On The Heston Model with Stochastic Interest Rates

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**Abstract**

We discuss the Heston [[Heston-1993](#_bookmark94)] model with stochastic interest rates driven by Hull-White [[Hull,White-1996](#_bookmark95)] (HW) or Cox-Ingersoll-Ross [[Cox,](#_bookmark83) *[et al.](#_bookmark83)*[-1985](#_bookmark83)] (CIR) processes. Two projection techniques to derive affine approximations of the original hybrid models are presented. In these approximations we can prescibe a non-zero correlation structure between all underlying processes. The affine approximate models admit pricing basic derivative products by Fourier techniques [[Carr,Madan-1999](#_bookmark82); [Fang,Oosterlee-2008](#_bookmark88)], and can therefore be used for fast calibration of the hybrid model.

**Key words:** Heston-Hull-White; Heston-Cox-Ingersoll-Ross; equity-interest rate hybrid products; stochastic volatility; affine jump diffusion processes.

# Introduction

Modelling derivative products in Finance usually starts with the specification of a system of Stochastic Differential Equations (SDEs), that correspond to state variables like stock, interest rate and volatility. By correlating the SDEs from the different asset classes one can define so-called hybrid models, and use them for pricing multi-asset derivatives. Even if each of these SDEs yields a closed form solution, a non-zero correlation structure between the processes may cause difficulties for modelling and product pricing. Typically, a closed form solution of the hybrid models is not known, and numerical approximation by means of Monte Carlo (MC) simulation or discretization of the corresponding Partial Differential Equations (PDEs) has to be employed for model evaluation and derivative pricing. The speed of pricing European products is however crucial, especially for the calibration. Several theoretically attractive SDE models, that cannot fulfil the speed requirements, are not used in practice.

The aim of this paper is to define hybrid SDE models that fit in the class of affine diffusion processes (AD), as in Duffie, Pan and Singleton [[Duffie,](#_bookmark86) *[et al.](#_bookmark86)*[-2000](#_bookmark86)]. For processes within this class a closed form solution of the characteristic function exists. Suppose we have given a system of SDEs, i.e.,

d**X**(*t*) = *µ*(**X**(*t*))d*t* + *σ*(**X**(*t*))d**W**(*t*)*.* (1.1)

This system ([1.1](#_bookmark0)) is said to be of the affine form if:

*µ*(**X**(*t*)) = *a*0 + *a*1**X**(*t*)*,* for any (*a*0*, a*1) *∈* R*n ×* R*n×n,* (1.2) *σ*(**X**(*t*))*σ*(**X**(*t*))T = (*c*0)*ij* + (*c*1)T **X**(*t*)*,* for arbitrary (*c*0*, c*1) *∈* R*n×n ×* R*n×n×n,* (1.3) *r*(**X**(*t*)) = *r*0 + *r*T**X**(*t*)*,* for (*r*0*, r*1) *∈* R *×* R*n,* (1.4)

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for *i, j* = 1*, . . . , n*, with *r*(**X**(*t*)) being an interest rate component. Then, the discounted characteristic function (ChF) is of the following form [[Duffie,](#_bookmark86) *[et al.](#_bookmark86)*[-2000](#_bookmark86)]:

Q . . ∫ *T*

*φ*(**u***,* **X**(*t*)*, t, T* ) = E

exp

*−*

*t*

T Σ . Σ

*A*(**u***,τ* )+**B**T(**u***,τ* )**X**(*t*)

= e

*,*

where the expectation is taken under the risk-neutral measure, Q. For a time lag, *τ* := *T t*, the coefficients *A*(**u***, τ* ) and **B**T(**u***, τ* ) have to satisfy the following complex-valued ordinary differential equations (ODEs):

*−*

*r*(*s*)d*s* + *i***u**

**X**(*T* )

*Ft*

2

1

1

(1.5)

 d **B**(**u***, τ* ) = *−r*

d*τ* d

1

1

+ *a*T**B**+ 1 **B**T*c* **B***,*

 d*τ*

*A*(**u***, τ* ) = *−r*0 + **B**T*a*0+

2 **B**T*c*0**B***,*

with *ai, ci, ri, i* = 0*,* 1*,* as in ([1.2](#_bookmark1)), ([1.3](#_bookmark1)) and ([1.4](#_bookmark1)).

In this article we focus our attention specifically on a hybrid model which combines the equity and interest rate asset classes. Brigo and Mercurio [[Brigo,Mercurio-2007](#_bookmark81)] have shown that the assumption of constant interest rates in the classical Black-Scholes model [[Black,Scholes-1973](#_bookmark79)] can be generalized, and by including the stochastic interest rate process of Hull and White [[Hull,White-1996](#_bookmark95)], one is still able to obtain a closed form solution for European-style option prices. Originally, the Black-Scholes-Hull-White model in [[Brigo,Mercurio-2007](#_bookmark81)] was not dedicated to pricing hybrid products, but to increasing the accuracy for long-maturity options. The model is, however, not able to describe any smile and skew shapes present in the equity markets.

In [[Zhu-2000](#_bookmark109)] a hybrid model was presented which could provide a skew pattern for the equity and included a stochastic (but uncorrelated) interest rate process. Generalizations were presented in [[Giese-2006](#_bookmark91)] and [[Andreasen-2006](#_bookmark75)], where the Heston [[Heston-1993](#_bookmark94)] stochastic volatility model was used, and an indirectly correlated interest rate process. Some form of correlation was indirectly modeled by including additional terms in the SDEs (this approach is discussed in some detail in Section [3.1.1](#_bookmark35)).

In [[Grzelak,](#_bookmark92) *[et al.](#_bookmark92)*[-2009](#_bookmark92); [vanHaastrecht,](#_bookmark93) *[et al.](#_bookmark93)*[-2009](#_bookmark93)] the Heston stochastic volatility model was replaced by the Sch¨obel-Zhu [[Sch¨obel,Zhu-1999](#_bookmark107)] model, while the interest rate was still driven by a Hull-White process (SZHW model). In this model a full matrix of correlations can be directly imposed on the driving Brownian motions. The model is well-defined under the class of AD processes, but since the SZHW model is based on a Vaˇsiˇcek-type process [[Vaˇsiˇcek-1977](#_bookmark108)] for the stochastic volatility, the volatilities can become negative.

A different approach to modelling equity-interest rate hybrids was presented by Benhamou *et al.* [[Benhamou,](#_bookmark78) *[et al.](#_bookmark78)*[-2008](#_bookmark78)], extending the local volatility framework of Dupire [[Dupire-1994](#_bookmark85)] and Derman, Kani [[Derman,Kani-1998](#_bookmark84)] and incorporating stochastic interest rates.

Here, we investigate the Heston-Hull-White, and the Heston-Cox-Ingersoll-Ross hybrid models and propose approximations so that we can obtain their characteristic functions. The framework presented is relatively easy to understand and implement. It is inspired by the techniques in [[Giese-2006](#_bookmark91); [Andersen-2008](#_bookmark73)].

Our approximations do not require several preliminary calculations of expectations like in the case of Markovian projection methods [[Antonov-2007](#_bookmark76); [Antonov,](#_bookmark77) *[et al.](#_bookmark77)*[-2008](#_bookmark77)]. The resulting option pricing method benefits greatly from the speed of characteristic function evaluations.

The interest rate models studied here cannot generate implied volatility interest rate smiles or skews. They can therefore mainly be used for long-term equity options, and for ‘not too complicated’ equity-interest rates hybrid products. As described in [[Hunter-2005](#_bookmark96)], for accurate modelling of hybrid derivatives it is necessary to be able to describe a non-zero correlation between equity and interest rate. This is possible in the approximations presented here.

The paper is organized as follows. In Section 2 we discuss the full-scale Heston hybrid models with stochastic interest rate processes. Section 3 presents a deterministic approximation of the Heston-Hull-White hybrid model, together with the corresponding characteristic function, and Section 4 gives the characteristic function based on another, stochastic, approximation of that hybrid model. In Section 5 we deal with the Heston-Cox-Ingersoll- Ross model. In Section 6 the calibration based on the approximations of the full-scale hybrid models is applied. Section 7 concludes. Details of proofs and tests are in appendices, where, in particular, in Appendix [C](#_bookmark118) we compare the performance of the approximations developed with the Markovian projection method studied in [[Antonov-2007](#_bookmark76); [Antonov,](#_bookmark77) *[et al.](#_bookmark77)*[-2008](#_bookmark77)].

# Heston Hybrid Models with Stochastic Interest Rate

With state vector **X**(*t*) = [*S*(*t*)*, v*(*t*)]T, under the risk-neutral pricing measure, the Heston stochastic volatility model [[Heston-1993](#_bookmark94)], which is our point-of-departure, is specified by the following system of SDEs:

d*S*(*t*)*/S*(*t*) = *r*d*t*+ *v*(*t*)d*Wx*(*t*)*, S*(0) *>* 0*,*

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d*v*(*t*) = *κ*(*v*¯ *− v*(*t*))d*t*+ *γ*√*v*(*t*)d*Wv*(*t*)*, v*(0) *>* 0*,*

(2.1)

with *r >* 0 a constant interest rate, correlation d*Wx*(*t*)d*Wv*(*t*) = *ρx,v*d*t*, and *ρx,v <* 1. The variance process, *v*(*t*), of the stock *S*(*t*) is a mean reverting square root process, in which *κ >* 0 determines the speed of adjustment of the volatility towards its theoretical mean, *v*¯ *>* 0, and *γ >* 0 is the second-order volatility, i.e., the volatility of the volatility.

*| |*

As already indicated in [[Heston-1993](#_bookmark94)], the model given in ([2.1](#_bookmark2)) is not in the class of affine processes, whereas under the log transform for the stock, *x*(*t*) = log *S*(*t*), it is. Then, the discounted ChF is given by:

*φ*H(*u,* **X**(*t*)*, τ* ) = exp (*A*(*u, τ* ) + *B*(*u, τ* )*x*(*t*) + *C*(*u, τ* )*v*(*t*)) *,* (2.2)

where the functions *A*(*u, τ* ), *B*(*u, τ* ) and *C*(*u, τ* ) are known in closed form (see [[Heston-1993](#_bookmark94)]).

The ChF is explicit, but also its inverse has to be found for pricing purposes. Because of the form of the ChF, we cannot get its inverse analytically and a numerical method for integration has to be used, see, for example, [[Carr,Madan-1999](#_bookmark82); [Fang,Oosterlee-2008](#_bookmark88); [Lee-2004](#_bookmark99); [Lewis-2001](#_bookmark100)] for Fourier methods.

## 2.1 Full-Scale Hybrid Models

A constant interest rate, *r*, may be insufficient for pricing interest rate sensitive products. Therefore, we extend our state vector with an additional stochastic quantity, i.e.: **X**(*t*) = [*S*(*t*)*, v*(*t*)*, r*(*t*)]T. This model corresponds to a *hybrid stochastic volatility equity model with a stochastic interest rate* process, *r*(*t*). In particular, we add to the Heston model the Hull-White (HW) interest rate [[Hull,White-1996](#_bookmark95)], or the square root Cox-Ingersoll-Ross [[Cox,](#_bookmark83) *[et al.](#_bookmark83)*[-1985](#_bookmark83)] (CIR) process. The extended model can be presented in the following way:

d*v*(*t*) = *κ*(*v*¯ *v*(*t*))d*t*+ *γ v*(*t*)d*Wv*(*t*)*, v*(0) *>* 0*,*

**** d*r*(*t*) = *λ*(*θ*(*t*) *− r*(*t*))d*t*+ *ηrp*(*t*)d*Wr*(*t*)*, r*(0) *>* 0*,*

√

**** d*S*(*t*)*/S*(*t*) = *r*(*t*)d*t*+ √*v*(*t*)d*Wx*(*t*)*, S*(0) *>* 0*,*

*−*

(2.3)

where exponent *p* = 0 in ([2.3](#_bookmark3)) represents the Heston-Hull-White (HHW) model and for *p* = 1

it becomes the Heston-Cox-Ingersoll-Ross (HCIR) model. For both models the correlations are given by d*Wx*d*Wv* = *ρx,v*d*t,* d*Wx*d*Wr* = *ρx,r*d*t*, d*Wv*(*t*)d*Wr*(*t*) = *ρv,r*d*t,* and *κ*, *γ* and *v*¯ are as in ([2.1](#_bookmark2)), *λ >* 0 determines the speed of mean reversion for the interest rate process; *θ*(*t*) is the interest rate term-structure and *η* controls the volatility of the interest rate. We note that the interest rate process in ([2.3](#_bookmark3)) for *p* = 1 is of the same form as the variance process *v*(*t*).

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System ([2.3](#_bookmark3)) is not in the affine form, not even with *x*(*t*) = log *S*(*t*). In particular, the symmetric instantaneous covariance matrix is given by:

*σ*(**X**(*t*))*σ*(**X**(*t*))T = 

 *v*(*t*) *ρx,vγv*(*t*) *ρx,rηrp*(*t*)√√*v*(*t*) 

*∗ γ*2*v*(*t*) *ρr,vγηrp*(*t*)

*∗ ∗ η*2*r*2*p*(*t*)

*v*(*t*)

(3*×*3)



*.* (2.4)

Setting the correlation *ρr,v* to zero would still not make the system affine. Matrix ([2.4](#_bookmark4)) is of the linear form w.r.t. state vector [*x*(*t*) = log *S*(*t*)*, v*(*t*)*, r*(*t*)]T, if two correlations, *ρr,v* and *ρx,r*, are set to zero[1](#_bookmark5). Models with two correlations equal to zero are covered in [[Muskulus,](#_bookmark101) *[et al.](#_bookmark101)*[-2007](#_bookmark101)]. Since for pricing equity-interest rate products a non-zero correlation between stock and interest rate is crucial (see, for example, [[Hunter-2005](#_bookmark96)] ), alternative approximations to the Heston hybrid models need to be formulated, so that correlations can be imposed. Variants

1where we assume positive parameters

are discussed in the sections to follow. These approximate models are evaluated with the help of the Cholesky decomposition of a correlation matrix.

We can decompose a given general symmetric correlation matrix, **C**, denoted by

1 *ρ*1 *ρ*2



**C** = *∗* 1 *ρ*3

*∗ ∗* 1

 *,* (2.5)

as **C** = **LL**T*,* where **L** is a lower triangular matrix with strictly positive entries:

 1 √ 0 0 

**L** =

1

*.* (2.6)





*ρ*1

1 *− ρ*2

.

0



. 2

Σ



*ρ ρ*3 *ρ*2*ρ*1

1*−ρ*1

*√−*2 2

2

*√*

1 *− ρ*2 *−*

2

*ρ*3*−ρ*2*ρ*1

1*−ρ*

1

We can rewrite a system of SDEs in terms of the independent Brownian motions, d**W**(*t*),

˜

with the help of the lower triangular matrix **L**.

Since our main objective is to derive a closed form ChF while assuming a non-zero correlation between the equity process, *S*(*t*), and the interest rate, *r*(*t*), we first assume that the Brownian motions for the interest rate *r*(*t*) and the variance *v*(*t*) are not correlated (the case of a full correlation structure is discussed in detail in Appendix [B](#_bookmark116)).

By exchanging the order of the state variables **X**(*t*) = [*S*(*t*)*, v*(*t*)*, r*(*t*)]T to **X***∗*(*t*) = [*r*(*t*)*, v*(*t*)*, S*(*t*)]T, the HHW and HCIR models in ([2.3](#_bookmark3)) then have *ρ*1 *≡ ρr,v* = 0, *ρ*2 *≡ ρx,r* =*ƒ* 0 and *ρ*3 *≡ ρx,v ƒ*= 0 in ([2.5](#_bookmark6)) and read:

 d*r*(*t*)





 *λ*(*θ*(*t*) *− r*(*t*)) 

*r t*

)

 *ηrp*(*t*) 0 0

  d*W*˜ (*t*) 

*r*

*,*

d*v*(*t*)

*S*(*t*)

=  (¯

( ))

 d + 

0 √ ( ) 0  

 (2.7)

 d *S*(*t*) 

*κ v −*( *v t t*

*γ v t*

 d*W*˜*v* (*t*) 

with *L*1 = *ρx,r*, *L*2 = *ρx,v* and *L*3 = .1 *− ρ*2

*x,v*

*L*1

*v*(*t*) *L*2

*v*(*t*) *L*3

*v*(*t*)

2

*x,r*

√

*− ρ*

d*W*˜*x*(*t*)

√

√

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## Reformulated Heston Hybrid Models

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In the previous section we have seen that for the HHW and HCIR models with a full matrix

of correlations given in ([2.3](#_bookmark3)), the affinity relations [[Duffie,](#_bookmark86) *[et al.](#_bookmark86)*[-2000](#_bookmark86)] are not satisfied, so that

the ChF cannot be obtained by standard techniques.

In order to obtain a well-defined Heston hybrid model with an *indirectly imposed correlation*,

*ρx,r*, we propose the following system of SDEs:

d*S*(*t*)*/S*(*t*) = *r*(*t*)d*t* + *v*(*t*)d*Wx*(*t*) + Ω(*t*)*rp*(*t*)d*Wr*(*t*) + ∆ *v*(*t*)d*Wv*(*t*)*, S*(0) *>* 0*,* (2.8)

with

where



*S*(*t*)



d*v*(*t*) = *κ*(*v*¯ *− v*(*t*))d*t*+ *γ v*(*t*)d*Wv*(*t*)*, v*(0) *>* 0*,*

d*r*(*t*) = *λ*(*θ*(*t*) *− r*(*t*))d*t*+ *ηrp*(*t*)d*Wr*(*t*)*, r*(0) *>* 0*,*

*r t*

)

Ω(*t*)*rp*(*t*)

*v*(*t*) (*ρ*ˆ*x,v* + ∆)

*v*(*t*)

1 *− ρ*ˆ2

*t*

(2.9)

d*Wx*(*t*)d*Wv*(*t*) = *ρ*ˆ*x,v*d*t,* d*Wx*(*t*)d*Wr*(*t*) = 0*,* d*Wv*(*t*)d*Wr*(*t*) = 0*,* (2.10)

*,*

*x,v*

˜

d*Wx*

(2.11)

(*t*)

*r*

where *p* = 0 for HHW and *p* = 1 for HCIR. We have included a function[2](#_bookmark11), Ω(*t*), and a constant

parameter, ∆. Note that we still assume independence between the instantaneous short rate,

*r*(*t*), and the variance process *v*(*t*), i.e., *ρ*ˆ*r,v* = 0.

By exchanging the order of the state variables, to **X***∗*(*t*) = [*r*(*t*)*, v*(*t*)*, S*(*t*)]T, system ([2.8](#_bookmark8)) is given, in terms of the independent Brownian motions, by:

 d*r*(*t*)

 *λ*(*θ*(*t*) *− r*(*t*)) 

 *ηrp*(*t*) 0 0

  d*W*˜ (*t*) 

d*v*(*t*)

=  (¯

( ))

 d +

0 *γ*√*v*(*t*) 0   

 d *S*(*t*) 

*κ v −*( *v t*  √

√ .  

d*W*˜*v* (*t*) 

2which under certain conditions can also be stochastic

In the lemma below we show that the model ([2.8](#_bookmark8)) is equivalent to the full-scale HHW model in ([2.3](#_bookmark3)), with a non-zero correlation *ρ**x,r.*

**Lemma 2.1.** *Model ([2.8](#_bookmark8)) satisfies the system in ([2.3](#_bookmark3)) with non-zero correlation, ρx,r, for:*

Ω(*t*) = *ρ*

*v*(*t*)

*x,r rp*(*t*)

√ *,*

2

*x,v*

*ρ*ˆ

2

*x,v*

= *ρ*

2

*x,r*

+ *ρ*

*,* ∆ = *ρ*

*x,v*

*− ρ*ˆ*x,v*

*,* (2.12)

*where correlation ρ*ˆ*x,v is as in model ([2.8](#_bookmark8)) and ρx,v as in model ([2.3](#_bookmark3)).*

*Proof.* We presented the two models ([2.3](#_bookmark3)) and ([2.8](#_bookmark8)) in terms of the independent Brownian motions, ([2.7](#_bookmark7)) and ([2.11](#_bookmark10)), respectively. By matching the appropriate coefficients in ([2.7](#_bookmark7)) and ([2.11](#_bookmark10)), we find that the following relations should hold:

**** Ω(*t*)*rp*(*t*)*S*(*t*) = *ρx,r*√*v*(*t*)*S*(*t*)*,*

*x,v*

*− ρ*

 .1 *− ρ*ˆ2

√*v*(*t*)*S*(*t*) = .1 *− ρ*2

2

*x,r*

√*v*(*t*)*S*(*t*)*,*

(2.13)

*x,v*

(*ρ*ˆ*x,v* + ∆) *v*(*t*)*S*(*t*) = *ρx,v v*(*t*)*S*(*t*)*.*

**** √ √

By simplifying ([2.13](#_bookmark14)) the proof is finished.

When including the results ([2.12](#_bookmark13)) directly in the main system ([2.8](#_bookmark8)) the affinity property of the system would be lost. So, in order to satisfy the affinity constraints, appropriate *approximations* need to be introduced.

## Log-Transform

Before going into the details of the approximations of the HHW and HCIR models let us first find the dynamics for the log-transform for the reformulated Heston hybrid models. By applying Itˆo’s lemma, model ([2.8](#_bookmark8)) in log-equity space, *x*(*t*) = log *S*(*t*), with a constant parameter, ∆, and a function Ω(*t*), is given by:

d*x*(*t*) = Σ*r*(*t*) *−*  1 .Ω2(*t*)*r*2*p*(*t*) + *v*(*t*) .1 + ∆2 + 2*ρ*ˆ

2

*x,v*

+Ω(*t*)*rp*(*t*)d*Wr*(*t*) + ∆√*v*(*t*)d*Wv*(*t*)

∆ΣΣΣ d*t* + √*v*(*t*)d*W*

(*t*)

*x*

= .*r*(*t*) *−*  1 *v*(*t*)Σ d*t* + √*v*(*t*)d*W*

(*t*) + Ω(*t*)*rp*(*t*)d*W* (*t*) + ∆√*v*(*t*)d*W* (*t*)*,*

2

because of ([2.12](#_bookmark13)).

*x r v*

For a given state vector **X***∗*(*t*) = [*r*(*t*)*, v*(*t*)*, x*(*t*)]T*,* the symmetric instantaneous covariance matrix ([1.3](#_bookmark1)) is given by:

 *η*2*r*2*p*(*t*) 0 *η*Ω(*t*)*r*2*p*(*t*) 

(*t*) *γv*(*t*) (*ρ*ˆ + ∆) *.* (2.14)

**Σ** :=  *∗ γ*2*v x,v* 

.

*∗ ∗* Ω2(*t*)*r*2*p*(*t*) + *v*(*t*)

1 + ∆2 + 2*ρ*ˆ*x,v*∆

Σ

As we consider two cases for parameter *p* = 0*,*1*/*2 , the affinity issue appears in only one term of matrix ([2.14](#_bookmark16)), namely, in element (1*,* 3) :

*{ }*

√*v*(*t*)√*r*(*t*)*,* for HCIR*.*

**Σ** = *η*Ω(*t*)*r*2*p*(*t*) = *ηρ*

(1*,*3)

*x,r*

√*v*(*t*)*rp*(*t*) = . *ηρx,r*√*v*(*t*)*,* for HHW*,*

*ηρ*

*x,r*

(2.15)

Although term **Σ**(3*,*3) does not seems to be of the affine form, by ([2.12](#_bookmark13)), it equals **Σ**(3*,*3) = *v*(*t*), and therefore it is linear in the state variables.

**Remark***.* We see that, in order to make either the HHW or the HCIR model affine, one does not necessary need to approximate function Ω(*t*), but only the non-affine terms in the corresponding instantaneous covariance matrix[3](#_bookmark18). By approximation of the non-affine covariance

3The drifts and the interest rate are already in the affine form, presented in ([1.2](#_bookmark1)) and ([1.4](#_bookmark1)).

term, **Σ**(1*,*3), the corresponding pricing PDE also changes. The Kolmogorov backward equation for the log-stock price (see, for example, [[Øksendal-2000](#_bookmark105)]) is now given by:

0 = *∂φ* + .

*∂t*

1 Σ *∂φ* + (¯

) *∂φ* +

( ( )

*λ θ t*

) *∂φ* + 1

*∂*2*φ*

+ 1 2 *∂*2*φ*

*r −* 2 *v*

*∂x*

*κ v − v*

1 2 2*p ∂*2*φ*

*∂v*

*− r*

*∂r*

2 *v ∂x*2

*∂*2*φ*

*∂*2*φ*

*γ v* + *η r*

2 *∂v*2 2

*∂r*2 + *ρx,vγv∂x∂v* + **Σ**(1*,*3) *∂x∂r − rφ,* (2.16)

subject to terminal condition *φ*(*u,* **X**(*T* )*, T, T* ) = exp (*iux*(*T* )).

The derivations in Section [2.3](#_bookmark15) show that System ([2.8](#_bookmark8)) is nothing but a reformulation of the original HHW system under the conditions in ([2.12](#_bookmark13)). It is therefore sufficient to linearize the non-affine terms in the covariance matrix to determine an affine approximation of the full-scale model. In the sections to follow we discuss two possible approximations for **Σ**(1*,*3)*.*

# Deterministic Approximation for Hybrid Models

In order to make the Heston hybrid model affine we provide a first approximation for the expressions in ([2.15](#_bookmark17)) in Section [3.1](#_bookmark20). The corresponding ChF is derived in Subsection [3.2](#_bookmark41).

## Deterministic Approach, the H1-HW Model

√

The first approach to finding an approximation for the term **Σ**(1*,*3) = *ηρx,r v*(*t*)*rp*(*t*) in matrix ([2.14](#_bookmark16)) is to replace it by its expectation, i.e.:

**Σ**(1*,*3) *≈ ηρx,r*E .*rp*(*t*)√*v*(*t*)Σ =*⊥ ηρx,r*E(*rp*(*t*))E(√*v*(*t*))*,* (3.1) assuming independence between *r*(*t*) and *v*(*t*).

The approximation for **Σ**(1*,*3) in ([3.1](#_bookmark21)) consists of two expectations: one with respect to

√ √

*v*(*t*) and another with respect to *rp*(*t*). E(*rp*(*t*)) = 1 for *p* = 0, and it is E( *r*(*t*)) for *p* = 1*/*2. Since the processes for *v*(*t*) and *r*(*t*) are then of the same type, the approximations are analogous. By taking the expectations of the stochastic variables the model becomes of the affine form, so that we can obtain the corresponding characteristic function.

In Lemma [3.1](#_bookmark22) the closed form expressions for the expectation and the variance of *v*(*t*) (a CIR-type process) are presented.

√

**Lemma 3.1** (Expectation and variance for CIR-type process)**.** *For a given time t >*0 *the expectation and variance of v*(*t*)*, where v*(*t*) *is a CIR-type process ([2.1](#_bookmark2)), are given by:*

√

(√ ( )) = √2 ( )e*−*

Σ 1 (

( ) 2)*k* Γ . 1+*d* + *k*Σ

2

2

(3.2)

*and*

E *v t*

*c t λ*(*t*)*/*2

*k*!

*k*=0

*∞*

*λ t /*

Γ( *d* + *k*) *,*

*where*

V*ar*

.√*v*(*t*)Σ

= *c*(*t*)(*d* + *λ*(*t*)) *−* 2*c*(*t*)e*−λ*(*t*)

*∞*

*k*=0

.Σ

1 (*λ*(*t*)*/*2)*k*

*k*!

1+*d* 2

2

. ΣΣΓ + *k*

. ΣΓ + *k*

*d*

2

*,* (3.3)

( ) = 1 2(1

e*−κt*)

= 4*κv*¯ ( ) = 4*κv*(0)e*−κt*

(3.4)

*c t* 4*κγ −*

*, d γ*2 *, λ t*

*γ*2(1 *−* e*−κt*) *,*

*with* Γ(*k*) *being the gamma function defined by:*

Γ(*k*) = ∫0*∞ tk−*1e*−t*d*t.*

*Proof.* By [[Dufresne-2001](#_bookmark87)] one can find the closed form expression for the expectation

√

E( *v*(*t*)), which by the principle of Kummer [[Kummer-1936](#_bookmark103)] can be simplified.

√ √

The analytic expression for the expectation, either of *v*(*t*) or *r*(*t*) in ([3.1](#_bookmark21)) is involved and requires rather expensive numerical operations.

In order to find a first order approximation we can apply the so-called *delta method*, see for example [[Amstrup,](#_bookmark74) *[et al.](#_bookmark74)*[-2006](#_bookmark74); [Oehlert-1992](#_bookmark104)], which states that a function *ϕ*(*X*) can be approximated by a first order Taylor expansion at E(*X*), for a given random variable, *X*, with expectation, E(*X*), and variance, Var(*X*), assuming that for *ϕ*(*X*) its first derivative with respect to *X* exists and is sufficiently smooth.

The lemma below provides details of the approximation.

√

**Lemma 3.2.** *The expectation,* E( *v*(*t*))*, with stochastic process v*(*t*) *given by Equation ([2.3](#_bookmark3)), can be approximated by:*

E(√*v*(*t*)) *≈* .*c*(*t*)(*λ*(*t*) *−* 1) + *c*(*t*)*d* + *c*(*t*)*d* =: Λ(*t*)*,* (3.5)

2(*d* + *λ*(*t*))

*with c*(*t*)*, d and λ*(*t*) *given in Lemma [3.1](#_bookmark22), and κ, v*¯*, γ and v*(0) *are the parameters given in ([2.3](#_bookmark3)).*

*We will discuss under which conditions the expression under the square-root in ([3.5](#_bookmark26)) remains non-negative in Appendix [A.1](#_bookmark110).*

*Proof.* Assuming the function *ϕ* to be sufficiently smooth, and the first two moments of *X* to exist, we obtain by first order Taylor expansion:

*ϕ*(*X*) *≈ ϕ*(E*X*) + (*X −* E*X*) *∂X* (E*X*)*.* (3.6)

*∂ϕ*

Since the variance of *ϕ*(*X*) can be approximated by the variance of the right-hand side of ([3.6](#_bookmark27)) we have:

Var(*ϕ*(*X*)) *≈* Var .*ϕ*(E*X*) + (*X −* E*X*) *∂ϕ* (E*X*)Σ

*∂X*

. *∂ϕ* Σ2

=

*∂X* (E*X*)

Var*X.* (3.7)

Now, by using this result for function *ϕ*(*v*(*t*)) = √*v*(*t*)*,* we find

√ . 1 1 Σ2 1 Var(*v*(*t*))

Var(

*v*(*t*)) *≈*

2 √E(*v*(*t*))

Var(*v*(*t*)) = 4

E(*v*(*t*)) *.* (3.8)

However, from the definition of the variance we also have:

Var( *v*(*t*)) = E(*v*(*t*)) *−* .E( *v*(*t*))Σ2 *.* (3.9)

√ √

and by combining Equations ([3.8](#_bookmark28)) and ([3.9](#_bookmark29)) we obtain the following approximation:

4

Since *v*(*t*) is a square root process, as in ([2.8](#_bookmark8)), we have

E(√*v*(*t*)) *≈* .E(*v*(*t*)) *−*  1 Var(*v*(*t*)) *.* (3.10)

*κt*

*κt*

E(*v*(*t*))

( ) =

*v t*

*v*

(0)e*−*

+ ¯(1

*v*

e*−* ) +

∫ *t* e

0

*−* √ ( )d ( )

(3.11)

The expectation of E(*v*(*t*)) equals E(*v*(*t*)) = *c*(*t*)(*d* + *λ*(*t*)), and for the variance we get,

*−*

*γ*

*κ*(*s*

*t*)

*v s*

*Wv s .*

Var(*v*(*t*)) = *c*2(*t*)(2*d* + 4*λ*(*t*)), with *c*(*t*), *d* and *λ*(*t*) given in ([3.4](#_bookmark24)).

Now, by substituting these expressions in ([3.10](#_bookmark30)), the lemma is proved.

Since Lemma [3.2](#_bookmark25) provides an explicit approximation for Σ(1*,*3) in ([3.1](#_bookmark21)) in terms of a deterministic function for E( *v*(*t*)), we are, in principle, able to derive the corresponding ChF.

√

**Remark***.* We assume that the first-order linear terms around the parameter values in the Taylor expansion give an accurate representation. However, this may not work satisfactory for ’flat’ density functions, like those from a uniform distribution. In order to increase the accuracy, higher order terms can be included in the expansion [[Amstrup,](#_bookmark74) *[et al.](#_bookmark74)*[-2006](#_bookmark74)]. More discussion on the conditions for the delta method to perform well can be found in [[Oehlert-1992](#_bookmark104)].

The approximation for E( *v*(*t*)) in ([3.5](#_bookmark26)) is still non-trivial, and may cause difficulties when deriving the corresponding characteristic functions. In order to find the coefficients of the ChF, a routine for numerically solving the corresponding ODEs has to be incorporated. Numerical integration, however, slows down the option pricing engine, and would make the SDE model less attractive. As we aim to find a closed form expression for the ChF, we simplify Λ(*t*) in ([3.5](#_bookmark26)). Expectation E( *v*(*t*)) can be further approximated by a function of the following form:

√

E( *v*(*t*)) *≈ a* + *b*e*−ct* =: Λ(*t*)*,* (3.12)

with *a*, *b* and *c* constant. Appropriate values for *a*, *b* and *c* in ([3.12](#_bookmark31)) can be obtained via an optimization problem of the form, min*a,b,c* Λ(*t*) Λ(*t*) *n,* where *n* is any *nth* norm.

˜*|| − || || · ||*

We propose here, instead of a numerical approximation for these coefficients, a simple

analytic expression in Result [3.3](#_bookmark32):

lim

√

√ ˜

Λ( ) = .¯

*γ*2 =

= lim

Λ˜( )

lim Λ(*t*) = √*v*(0) = *a* + *b* = lim Λ˜(*t*)*,*

**Result 3.3.** *By matching functions* Λ(*t*) *and* Λ˜(*t*) *for t →* +*∞, t →* 0 *and t* = 1*, we find:*

*t→*+*∞*

*t*

*v −* 8*κ*

*a*

*t→*+*∞*

*t ,*

*t→*0

*t→*0

(3.13)

lim Λ(*t*) = Λ(1) = *a* + *b*e*−c* = lim Λ˜(*t*)*.*

*t→*1

*The values a, b and c can now be estimated by:*

*t→*1

. *γ*2 √

*a* =

*v*¯ *−* 8*κ, b* =

*v*(0) *− a, c* = *−* log

*b*

(Λ(1) *− a*)

*,* (3.14)

. *−*1 Σ

*where* Λ(*t*) *is given by ([3.5](#_bookmark26)).*

The approximation given in Result [3.3](#_bookmark32) may give difficulties for *v*¯ *< γ*2*/*8*κ* in Equation ([3.14](#_bookmark33)) (the expression under the square root then becomes negative). The variance process *v*(*t*) is always positive and cannot reach zero if 2*κv*¯ *> γ*2 (the Feller condition), which, rewritten, equals *v*¯ *> γ*2*/*2*κ*. With all the parameters assumed to be positive, this means that, if the Feller condition is satisfied, the approximation in ([3.14](#_bookmark33)) is also well-defined. However, if the Feller condition does not hold our experience shows that one can safely use the exact formula for the expectation given in Lemma [3.1](#_bookmark22).

√

In order to measure the quality of approximation ([3.14](#_bookmark33)) to E( *v*(*t*)) in ([3.2](#_bookmark23)), we perform a numerical experiment (see the results in Figure [3.1](#_bookmark34)). For randomly chosen sets of parameters the approximation ([3.14](#_bookmark33)) resembles E( *v*(*t*)) in ([3.2](#_bookmark23)) very well.

√

0.22

proxy: κ =1.2,γ =0.1,v¯ =0.03,v(0) =0.04

exact

proxy: κ =1.2,γ =0.1,v¯ =0.02,v(0) =0.035

exact

proxy: κ =1.2,γ =0.1,v¯ =0.04,v(0) =0.01 exact

proxy: κ =0.8,γ =0.1,v¯ =0.04,v(0) =0.015

exact

proxy: κ =1,γ =0.2,v¯ =0.04,v(0) =0.02 exact

0.2

0.18

0.16

E( v(t))

0.14

0.12

0.1

0 1 2 3 4 5 6 7 8 9 10

time (t)

Figure 3.1: The quality of the approximation E( *v*(*t*)) *a* + *b*e*−ct* (continuous line) versus exact solution given in Equation ([3.2](#_bookmark23)) (squares) for 5 random *κ*, *γ*, *v*¯ and *v*(0).

√ *≈*

We call the resulting model the H1-HW model (Heston-Hull-White model-1).

**3.1.1 The Case** ∆ = 0 **and** Ω(*t*) *≡* **const.**

With ∆ = 0 in the Systems ([2.8](#_bookmark8)) and ([2.11](#_bookmark10)), the model resembles the one in [[Giese-2006](#_bookmark91); [Andreasen-2006](#_bookmark75)]. There, a constant parameter Ω¯ = Ω(*t*) was prescribed, and an instantaneous correlation was *indirectly* imposed.

The following lemma, however, shows that this model with ∆ = 0 resembles the full-scale HHW and HCIR models only for correlation *ρ**x,r* = 0.

**Lemma 3.4.** *The hybrid models ([2.8](#_bookmark8)) with* ∆ = 0 *are full-scale HHW and HCIR models, in the sense of System ([2.3](#_bookmark3)), only if the instantaneous correlation between the stock and the interest rate processes in System ([2.3](#_bookmark3)) equals zero, i.e., ρx,r* = 0*.*

*Proof.* The proof is analogous to the proof of Lemma [2.1](#_bookmark12). We see from the equalities in ([2.12](#_bookmark13)) that System ([2.7](#_bookmark7)) resembles System ([2.11](#_bookmark10)) with ∆ = 0, only if:

Ω¯ = *ρ*

*v*(*t*)

*x,r rp*(*t*)

√ *,*

*ρ*ˆ*x,v*

= *ρx,v,*

2

*x,v*

*ρ*ˆ

2

*x,v*

= *ρ*

2

*x,r*

+ *ρ*

*.* (3.15)

The equations ([3.15](#_bookmark37)) only hold for *ρx,r* = 0. So, the models with ∆ = 0 are not full-scale HHW and HCIR models with a non-zero correlation *ρx,r*.

Although the model with ∆ = 0 is not a properly defined Heston hybrid model, one can

still proceed with the analysis. Parameter Ω¯ was derived based on the following equality,

see [[Giese-2006](#_bookmark91)], using the definition of the instantaneous correlation,

*ρ*ˆ*x,r*

E (d*S*(*t*)d*r*(*t*)) E(d*S*(*t*))E(d*r*(*t*))

√*v*(*t*)*S*2(*t*) d*t* + Ω¯ 2*r*2*p*(*t*)*S*2(*t*) d*t*√*η*2*r*2*p*(*t*) d*t*

Ω¯ *rp*(*t*)

√*v*(*t*) + Ω¯ 2*r*2*p*(*t*) *.*

*−*= =

(3.16)

To deal with the affinity issue a constant approximation for Ω¯ was proposed, given by:

. ∫ Σ 1 . ∫ Σ*p*

*v*(*t*)d*t*

*r*(*t*)d*t*

*.* (3.17)

.*≈* 1 *− ρ*ˆ

Ω¯ *ρ*ˆ*x,r* E

2

*x,r*

1

*T*

*T*

2

,E

1

*T*

*T*

0

0

By choosing Ω¯ = 0 the model collapses to the well-known Heston-Hull-White model (*p* = 0) or Heston-CIR model (*p* = 1 ) with zero correlation *ρx,r*.

2

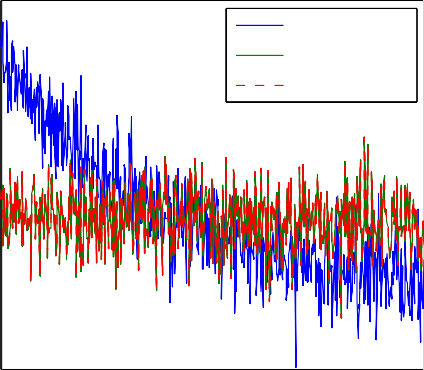
In Figure [3.2](#_bookmark38) we present the behavior of the instantaneous correlation between the equity and the interest rates. We see that for time-dependent Ω(*t*), as defined in Lemma [2.1](#_bookmark12), the

instantaneous correlations are stable and oscillate around the exact value, chosen to be *ρx,r* = 60%, whereas for the model with Ω(*t*) = Ω¯ a different correlation pattern is observed. For the latter model, initially the correlation is significantly higher than 60%, and it decreases in time.

These results show that a constant Ω¯ in the model with ∆ = 0 may give an average correlation

close to the exact value, although the instantaneous correlation is not stable in time.

64



Ω¯ =const Ω(t)

Full-Scale Model

63

62

Instantaneous Correlation (x,r), %

61

60

59

58

57

0 0.5 1 1.5 2

time

Figure 3.2: The instantaneous correlations for different models. The blue line represents the model with ∆ = 0 with constant Ω¯ , the dotted-red line corresponds to the full-scale HHW model, and the green line to the model with time-dependent Ω(*t*). Maturity is chosen to *τ* = 2 years.

The assumptions of constant Ω¯ and ∆ = 0 also have an impact on the corresponding pricing PDE. With the Feynman-Kac theorem the corresponding PDE is given by:

1

.

0 = *∂φ* + Σ

1 +

2*p*Ω¯ 2ΣΣ *∂φ* + (¯

) *∂φ* +

( ( )

) *∂φ* + .

+ 2*p*Ω¯ 2Σ *∂*2*φ*

*∂t*

+ 1 2

*r −* 2 *v*

*∂*2*φ* 1 2

*r*

2*p ∂*2*φ*

*∂x κ v − v ∂v*

*∂*2*φ* ¯

*λ θ t*

2*p ∂*2*φ*

*− r ∂r*

2 *v r*

*∂x*2

*γ v* + *η r*

2 *∂v*2 2

*∂r*2 + *ρ*ˆ*x,vγv∂x∂v* + *η*Ω*r*

*∂x∂r − rφ,* (3.18)

with the same terminal condition as for ([2.16](#_bookmark19)). The assumption of constant Ω¯ and ∆ = 0 gives rise to additional terms in the convection and diffusion parts of PDE ([3.18](#_bookmark39)).

By means of a numerical experiment, we check the accuracy of the model with ∆ = 0 and determine whether the model approximates the full-scale HHW hybrid model sufficiently well. We consider here the following set of parameters: *S*(0) = 1, *κ* = 2, *v*(0) = *v*¯ = 0*.*05, *γ* = 0*.*1, *λ* = 1*.*2, *r*(0) = *θ* = 0*.*05, *η* = 0*.*01 and correlation *ρx,v* = 40%. In the simulation we choose two different values for correlation *ρx,r* = 30%*,* 50% *.*

*{ }*

*−*

We compare the following three models: The full-scale HHW model (with Monte Carlo simulation), the model with ∆ = 0 and our approximation for Σ(1*,*3) in PDE ([2.16](#_bookmark19)) with the projection according to Equation ([3.1](#_bookmark21)).

Implied volatilities for T=2 and x,r=30%

55

Full Scale Model

=0, Eqn.(3.18)

50 Proxy Eqn.(2.16), with (3.1)

Implied volatilities for T=2 and x,r=50%

55

Full Scale Model

=0, Eqn.(3.18)

50 Proxy Eqn.(2.16), with (3.1)

45 45

Implied Black−Scholes volatilities, %

Implied Black−Scholes volatilities, %

40 40

35 35

30 30

25 25

20

0.5 1 1.5 2

Strike

20

0.5 1 1.5 2

Strike

Figure 3.3: The implied Black-Scholes volatilities for the full-scale Heston model and two approximations: deterministic approach (model ([2.16](#_bookmark19)) with ([3.1](#_bookmark21))), and model with ∆ = 0 (model ([3.18](#_bookmark39))).

In Figure [3.3](#_bookmark40) the implied volatilities obtained are compared. The model with ∆ = 0 in ([3.18](#_bookmark39)) does not provide a satisfactory fit to the full-scale HHW model, whereas the implied volatilities obtained with the deterministic hybrid approximation compare very well (they essentially overlap) with the full-scale reference results, see Figure [3.3](#_bookmark40). The *volatility compensator* ∆, as defined in Lemma [2.1](#_bookmark12), cannot be neglected when approximating the full-scale HHW model, as was stated in Lemma [3.4](#_bookmark36).

## Characteristic Function for the H1-HW Model

We derive a ChF for the Heston-Hull-White hybrid model given in ([2.16](#_bookmark19)). For *p* = 0, the

√

non-affine term, **Σ**(1√*,*3), in matrix ([2.16](#_bookmark19)) equals **Σ**(1*,*3) = *ηρx,r v*(*t*) and will be approximated

*v*(*t*))*.*

We assume here that the term-structure for the interest rate *θ*(*t*) is constant, *θ*(*t*) = *θ*. A generalization can be found in [[Brigo,Mercurio-2007](#_bookmark81)].

According to [[Duffie,](#_bookmark86) *[et al.](#_bookmark86)*[-2000](#_bookmark86)], the discounted ChF for the H1-HW model is of the following form:

by **Σ**(1*,*3) *≈ ηρx,r*E(

*φ*H1-HW(*u,* **X**(*t*)*, τ* ) = exp (*A*(*u, τ* ) + *B*(*u, τ* )*x*(*t*) + *C*(*u, τ* )*r*(*t*) + *D*(*u, τ* )*v*(*t*)) *,* (3.19) with boundary conditions *A*(*u,* 0) = 0, *B*(*u,* 0) = *iu*, *C*(*u,* 0) = 0, and *D*(*u,* 0) = 0, and

*τ* := *T t*.

*−*

The ChF for the H1-HW model can be derived in closed form, with the help of the following lemmas:

**Lemma 3.5** (The ODEs related to the H1-HW model)**.** *The functions B*(*u, τ* ) =: *B*(*τ* )*, C*(*u, τ* ) =: *C*(*τ* )*, D*(*u, τ* ) =: *D*(*τ* ) *and A*(*u, τ* ) =: *A*(*τ* ) *for u* R *and τ* 0 *in ([3.19](#_bookmark42)) for the H1-HW model satisfy the following system of ODEs:*

*∈ ≥*

*Bj*(*τ* ) = 0*, B*(*u,* 0) = *iu,*

*Cj*(*τ* ) = *−*1 *− λC*(*τ* ) + *B*(*τ* )*, C*(*u,* 0) = 0*,*

*Dj*(*τ* ) = *B*(*τ* )(*B*(*τ* ) *−* 1)*/*2 + (*γρx,vB*(*τ* ) *− κ*) *D*(*τ* ) + *γ*2*D*2(*τ* )*/*2*, D*(*u,* 0) = 0*,*

√

*Aj*(*τ* ) = *λθC*(*τ* ) + *κv*¯*D*(*τ* ) + *η*2*C*2(*τ* )*/*2 + *ηρx,r*E( *v*(*t*))*B*(*τ* )*C*(*τ* )*, A*(*u,* 0) = 0(*,*3.20)

*with τ* = *T t, and κ, λ, θ and η, ρx,r and ρx,v correspond to the parameters in the HHW model ([2.3](#_bookmark3)).*

*−*

*Proof.* The proof can be found in Appendix [A.2](#_bookmark112).

The following lemma gives the closed form solution for the functions *B*(*u, τ* ), *C*(*u, τ* ),

*D*(*u, τ* ) and *A*(*u, τ* ) in ([3.19](#_bookmark42)).

**Lemma 3.6** (Characteristic function for the H1-HW model)**.** *The solution of the ODE system in Lemma [3.5](#_bookmark43) is given by:*

|  |  |  |  |
| --- | --- | --- | --- |
| *B*(*u, τ* ) | = | *iu,* | (3.21) |
| *C*(*u, τ* ) | = | (*iu −* 1)*λ−*1(1 *−* e*−λτ* )*,* | (3.22) |
| *D*(*u, τ* ) | = | 1 *−* e*−D*1*τ* ( )  *κ − γρx,viu − D*1 *,*  *γ*2 (1 *− g*e*−D*1*τ* ) | (3.23) |

*A*(*u, τ* ) = *λθI* (*τ* ) + *κv*¯*I* (*τ* ) + 1 *η*2*I* (*τ* ) + *ηρ*

*I* (*τ* )*,* (3.24)

1 2 2 3

*x,r* 4

*with D*1

= √(*γρ*

*x,v*

*iu − κ*)2 *− γ*2*iu*(*iu −* 1)*, g* = *κ − γρx,v iu − D*1 *, κ, θ, λ, γ are as in ([2.9](#_bookmark9)).*

*The integrals I*1(*τ* )*, I*2(*τ* )*, and I*3(*τ* ) *admit an analytic solution, and I*4(*τ* ) *a semi-analytic solution:*

*κ − γρ iu* + *Dx,v* 1

*I* (*τ* ) = 1 (*iu −* 1) .*τ* +

1 *λ*

*τ*

1 (e

*λ*

*−λτ −* 1)Σ *,*

2

1. 1 *− g*e*−D*1*τ* Σ

*,*

*I*2(*τ* ) =

*γ*2 (*κ − γρx,viu − D*1) *− γ*2 log

1

1 *− g*

*I*3(*τ* ) =

2*λ*3

(*i* + *u*)2 .3 + e*−*2*λτ −* 4e*−λτ −* 2*λτ* Σ *,*

∫ *τ* √

*I*4(*τ* ) = *iu*

0

E(

*v*(*T − s*))*C*(*u, s*)d*s*

*−*

*iu*

*u*2

E

*v T − s*

*−*

*−λs*

*s.*

= 1 ( +

) ∫ *τ*

0

(√ (

)) .1 e Σ d

*Proof.* The proof can be found in Appendix [A.3](#_bookmark114).

√ *− ≈*

*λ*

Note that by taking E( *v*(*T s*)) *a* + *b*e*−c*(*T −s*), with *a*, *b* and *c* as given in ([3.12](#_bookmark31)) we obtain a closed form expression:

*I* (*τ* ) = *−*  1 (*iu* + *u*2) Σ *b* .e*−ct −* e*−cT* Σ + *aτ* + *a* .e*−λτ −* 1Σ + *b* e*−cT* .1 *− e−τ*(*λ−c*)ΣΣ *.*

4

*λ*

*c*

*λ*

*c − λ*

In Appendix [B](#_bookmark116) we present the generalization to a *full matrix of non-zero correlations* between the processes, and discuss the effect of the correlations on at-the-money implied volatilities.

# Stochastic Approximation for Hybrid Models

In the previous section a rather straightforward way to approximate the non-affine elements in the instantaneous covariance matrix was presented. Here, we model those elements by stochastic processes, and call the resulting approximate model H2-HW (Heston-Hull-White model-2).

## Stochastic Approach, the H2-HW Model

In the lemma below an approximation for finite time *t* and a non-zero centrality parameter is presented.

√ *∞ ∞*

**Lemma 4.1** (Normal approximation for *v*(*t*), for 0 *< t <* )**.** *For any time, t < , the square root of v*(*t*) *in ([2.8](#_bookmark8)) can be approximated by*

√*v*(*t*) *≈ N* ..*c*(*t*)(*λ*(*t*) *−* 1) + *c*(*t*)*d* + *c*(*t*)*d , c*(*t*) *−*  *c*(*t*)*d* Σ *,* (4.1)

2(*d* + *λ*(*t*))

2(*d* + *λ*(*t*))

*with c*(*t*)*, d and λ*(*t*) *from ([3.4](#_bookmark24)). Moreover, for a fixed value of x in the cumulative distribution function F√* (*x*)*, and a fixed value for parameter d, the error is of order O*(*λ*2(*t*)) *for λ*(*t*) *→*

*v*(*t*)

0 *and O*(*λ*(*t*)*−* 2 ) *for λ*(*t*) *→ ∞.*

1

*Proof.* As given in [[Patnaik-1949](#_bookmark106)] an accurate approximation for the non-central chi-square distribution, *χ*2(*λ*(*t*)), can be obtained by an approximation with a centralized chi-square distribution, i.e.:

*d*

*χ*2(*d, λ*(*t*)) *≈ a*(*t*)*χ*2(*f* (*t*))*,* (4.2)

with *a*(*t*) and *f* (*t*) in ([4.2](#_bookmark48)) chosen so that the first two moments match, i.e.:

*a*(*t*) =

*d* + 2*λ*(*t*)

*d* + *λ*(*t*)

*, f* (*t*) = *d* +

*λ*(*t*)2

*d* + 2*λ*(*t*)

*.* (4.3)

It was shown in [[Cox,](#_bookmark83) *[et al.](#_bookmark83)*[-1985](#_bookmark83); [Broadie,Yamamoto-2003](#_bookmark80)] that, for a given time *t >* 0, *v*(*t*) is distributed as *c*(*t*) times a non-central chi-squared random variable, *χ*2(*d, λ*(*t*)), with *d* the degrees of freedom parameter and non-centrality parameter *λ*(*t*), i.e.: *v*(*t*) = *c*(*t*)*χ*2 (*d, λ*(*t*)) *, t >* 0. By combining this with ([4.2](#_bookmark48)) we have:

√ √ √

*v*(*t*) *≈ c*(*t*) *a*(*t*)*χ*2(*f* (*t*))*.* (4.4) Now, we use a result by Fisher [[Fisher-1922](#_bookmark89)] that for a given central chi-square random variable,

√ *√ −*

*χ*2(*d*), the expression 2*χ*2(*d*) is approximately normally distributed with mean 2*d* 1 and

unit variance, i.e.:

which implies:

*Fχ*2(*d*)(*x*) *≈* Φ .*√*2*x − √*2*d −* 1Σ *,* (4.5)

√*v*(*t*) *≈ N* ...*f* (*t*) *−*  1 Σ *c*(*t*)*a*(*t*) 1 (*t*)*a*(*t*)Σ *.* (4.6)

2

*,* 2 *c*

The order of this approximation can be found in [[Johnson,](#_bookmark97) *[et al.](#_bookmark97)*[-1994](#_bookmark97)].

As already indicated in [[Patnaik-1949](#_bookmark106)], the normal approximation resembles the non-central chi-square distribution very well for either a large number of degrees of freedom, *d*, or a large non-centrality *λ*(*t*). For *t* 0, the non-centrality parameter, *λ*(*t*), tends to infinity. Therefore, accurate approximations are expected.

*→*

In the case of long maturities, the non-centrality parameter converges to 0, which may give an inaccurate approximation. In this case, satisfactory results depend on the size of the degrees of freedom parameter *d*. It is clear that *d* in ([3.4](#_bookmark24)) is directly related to the Feller condition. In practical applications, however, 2*κv*¯ is often smaller than *γ*2. In the numerical experiments to follow we will study the impact of *not* satisfying the Feller condition.

√*v t*

In Lemma [4.1](#_bookmark47) we have shown that ( ) can be well approximated by a normally distributed random variable. As the application of Itˆo’s lemma to find the dynamics for *v*(*t*) is not allowed (the square root process is not twice differentiable at the origin [[J¨ackel-2004](#_bookmark98)]), we construct here a stochastic process, *ξ*(*t*), so that *equality in distribution* holds, i.e.:

[√](#_bookmark98)

*ξ*(*t*) d √*v*(*t*)*.* Since a normal random variable is completely described by the first two moments,

*≈* √ √

we need to ensure that E(*ξ*(*t*)) = E( propose the following dynamics:

*v*(*t*)) and Var(*ξ*(*t*)) = Var(

*v*(*t*)). For this purpose we

d*ξ*(*t*) = *µξ*(*t*)d*t* + *ψξ*(*t*)d*Wv*(*t*)*, ξ*(0) = √*v*(0)*,* (4.7)

with some deterministic, time-dependent functions *µξ*(*t*), and *ψξ*(*t*), determined so that the first two moments match. By moment matching the unknown functions *µξ*(*t*) and *ψξ*(*t*) in ([4.7](#_bookmark49)) read:

*µξ*(*t*) = d E(√*v*(*t*))*, ψξ*(*t*) = . d Var(√*v*(*t*))*.* (4.8)

√ √

d*t*

d*t*

Using the results from Lemma [3.1](#_bookmark22), the expectation, E( *v*(*t*)), and the variance, Var( *v*(*t*)),

can be derived:

1 Γ . 1+*d* Σ .

2

*µξ*(*t*) =

2*√*

√*c*(*t*)

1*F*˜1

*−* 2 *,* 2 *, −*

2 *γ*2e*−κt*

2

. 1 *d*

*λ*(*t*) Σ 1

2

+ *F*˜

. 1 *,* 2 + *d, −λ*(*t*) Σ *v*(0)*κ* Σ *,*

2

1 1 2 2

.

*ψξ*(*t*) =

*κ*(*v*¯ *− v*(0))e*−κt −* 2E(

2 1 *−* e*κt*

√ Σ 1

*v*(*t*)) *µξ*(*t*)

*.* (4.9)

Here, E( *v*(*t*)) and *d*, *c*(*t*) and *λ*(*t*) are as in ([3.2](#_bookmark23)) and the regularized hyper-geometric function

√

1*F*1(*a*; *b*; *z*) =: 1*F*1(*a*; *b*; *z*)*/*Γ(*b*)*.*

˜

The expressions for *µξ*(*t*) and *ψξ*(*t*) in ([4.9](#_bookmark50)) are exact. However, since those expressions are not cheap to compute one can find suitable approximations based on the results in Lemma [3.2](#_bookmark25), which are however not guaranteed to be well defined for all sets of parameters.

Since the approximate hybrid models are to be used for the calibration to European-style options (with one terminal payment) we do not need path-wise equality between processes *ξ*(*t*) and *v*(*t*), but only equality in terminal distribution.

√

√

*∈*

**Remark***.* In Section [4.1](#_bookmark46) we projected *v*(*t*) onto a normal process, *ξ*(*t*). As it is common with approximations by normal processes (a non-negative random variable is projected onto another variable R), this approximation comes with an error (as we indicated in Lemma [4.1](#_bookmark47)). During stress-testing, examples of which are presented in Section [4.3](#_bookmark55) and in Appendix [C](#_bookmark118), we did not encounter any problems with this approximation. Typically, the stochastic approximation is somewhat more accurate than the deterministic approach (which is not based on a normal approximation) [4](#_bookmark53).

## Characteristic Function for the H2-HW Model

We now use the (stochastic) approximation for the term **Σ**(1*,*3), with the process d*ξ*(*t*) given by ([4.7](#_bookmark49)), and the time-dependent functions *µξ*(*t*) and *ψξ*(*t*) as in ([4.9](#_bookmark50)).

This approximation gives rise to an extension of the 3D space variable **X**(*t*) =

˜

[*S*(*t*)*, v*(*t*)*, r*(*t*)]T to a 4D space **X**(*t*) = [*S*(*t*)*, v*(*t*)*, r*(*t*)*, ξ*(*t*)]T, with the following system of SDEs:

**** d*S*(*t*)*/S*(*t*) = *r*(*t*)d*t* + √√*v*(*t*)d*Wx*(*t*)*, S*(0) *>* 0*,*

 d*v*(*t*) = *κ*(*v*¯ *− v*(*t*))d*t* + *γ v*(*t*)d*Wv*(*t*)*, v*(0) *>* 0*,*

(4.10)

where

d*r*(*t*) = *λ*(*θ*(*t*) *− r*(*t*))d*t* + *η*d*Wr*(*t*)*, r*(0) *>* 0*,*

d*ξ*(*t*) = *µξ*(*t*)d*t* + *ψξ*(*t*)d*Wv*(*t*)*, ξ*(0) = √*v*(0)*,*

****

d*Wx*(*t*)d*Wv*(*t*) = *ρx,v*d*t,* d*Wx*(*t*)d*Wr*(*t*) = *ρx,r*d*t,*



 d*Wv*(*t*)d*Wr*(*t*) = 0*,*

(4.11)

with *v*(*t*) *ξ*(*t*) and *µξ*(*t*),*ψξ*(*t*) are defined in ([4.9](#_bookmark50)).

√ *≈*

By taking the log-transform, *x*(*t*) = log *S*(*t*), in the model above all the drift terms are linear, and the symmetric instantaneous covariance matrix, with *ξ*(*t*) *≈ v*(*t*), is given by:

√

 

*v*(*t*) *γρx,vv*(*t*) *ρx,rηξ*(*t*) *ρx,vψξ*(*t*)*ξ*(*t*)

(*t*) 0 *γψ* (*t*)*ξ*(*t*)

**Σ**˜ = 

*∗ γ*2*v ξ*

*∗ ∗ η*2 0

*∗ ∗ ∗*

*ψξ*(*t*) 2

[.](#_bookmark77)

[Σ](#_bookmark77)

 *,*

(4.12)

4The method by Antonov from [[Antonov-2007](#_bookmark76); [Antonov,](#_bookmark77) *[et al.](#_bookmark77)*[-2008](#_bookmark77)] is also not based on normal approximations.

which, since *ψξ*(*t*) is a deterministic time-dependent function, is now affine.

Since the system of SDEs ([4.10](#_bookmark52)), is affine, we derive the corresponding ChF:

*φ*H2-HW(*u,* **X**(*t*)*, τ* ) = exp (*A*(*u, τ* ) + *B*(*u, τ* )*x*(*t*) + *C*(*u, τ* )*r*(*t*) + *D*(*u, τ* )*v*(*t*) + *E*(*u, τ* )*ξ*(*t*)) *,*

with boundary conditions *φ*H2-HW(*u,* **X**(*T* )*,* 0) = exp(*iux*(*T* )) and *ξ*(*t*) *≈* √*v*(*t*).

(4.13)

The functions *A*(*u, τ* ), *B*(*u, τ* ), *C*(*u, τ* ), *D*(*u, τ* ) and *E*(*u, τ* ) satisfy the complex-valued ODEs given by the lemma below.

**Lemma 4.2** (The ODEs related to the H2-HW model)**.** *The functions B*(*u, τ* ) =: *B*(*τ* )*, C*(*u, τ* ) := *C*(*τ* )*, D*(*u, τ* ) =: *D*(*τ* )*, E*(*u, τ* ) =: *E*(*τ* ) *and A*(*u, τ* ) =: *A*(*τ* ) *for u ∈* R *and τ* = *T − t >* 0 *in ([4.13](#_bookmark54)), satisfy:*

*Bj*(*τ* ) = 0*, B*(*u,* 0) = *iu,*

*Cj*(*τ* ) = *−*1 + *B*(*τ* ) *− λC*(*τ* )*, C*(*u,* 0) = 0*,*

*Dj*(*τ* ) = (*B*(*τ* ) *−* 1) *B*(*τ* )*/*2 + (*γρx,vB*(*τ* ) *− κ*) *D*(*τ* ) + *γ*2*D*2(*τ* )*/*2*, D*(*u,* 0) = 0*,*

*Ej*(*τ* ) = *ρx,rηB*(*τ* )*C*(*τ* ) + *ψξ*(*t*)*ρx,vB*(*τ* )*E*(*τ* ) + *γψξ*(*t*)*D*(*τ* )*E*(*τ* )*, E*(*u,* 0) = 0*,*

. Σ

*Aj*(*τ* ) = *κv*¯*D*(*τ* ) + *λθC*(*τ* ) + *µξ*(*t*)*E*(*τ* ) + *η*2*C*2(*τ* )*/*2 + *ψξ*(*t*) 2 *E*2(*τ* )*/*2*, A*(*u,* 0) = 0*,*

*with µξ*(*t*)*, ψξ*(*t*) *as given in ([4.9](#_bookmark50)).*

*Proof.* The proof is very similar to the proof of Lemma [3.5](#_bookmark43).

Solutions to the ODEs for *B*(*u, τ* ), *C*(*u, τ* ) and *D*(*u, τ* ) can be found in Lemma [3.6](#_bookmark44) where the deterministic linearization was applied.

Note that the remaining two functions, *E*(*u, τ* ) and *A*(*u, τ* ), involve the rather complicated functions *µξ*(*t*) and *ψξ*(*t*). We leave these equations to be solved numerically by a basic ODE routine.

## Numerical Experiment

Here we check the performance of the deterministic (Section [3.2](#_bookmark41)) and the stochastic (Section [4.2](#_bookmark51)) approximations to the full-scale HHW model, in terms of differences in implied volatilities. The HHW benchmark prices were obtained by Monte Carlo simulation, as in [[Andersen-2008](#_bookmark73)].

In Table [4.1](#_bookmark57) we present the errors for Black Scholes implied volatilities, *s*(*ρx,r*), for different correlations between the stock, *S*(*t*), and the short rate, *r*(*t*), and different strikes. We show results for a maturity of ten years, *τ* = 10*,* and for parameters that do not satisfy the Feller condition[5](#_bookmark56).

Both approximations give very similar, highly accurate, results for low correlations, *ρx,r*. This is different for high values of *ρx,r*. The deterministic approach generates somewhat more bias for high strikes, whereas the stochastic approach is essentially bias-free. The errors presented in Table [4.1](#_bookmark57) depend on the size of the volatility parameter of the interest rate process, *η*. For very low volatility, the two approximations provide a similar level of accuracy. As the volatility of the short rate process increases, a higher accuracy is expected for the stochastic approximation.

Calibration results will be presented in Section [6](#_bookmark69). The performance of the methods developed is also presented in Appendix [C](#_bookmark118), where our schemes are compared to the Markovian projection method [[Antonov,](#_bookmark77) *[et al.](#_bookmark77)*[-2008](#_bookmark77)].

# Heston-Cox-Ingersoll-Ross Hybrid Model

We also present the ChF for a Heston-Cox-Ingersoll-Ross hybrid model, *p* = 1*/*2 in ([2.3](#_bookmark3)), which is more involved than the Hull-White based hybrid models. In the Heston-CIR model the non-affine term is given in ([2.15](#_bookmark17)). Again we use two approximations to obtain the ChF. In the first model, H1-CIR, we use the deterministic setup and for the second model, H2-CIR, we determine the stochastic approximation.

5For short maturities, *τ <* 10, and for model parameters for which the Feller condition is satisfied, we did not find any significant differences between the two approximations and the full-scale model.

|  |  |  |  |  |  |  |
| --- | --- | --- | --- | --- | --- | --- |
| *ρx,r* | Strike | Monte Carlo Imp.vol. [%] | Approx 1 | Approx 2 | err.1 | err.2 |
|  | 40 | 37.57 (0.22) | 37.64 | 37.79 | 0.22 | 0.15 |
|  | 80 | 27.68 (0.22) | 27.67 | 27.71 | 0.03 | 0.04 |
| 20% | 100 | 24.85 (0.24) | 24.68 | 24.74 | -0.11 | 0.07 |
|  | 120 | 23.02 (0.20) | 22.70 | 22.80 | -0.22 | 0.09 |
|  | 180 | 21.16 (0.22) | 20.96 | 21.01 | -0.15 | 0.05 |
|  | 40 | 37.76 (0.14) | 37.98 | 37.79 | 0.03 | -0.19 |
|  | 80 | 28.46 (0.11) | 28.39 | 28.13 | -0.33 | -0.26 |
| 60% | 100 | 26.00 (0.10) | 25.44 | 25.35 | -0.65 | -0.09 |
|  | 120 | 24.43 (0.10) | 23.44 | 23.56 | -0.87 | 0.12 |
|  | 180 | 22.59 (0.11) | 21.99 | 21.89 | -0.70 | -0.10 |

Table 4.1: The implied volatilities and errors for the deterministic approximation (Approx 1) from ([2.16](#_bookmark19)) with approximation ([3.2](#_bookmark23)) and stochastic approximation (Approx 2) from Section [4.1](#_bookmark46) of the HHW model compared to the Monte Carlo simulation performed with 20T steps and

100.000 paths. The error is defined as a difference between reference implied volatilities and the approximations. The parameters were chosen as: *κ* = 0*.*3, *γ* = 0*.*6, *v*(0) = *v*¯ = 0*.*05, *λ* = 0*.*01, *r*(0) = *θ* = 0*.*02, *η* = 0*.*01, *S*(0) = 100 and the correlations *ρx,v* = *−*30% and

*ρx,r ∈ {*20%*,* 60%*}*. Numbers in brackets indicate standard deviations.

## Characteristic Function for the H1-CIR model

The dynamics for the stock, *S*(*t*), in the Heston-CIR model read:

d*S*(*t*)*/S*(*t*) = *r*(*t*)d*t*+

****

d*v*(*t*) = *κ*(*v*¯ *− v*(*t*))d*t*+ *γ*

*v*(*t*)d*Wx*(*t*)*, S*(0) *>* 0

√*v*(*t*)d*Wv*(*t*)*, v*(0) *>* 0*,*

(5.1)

**** d*r*(*t*) = *λ*(*θ*(*t*) *− r*(*t*))d*t*+ *η*√*r*(*t*)d*Wr*(*t*)*, r*(0) *>* 0*,*

with d*Wx*(*t*)d*Wv*(*t*) = *ρx,v*d*t*, d*Wx*(*t*)d*Wr*(*t*) = *ρx,r*d*t* and d*Wv*(*t*)d*Wr*(*t*) = 0*.*

Here, we assume that the non-affine term in the pricing PDE ([2.16](#_bookmark19)), **Σ**(1*,*3), in ([2.15](#_bookmark17)) can be approximated, as:

**Σ**(1*,*3) *≈ ηρx,r*E .√*r*(*t*)√*v*(*t*)Σ =*⊥ ηρx,r*E(√*r*(*t*))E(√*v*(*t*))*.* (5.2)

Since the processes involved are of the same type, the expectations in ([5.2](#_bookmark58)) can be determined as presented in Section [3.1](#_bookmark20). For the log-stock, *x*(*t*) = log *S*(*t*)*,* the ChF and the corresponding Riccati ODEs are defined as below:

*φ*H1-CIR(*u,* **X**(*t*)*, τ* ) = exp (*A*(*u, τ* ) + *B*(*u, τ* )*x*(*t*) + *C*(*u, τ* )*r*(*t*) + *D*(*u, τ* )*v*(*t*)) *,* (5.3)

**Lemma 5.1** (The ODEs related to the H1-CIR model)**.** *The functions B*(*u, τ* ) =: *B*(*τ* )*,*

*C*(*u, τ* ) =: *C*(*τ* )*, D*(*u, τ* ) =: *D*(*τ* ) *and A*(*u, τ* ) =: *A*(*τ* ) *for u ∈* R *and τ >* 0 *in ([5.3](#_bookmark59)) satisfy:*

*Bj*(*τ* ) = 0*, B*(*u,* 0) = *iu,*

*Cj*(*τ* ) = *−*1 + *B*(*τ* ) *− λC*(*τ* ) + *η*2*C*2(*τ* )*/*2*, C*(*u,* 0) = 0*,*

*Dj*(*τ* ) = (*B*(*τ* ) 1) *B*(*τ* )*/*2 + (*γρx,vB*(*τ* ) *κ*) *D*(*τ* ) + *γ*2*D*2(*τ* )*/*2*, D*(*u,* 0) = 0*,*

*− −*

*Aj*(*τ* ) = *κv*¯*D*(*τ* ) + *λθC*(*τ* ) + *ηρx,r*E(√*v*(*t*))E(√*r*(*t*))*B*(*τ* )*C*(*τ* )*, A*(*u,* 0) = 0*.* (5.4)

√ √

*with τ* = *T − t,* E( *v*(*t*)) *and* E( *r*(*t*)) *from Lemma [3.1](#_bookmark22). Proof.* The proof is very similar to the proof in Appendix [A.2](#_bookmark112).

**Lemma 5.2** (Solutions for the ChF coefficients of the H1-CIR model)**.** *The solutions for the ODEs for B*(*u, τ* )*, C*(*u, τ* )*, D*(*u, τ* ) *and A*(*u, τ* )*, defined in Lemma [5.1](#_bookmark60), are given by:*

*B*(*u, τ* ) = *iu,* (5.5)

1 *−* e*−D*1*τ*

*C*(*u, τ* ) =

*D*(*u, τ* ) =

*η*2 (1 *− tt* e*−D*1*τ* ) (*λ − D*1) *,* (5.6)

1 *−* e*−D*2*τ* ( ) (5.7)

1

*γ*2 (1 *− −D*2*τ κ − γρx,viu − D*2 *,tt*e )

2

*and*

∫ *τ* .

0

Σ

*v*(*T − s*))E(

*r*(*T − s*))*C*(*u, s*)

d*s,*

*with D*1 = √*λ*2 + 2*η*2(1 *− iu*)*, D*2 = .(*γρx,viu − κ*)2 *−* (*iu −* 1)*iuγ*2*,*

√

*A*(*u, τ* ) =

*κv*¯*D*(*u, s*) + *λθC*(*u, s*) + *ρx,rηiu*E(

√

*tt*1

= *λ − D*1

*λ* + *D*1

*and tt*2

= *κ − γρx,viu − D*2 *.*

*κ − γρx,viu* + *D*2

*Proof.* The proof is very similar to the proof in Appendix [A.3](#_bookmark114).

The integral for *A*(*u, τ* ) in Lemma [5.2](#_bookmark61) can only be determined analytically for constant approximations of the two expectations involved.

## Characteristic Function for the H2-CIR model

As before, we aim to find an approximation of the instantaneous covariance matrix for which the affinity of the approximation model is obtained, but now with the stochastic approximation.

√ √

**Σ**(1*,*3) now consists of two stochastic components, *v*(*t*) and *r*(*t*). We approximate both and obtain:

˜ √ √

**Σ**(1*,*3) *≈* **Σ**(1*,*3) = *ρx,rηξ*(*t*)*R*(*t*)*, R*(*t*) *≈ r*(*t*)*, ξ*(*t*) *≈ v*(*t*)*.* (5.8) This form, based on the product of two random variables, is not affine. To linearize ([5.8](#_bookmark63)) we need to specify the joint dynamics, d( ( ) ( )). If we assume that the dynamics for d( *v*(*t*)) and d( *r*(*t*)) can be approximated by normally distributed processes, we find, by Itˆo’s lemma, that the dynamics of *z*(*t*) = *ξ*(*t*)*R*(*t*) are given by:

√ √*v t r t*

√ √

. Σ

d*z*(*t*) = *µR*(*t*)*ξ*(*t*) + *µξ*(*t*)*R*(*t*) d*t* + *ψξ*(*t*)*R*(*t*)d*Wv*(*t*) + *ψR*(*t*)*ξ*(*t*)d*Wr*(*t*)*.* (5.9)

With three additional variables, *ξ*(*t*), *R*(*t*) and *z*(*t*), the state vector **X**(*t*), with log- stock process *x*(*t*) = log *S*(*t*) is expanded to **X**(*t*) = [*x*(*t*)*, v*(*t*)*, r*(*t*)*, ξ*(*t*)*, R*(*t*)*, z*(*t*)]T, with the following corresponding system of SDEs:

**** d*x*(*t*) = .*r*(*t*) *−*  1 *v*(*t*)Σ d*t*+ √*v*(*t*)d*Wx*(*t*)*, x*(0) = log(*S*(0))*,*

2

**** *−* √

 d*v*(*t*) = *κ*(*v*¯ *v*(*t*))d*t*+ *γ v*(*t*)d*Wv*(*t*)*, v*(0) *>* 0*,*

d*r*(*t*) = *λ*(*θ*(*t*) *− r*(*t*))d*t*+ *η r*(*t*)d*Wr*(*t*)*, r*(0) *>* 0*,* with the linearizing variables *ξ*(*t*), *R*(*t*) and *z*(*t*) given by:

√

 √

d*ξ*(*t*) = *µξ*(*t*)d*t*+ *ψξ*(*t*)d*Wv*(*t*)*, ξ*(0) = *v*(0)*,*

√

d*R*(*t*) = *µR*(*t*)d*t*+ *ψR*(*t*)d*Wr*(*t*)*, R*(0) = *r*(0)*,*

d*z*(*t*) = .*µR*(*t*)*ξ*(*t*) + *µξ*(*t*)*R*(*t*)Σ d*t*+ *ψξ*(*t*)√*r*(*t*)d*Wv*(*t*)+ *ψR*(*t*)√*v*(*t*)d*Wr*(*t*)*,*

√ √ √ √ √ √*≈ ≈ ≈*

(5.10)

(5.11)

with *z*(0) = *r*(0) *v*(0), *ξ*(*t*) *v*(*t*), *R*(*t*) *r*(*t*), *z*(*t*) *v*(*t*) *r*(*t*) and the other

parameters as in ([2.3](#_bookmark3)). The symmetric instantaneous covariance matrix reads:

 *v*(*t*) *ρx,vγv*(*t*) 

|  |  |  |  |
| --- | --- | --- | --- |
| *ρx,rηz*(*t*) | *ρx,vψξ*(*t*)*ξ*(*t*) | *ρx,rψR*(*t*)*ξ*(*t*) | *ρx,vψξ*(*t*)*z*(*t*) + *ρx,rψR*(*t*)*v*(*t*) |
| 0 | *ψξ*(*t*)*γξ*(*t*) | 0 | *γψξ*(*t*)*z*(*t*) |
| *η*2*r*(*t*) | 0 | *ψR*(*t*)*ηR*(*t*) | *ηψR*(*t*)*z*(*t*) |

**Σ**˜*∗* = 

*∗ γ*2*v*(*t*)

*∗ ∗ ξ* 2

*∗ ∗ ∗ ∗*

*ξ* 2  *,*

 *∗ ∗ ∗* (*ψ* (*t*)) 0 (*ψ* (*t*)) *R*(*t*)

*∗ ∗ ∗ ∗ ∗*







(*ψR*(*t*))2 (*ψR*(*t*))2*ξ*(*t*)

(*ψξ*(*t*))2*r*(*t*) + (*ψR*(*t*))2*v*(*t*)

(5.12)

Since *ψξ*(*t*) and *ψR*(*t*) are deterministic time-dependent functions, the approximate H2-CIR

model is now affine and we can derive the corresponding ChF:

*φ*H2-CIR(*u,* **X**(*t*)*, τ* ) = exp (*A*(*u, τ* ) + *B*(*u, τ* )*x*(*t*) + *C*(*u, τ* )*r*(*t*) + *D*(*u, τ* )*v*(*t*)

+*E*(*u, τ* )*ξ*(*t*) + *F* (*u, τ* )*R*(*t*) + *tt*(*u, τ* )*z*(*t*)) *,*

(5.13)

with *ξ*(*t*) = *v*(*t*)*, R*(*t*) = *r*(*t*), *z*(*t*) = *v*(*t*) *r*(*t*), and the functions *A*(*u, τ* )*, B*(*u, τ* ),

*C*(*u, τ* ), *D*(*u, τ* ), *E*(*u, τ* ), *F* (*u, τ* ) and *tt*(*u, τ* ) satisfy the ODEs given by the lemma below.

√ √ √ √

**Lemma 5.3** (The ODEs related to the H2-CIR model)**.** *The functions B*(*u, τ* ) =: *B*(*τ* )*, C*(*u, τ* ) =: *C*(*τ* )*, D*(*u, τ* ) =: *D*(*τ* )*, E*(*u, τ* ) =: *E*(*τ* )*, F* (*u, τ* ) =: *F* (*τ* )*, tt*(*u, τ* ) =: *tt*(*τ* ) *and A*(*u, τ* ) =: *A*(*τ* ) *for u ∈* R *and τ >* 0 *in ([5.13](#_bookmark65)), satisfy:*

*Bj*(*τ* ) = 0*,*

*Cj*(*τ* ) = *−*1 + *B*(*τ* ) *− λC*(*τ* ) + *η*2*C*2(*τ* )*/*2 + (*ψξ*(*t*))2*tt*2(*τ* )*/*2*,*

*Fj*(*τ* ) = *µξ*(*t*)*tt*(*τ* ) + *ψR*(*t*)*ηC*(*τ* )*tt*(*τ* ) + (*ψξ*(*t*))2*E*(*τ* )*tt*(*τ* )*,*

*ttj*(*τ* ) = *ηρx,rB*(*τ* )*C*(*τ* ) + *ρx,vψξ*(*t*)*B*(*τ* )*tt*(*τ* ) + *γψξ*(*t*)*D*(*τ* )*tt*(*τ* ) + *ηψR*(*t*)*C*(*τ* )*tt*(*τ* )*,*

*Aj*(*τ* ) = *κv*¯*D*(*τ* ) + *λθC*(*τ* ) + *µξ*(*t*)*E*(*τ* ) + *µR*(*t*)*F* (*τ* ) + (*ψξ*(*t*))2*E*2(*τ* )*/*2 + (*ψR*(*τ* ))2*F* 2(*τ* )*/*2*,*

*and*

*Dj*(*τ* ) = *B*(*τ* ) (*B*(*τ* ) *−* 1) */*2 *− κD*(*τ* ) + *γρx,vB*(*τ* )*D*(*τ* ) + *γ*2*D*2(*τ* )*/*2

+*ρx,rψR*(*t*)*B*(*τ* )*tt*(*τ* ) + (*ψR*(*t*))2*tt*2(*t*)*/*2*,*

*Ej*(*τ* ) = *µR*(*t*)*tt*(*τ* ) + *ψξ*(*t*)*ρx,vB*(*τ* )*E*(*τ* ) + *γψξ*(*t*)*D*(*τ* )*E*(*τ* )

+*ρx,rψR*(*t*)*B*(*τ* )*F* (*τ* ) + (*ψR*(*t*))2*F* (*τ* )*tt*(*τ* )*,*

*with the boundary conditions: B*(*u,* 0) = *iu, C*(*u,* 0) = 0*, D*(*u,* 0) = 0*, E*(*u,* 0) = 0*, F* (*u,* 0) = 0*, tt*(*u,* 0) = 0 *and A*(*u,* 0) = 0*. Parameters µξ*(*t*)*, µR*(*t*)*, ψξ*(*t*)*, ψR*(*t*) *are specified in ([4.9](#_bookmark50)), and the remaining parameters are in ([5.10](#_bookmark64)).*

*Proof.* The proof is very similar to the proof in Appendix [A.2](#_bookmark112).

The system of the ODEs given in Lemma [5.3](#_bookmark66) is difficult to solve analytically. To find the solution we have used an explicit Runge-Kutta method [[Forsythe,](#_bookmark90) *[et al.](#_bookmark90)*; [Kahaner-1989](#_bookmark102)], *ode45* from the Matlab package. Numerical results are presented in the next subsection.

The extension of the H2-CIR model to the case of a full matrix of correlations is a trivial exercise.

## Numerical Experiment

We compare the performance of the approximations H1-CIR and H2-CIR with the full-scale HCIR model. As in the case of the HHW models, we have chosen here *T* = 10, and the model parameters are chosen so that the Feller condition does not hold. The results, presented in Table [5.1](#_bookmark67), are very satisfactory. Both approximation models, H1-CIR and H2-CIR, provide an error, *s*(*ρx,r*), for a call option within the confidence bounds. For higher correlation *ρx,r* the error grows, but it is still small.

|  |  |  |  |  |  |  |
| --- | --- | --- | --- | --- | --- | --- |
| *ρx,r* | Strike | Monte Carlo Imp.vol. [%] | Approx 1 | Approx 2 | err.1 | err.2 |
|  | 40 | 38.29 (0.17) | 38.30 | 38.33 | -0.01 | -0.04 |
|  | 80 | 27.65 (0.15) | 27.68 | 27.71 | -0.03 | -0.06 |
| 20% | 100 | 24.12 (0.18) | 24.19 | 24.11 | -0.07 | 0.01 |
|  | 120 | 21.59 (0.17) | 21.72 | 21.67 | -0.13 | -0.08 |
|  | 180 | 19.68 (0.18) | 19.75 | 19.71 | -0.06 | -0.03 |
|  | 40 | 37.95 (0.14) | 38.32 | 38.35 | -0.37 | -0.40 |
|  | 80 | 27.47 (0.12) | 27.76 | 27.76 | -0.29 | -0.29 |
| 60% | 100 | 23.97 (0.13) | 24.35 | 24.09 | -0.38 | -0.13 |
|  | 120 | 21.44 (0.13) | 21.98 | 21.74 | -0.54 | -0.31 |
|  | 180 | 19.40 (0.14) | 19.97 | 19.83 | -0.56 | -0.43 |

Table 5.1: The implied volatilities and errors for a deterministic (Approx 1) from ([2.16](#_bookmark19)) with approximation ([3.2](#_bookmark23)) and stochastic (Approx 2) approximation from Section [4.1](#_bookmark46) of the HCIR model compared to the Monte Carlo simulation performed with 20T steps and 100.000 paths. The error is defined as a difference between the reference implied volatilities and the approximation. The parameters were chosen as follows: *κ* = 0*.*3, *γ* = 0*.*6, *v*(0) = *v*¯ = 0*.*05,

*λ* = 0*.*01, *r*(0) = *θ* = 0*.*02, *η* = 0*.*01, *S*(0) = 100 and the correlations *ρx,v* = *−*30% and

*ρx,r ∈ {*20%*,* 60%*}*. Numbers in brackets indicate standard deviations.

We also present the time needed for obtaining the plain vanilla option prices, with the characteristic functions H2-HW (Section [4.2](#_bookmark51)) and H2-CIR (Section [5.2](#_bookmark62)) based on the numerical solution for the system of Riccati ODEs. Table [5.2](#_bookmark68) shows that, although the ODEs in

Lemma [5.3](#_bookmark66) need to be solved numerically, the time for obtaining European option prices, by the COS pricing method [[Fang,Oosterlee-2008](#_bookmark88)], is often less than 0.1 seconds. The pricing of the options by means of the COS method, a method based on Fourier cosine series expansions, was performed with a fixed number of 250 terms, which guaranteed highly accurate option prices (up to machine precision).

The tolerance for the ODE solves, by Matlab’s *ode45*, is varied in the experiments shown in the table.

Table 5.2: Time in seconds for pricing a call option based on an explicit Runge-Kutta method combined with the COS method [[Fang,Oosterlee-2008](#_bookmark88)].

|  |  |  |  |  |  |  |
| --- | --- | --- | --- | --- | --- | --- |
| **Model** | **Accuracy** | **Maturity** | | | | |
| *τ* = 0*.*5 | *τ* = 1 | *τ* = 2 | *τ* = 5 | *τ* = 10 |
| **H2-HW** | 10*−*2  10*−*5 | 4.37e-2  5.32e-2 | 4.80e-2  5.82e-2 | 6.41e-2  8.05e-2 | 7.49e-2  9.74e-2 | 8.10e-2  1.21e-1 |
| **H2-CIR** | 10*−*2  10*−*5 | 7.78e-2  8.33e-2 | 7.80e-2  8.97e-2 | 8.38e-2  1.05e-1 | 8.48e-2  1.34e-1 | 8.90e-2  1.62e-1 |

# Calibration of the Heston Hybrid Models

Here, we evaluate the performance of the approximations H1-HW and H2-HW for the HHW hybrid model in a calibration setting.

Reference call option prices, based on synthetic data that is representative for the skew and smile patterns observed in real-life applications. For all models the simulation was performed with an a-priori defined speed of mean reversion for the variance process, *κ* = 0*.*3 (which is set small on purpose). The calibration is here performed with constant correlation, *ρx,r* = 20%. In practice, this correlation can be obtained from historical data.

The calibration procedure is performed in two stages. First, the parameters for the short rate process are determined (independent of the equity part). In the second stage, the calibrated *r*(*t*) is included in the Heston model, and the remaining parameters are determined. The parameters for the interest rate part are found to be *λ*HW = 0*.*501, *η*HW = 0*.*005 and *r*(0) = 0*.*04.

First, we also perform, as a benchmark, the calibration of the pure Heston model with constant interest rate, see Table [6.1](#_bookmark70). SSE stands stands for the “sum-squared error”. We calibrate the models for different maturities, *τ* .

Table 6.1: Calibration results for the Heston stochastic volatility model with deterministic interest rate. The mean reversion parameter is *κ* = 0*.*3.

|  |  |  |  |  |  |  |
| --- | --- | --- | --- | --- | --- | --- |
| **model** | *γ* | *v*¯ | *ρx,v* | *v*(0) | *r* | **SSE** |
| **Heston** (*τ* = 0*.*5)  **Heston** (*τ* = 10) | 0.5992  0.6019 | 0.0823  0.0828 | -58.32%  -48.49% | 0.0407  0.0411 | 0.04  0.04 | 4.9063E-4  1.2182E-4 |

In Table [6.2](#_bookmark71) the calibration results for the HHW approximations, H1-HW and H2-HW, are presented. For both models a highly satisfactory fit is obtained, with a slightly better performance of the stochastic approximation H2-HW. For *ρx,r* = 0*.*2 the calibration procedure gives roughly the same sets of parameters for both models. When comparing the calibration results for HHW with those for the pure Heston model, we see that the inclusion of stochastic interest rates in the model results in a lower vol-vol parameter, *γ*, and a more negative correlation, *ρx,v*. The lower value of parameter *γ* can be explained by the additional volatility which comes from the interest rate process.

In Figure [6.1](#_bookmark72) the corresponding implied volatilities, for the full-scale model, for a short and long maturity time (*τ* = 0*.*5 and *τ* = 10*y*) are presented. The left-hand sides of the figure present the implied volatilities and their errors for H1-HW and H2-HW. The related implied volatilities of the full-scale HHW model, with the parameters from H1-HW and H2-HW, are shown in the right-hand side of the figure.

Both hybrid models perform very well. For long maturities a higher accuracy for the hybrid models compared to the plain Heston model can be observed.

Table 6.2: Calibration results for the H1-HW model from Section [3.2](#_bookmark41), and the H2-HW model from Section [4.2](#_bookmark51), with *κ* = 0*.*3*,* and correlation *ρx,r* = 20%.

|  |  |  |  |  |  |  |
| --- | --- | --- | --- | --- | --- | --- |
| **model** | *τ* | *γ* | *v*¯ | *ρx,v* | *v*(0) | **SSE** |
| **H1-HW** | *τ* = 0*.*5  *τ* = 10 | 0.5840  0.4921 | 0.0822  0.0826 | -60.06%  -61.50% | 0.0407  0.0418 | 4.4581E-4  3.2912E-4 |
| **H2-HW** | *τ* = 0*.*5  *τ* = 10 | 0.5879  0.4884 | 0.0930  0.0820 | -60.10%  -60.72% | 0.0398  0.0421 | 4.9677E-4  8.5934E-5 |

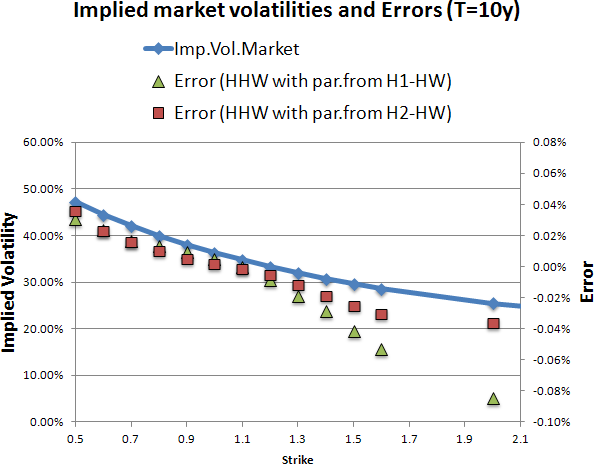
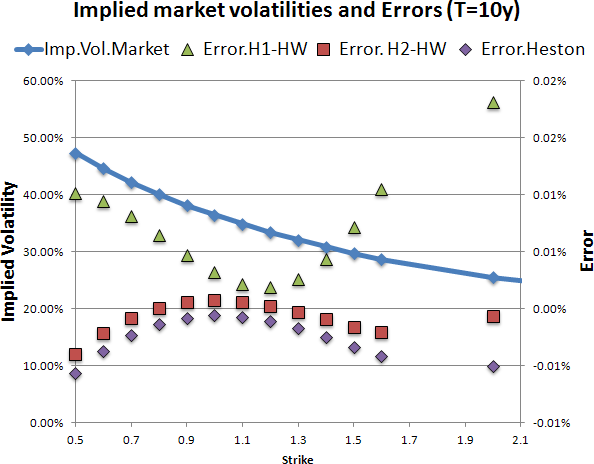
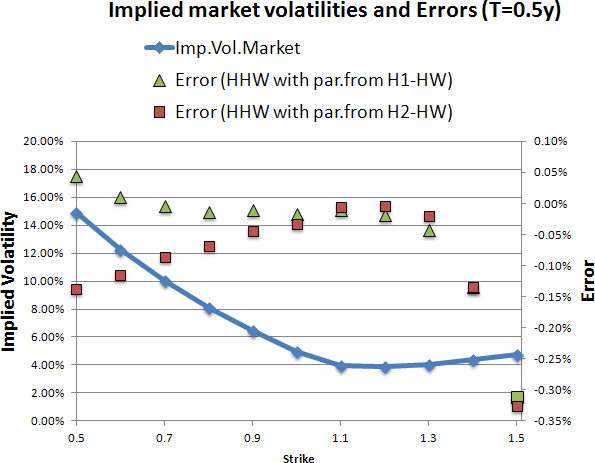
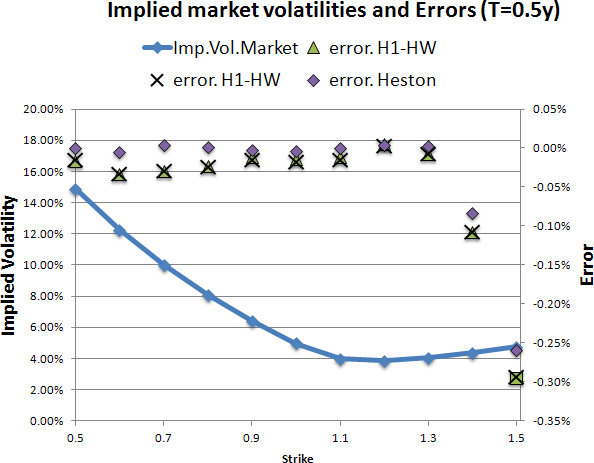


Figure 6.1: For *τ* = 0*.*5 and *τ* = 10, *ρx,r* = 20%, the implied Black-Scholes volatilities for Heston hybrid models are compared to the pure Heston model and a reference implied volatility curve. The left-hand graphs present the implied volatilities and errors for H1-HW and H2-HW. The implied volatilities for the full-scale HHW model, with the parameters from H1-HW and H2-HW are in the right-hand figures.

# Concluding Remarks

In this article we have presented the extension of the Heston stochastic volatility equity model by stochastic interest rates. We have focused our attention on two hybrid models, the Heston-Hull-White and the Heston-Cox-Ingersoll-Ross models.

By approximations of the non-affine terms in the corresponding instantaneous covariance matrix, we placed the approximation hybrid models in the framework of affine diffusion processes. The approximations in the models have been validated by comparing the implied volatilities to the full-scale hybrid models.

The approximations in the Heston-Hull-White and the Heston-Cox-Ingersoll-Ross models lead to highly efficient determination of the corresponding characteristic functions. The more sophisticated approximation is based on a transformation of the 3D Heston-CIR model to a 6D representation.

The deterministic and the stochastic approaches for approximating the instantaneous covariance matrix of the hybrid model provide highly satisfactory approximations for prices for European options.

The approximations compare favorably, in terms of accuracy and CPU time, to the alternative methods available.

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# Proofs and Details

## Limits of the Approximation in Equation ([3.5](#_bookmark26))

We show here for which parameters the expression under the square-root in approxima- tion ([3.5](#_bookmark26)), i.e.,

E(√*v*(*t*)) *≈* .*c*(*t*)(*λ*(*t*) *−* 1) + *c*(*t*)*d* + *c*(*t*)*d*

2(*d* + *λ*(*t*))

(A.1)

(repeated here for convenience) is non-negative.

Consider the following inequality, with *c*(*t*) *>* 0:

*c*(*t*)*d*

*c*(*t*)(*λ*(*t*) *−* 1) + *c*(*t*)*d* + 2(*d* + *λ*(*t*)) *≥* 0*.* (A.2)

Dividing both sides by *c*(*t*) *>* 0 gives:

2 (*λ*(*t*) + *d*) (*d* + *λ*(*t*)) + *d*

2(*d* + *λ*(*t*)) *≥* 1*.* (A.3)

So,

2 (*λ*(*t*) + *d*)2 *−* 2(*λ*(*t*) + *d*) + *d ≥* 0*.* (A.4)

By setting *y* = *λ*(*t*) + *d* we find 2*y*2 *−* 2*y* + *d ≥* 0. The parabola is non-negative for the

discriminant 4 *−* 4 *·* 2 *· d ≤* 0, so that the expression in ([A.1](#_bookmark111)) is nonnegative for *d ≥* 1 (i.e.,

2*d* 1). With *d* = 4*κv*¯*/γ*2 we can compare the inequality obtained to the Feller condition. If the Feller condition is satisfied, the expression under the square-root is certainly well-defined. If 8*κv*¯*/γ*2 1 but the Feller condition is not satisfied, the approximation is also valid. If the expression under the square-root in ([A.1](#_bookmark111)) gets negative, we suggest to use the approximations in Lemma [3.1](#_bookmark22) instead.

2

*≥*

*≥*

## Proof of Lemma [3.5](#_bookmark43)

*Proof.* For a given state vector *X*(*t*) = [*x*(*t*)*, r*(*t*)*, v*(*t*)]T, and *φ* := *φ*(*u, X*(*t*)*, t, T* ) we find the system of the ODEs satisfying the following pricing PDE:

0 = *∂φ* + .

*∂t*

*r −* 2 *v*

1 Σ *∂φ* + (¯

) *∂φ* +

( ( )

*λ θ t*

) *∂φ* + 1

*∂*2*φ*

+ 1

*∂x*

*κ v − v*

*∂v*

*− r*

*∂r*

2 *v ∂x*2

2 *γ*

*v ∂v*2

2 *∂*2*φ* + 1

2 *∂*2*φ* +

*∂*2*φ* +

E(√

( )) *∂*2*φ*

(A.5)

subject to terminal condition *φ*(*u,* **X**(*T* )*, T, T* ) = exp (*iux*(*T* )).

2 *η*

*∂r*2

*ρx,v γv∂x∂v*

*ηρx,r*

*v t*

*∂x∂r − rφ,*

Since the PDE in ([A.5](#_bookmark113)) is affine, its solution is of the following form:

*φ* := *φ*(*u, X*(*t*)*, t, T* ) = exp (*A*(*u, t, T* ) + *B*(*u, t, T* )*x*(*t*) + *C*(*u, t, T* )*r*(*t*) + *D*(*u, t, T* )*v*(*t*)) *.*

By setting *A* := *A*(*u, t, T* ), *B* := *B*(*u, t, T* ), *C* := *C*(*u, t, T* ) and *D* := *D*(*u, t, T* ) we find the following partial derivatives:

*∂φ* = *φ* . *∂A* + *x*(*t*) *∂B* + *r*(*t*) *∂C* + *v*(*t*) *∂D* Σ *,* (A.6)

*∂t*

*∂φ* =

*Bφ,*

*∂t*

*∂*2*φ*

*∂t*

= *B*2*φ,*

*∂*2*φ*

*∂t*

= *BDφ,*

*∂t*

*∂*2*φ*

= *BCφ,* (A.7)

*∂x*

*∂φ* =

*∂x*2

*∂*2*φ*

*∂x∂v*

2

*∂x∂r*

*∂r*

*∂φ* =

*Cφ,*

*∂r*2

*∂*2*φ*

= *C φ,* (A.8)

2

*Dφ,*

*∂v*

*∂v*2

= *D φ.* (A.9)

By substitution, PDE ([A.5](#_bookmark113)) becomes:

0 = *∂A* + *x∂B* + *r∂C* + *v∂D* + .*r −*  1 *v*Σ *B* + *κ*(*v*¯ *− v*)*D* + *λ*(*θ*(*t*) *− r*)*C*

*∂t*

*∂t*

*∂t*

*∂t*

2

+ 1 *vB*2 + 1 *γ*2*vD*2 + 1 *η*2*C*2 + *ρ γvBD* + *ηρ* E(√*v*(*t*))*BC − r.* (A.10)

2

2

2

*x,v*

*x,r*

Now, by collecting the terms for *x*(*t*), *r*(*t*) and *v*(*t*) we find the following set of ODEs:

*∂B* = 0*,* (A.11)

*∂t*

*∂C*

*∂t* = *−B* + *λC* + 1*,* (A.12)

*∂D* = 1 *B* + *κD −* 1 *γ*2*D*2 *− ρ γBD −* 1 *B*2*,* (A.13)

*∂t*

2

2

*x,v*

2

*∂A* = *−κv*¯*D − λθC −*  1 *η*2*C*2 *− ρ η*E(√*v*(*t*))*BC.* (A.14)

2

*x,r*

*∂t*

By setting *τ* = *T − t* the proof is finished.

## Proof of Lemma [3.6](#_bookmark44)

Obviously, due to the boundary condition, *B*(*u,* 0) = *iu*, we have *B*(*u, τ* ) = *iu*. For the second ODE, by multiplying both sides with e*λτ* we get:

d

d .e*λτ C*(*u, τ* )Σ = (*iu −* 1)e*λτ ,* (A.15)

by integrating both sides and using the boundary condition, *C*(*u,* 0) = 0, we find

. Σ

*τ*

*C*(*u, τ* ) = (*iu −* 1)*λ−*1 1 *−* e*−λτ .*

By setting *a* = *−* 1 (*u*2 + *iu*)*, b* = *γρx,viu− κ*, and *c* = 1 *γ*2*,* the ODEs for *D*(*u, τ* ) and *I*2(*τ* ) are

2 2

given by the following Riccati-type of equation:

d *D*(*u, τ* ) = *a* + *bD*(*u, τ* ) + *cD*2(*u, τ* )*, D*(*u,* 0) = 0*,* (A.16)

d*τ*

∫

*I*2(*τ* ) = *κv*¯

*τ*

*D*(*u, s*)d*s.* (A.17)

0

Equations ([A.16](#_bookmark115)) and ([A.17](#_bookmark115)) are of the same form as those in [[Heston-1993](#_bookmark94)]. Their solutions are given by:

( ) = *−b − D*1 (1 e*−D*1*τ* ) (A.18)

*D u, τ − ,*

2*c*(1 *− tt*e*−D*1*τ* )

.

. ΣΣ

*I*2(*τ* ) =

1

2*c* (*−b − D*1)*τ −* 2 log

1. *− tt*e*−D*1*τ*

1 *− tt*

*,* (A.19)

with *D*1

= *√b*2 *−* 4*ac, tt* = *−*

*b − D*1 *.*

*b* + *D*1

The evaluation of the integrals *I*1(*τ* ), *I*3(*τ* ) and *I*4(*τ* ) is straightforward. The proof is

*−*

finished by appropriate substitutions.

# Hybrid Model with Full Matrix of Correlations

Similar to the approximation of the non-affine terms in the instantaneous covariance matrix of the Heston hybrid model presented in Section [3.1](#_bookmark20), we discuss here the inclusion of the additional correlation, *ρr,v*, between the interest rate, *r*(*t*), and the stochastic variance, *v*(*t*). We call the resulting model the Heston-Hull-White Hybrid Model-3, and denote it by H3-HW. For the state vector **X**(*t*) = [*x*(*t*)*, v*(*t*)*, r*(*t*)]T the H3-HW model has the following symmetric instantaneous covariance matrix:

 *v*(*t*) *ρx,vγv*(*t*) *ρx,rη*√√*v*(*t*) 

**Σ** := *σ*(**X**(*t*))*σ*(**X**(*t*))T = 

*∗ γ*2*v*(*t*) *ρr,vγη*

*∗ ∗ η*2

*v*(*t*)

(3*×*3)



*.* (B.1)

The affinity issue arises in two terms of matrix ([B.1](#_bookmark117)), namely, in elements (1*,* 3) and (2*,* 3):

√ √

**Σ**(1*,*3) = *ρx,rη v*(*t*)*,* **Σ**(2*,*3) = *ρr,vγη v*(*t*)*.*

For completeness, we also present the associated Kolmogorov backward equation, which is now given by:

0 = *∂φ* + .

1 Σ *∂φ* + (¯

) *∂φ* +

( ( )

) *∂φ* + 1

*∂*2*φ* + 1

2 *∂*2*φ*

*∂t r −* 2 *v*

+ 1 2 *∂*2*φ*

*∂x*

*∂*2*φ*

*κ v − v*

*∂v*

*∂*2*φ*

*λ θ t*

*− r ∂r*

*∂*2*φ*

2 *v ∂x*2

2 *γ v ∂v*2

2 *η ∂r*2 + *ρx,vγv∂x∂v* + **Σ**(1*,*3) *∂x∂r* + **Σ**(2*,*3) *∂r∂v − rφ,* (B.2)

with boundary condition equal to:

*φ*(*u,* **X**(*T* )*, T, T* ) = exp(*iux*(*T* ))*.*

With *ρr,v* = 0 the H3-HW model with a full matrix of correlations collapses to the setup in Section [3.1](#_bookmark20).

√*≈ ≈x,r*(1*,*3) (2*,*3)

As before, we can use the deterministic approximation **Σ** *ρ η*E( *v*(*t*)) and **Σ**

*ρr,vγη*E( *v*(*t*)) for which Result [3.3](#_bookmark32) can be used.

√

The representations of the Heston-Hull-White model in ([2.8](#_bookmark8)) and the model in ([2.3](#_bookmark3)) with *ρr,v* = 0 for *p* = 0 are closely related. The lemma below specifies the relation in terms of the coefficients of the corresponding ChF.

*ƒ*

**Lemma B.1** (The ChF for the H3-HW model with a full matrix of correlations)**.** *The discounted ChF for the H3-HW model is of the following form:*

. Σ

*φH3-HW*(*u,* **X**(*t*)*, τ* ) = exp *A*ˆ(*u, τ* ) + *B*ˆ(*u, τ* )*x*(*t*) + *C*ˆ(*u, τ* )*r*(*t*) + *D*ˆ(*u, τ* )*v*(*t*) *,*

*with the functions A*ˆ(*u, τ* )*, B*ˆ(*u, τ* )*, C*ˆ(*u, τ* ) *and D*ˆ(*u, τ* ) *given by:*

*B*ˆ(*u, τ* ) = *B*(*u, τ* )*,*

*C*ˆ(*u, τ* ) = *C*(*u, τ* )*,*

*D*ˆ(*u, τ* ) = *D*(*u, τ* )*,* (B.3)

*with B*(*u, τ* ) *in ([3.21](#_bookmark45)), C*(*u, τ* ) *in ([3.22](#_bookmark45)) and D*(*u, τ* ) *given in ([3.23](#_bookmark45)). For A*ˆ(*u, τ* ) *we have:*

ˆ ∫ *τ* √ ˆ ˆ

*A*(*u, τ* ) = *A*(*u, τ* ) + *ρr,vγη* E(

0

*where A*(*u, τ* ) *is given in ([3.24](#_bookmark45)).*

*v*(*T − s*))*C*(*u, s*)*D*(*u, s*)d*s,* (B.4)

The accuracy of the HHW approximations with a full matrix of correlations is discussed in Appendix [C](#_bookmark118).

# Comparison to Markov Projection Method

In this appendix we compare our results to the Markovian projection (MP) method [[Antonov,](#_bookmark77) *[et al.](#_bookmark77)*[-2008](#_bookmark77)]. We check the results of three different approximation schemes: The MP method, Approx 1, i.e. the approximation with ( ) ( ( )) (Section [3.1](#_bookmark20)), and Approx 2, i.e. the method with *v*(*t*) ( ) (Section [4.1](#_bookmark46)).

√ √*v t ≈* E *v t*

[√](#_bookmark76) *≈ N ·*

In the experiment, taken directly from [[Antonov-2007](#_bookmark76)], we price an equity option with continuous dividend. The model parameters for the HHW model are given by *κ* = 0*.*25, *v*¯ = *v*(0) = 0*.*0625, *γ* = 0*.*625, *λ* = 0*.*05, *η* = 0*.*01 and a zero-coupon bond is given by *P* (0*, T* ) =

e*−*0*.*05*T* , and a continuous dividend of 2%. A full matrix of correlations, as in [[Antonov-2007](#_bookmark76)],

is given by:





1 *ρx,v ρx,r C* = *ρx,v* 1 *ρv,r*

*ρx,r ρv,r* 1

 =

100% 40% 30%

40% 100% 15%

*−*

*−*

30% 15% 100%

 *.* (C.1)

The Monte Carlo reference for the implied volatilities, the corresponding standard deviations, as well as the results for the MP method are all taken from [[Antonov-2007](#_bookmark76)].

In order to incorporate a continuous dividend in the equity model one can model foreign- exchange (FX), in which the volatility of the foreign interest rates is set to zero. In such a setup, the forward, *F* (*t*), is defined as:

*F* (*t*) = *S*(*t*)

*Pf* (*t, T* )

*Pd*(*t, T* )

*,* and *F* (0) = *S*(0)

e*−*0*.*02*T* e*−*0*.*05*T ,*

where *Pf* (*t, T* ) and *Pd*(*t, T* ) are the foreign and domestic zero-coupon bonds, respectively, paying e1 at the maturity *T* . By switching from the spot risk-neutral measure, Q, to the *T−*forward measure, Q*T* , discounting will be decoupled from taking the expectation, i.e.:

E . 1 max(*S*(*T* ) *− K,* 0)*|F* Σ = *P* (0*, T* )E*T* (max(*F* (*T* ) *− K,* 0)*|F* ) *.*

*B*(*t*)

0

*d*

0

Moreover, the forward, *F* (*t*), is a martingale with dynamics given by:

d*v*(*t*) = .*κ*(*v*¯ *− v*(*t*)) + *γρ ηB* (*t, T* )√*v*(*t*)Σ d*t* + *γ*√*v*(*t*)d*W T* (*t*)*,* (C.2)

where *Br*(*t, T* ) = 1 e*−λ*(*T −t*) 1 *,* and the full correlation structure given in ([C.1](#_bookmark119)).

*λ*

. Σ*−*

*x*

*r*

d*F* (*t*)*/F* (*t*) = √*v*(*t*)d*W T* (*t*) *− ηBr*(*t, T* )d*W T* (*t*)*,*

*v,r*

*r*

*v*

Under the log-transform, *x*(*t*) = log *F* (*t*), the Kolmogorov backward partial differential equation reads:

Σ

*v −* 2 *η Br* (*t, T* )

*∂x*2 *− ∂x*

*∂φ* .

*− ∂t* =

*κ*(*v*¯ *− v*) + *ρv,rγη*

*√ ∂φ*

. 1

*√* 1 2 2

Σ . *∂*2*φ*

*∂φ* Σ

+ . *√*

*v*

+

*∂v*

2 *v − ρx,rηBr*(*t, T* )

*ρx,vγv − ρv,rγη*

( )Σ *∂*2*φ* +

1. 2*φ*

*v ∂v*2 *,*

(C.3)

with the final condition *φ*(*u,* **X**(*T* )*, T, T* ) = e*iux*(*T* )*.*

*vBr t, T*

*∂x∂v*

2 *γ*

1

*∂*

We linearize PDE ([C.3](#_bookmark120)) in two ways: By the deterministic approach described in Section [3.1](#_bookmark20) and Appendix [B](#_bookmark116)), and by the stochastic approach as in Section [4.1](#_bookmark46). Both approximations result in affine approximations of PDE ([C.3](#_bookmark120)).

The results of the experiments performed, presented in Table [C.1](#_bookmark121), show a highly satisfactory accuracy of the HHW approximations introduced in this paper. When comparing to the MP method, we see that the MP method is more accurate for low strike values, whereas our proxies perform favorably for larger strike values, especially when large maturities are considered.

In Figure [C.1](#_bookmark122) the error results for *T* = 10 are presented. In this experiment, the stochastic approximation, Approx 2, performed somewhat better than the deterministic approach, Approx 1.

In the case of the deterministic approach, pricing of European options is done in a split- second (the corresponding ChF is analytic for when the Feller condition is satisfied; one integration step is required otherwise). In the case of the stochastic approach a numerical routine for solving the ODEs is employed. This however can also be done highly efficiently, as already presented in Table [5.2](#_bookmark68).

|  |  |  |  |  |  |  |  |  |
| --- | --- | --- | --- | --- | --- | --- | --- | --- |
| *T* | Strike | Imp.vol [%] | MP | Approx 1 | Approx 2 | err.MP | err.1 | err.2 |
|  | 86.07 | 24.45 | 24.49 | 24.48 | 24.48 | -0.04 | -0.03 | -0.03 |
|  | 92.77 | 22.25 | 22.27 | 22.27 | 22.25 | -0.02 | -0.02 | 0.00 |
| 1y | 100.00 | 20.36 | 20.32 | 20.35 | 20.30 | 0.04 | 0.01 | 0.06 |
|  | 107.79 | 19.42 | 19.34 | 19.38 | 19.34 | 0.08 | 0.04 | 0.08 |
|  | 116.18 | 19.67 | 19.64 | 19.62 | 19.64 | 0.03 | 0.05 | 0.03 |
|  | 77.12 | 22.61 | 22.65 | 22.61 | 22.63 | -0.04 | 0.00 | -0.02 |
|  | 87.82 | 20.05 | 20.05 | 20.09 | 20.06 | 0.00 | -0.04 | -0.01 |
| 3y | 100.00 | 17.95 | 17.91 | 18.09 | 17.90 | 0.04 | -0.14 | 0.05 |
|  | 113.87 | 17.23 | 17.14 | 17.32 | 17.15 | 0.09 | -0.09 | 0.08 |
|  | 129.67 | 18.02 | 17.92 | 17.93 | 18.00 | 0.10 | 0.09 | 0.02 |
|  | 71.50 | 21.89 | 21.94 | 21.90 | 21.95 | -0.05 | -0.01 | -0.06 |
|  | 84.56 | 19.43 | 19.45 | 19.52 | 19.48 | -0.02 | -0.09 | -0.05 |
| 5y | 100.00 | 17.49 | 17.44 | 17.71 | 17.45 | 0.05 | -0.22 | 0.04 |
|  | 118.26 | 16.83 | 16.72 | 17.01 | 16.76 | 0.11 | -0.18 | 0.07 |
|  | 139.85 | 17.55 | 17.42 | 17.49 | 17.57 | 0.13 | 0.06 | -0.02 |
|  | 62.23 | 21.55 | 21.61 | 21.57 | 21.68 | -0.06 | -0.02 | -0.13 |
|  | 78.89 | 19.52 | 19.51 | 19.67 | 19.61 | 0.01 | -0.15 | -0.09 |
| 10y | 100.00 | 18.01 | 17.91 | 18.31 | 17.97 | 0.10 | -0.30 | -0.04 |
|  | 126.77 | 17.41 | 17.22 | 17.67 | 17.30 | 0.19 | -0.26 | 0.11 |
|  | 160.70 | 17.75 | 17.51 | 17.79 | 17.78 | 0.24 | -0.04 | -0.03 |
|  | 51.13 | 22.28 | 22.32 | 22.37 | 22.47 | -0.04 | -0.09 | -0.19 |
|  | 71.50 | 20.91 | 20.86 | 21.14 | 21.03 | 0.05 | -0.23 | -0.12 |
| 20y | 100.00 | 19.94 | 19.77 | 20.27 | 19.91 | 0.17 | -0.33 | 0.03 |
|  | 139.85 | 19.44 | 19.16 | 19.77 | 19.32 | 0.28 | -0.33 | 0.12 |
|  | 195.58 | 19.40 | 19.05 | 19.63 | 19.39 | 0.35 | -0.23 | 0.01 |

Table C.1: The error for a deterministic (Approx 1) and stochastic approximation (Approx 2) of the HHW model compared to the MP method. The Markovian projection and Monte Carlo results with the corresponding standard deviations were taken from [[Antonov-2007](#_bookmark76)]. The error is defined as a difference between the reference implied volatilities and the approximation.

22 0.3

Reference MP

Approx 1

Approx 2

−stddev

+stddev MP

Approx 1

Approx 2

21.5

21

Implied Black−Scholes volatilities, %

20.5

0.2

0.1

20

19.5

19

0

−0.1

errors in vol, BPs

18.5 −0.2

18

17.5

−0.3

17

60 80 100 120 140 160

Strikes, ATM %

−0.4

60 80 100 120 140 160

Strikes, ATM %

Figure C.1: LEFT: Implied volatilities for a maturity of 10 years. RIGHT: The error for the different approximations. (MP stands for Markovian Projection, Approx 1 is the deterministic approach, and Approx 2 corresponds to the approximation with *v*(*t*) *≈ N* (*·*).)

√