

FINM 33000: Homework 5

Due Thursday, November 2, 2023 at 11:59pm

Problem 1

Let W be a Brownian motion and let

$$Z_t = \exp(W_t^2 - 1), \quad \text{for } t \geq 0.$$

Write Z_t in terms of drift and diffusion components. You may give your answer using differential notation, i.e. of the form

$$dZ_t = \underline{\hspace{1cm}} dt + \underline{\hspace{1cm}} dW_t,$$

or using integral notation. Give two solutions (a,b):

- Let $X_t = W_t$, so $dX_t = dW_t$. Then apply Itô to $f(x) = e^{x^2-1}$.
- Let $X_t = W_t^2 - 1$, so $dX_t = dt + 2W_t dW_t$. Then apply Itô to $f(x) = e^x$.
- Is Z a martingale?

Comment on part (b)

When X is defined by $X_t = W_t^2 - 1$, how did we know that $dX_t = dt + 2W_t dW_t$.

One way is to use Ito's rule on the function $g(w) = w^2 - 1$, to obtain

$$dX_t = dg(W_t) = g'(W_t)dW_t + \frac{1}{2}g''(W_t)(dW_t)^2 = dt + 2W_t dW_t, \text{ as claimed.}$$

Alternatively, a second way is to recall that we already calculated $d(W_t^2)$ in L4.26, so we simply have $d(W_t^2 - 1) = d(W_t^2) - 0 = dt + 2W_t dW_t$, as claimed.

How do we know that $d(W_t^2 - 1) = d(W_t^2) - 0$?

First recall: by L4.10 second point, for any Ito processes F_t and G_t and any constants a, b ,

$$\overline{\mathrm{d}(aF_t + bG_t)} = a \, \mathrm{d}F_t + b \, \mathrm{d}G_t$$

and recall L4.10 first point, for the particular case that F_t and G_t are: constant, or t , or W_t . Specifically, for any constants a, b, c , we have

$$\boxed{d(at + bW_t + c) = a dt + b dW_t}$$

and in particular $dc = 0$ if c is constant.

$$a) \quad Z_t = e^{W_t^2 - 1}$$

$$Z_t = f(X_t)$$

$$f(x) = e^{x^2 - 1} \quad f'(x) = e^{x^2 - 1} \cdot 2x \quad f''(x) = e^{x^2 - 1} \cdot 4x^2 + 2e^{x^2 - 1}$$

$$X_t = W_t \Rightarrow dX_t = dW_t$$

$$\begin{aligned} dZ_t &= df(X_t) = f'(X_t) dX_t + \frac{1}{2} f''(X_t) (dX_t)^2 \\ &= e^{W_t^2 - 1} \cdot 2W_t \cdot dW_t + [2W_t^2 e^{W_t^2 - 1} + e^{W_t^2 - 1}] (dW_t)^2 \\ &= \underline{2W_t e^{W_t^2 - 1} dW_t} + \underline{[2W_t^2 e^{W_t^2 - 1} + e^{W_t^2 - 1}] dt} \end{aligned}$$

$$b) \quad \text{Let } X_t = W_t^2 - 1$$

$$dX_t = dt + 2W_t dW_t$$

$$f(x) = e^x, \quad f'(x) = e^x, \quad f''(x) = e^x$$

$$\begin{aligned} dZ_t &= df(X_t) = f'(X_t) dX_t + \frac{1}{2} f''(X_t) (dX_t)^2 \\ &= e^{W_t^2 - 1} [dt + 2W_t dW_t] + \frac{1}{2} e^{W_t^2 - 1} [dt + 2W_t dW_t]^2 \\ &= e^{W_t^2 - 1} dt + 2W_t e^{W_t^2 - 1} dW_t + \frac{1}{2} e^{W_t^2 - 1} \cdot \end{aligned}$$

$$\left[\underbrace{dt^2}_{=0} + 4W_t \underbrace{dt dW_t}_{=0} + 4W_t^2 \underbrace{dW_t^2}_{=dt} \right]$$

$$= \underline{[e^{W_t^2 - 1} + 2W_t^2 e^{W_t^2 - 1}] dt} + \underline{2W_t e^{W_t^2 - 1} dW_t}$$

c). it is not martingale because it contains dt , it's

I_t^0 process not I_t^0 integral that contains only dW_t .

so it is not a martingale. drift does not vanish

Problem 2

Let W be a Brownian motion. Define X by

$$dX_t = \kappa(\theta - X_t)dt + \sigma dW_t$$

where κ , θ , σ , and X_0 are all constants.

- (a) Write $e^{\kappa T}X_T$ as the sum of a constant, a Riemann integral with respect to dt , and an Itô integral with respect to dW_t , such that both integrands may depend on t , but not on X .

Hint: As a first step, calculate $d(e^{\kappa t}X_t) = \dots$

- (b) Find explicit formulas for the mean and variance of X_T .

In part (b) you may use the following fact (without providing a proof):

If β_t is a *nonrandom* piecewise continuous function of t , then

$\int_0^T \beta_t dW_t$	has distribution:	Normal(mean 0, variance $\int_0^T \beta_t^2 dt$)
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essentially because the sum of independent normals is normal; more specifically because

$$\sum_{n=0}^{N-1} \beta_{t_n} \Delta W_{t_n} \quad \text{has distribution:} \quad \text{Normal}\left(\text{mean } 0, \text{ variance } \sum_{n=0}^{N-1} \beta_{t_n}^2 \Delta t\right)$$

for all positive integer N , where $\Delta t := T/N$ and $t_n := n\Delta t$ and $\Delta W_{t_n} := W_{t_{n+1}} - W_{t_n}$.

Problem 3

On next page

$$a) f(t, X) = e^{kt} X$$

$$\begin{aligned} d(e^{kt} X) &= e^{kt} dX_t + X_t de^{kt} + dX_t de^{kt} \quad (14.32) \\ &= e^{kt} dX_t + X_t \cdot e^{kt} \cdot k dt + 0 \\ &= e^{kt} dX_t + k e^{kt} X_t dt \\ &= e^{kt} [k(\theta - X_t) dt + \sigma dW_t] + k e^{kt} X_t dt \\ &= k\theta e^{kt} dt + \sigma e^{kt} dW_t \end{aligned}$$

$$\begin{aligned} \Rightarrow e^{kT} X_T &= e^{k0} X_0 + \int_0^T k\theta e^{kt} dt + \int_0^T \sigma e^{kt} dW_t \\ &= X_0 + (\theta e^{kT} - \theta) + \int_0^T \sigma e^{kt} dW_t \\ &= X_0 + \theta(e^{kT} - 1) + \int_0^T \sigma e^{kt} dW_t \end{aligned}$$

b) If $\beta_t = \sigma e^{kt}$ is a nonrandom piecewise continuous function of t , then $\int_0^T \sigma e^{kt} dW_t$ has distribution

$$\sim N(0, \int_0^T \sigma^2 e^{2kt} dt = \frac{\sigma^2}{2k} [e^{2kT} - 1])$$

$$\therefore \int_0^T \sigma e^{kt} dW_t \sim N(0, \frac{\sigma^2}{2k} (e^{2kT} - 1))$$

$$\therefore e^{kT} X_T = X_0 + \theta(e^{kT} - 1) + \int_0^T \sigma e^{kt} dW_t$$

$$\therefore e^{kT} X_T \sim N(X_0 + \theta(e^{kT} - 1), \frac{\sigma^2}{2k} (e^{2kT} - 1))$$

$$\therefore X_T \sim N\left(\frac{X_0 + \theta(e^{kT} - 1)}{e^{kT}}, \frac{\frac{\sigma^2}{2k} (e^{2kT} - 1)}{e^{2kT}}\right)$$

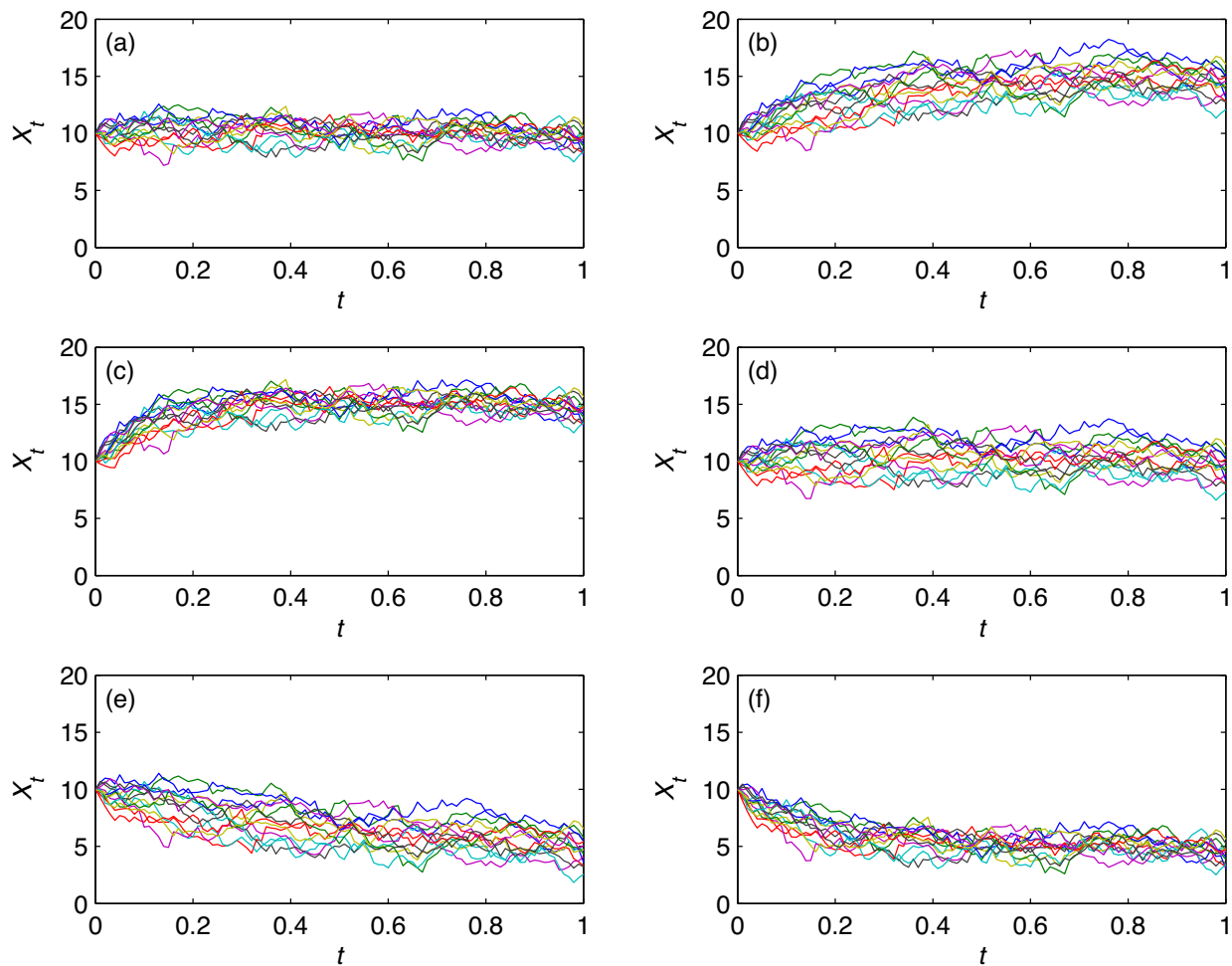
$\nearrow \text{Var}(bX) = b^2 \text{Var}(X)$

Problem 3

Here are 6 examples of the dynamics in Problem 2. All have the form

$$dX_t = \kappa(\theta - X_t)dt + \sigma dW_t$$

where $\sigma = 4$ and $X_0 = 10$ in all cases. For each of the $2 \times 3 = 6$ combinations of choices $\kappa \in \{3, 8\}$ and $\theta \in \{5, 10, 15\}$, I plotted some sample paths.



For each process (a,b,c,d,e,f), state the κ and the θ that I used to generate that process.

No justification necessary.

Hint: In each case the process is *mean-reverting*. Intuitively, θ is the mean reversion “level” or the “long-term mean”; and κ is the mean reversion “rate” or “speed”.

$$dX_t = \kappa(\theta - X_t)dt + 4dW_t$$

a $\kappa = 8$ $\theta = 10$

b $\kappa = 3$ $\theta = 15$

c $\kappa = 8$ $\theta = 15$

d $\kappa = 3$ $\theta = 10$

e $\kappa = 3$ $\theta = 5$

f $\kappa = 8$ $\theta = 5$