# Identify shortcomings of Estimators of Discriminative Performance in Time-to-Event Analyses: A Comparison Study

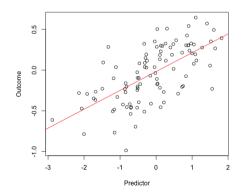
Ying Jin, Andrew Leroux

#### Question

If the evaluation metric reveals perfect out-of-sample performance of the underlying model, should we conclude that the model fits the population well?

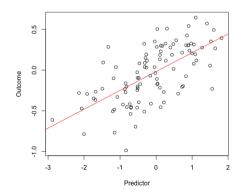
#### Example

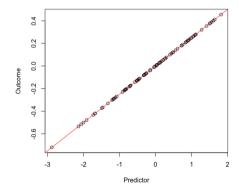
A linear regression model with out-of-sample  $R^2 = 1$  or MSE = 0?



#### Example

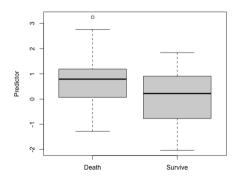
A linear regression model with out-of-sample  $R^2 = 1$  or MSE = 0?





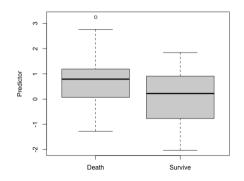
#### Example

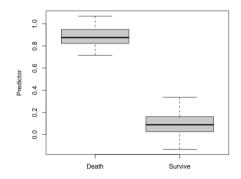
A logistic regression model with out-of-sample AUC = 1, indicating perfect separation?



#### Example

A logistic regression model with out-of-sample AUC = 1, indicating perfect separation?





#### Alert

This can actually happen when we have noisy or abnormal observations!

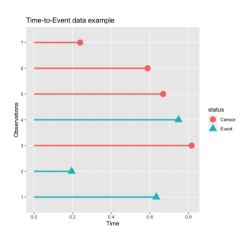
- Example: With the same model, adding one outlier inflates the AUC estimates to 1
- Estimator does not reflect true prediction performance of model

Incident/Dynamic ROC Curve at a single time point Comparing Estimated Results when Adding in A Single Outlier True Positive Rate Model TOTIQINAL data Original data with 1 Outlier 0.25 AUC = 0.998AUC = 0.811 0.00

False Positive Rate

0.00

#### Time-to-event data



- Observed outcomes include timing and occurrence of a specific event.
   e.g. death, disease onset, relapse, etc.
- Observations are usually subject to right censoring, which means event has not happened until censoring time, but no information is available after censoring.
   e.g. Fixed follow-up period, patient dropout, etc

## **Notation**

- let i = 1...N indicates individuals
- For each individual,  $T_i^*$  is true event time subject to independent right censoring;  $C_i$  is censoring time
- Observed time  $T_i = min(T_i^*, C_i)$ ; observed status  $\delta_i = I(T_i^* < C_i)$
- Observed covariate  $\boldsymbol{X}_i = (X_{i1},...X_{ip})^t$ ; risk score  $\eta_i = \boldsymbol{X}_i^t \boldsymbol{\beta}$
- Assume survival time is associated with risk score through a proportional hazard model as follows:

$$\log \lambda_i(t|\boldsymbol{X}_i) = \log \lambda_0(t) + \boldsymbol{X}_i^t \boldsymbol{\beta} , \quad t > 0$$
  
=  $\log \lambda_0(t) + \eta_i$ 

where  $\lambda_0(t)$  is constant across population

 We aim to evaluate discriminative performance of models, which is the ability to predict timing of event with covariates

We use Incident/dynamic AUC to measure discriminative performance of a model. At a specific time t and a fixed threshold of risk score c:

Incident sensitivity

$$\mathsf{sensitivity}^{\mathbb{I}}(c,t) = \mathsf{TP}^{\mathbb{I}}_t(c) = \mathsf{Pr}(\eta_i > c | T_i^* = t)$$

We use Incident/dynamic AUC to measure discriminative performance of a model. At a specific time t and a fixed threshold of risk score c:

Incident sensitivity

$$\mathsf{sensitivity}^{\mathbb{I}}(c,t) = \mathsf{TP}^{\mathbb{I}}_t(c) = \mathsf{Pr}(\eta_i > c | T_i^* = t)$$

Dynamic specificity

$$1-\mathsf{specificity}^{\mathbb{D}}(c,t)=\mathsf{FP}^{\mathbb{D}}_t(c)=1-\mathsf{Pr}(\eta_i\leq c|\,T_i^*>t)$$

We use Incident/dynamic AUC to measure discriminative performance of a model. At a specific time t and a fixed threshold of risk score c:

• Incident sensitivity

$$\mathsf{sensitivity}^{\mathbb{I}}(c,t) = \mathsf{TP}^{\mathbb{I}}_t(c) = \mathsf{Pr}(\eta_i > c | T_i^* = t)$$

• Dynamic specificity

$$1 - \mathsf{specificity}^{\mathbb{D}}(c, t) = \mathsf{FP}^{\mathbb{D}}_t(c) = 1 - \mathsf{Pr}(\eta_i \le c | T_i^* > t)$$

• For all possible thresholds c:  $\mathsf{ROC}^{\mathbb{I}/\mathbb{D}}_t(p) = \mathsf{TP}^{\mathbb{I}}_t\{[\mathsf{FP}^{\mathbb{D}}_t]^{-1}(p)\}$ 

We use Incident/dynamic AUC to measure discriminative performance of a model. At a specific time t and a fixed threshold of risk score c:

Incident sensitivity

$$\mathsf{sensitivity}^{\mathbb{I}}(c,t) = \mathsf{TP}^{\mathbb{I}}_t(c) = \mathsf{Pr}(\eta_i > c | T_i^* = t)$$

• Dynamic specificity

$$1 - \mathsf{specificity}^{\mathbb{D}}(c, t) = \mathsf{FP}^{\mathbb{D}}_t(c) = 1 - \mathsf{Pr}(\eta_i \le c | T_i^* > t)$$

- For all possible thresholds c:  $\mathsf{ROC}_t^{\mathbb{I}/\mathbb{D}}(p) = \mathsf{TP}_t^{\mathbb{I}}\{[\mathsf{FP}_t^{\mathbb{D}}]^{-1}(p)\}$
- Incident/dynamic AUC:  $\mathsf{AUC}^{\mathbb{I}/\mathbb{D}}(t) = \int_0^1 \mathsf{ROC}_t^{\mathbb{I}/\mathbb{D}}(p) dp$

#### **Estimands: Concordance**

We use concordance to measure descriminative performance of model over the entire follow-up period:

Concordance

$$C = \Pr(\eta_i < \eta_j | T_i^* > T_j^*)$$
.

#### **Estimands: Concordance**

We use concordance to measure descriminative performance of model over the entire follow-up period:

Concordance

$$C = \Pr(\eta_i < \eta_j | T_i^* > T_j^*)$$
.

Concordance subject to administrative censoring

$$C^{\tau} = \Pr(\eta_i < \eta_j | T_i^* > T_j^*, T_j^* < \tau),$$

where au is the end of follow-up period

## **Estimands: Concordance**

We use concordance to measure descriminative performance of model over the entire follow-up period:

Concordance

$$C = \Pr(\eta_i < \eta_j | T_i^* > T_i^*) .$$

• Concordance subject to administrative censoring

$$C^{\tau} = \Pr(\eta_i < \eta_j | T_i^* > T_j^*, T_j^* < \tau),$$

where  $\tau$  is the end of follow-up period

Concordance by integrating AUC

$$\mathsf{C}^{ au} = \int_0^{ au} \mathsf{AUC}^{\mathbb{I}/\mathbb{D}}(t) w^{ au}(t) dt$$

where 
$$w^{\tau}(t) = 2f(t)S(t)/1 - S^{2}(\tau)$$

- Now let's talk about ways to estimator these evaluation metrics.
- Many estimators proposed, roughly categorized as semi-parametric and non-parametric.
- Semi-parametric estimators suffer from out-of-sample inflation
- Non-parametric estimators are highly variable

Incident/dynamic AUC: at time t and a specific threshold for risk threshold c,

• Dynamic False-positive rate

$$\widehat{\mathsf{FP}}^{\mathbb{D}}_t(c) = \frac{\sum_k I(\eta_k > c)I(T_k > t)}{\sum_j I(T_j > t)}$$

Incident/dynamic AUC: at time t and a specific threshold for risk threshold c,

Dynamic False-positive rate

$$\widehat{\mathsf{FP}}_t^{\mathbb{D}}(c) = \frac{\sum_k I(\eta_k > c)I(T_k > t)}{\sum_j I(T_j > t)}$$

Incident True-positive rate:
 Non-parametric:

$$\widehat{\mathsf{TP}}_t^{\mathbb{I}}(c) = \frac{\sum_k I(\eta_k > c)I(T_k = t)}{\sum_j I(T_j = t)}$$

Incident/dynamic AUC: at time t and a specific threshold for risk threshold c,

Dynamic False-positive rate

$$\widehat{\mathsf{FP}}_t^{\mathbb{D}}(c) = \frac{\sum_k I(\eta_k > c)I(T_k > t)}{\sum_j I(T_j > t)}$$

Incident True-positive rate:
 Non-parametric:

$$\widehat{\mathsf{TP}}_t^{\mathbb{I}}(c) = \frac{\sum_k I(\eta_k > c)I(T_k = t)}{\sum_i I(T_i = t)}$$

Semi-parametric [Heagerty and Zheng, 2005]:

$$\widehat{\mathsf{TP}}_t^{\mathbb{I}}(c) = \frac{\sum_k I(\eta_k > c) I(T_k \ge t) \mathsf{exp}(\eta_k)}{\sum_j I(T_j \ge t) \mathsf{exp}(\eta_j)}$$

#### Concordance:

• Integrating  $\mathsf{AUC}^{\mathbb{I}/\mathbb{D}}(t)$  estimates

$$\mathsf{C}^{ au} = \int_0^ au \mathsf{AUC}^{\mathbb{I}/\mathbb{D}}(t) w^ au(t) dt$$

Requires estimates of  $\mathsf{AUC}^{\mathbb{I}/\mathbb{D}}(t),\ S(t)$  and f(t)

#### Concordance:

• Integrating  $\mathsf{AUC}^{\mathbb{I}/\mathbb{D}}(t)$  estimates

$$\mathsf{C}^{ au} = \int_0^ au \mathsf{AUC}^{\mathbb{I}/\mathbb{D}}(t) w^ au(t) dt$$

Requires estimates of AUC $^{\mathbb{I}/\mathbb{D}}(t)$ , S(t) and f(t)

• Gonen-Heller [Gonen and Heller, 2005]: semi-parametric

$$C = \frac{2}{n(n-1)} \sum_{i < j} \frac{I(\eta_j - \eta_i < 0)}{1 + exp(\eta_j - \eta_i)} + \frac{I(\eta_i - \eta_j < 0)}{1 + exp(\eta_i - \eta_j)}$$

#### Concordance:

• Integrating  $\mathsf{AUC}^{\mathbb{I}/\mathbb{D}}(t)$  estimates

$$\mathsf{C}^{ au} = \int_0^ au \mathsf{AUC}^{\mathbb{I}/\mathbb{D}}(t) w^ au(t) dt$$

Requires estimates of AUC $^{\mathbb{I}/\mathbb{D}}(t)$ , S(t) and f(t)

• Gonen-Heller [Gonen and Heller, 2005]: semi-parametric

$$C=rac{2}{n(n-1)}\sum_{i< j}rac{I(\eta_j-\eta_i<0)}{1+exp(\eta_j-\eta_i)}+rac{I(\eta_i-\eta_j<0)}{1+exp(\eta_i-\eta_j)}$$

• Harrell's C index: non-parametric

$$C = \frac{\sum_{i < j} I(T_i < T_j) I(\eta_i > \eta_j) I(\delta_i = 1) + I(T_i > T_j) I(\eta_i < \eta_j) I(\delta_j = 1)}{\sum_{i < j} I(T_i < T_j) I(\delta_i = 1) + I(T_i > T_j) I(\delta_j = 1)}$$

## Simulation setup

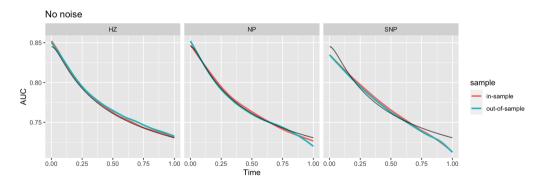
- 1000 simulated data sets with sample size N = 500
- Generate three signals independently from N(0, 1)
- Survival generated from Cox propotional hazard model with Weibull baseline hazard

$$\log \lambda_i(t|X_i) = \log p\theta t^{p-1} + X_{i1}\beta_1 + X_{i2}\beta_2 + X_{i3}\beta_3$$

• Censoring time generated uniformly from (0.5, 1)

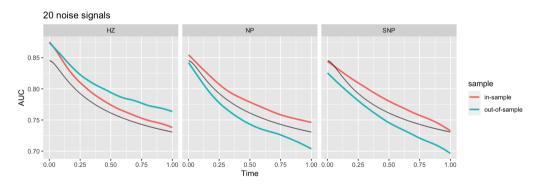
## Results: Incident/Dynamic AUC

Note: Incident/Dynamic AUC is smoothed across all simulation



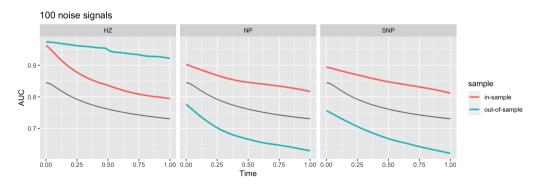
# Results: Incident/Dynamic AUC

Note: Incident/Dynamic AUC is smoothed across all simulation

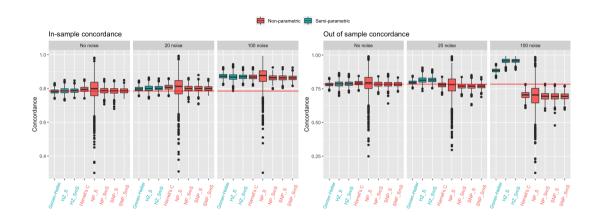


## Results: Incident/Dynamic AUC

Note: Incident/Dynamic AUC is smoothed across all simulation



## **Results: Concordance**



## **Conclusion**

Estimator	Bias	Variability	Inflation with noise
Semi-parametric (HZ)	No bias	Small	Large
Non-parametric (NP)	No bias	Large	No inflation
Smoothed non- parametric (SNP)	Underestimate at edges and overestimate in the middle	Medium	No inflation

Comparision of I/D AUC estimators

## **Conclusion**

Estimator	Bias	Variability	Inflation with noise
Semi-parametric Non-parametric	No bias Overestimation	Small Large	Large No inflation
Non-parametric with smoothed weight	No bias	Medium	No inflation

Comparision of concordance estimators

## **Data Application**

- Data:
  - NHANES 2011-2014
  - 3556 participants age 50-80
  - Analytic dataset
    - Complete data: age, mortality follow-up, BMI, PIR
    - $\bullet$   $\geq$  3 days of accelerometry data with 95% wear
- Goals:
  - Predict time to all-cause mortality using PA features and other covariate data using a complicated mean model
  - Compare estimated in- and out-of-sample performance for discrimination
  - Compare results to a linear regression and  $\hat{R}^2$

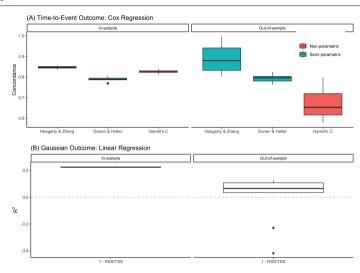
## **Data Application**

- Suppose we have a covariate vector  $[x_{i1}, \dots, x_{i6}]^t = \mathbf{X}_i \in \mathbb{R}^6$
- Models:

Cox Regression: 
$$\log \lambda_i(t|X) = \log \lambda_0(t) + f(\boldsymbol{X}_i)$$
  
Linear Regression:  $E[age_i] = \beta_0 + f(\boldsymbol{X}_i)$ 

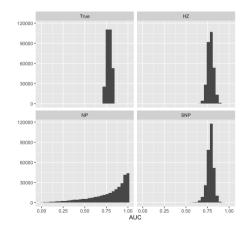
- $f(\cdot)$  is a smooth function of the 5 covariates modelled as a linear combination of 200 (penalized) thin plate regression splines
- 200 coefficients (parameters) with N=3556 will tend to overfit, particularly for non-Gaussian models (e.g. log hazard)

# **Data Application**



#### **Discussion**

- Use ridge regression to reduce overfit
- Mitigate bias of smoothed non-parametric estimator (SNP) of AUC<sup>I/D</sup>(t)
  - Skewed distribution of  $AUC^{\mathbb{I}/\mathbb{D}}(t)$
  - Neither transformation of outcome nor weighted regression by varaince was helpful
  - Bounded regression led to slight improvement
- Smoothness of survival function seems to reduce bias of non-parametric concordance estimator



#### References

- Gonen, M. and Heller, G. (2005).

  Concordance probability and discriminatory power in proportional hazards regression.

  Biometrika, 92(4):965–970.
- Heagerty, P. J. and Zheng, Y. (2005). Survival model predictive accuracy and roc curves. *Biometrics*, 61(1):92–105.
- Uno, H., Cai, T., Pencinac, M. J., D'Agostinod, R. B., and Weib, L. J. (2011). On the c-statistics for evaluating overall adequacy of risk prediction procedures with censored survival data.

Statistics in medicine, 30(10), 1105–1117. https://doi.org/10.1002/sim.4154, 30(10):1105–1117.

# Thank you!