) > 0$ , then the point  $X$  lies on one side of the hyperplane,
  - ▶ if  $f(X) < 0$ , then the point  $X$  lies on the other side of the hyperplane.

# A Hyperplane in $p = 2$ Dimensions



# Separating Hyperplane

- For a binary response, we label a “yes” as  $+1$ , and a “no” as  $-1$ .
- If there exists a hyperplane  $f(X) = 0$  such that

$$f(X_i) \begin{cases} > 0 & \text{if } y_i = 1 \\ < 0 & \text{if } y_i = -1, \end{cases}$$

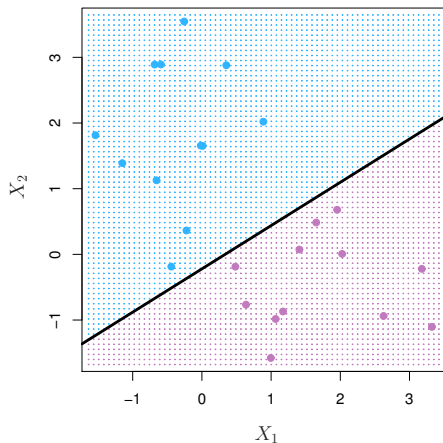
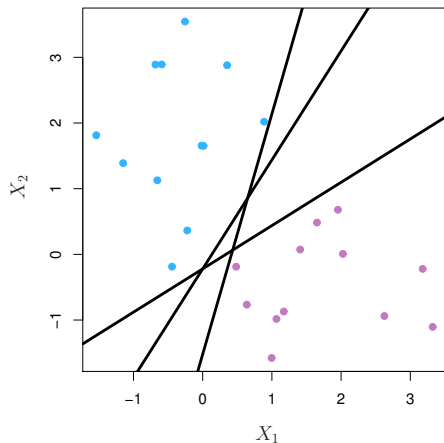
then we say  $f(X) = 0$  is a *separating hyperplane*.

- Equivalently,  $f(X) = 0$  is a separating hyperplane if

$$y_i f(X_i) > 0, \quad \text{for all } i = 1, 2, \dots, n.$$

- If a separating hyperplane exists, we can use it to construct a very natural classifier: a test observation is assigned a class depending on which side of the hyperplane it is located.
- *Magnitude* of an observation  $x^*$  is  $f(x^*)$ : sign, absolute value

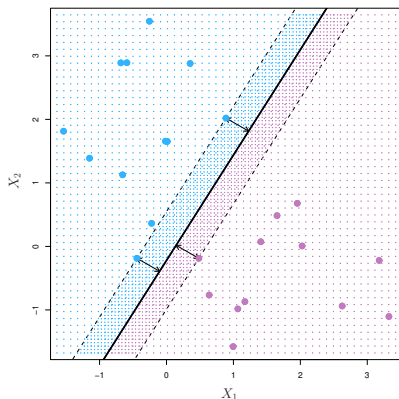
# A Example of Separating Hyperplanes in $\mathbb{R}^2$



Blue:  $y = 1$ , Purple:  $y = -1$

# The Maximal Margin Classifier

- *Margin*: the minimal distance from the points to the hyperplane.
- *Maximal Margin Classifier*: among all separating hyperplanes, the one that makes the biggest margin (i.e., gap between the two classes).



## Terminologies

- Maximal margin hyperplane: the solid line
- Support vectors: points on the dashed lines
- Margin: the distance from either dashed line to the solid line



# Finding the Maximal Margin Classifier

For a dataset, if there exist separating hyperplanes, then we can construct of the Maximal Margin Classifier by solving an optimization question:

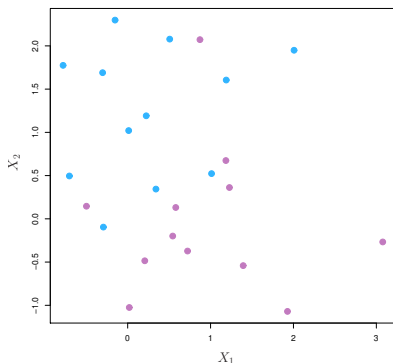
$$\begin{aligned} & \max_{\beta_0, \beta_1, \dots, \beta_p} M \\ & \text{subject to } \sum_{j=1}^p \beta_j^2 = 1 \\ & y_i(\beta_0 + \beta_1 x_{i1} + \dots + \beta_p x_{ip}) \geq M, \text{ for } i = 1, 2, \dots, n. \end{aligned}$$

- The perpendicular distance from the  $i$ th observation to the hyperplane is

$$y_i(\beta_0 + \beta_1 x_{i1} + \dots + \beta_p x_{ip}).$$

- $M$  represents the margin of the hyperplane

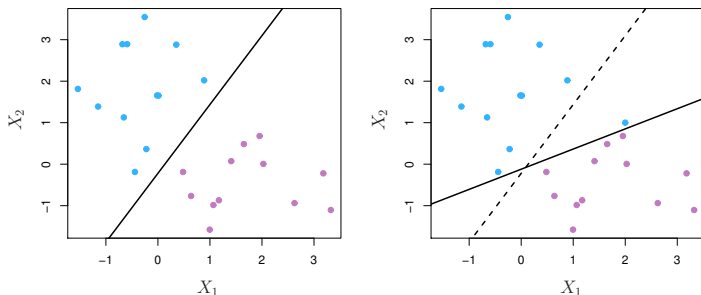
# Non-separable Data



- For this dataset, there does not exist a separating hyperplane.
- This is often the case, unless  $p > n$ .

# Maximal Marginal Classifier is Unstable

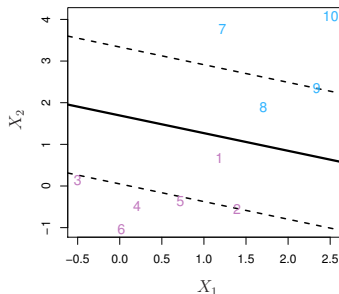
- The maximal margin hyperplane is extremely sensitive to a change in a single observation, so it may have overfit the training data.



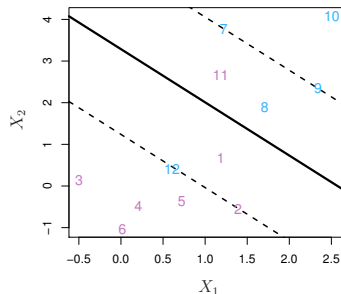
- It is worthwhile to misclassify a few training observations in order to do a better job in classifying the remaining observations.

# Support Vector Classifier

- The support vector classifier maximizes a soft margin.
- An observation can be not only on the wrong side of the margin, but also on the wrong side of the hyperplane.



Wrong side of the margin  
Observation 1, 8



Wrong side of the hyperplane  
Observation 11, 12

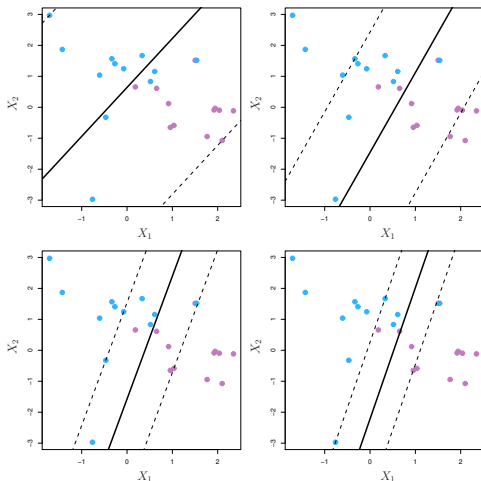
# Support Vector Classifier Solution

$$\begin{aligned}
 & \max_{\beta_0, \beta_1, \dots, \beta_p, \epsilon_1, \dots, \epsilon_n} M \\
 & \text{subject to } \sum_{j=1}^p \beta_j^2 = 1 \\
 & y_i(\beta_0 + \beta_1 x_{i1} + \dots + \beta_p x_{ip}) \geq M(1 - \epsilon_i) \\
 & \epsilon_i \geq 0, \quad \sum_{i=1}^n \epsilon_i \leq C.
 \end{aligned}$$

- $\epsilon_1, \dots, \epsilon_n$ : slack variables that allow individual observations to be on the wrong side of the margin or the hyperplane
  - ▶  $\epsilon_i = 0$ : on the correct side of the margin
  - ▶  $\epsilon_i > 0$ : on the wrong side of the margin
  - ▶  $\epsilon_i > 1$ : on the wrong side of the hyperplane
- $C$ : a nonnegative tuning parameter.

# $C$ is a Regularization Parameter

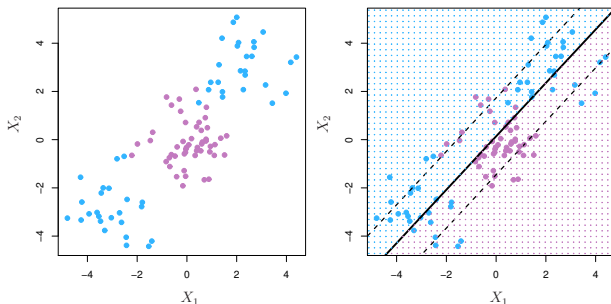
- A budget for the amount that the margin can be violated.
- Small  $C$ : narrow margins, few violations, highly fitting



- *Support vectors*: observations that lie directly on the margin, or on the wrong side of the margin.
- Support vector classifier's decision rule is based only on the support vectors: it is quite robust to the observations that are far away from the hyperplane.

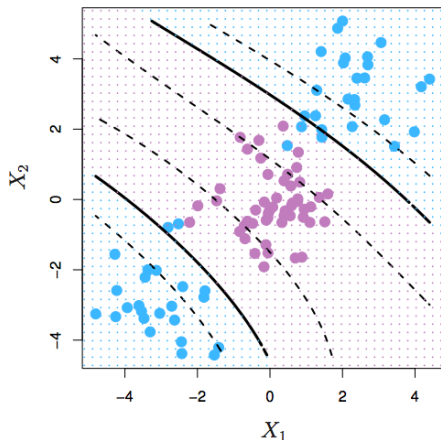
# Feature Expansion

Linear boundary can fail



- Enlarge the space of features (predictors) by including transformations; e.g.  $X_1^2, X_1^3, X_1X_2, \dots$
- Fit a support-vector classifier in the enlarged space.
- This results in non-linear decision boundaries in the original space.

# Cubic Polynomials



- We use a basis expansion of cubic polynomials
- The support-vector classifier in the enlarged space solves the problem in the lower-dimensional space
- Polynomials (especially high-dimensional ones) get wild rather fast.
- There is a more elegant and controlled way to introduce nonlinearities in support-vector classifiers — through *kernels*.

$$\beta_0 + \beta_1 X_1 + \beta_2 X_2 + \beta_3 X_1^2 + \beta_4 X_2^2 + \beta_5 X_1 X_2 + \beta_6 X_1^3 + \beta_7 X_2^3 + \beta_8 X_1^2 X_2 + \beta_9 X_1 X_2^2 = 0$$



# Kernels Representation of the Support Vector Classifier

- *Inner products* between vectors:

$$\langle x_i, x_{i'} \rangle = \sum_{j=1}^n x_{ij} x_{i'j}$$

- The linear support vector classifier can be represented as

$$f(x) = \beta_0 + \sum_{i=1}^n \alpha_i \langle x, x_i \rangle$$

To estimate the parameters  $\beta_0, \alpha_1, \dots, \alpha_n$ , all we need are the inner products  $\langle x_i, x_{i'} \rangle$  between all pairs of training observations.

- Actually, it turns out that most of the  $\alpha_i$  can be zero:

$$f(x) = \beta_0 + \sum_{i \in \mathcal{S}} \alpha_i \langle x, x_i \rangle,$$

where  $\mathcal{S}$  is the set of support vectors.

# Kernels and Support Vector Machines

- We can replace the inner product  $\langle x_i, x_{i'} \rangle$  in SV classifier with a generalization of the form  $K(x_i, x_{i'})$ , i.e., a *kernel* function.
  - ▶ For example, a polynomial kernel of degree  $d$ :

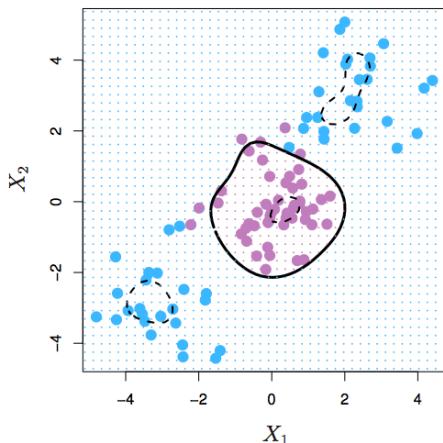
$$K(x_i, x_{i'}) = \left( 1 + \sum_{j=1}^p x_{ij} x_{i'j} \right)^d$$

- The solution has the form

$$f(x) = \beta_0 + \sum_{i \in \mathcal{S}} \alpha_i K(x, x_i).$$

- When the support vector classifier is combined with a non-linear kernel, the resulting classifier is known as a *support vector machine*.

# A Common Choice: the Radial Kernel



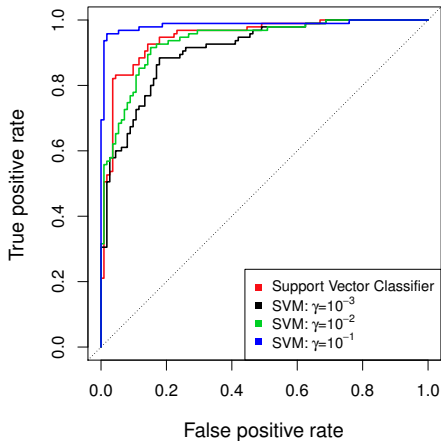
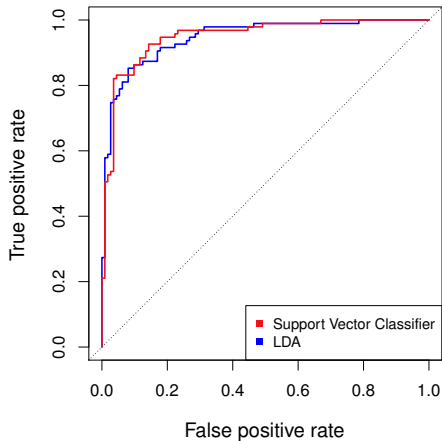
- *Radial kernel*

$$K(x_i, x_{i'}) = e^{-\gamma \sum_{j=1}^p (x_{ij} - x_{i'j})^2}$$

- Implicit feature space; very high dimensional.
- As  $\gamma$  increases and the fit becomes more non-linear.
- Use CV to decide the tuning parameter  $\gamma$ .

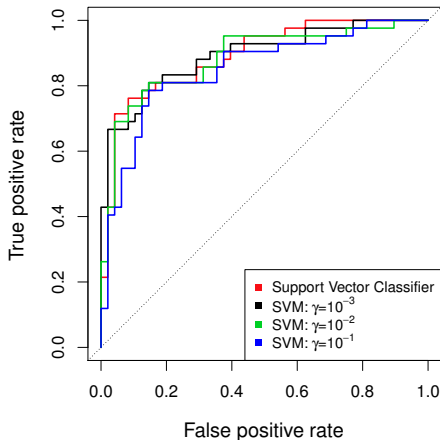
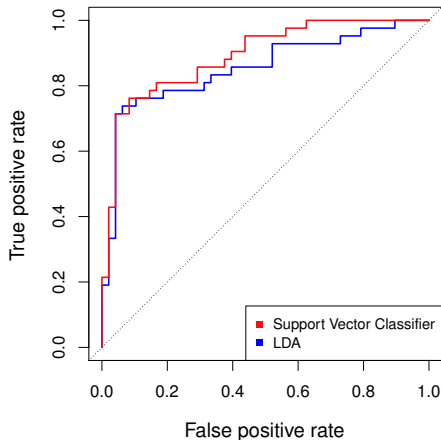
# The Heart Data Example

## Training data ROC curves



# The Heart Data Example

## Test data ROC curves



# SVMs: More Than Two Classes?

Two ways if we have  $K > 2$  classes in the response:

- One versus All.  
Fit  $K$  different 2-class SVM classifiers  $\hat{f}_k(x), k = 1, \dots, K$ ; each class versus the rest. Classify  $x^*$  to the class for which  $\hat{f}_k(x^*)$  is largest.
- One versus One.  
Fit all  $\binom{K}{2}$  pairwise classifiers  $\hat{f}_{kl}(x)$ . Classify  $x^*$  to the class that wins the most pairwise competitions.

Which to choose? If  $K$  is not too large, use OVO.