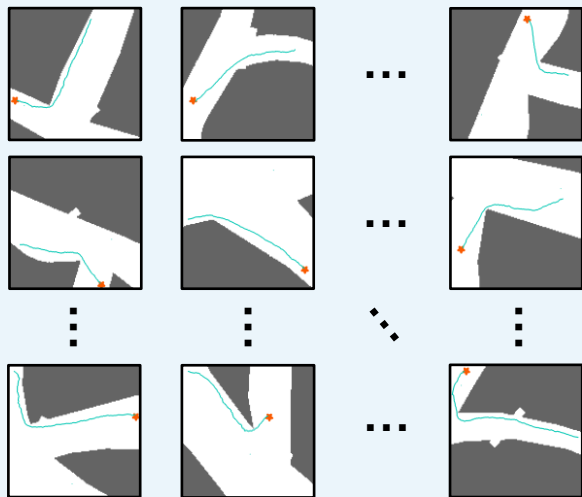


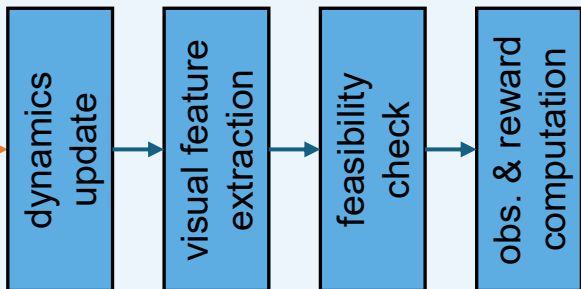
Large-scale simulation environment

parallel simulation



↑ visualization

fully-vectorized modules



robot position

target position

LiDAR scan

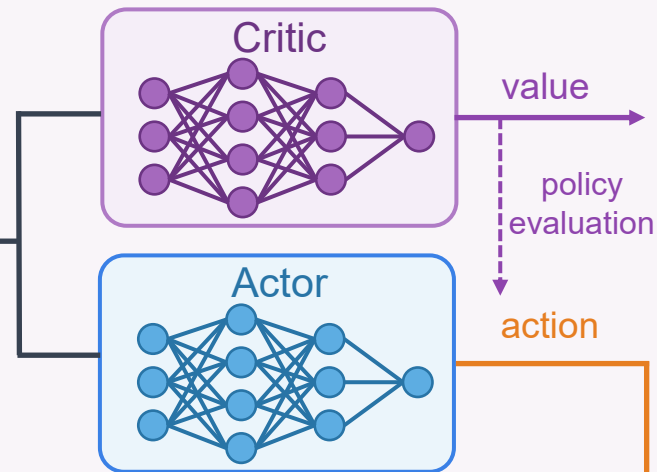


last action

observation

reward

Train using PPO



navigation
command

