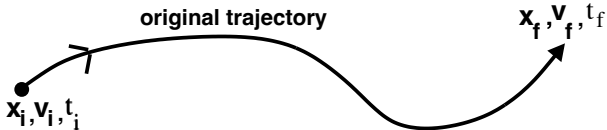


original trajectory



time reversed trajectory

