

A numerical example

We provide a simple numerical example to illustrate the ultrarobust support vector registration (Ur-SVR) algorithm.

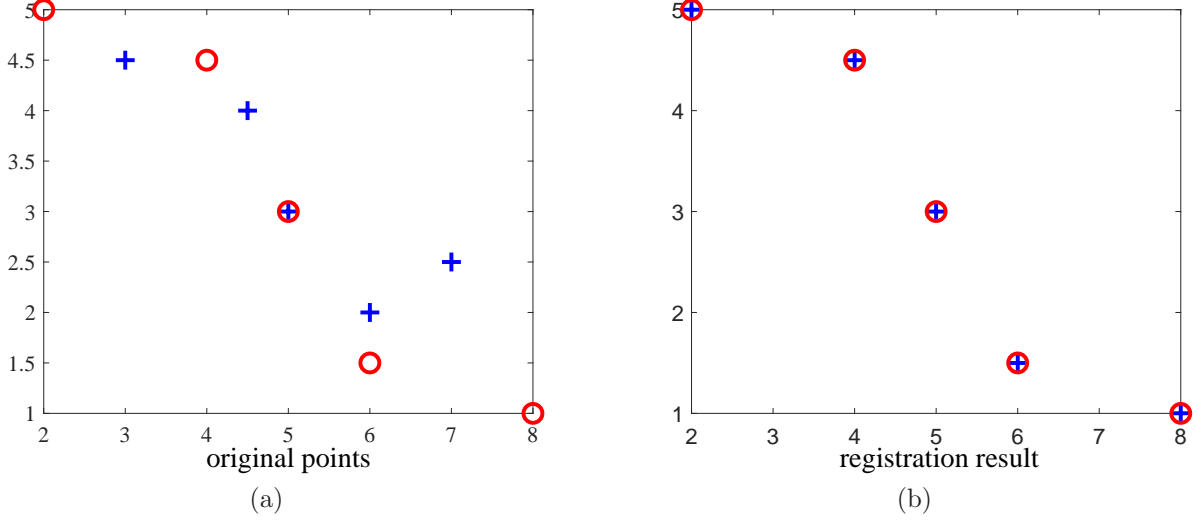


Figure 1: A numerical example for Ur-SVR. The goal is to warp the source point set ('+') to the target point set ('o'). The initial state of the point sets is presented in (a). The registration result is presented in (b).

Let \mathbf{X} be the source point set and \mathbf{Y} be the target point set:

$$\mathbf{X} = \begin{bmatrix} 3.0 & 4.5 \\ 4.5 & 4.0 \\ 5.0 & 3.0 \\ 6.0 & 2.0 \\ 7.0 & 2.5 \end{bmatrix}, \quad \mathbf{Y} = \begin{bmatrix} 2.0 & 5.0 \\ 4.0 & 4.5 \\ 5.0 & 3.0 \\ 6.0 & 1.5 \\ 8.0 & 1.0 \end{bmatrix},$$

where they are expressed as 5×2 matrices, and each row represents the coordinate of a point. The goal is to match \mathbf{X} to \mathbf{Y} . Since the points in \mathbf{X} and \mathbf{Y} are few, we use all points throughout the whole matching process by setting the coarse-to-fine threshold $\delta = 100\%$ and the number of basis functions $\Psi = 5$. The matching procedure is introduced as follows:

1. Build the feature correspondences \mathcal{M} based on the SC descriptor:

$$\mathcal{M} = \left\{ \left(\begin{bmatrix} 3.0 \\ 4.5 \end{bmatrix}, \begin{bmatrix} 2.0 \\ 5.0 \end{bmatrix} \right), \left(\begin{bmatrix} 4.5 \\ 4.0 \end{bmatrix}, \begin{bmatrix} 4.0 \\ 4.5 \end{bmatrix} \right), \left(\begin{bmatrix} 5.0 \\ 3.0 \end{bmatrix}, \begin{bmatrix} 5.0 \\ 3.0 \end{bmatrix} \right), \left(\begin{bmatrix} 6.0 \\ 2.0 \end{bmatrix}, \begin{bmatrix} 6.0 \\ 1.5 \end{bmatrix} \right), \left(\begin{bmatrix} 7.0 \\ 2.5 \end{bmatrix}, \begin{bmatrix} 8.0 \\ 1.0 \end{bmatrix} \right) \right\}.$$

2. Normalize data to have zero mean and unit variance before transformation estimation:

$$\mathbf{X} = \begin{bmatrix} -1.8074 & 1.1189 \\ -0.5164 & 0.6885 \\ -0.0861 & -0.1721 \\ 0.7746 & -1.0328 \\ 1.6353 & -0.6025 \end{bmatrix}, \quad \mathbf{Y} = \begin{bmatrix} -1.6641 & 1.1094 \\ -0.5547 & 0.8321 \\ 0 & 0 \\ 0.5547 & -0.8321 \\ 1.6641 & -1.1094 \end{bmatrix}.$$

3. Compute the Laplacian matrix \mathbf{L} :

$$\mathbf{L} = \mathbf{D} - \mathbf{W} = \begin{bmatrix} 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}.$$

There are only five points in \mathbf{X} and they are far from each other, resulting in the obtained \mathbf{L} being a zero matrix. A more detailed calculation process about \mathbf{L} is presented at the end of the document.

4. Compute the Gram matrix \mathbf{K}_Ψ :

$$\mathbf{K}_\Psi = \left(e^{-\tau \|\mathbf{x}_i - \mathbf{x}_j\|^2} \right)_{5 \times 5} = \begin{bmatrix} 1.0000 & 0.0246 & 0.0001 & 0 & 0 \\ 0.0246 & 1.0000 & 0.1569 & 0.0001 & 0 \\ 0.0001 & 0.1569 & 1.0000 & 0.0517 & 0.0018 \\ 0 & 0.0001 & 0.0517 & 1.0000 & 0.1569 \\ 0 & 0 & 0.0018 & 0.1569 & 1.0000 \end{bmatrix},$$

where $\tau = 2$, and $\mathbf{x}_i, \mathbf{x}_j \in \mathbf{X}$, $i, j = 1, 2, \dots, 5$.

5. Determine parameter ε using Eq. (20) and Eq. (3): $\varepsilon = 0.0205$. Note that all quoted formulas in the document come from the paper that proposes Ur-SVR.
6. Initialize the weight coefficients of the model in Eq. (11): $c_i = 1$, $i = 1, 2, \dots, 5$.
7. Estimate the transformation f by the coordinate descent method under the current c_i , $i = 1, 2, \dots, 5$:

Initialize the constraint conditions of the model in Eq. (11): $\mathbf{r}_i = \mathbf{0}$ and $\hat{\mathbf{r}}_i = \mathbf{0}$, $i = 1, 2, \dots, 5$.

- 1) Because the use of the displacement enables greater robustness, we estimate a displacement function g , defined as $g(\mathbf{x}) = f(\mathbf{x}) - \mathbf{x}$, instead of estimating f directly. Accordingly, \mathbf{Y} in Eq. (19) is assigned the difference of the target point set minus

the source point set. With $\mathbf{V} = \mathbf{K}_\Psi$, $\mathbf{U} = \mathbf{V}$, $\lambda_1 = 0.1$, and $\lambda_2 = 0.1$, we update the displacement function g (i.e., coefficient matrix $\bar{\mathbf{A}}$) using Eq. (19):

$$\bar{\mathbf{A}} = \begin{bmatrix} 0.1377 & -0.0118 \\ -0.0548 & 0.1168 \\ 0.1010 & 0.1345 \\ -0.2235 & 0.2626 \\ 0.0607 & -0.5223 \end{bmatrix}.$$

2) Update \mathbf{r}_i and $\hat{\mathbf{r}}_i$, $i = 1, 2, \dots, 5$ using Eq. (13):

$$\mathbf{R} = \begin{bmatrix} 0.0273 & 0.0199 \\ 0.0177 & 0.0263 \\ 0.0255 & 0.0272 \\ 0.0093 & 0.0336 \\ 0.0235 & 0 \end{bmatrix}, \quad \hat{\mathbf{R}} = \begin{bmatrix} 0.0136 & 0.0211 \\ 0.0232 & 0.0146 \\ 0.0154 & 0.0137 \\ 0.0316 & 0.0073 \\ 0.0174 & 0.0466 \end{bmatrix},$$

where $\mathbf{R} = (\mathbf{r}_1, \mathbf{r}_2, \dots, \mathbf{r}_5)^T$ and $\hat{\mathbf{R}} = (\hat{\mathbf{r}}_1, \hat{\mathbf{r}}_2, \dots, \hat{\mathbf{r}}_5)^T$.

Alternate between the above 1) and 2) until $\bar{\mathbf{A}}$ converges or the number of iterations reaches the maximum, obtaining:

$$\bar{\mathbf{A}} = \begin{bmatrix} 0.1155 & -0.0093 \\ -0.0417 & 0.0992 \\ 0.0800 & 0.1169 \\ -0.1935 & 0.2284 \\ 0.0459 & -0.4771 \end{bmatrix}.$$

Compute the transformed point set $f(\mathbf{X})$ using Eq. (18):

$$f(\mathbf{X}) = \mathbf{U}\bar{\mathbf{A}} + \mathbf{X} = \begin{bmatrix} -1.6929 & 1.1120 \\ -0.5427 & 0.8059 \\ -0.0225 & -0.0288 \\ 0.5924 & -0.8733 \\ 1.6509 & -1.0436 \end{bmatrix}.$$

8. Estimate the weight coefficients c_i , $i = 1, 2, \dots, 5$ by the EM algorithm under the current f :

Initialize the model parameters $\Theta = \{\sigma_k^2, \pi_k\}_{k=1}^3$ in Eq. (5):

$$\boldsymbol{\sigma}^2 = \begin{bmatrix} 0.0010 \\ 0.0011 \\ 0.0012 \end{bmatrix}, \quad \boldsymbol{\pi} = \begin{bmatrix} 0.3 \\ 0.3 \\ 0.3 \end{bmatrix},$$

where $\boldsymbol{\sigma}^2 = (\sigma_1^2, \sigma_2^2, \sigma_3^2)^T$ and $\boldsymbol{\pi} = (\pi_1, \pi_2, \pi_3)^T$.

- 1) E step: Update p_{ik} , $i = 1, 2, \dots, 5$ and $k = 1, 2, 3$ using Eq. (7) with $v = 7.3846$ (i.e., the area of the bounding box of the \mathbf{Y}):

$$\mathbf{P} = \begin{bmatrix} 0.3523 & 0.3327 & 0.3148 \\ 0.3524 & 0.3327 & 0.3147 \\ 0.3451 & 0.3333 & 0.3214 \\ 0.3195 & 0.3347 & 0.3454 \\ 0.3001 & 0.3349 & 0.3642 \end{bmatrix},$$

where the ik th entry of \mathbf{P} is p_{ik} .

- 2) M step: Update σ_k^2 and π_k , $k = 1, 2, 3$ using Eq. (10):

$$\boldsymbol{\sigma}^2 = \begin{bmatrix} 0.0010 \\ 0.0011 \\ 0.0011 \end{bmatrix}, \quad \boldsymbol{\pi} = \begin{bmatrix} 0.3339 \\ 0.3337 \\ 0.3321 \end{bmatrix},$$

where $\boldsymbol{\sigma}^2 = (\sigma_1^2, \sigma_2^2, \sigma_3^2)^T$ and $\boldsymbol{\pi} = (\pi_1, \pi_2, \pi_3)^T$.

Alternate between the above 1) and 2), until Q in Eq. (8) converges or the number of iterations reaches the maximum, obtaining:

$$\mathbf{P} = \begin{bmatrix} 0.3381 & 0.3336 & 0.3284 \\ 0.3381 & 0.3336 & 0.3283 \\ 0.3364 & 0.3337 & 0.3298 \\ 0.3307 & 0.3342 & 0.3351 \\ 0.3263 & 0.3345 & 0.3392 \end{bmatrix},$$

where the ik th entry of \mathbf{P} is p_{ik} , $i = 1, 2, \dots, 5$ and $k = 1, 2, 3$.

Compute the weight coefficients c_i , $i = 1, 2, \dots, 5$:

$$\mathbf{C} = \begin{bmatrix} 1 & 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 1 \end{bmatrix}$$

where \mathbf{C} is a diagonal matrix with the ii th entry being the $c_i = \sum_{k=1}^3 p_{ik}$. The converged probabilistic model concludes that the matching probability of each point pair in \mathcal{M} approximates or equals 1.

9. Iterate between the above step 7 and step 8 until $\bar{\mathbf{A}}$ converges or the number of iterations reaches the maximum, obtaining the estimated transformation f under the optimized c_i , $i = 1, 2, \dots, 5$:

$$\bar{\mathbf{A}} = \begin{bmatrix} 0.1155 & -0.0093 \\ -0.0417 & 0.0992 \\ 0.0800 & 0.1169 \\ -0.1935 & 0.2284 \\ 0.0459 & -0.4771 \end{bmatrix}, \quad f(\mathbf{X}) = \begin{bmatrix} -1.6929 & 1.1120 \\ -0.5427 & 0.8059 \\ -0.0225 & -0.0288 \\ 0.5924 & -0.8733 \\ 1.6509 & -1.0436 \end{bmatrix}.$$

10. Update the source point set \mathbf{X} by $f(\mathbf{X})$ and inverse normalize \mathbf{X} :

$$\mathbf{X} = \begin{bmatrix} 1.9481 & 5.0047 \\ 4.0216 & 4.4528 \\ 4.9594 & 2.9481 \\ 6.0680 & 1.4257 \\ 7.9763 & 1.1187 \end{bmatrix}.$$

11. Repeat steps 1–10 until \mathbf{X} sufficiently approaches \mathbf{Y} or the number of repeats reaches the maximum, obtaining:

$$\mathbf{X} = \begin{bmatrix} 2.0000 & 5.0000 \\ 4.0000 & 4.5000 \\ 5.0000 & 3.0000 \\ 6.0000 & 1.5000 \\ 8.0000 & 1.0001 \end{bmatrix}.$$

The calculation results of the above steps are output by the program of Ur-SVR with only four decimal places retained. The initial state and the registration result of \mathbf{X} and \mathbf{Y} are shown in Figure 1.

The calculation process of the Laplacian matrix \mathbf{L} :

Given a weighted graph $G = (V, E, \omega)$, the vertex set V includes all \mathbf{x}_i , the edge set E contains edges e_{ij} joining vertices \mathbf{x}_i and \mathbf{x}_j , and ω_{ij} represents the weight of edge e_{ij} , with

$$\omega_{ij} = \begin{cases} e^{-\frac{1}{t}\|\mathbf{x}_i - \mathbf{x}_j\|^2}, & \|\mathbf{x}_i - \mathbf{x}_j\|^2 \leq \eta, \\ 0, & \|\mathbf{x}_i - \mathbf{x}_j\|^2 > \eta, \end{cases} \quad (t = 0.2, \eta = 0.2).$$

Since

$$(\|\mathbf{x}_i - \mathbf{x}_j\|^2)_{5 \times 5} = \begin{bmatrix} 0 & 1.8519 & 4.6296 & 11.2963 & 14.8148 \\ 1.8519 & 0 & 0.9259 & 4.6296 & 6.2963 \\ 4.6296 & 0.9259 & 0 & 1.4815 & 3.1481 \\ 11.2963 & 4.6296 & 1.4815 & 0 & 0.9259 \\ 14.8148 & 6.2963 & 3.1481 & 0.9259 & 0 \end{bmatrix},$$

we have

$$\mathbf{W} = \begin{bmatrix} 1 & 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 1 \end{bmatrix},$$

with the ij th entry being ω_{ij} . Hence, the diagonal matrix \mathbf{D} can be constructed:

$$\mathbf{D} = \begin{bmatrix} 1 & 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 1 \end{bmatrix},$$

in which the ii th entry is $d_{ii} = \sum_{j=1}^5 \omega_{ij}$.

Therefore, we have

$$\mathbf{L} = \mathbf{D} - \mathbf{W} = \begin{bmatrix} 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}.$$