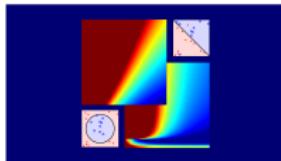


# Machine Learning Foundations (機器學習基石)



Lecture 16: Three Learning Principles

Hsuan-Tien Lin (林軒田)

[htlin@csie.ntu.edu.tw](mailto:htlin@csie.ntu.edu.tw)

Department of Computer Science  
& Information Engineering

National Taiwan University  
(國立台灣大學資訊工程系)



# Roadmap

- ① When Can Machines Learn?
- ② Why Can Machines Learn?
- ③ How Can Machines Learn?
- ④ How Can Machines Learn **Better?**

## Lecture 15: Validation

(crossly) reserve **validation data** to simulate testing procedure for **model selection**

## Lecture 16: Three Learning Principles

- Occam's Razor
- Sampling Bias
- Data Snooping
- Power of Three

# Occam's Razor

*An explanation of the data should be made as simple as possible, but no simpler.*—Albert Einstein? (1879-1955)

*entia non sunt multiplicanda praeter necessitatem*  
(entities must not be multiplied **beyond necessity**)  
—William of Occam (1287-1347)

'Occam's razor' for trimming down unnecessary explanation

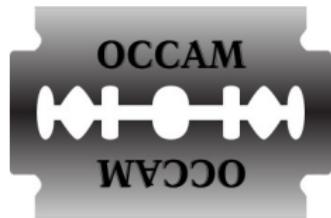
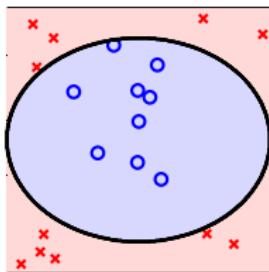


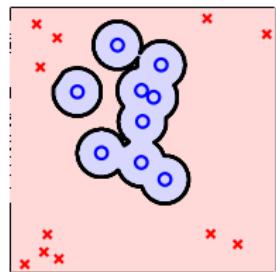
figure by Fred the Oyster (Own work) [CC-BY-SA-3.0], via Wikimedia Commons

# Occam's Razor for Learning

**The simplest model that fits the data is also the most plausible.**



which one do you prefer? :-)



two questions:

- ① What does it mean for a model to be simple?
- ② How do we know that simpler is better?

# Simple Model

## simple hypothesis $h$

- small  $\Omega(h)$  = ‘looks’ simple
- specified by **few parameters**

## simple model $\mathcal{H}$

- small  $\Omega(\mathcal{H})$  = not many
- contains **small number of hypotheses**

## connection

$h$  specified by  $\ell$  bits  $\Leftarrow |\mathcal{H}|$  of size  $2^\ell$

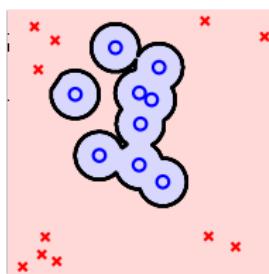
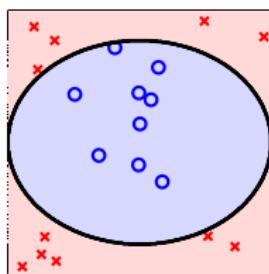
small  $\Omega(h) \Leftarrow$  small  $\Omega(\mathcal{H})$

simple: **small hypothesis/model complexity**

# Simple is Better

in addition to **math proof** that you have seen, philosophically:

- simple  $\mathcal{H}$
- $\implies$  smaller  $m_{\mathcal{H}}(N)$
- $\implies$  less 'likely' to fit data perfectly  $\frac{m_{\mathcal{H}}(N)}{2^N}$
- $\implies$  more significant when fit happens



direct action: **linear first**;  
always ask whether **data over-modeled**

# Fun Time

# Presidential Story

- 1948 US President election: Truman versus Dewey
- a newspaper phone-poll of how people **voted**,  
and set the title '**Dewey Defeats Truman**' based on polling



who is this? :-)

# The Big Smile Came from ...



Truman, and **yes he won**

suspect of the mistake:

- editorial bug?—**no**
- bad luck of polling ( $\delta$ )?—**no**

hint: phones were **expensive :-)**

# Sampling Bias

If the data is sampled in a biased way, learning will produce a similarly biased outcome.

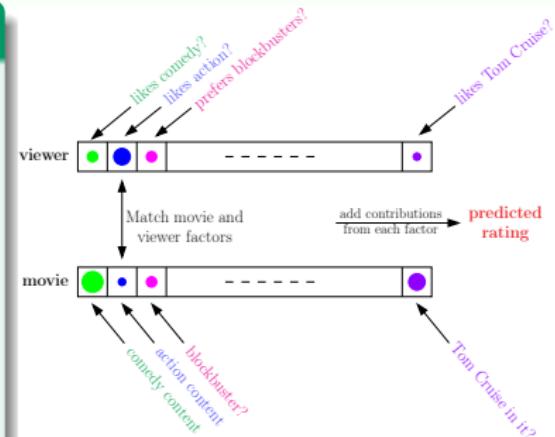
- technical explanation:  
data from  $P_1(x, y)$  but test under  $P_2 \neq P_1$ : VC fails
- philosophical explanation:  
study Math hard but test English: no strong test guarantee

‘minor’ VC assumption:  
data and testing both iid from  $P$

# Sampling Bias in Learning

## A True Personal Story

- Netflix competition for movie recommender system:  
**10% improvement = 1M US dollars**
- formed  $\mathcal{D}_{\text{val}}$ ,  
in my **first shot**,  
 $E_{\text{val}}(g)$  showed **13% improvement**
- **why am I still teaching here? :-)**



validation: **random examples** within  $\mathcal{D}$ ;  
test: '**last**' user records '**after**'  $\mathcal{D}$

# Dealing with Sampling Bias

If the data is sampled in a biased way, learning will produce a similarly biased outcome.

- practical rule of thumb:  
**match test scenario as much as possible**
- e.g. if test: ‘last’ user records ‘after’  $\mathcal{D}$ 
  - training: emphasize later examples (KDDCup 2011)
  - validation: use ‘late’ user records

last puzzle:

danger when learning ‘credit card approval’  
with **existing bank records**?

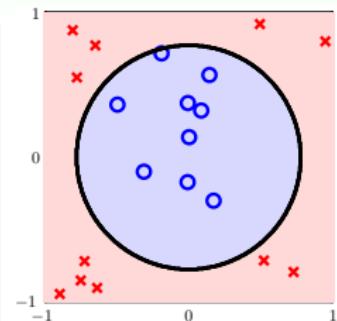
# Fun Time

# Visual Data Snooping

Visualize  $\mathcal{X} = \mathbb{R}^2$

- full  $\Phi_2$ :  $\mathbf{z} = (1, x_1, x_2, x_1^2, x_1x_2, x_2^2)$ ,  $d_{VC} = 6$
- or  $\mathbf{z} = (1, x_1^2, x_2^2)$ ,  $d_{VC} = 3$ , **after visualizing?**
- or better  $\mathbf{z} = (1, x_1^2 + x_2^2)$ ,  $d_{VC} = 2$ ?
- or even better  $\mathbf{z} = (\text{sign}(0.6 - x_1^2 - x_2^2))$ ?

—careful about **your brain's 'model complexity'**

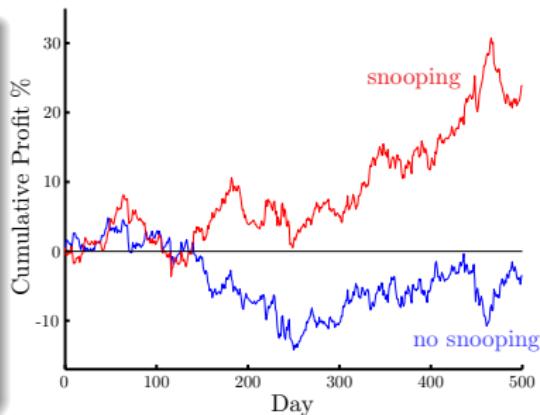


for VC-safety,  $\Phi$  shall be decided **without 'snooping'** data

# Data Snooping by Mere Shifting-Scaling

If a data set has affected any step in the learning process, its ability to assess the outcome has been compromised.

- 8 years of currency trading data
- first 6 years for **training**,  
last two 2 years for **testing**
- $x$  = previous 20 days,  
 $y$  = 21th day
- **snooping** versus **no snooping**:  
superior profit possible



- **snooping**: shift-scale all values by **training + testing**
- **no snooping**: shift-scale all values by **training** only

# Data Snooping by Data Reusing

## Research Scenario

benchmark data  $\mathcal{D}$

- paper 1: propose  $\mathcal{H}_1$  that works well on  $\mathcal{D}$
  - paper 2: find room for improvement, propose  $\mathcal{H}_2$ 
    - and **publish only if better** than  $\mathcal{H}_1$  on  $\mathcal{D}$
  - paper 3: find room for improvement, propose  $\mathcal{H}_3$ 
    - and **publish only if better** than  $\mathcal{H}_2$  on  $\mathcal{D}$
  - ...
- 
- if all papers from the same author in **one big paper**:  
bad generalization due to  $d_{VC}(\cup_m \mathcal{H}_m)$
  - step-wise: later author **snooped** data by reading earlier papers,  
bad generalization worsen by **publish only if better**

**if you torture the data long enough, it will confess :-)**

# Dealing with Data Snooping

- truth—**very hard to avoid**, unless being extremely honest
- extremely honest: **lock your test data in safe**
- less honest: **reserve validation and use cautiously**
- be blind: avoid **making modeling decision by data**
- be suspicious: interpret research results (including your own) by proper **feeling of contamination**

one secret to winning KDDCups:

careful balance between  
**data-driven modeling (snooping)** and  
**validation (no-snooping)**

# Fun Time

# Three Related Fields

## Power of Three

### Data Mining

- use **(huge)** data to **find property** that is interesting
- difficult to distinguish ML and DM in reality

### Artificial Intelligence

- compute something that shows **intelligent behavior**
- ML is one possible route to realize AI

### Statistics

- use data to **make inference** about an unknown process
- statistics contains many useful tools for ML

# Three Theoretical Bounds

## Power of Three

### Hoeffding

$$\begin{aligned} P[\text{BAD}] \\ \leq 2 \exp(-2\epsilon^2 N) \end{aligned}$$

- one hypothesis
- useful for verifying/testing

### Multi-Bin Hoeffding

$$\begin{aligned} P[\text{BAD}] \\ \leq 2M \exp(-2\epsilon^2 N) \end{aligned}$$

- $M$  hypotheses
- useful for validation

### VC

$$\begin{aligned} P[\text{BAD}] \\ \leq 4m_{\mathcal{H}}(2N) \exp(\dots) \end{aligned}$$

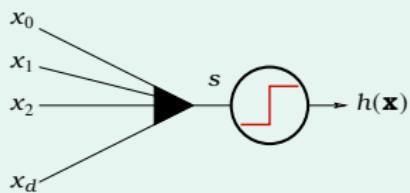
- all  $\mathcal{H}$
- useful for training

# Three Linear Models

## Power of Three

### PLA/pocket

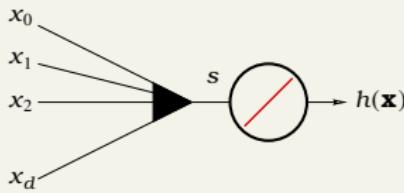
$$h(\mathbf{x}) = \text{sign}(s)$$



plausible err = 0/1  
 (small flipping noise)  
 minimize **specially**

### linear regression

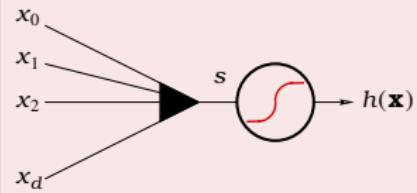
$$h(\mathbf{x}) = s$$



friendly err = squared  
 (easy to minimize)  
 minimize **analytically**

### logistic regression

$$h(\mathbf{x}) = \theta(s)$$



plausible err = CE  
 (maximum likelihood)  
 minimize **iteratively**

# Three Key Tools

## Power of Three

### Feature Transform

$$\begin{aligned} E_{\text{in}}(\mathbf{w}) &\rightarrow E_{\text{in}}(\tilde{\mathbf{w}}) \\ d_{\text{VC}}(\mathcal{H}) &\rightarrow d_{\text{VC}}(\mathcal{H}_\Phi) \end{aligned}$$

- by using **more complicated  $\Phi$**
- **lower  $E_{\text{in}}$**
- **higher  $d_{\text{VC}}$**

### Regularization

$$\begin{aligned} E_{\text{in}}(\mathbf{w}) &\rightarrow E_{\text{in}}(\mathbf{w}_{\text{REG}}) \\ d_{\text{VC}}(\mathcal{H}) &\rightarrow d_{\text{EFF}}(\mathcal{H}, \mathcal{A}) \end{aligned}$$

- by augmenting **regularizer  $\Omega$**
- **lower  $d_{\text{EFF}}$**
- **higher  $E_{\text{in}}$**

### Validation

$$\begin{aligned} E_{\text{in}}(h) &\rightarrow E_{\text{val}}(h) \\ \mathcal{H} &\rightarrow \{g_1^-, \dots, g_M^-\} \end{aligned}$$

- by reserving  **$K$  examples as  $\mathcal{D}_{\text{val}}$**
- **fewer choices**
- **fewer examples**

# Three Learning Principles

## Power of Three

Occam's Razer

simple is good

Sampling Bias

class matches exam

Data Snooping

honesty is best policy

# Three Future Directions

## Power of Three

More Transform

More Regularization

Less Label

semi-supervised learning	overfitting	stochastic gradient descent	SVM	<i>Q</i> learning
Gaussian processes	<b>deterministic noise</b>	data snooping	learning curves	
<i>distribution-free</i>	linear regression	VC dimension	neural networks	mixture of experts
collaborative filtering		sampling bias	noisy targets	no free lunch
decision trees	nonlinear transformation	training versus testing	Bayesian prior	
RBF		bias-variance tradeoff	weak learners	
active learning	linear models	logistic regression	data contamination	
ordinal regression		types of learning	perceptrons	hidden Markov models
ensemble learning		kernel methods	graphical models	
exploration versus exploitation		soft-order constraint		
clustering	is learning feasible?	weight decay	Occam's razor	Boltzmann machines
	regularization			

ready for the **jungle!**

# Fun Time

# Summary

- ① When Can Machines Learn?
- ② Why Can Machines Learn?
- ③ How Can Machines Learn?
- ④ How Can Machines Learn **Better?**

## Lecture 15: Validation

## Lecture 16: Three Learning Principles

- Occam's Razor  
**simple, simple, simple!**
  - Sampling Bias  
**match test scenario as much as possible**
  - Data Snooping  
**any use of data is 'contamination'**
  - Power of Three  
**relatives, bounds, models, tools, principles**
- 
- next: ready for jungle!