

Formulas of Four Multi-Armed Bandit Algorithms

1. Epsilon-Greedy Algorithm

Description: Epsilon-Greedy balances exploration and exploitation. With probability $1 - \varepsilon$, it selects the action with the highest estimated reward. With probability ε , it explores randomly.

$$A_t = \begin{cases} \arg \max_a Q_t(a), & \text{with probability } 1 - \varepsilon \\ \text{randomly select } a \in \mathcal{A}, & \text{with probability } \varepsilon \end{cases}$$

Explanation:

- A_t : the action selected at time t .
- $Q_t(a)$: estimated reward for action a at time t .
- ε : exploration probability.
- \mathcal{A} : set of all possible actions.

2. UCB (Upper Confidence Bound) Algorithm

Description: UCB selects actions based on the upper confidence bound, balancing current reward estimates with uncertainty.

$$A_t = \arg \max_a \left[Q_t(a) + c \sqrt{\frac{\ln t}{N_t(a)}} \right]$$

Explanation:

- $Q_t(a)$: average reward of action a .
- $N_t(a)$: number of times action a has been selected before time t .
- t : current round.
- c : exploration constant.

3. Softmax Algorithm

Description: Softmax assigns a probability to each action using the softmax function, allowing smoother exploration based on reward estimates.

$$P(a) = \frac{\exp(Q_t(a)/\tau)}{\sum_{b \in \mathcal{A}} \exp(Q_t(b)/\tau)}$$

Explanation:

- $P(a)$: probability of selecting action a .
- $Q_t(a)$: estimated reward of action a .
- τ : temperature parameter; higher values encourage more exploration.
- \mathcal{A} : set of all possible actions.

4. Thompson Sampling Algorithm

Description: Thompson Sampling uses Bayesian inference to maintain uncertainty and samples from posterior distributions to select actions.

$$\theta_a \sim p(\theta_a \mid \text{history}), \quad A_t = \arg \max_a \theta_a$$

Explanation:

- θ_a : a sampled parameter from the posterior distribution for action a .
- $p(\theta_a \mid \text{history})$: posterior distribution of action a based on past observations.
- A_t : action selected with the highest sampled value.