

# Yipeng ZHANG

+ (1) 4452607849 | [yipenggg@seas.upenn.edu](mailto:yipenggg@seas.upenn.edu) | [zhangyipeng66@outlook.com](mailto:zhangyipeng66@outlook.com) | Pennsylvania, U.S.

<https://yipengggg.github.io/zyp.github.io/>

## EDUCATION

---

**University of Pennsylvania** Sep 2023 - Jun 2025

*MSc in Mechanical Engineering & Applied Mechanics*

- Major courses: Machine Learning, Machine Perception, Introduction to Robotics, Linear System Theory, Mechatronic Design
- GPA: 3.90/4.00

**Sorbonne University** Aug 2021 - Jun 2023

*BSc in Mechanical Engineering*

- Major courses: Fundamentals of Continuum Mechanics, Applied Thermodynamics
- GPA: 3.70/4.00 (Top 3%)

**Swiss Federal Institute of Technology Lausanne (EPFL)** Feb 2023 - Jul 2023

*Exchange Student (Erasmus Exchange Program)*

**Université de Lille** Sep 2020 - Jun 2021

*Studied Mechanical Engineering (Transferred to Sorbonne University as the First Place)*

## RESEARCH EXPERIENCE

---

**Individual Master's Thesis, UPenn** Sept 2024 - Present

*Advisor: Prof. Cynthia Sung, Sung Lab at Grasp*

*Research topic: The Impact of Geometric Structures on Robots in Flow Field*

- Constructed a Particle Image Velocimetry (PIV) system to measure the flow field generated by robots underwater, obtaining the distribution of flow velocities.
- Used these velocity measurements; Calculated the thrust produced by the robots.
- Optimized the geometry of robots; Aimed to find the optimal solution for thrust and speed.

**Research Assistant, UPenn** May 2024 - Present

*Advisor: Prof. Cynthia Sung, Sung Lab at Grasp*

*Research topic: Salp-Inspired Underwater Swimmer*

- Investigated the effects of coordinated movement among multiple underwater robots on speed and efficiency based on a Salp-inspired robot.
- Assisted in designing components, setting up experimental environments, calibrating experiment videos using computer vision, and measuring velocities with motion capture.

**Milestone:** Paper "Effect of Jet Coordination on Underwater Propulsion with the Multi Robot SALP System" has been accepted for publication at the 8th IEEE-RAS International Conference on Soft Robotics (RoboSoft 2025)

**Research Assistant, UPenn** July 2024 - Present

*Advisor: Dr. Xiao Zhang*

*Research topic: Machine Learning in DFT*

- Learned and understood the combination of Density Functional Theory (DFT) and deep learning, and how to use equivariant neural networks to obtain the Hamiltonian matrix by inputting relevant geometric features.
- Gained knowledge of using evidential learning methods to estimate uncertainty.
- Understood the two-stage framework MEERL-H model, In the original model, an auxiliary model has

been introduced to assist in optimizing and evaluating the uncertainty of the original model's predictions.  
**Milestone:** submit to Nature Machine Intelligence

---

## PROJECT EXPERIENCE

---

### Project Member, UPenn

Nov 2023 - Dec 2023

*Project topic: The Design and Control of a Multifunctional Vehicle*

- Used SolidWorks to design structures of the cart, manufacturing them in 3D printing.
- Adopted C language to build functions on Arduino, such as ESP signal transmission, wall following, self-positioning, grabbing trophies, and other features.
- Built a website with JavaScript, and designed buttons to control the cart for corresponding functions.

### Project Leader, Sorbonne

Dec 2021 - Jan 2022

*Project topic: The Design and Actuation of Four Legs Robots*

- Used SolidWorks to build a four-legged robot, with emphasis on its mobility and stability.
- Designed the movement mechanism and wrote programs in C language to control four motors, enabling the robot to move; did the simulation of the locomotion by SolidWorks.
- Utilized 3D printing to manufacture the parts, selected sturdy, light, and economical material, specifications of the screw, and the power of the motor.

---

## WORKING EXPERIENCE

---

### Mercedes Benz

Jun 2022 - Sep 2022

*Internship Position: Robot Planning Engineer & Consultant*

- Understood the principles of forward kinematic and inverse kinematics, DH parameters, etc.
- Tested the mechanical arms in a simulation environment on Linux using Python; Compiled libraries on the basis of existing functions to improve the performance of the robotic arm.
- Coordinated with various departments such as R&D, marketing, and testing departments.
- Attended weekly meetings; Communicated with managers to followup on development progress.

---

## SKILLS & CERTIFICATION

---

**Language Skills:** Mandarin (Native), English (Advanced); French (Advanced)

**Technical Skills:** Python, C, Java, MATLAB, Fortran, CAD, Inventor, Catia, SolidWorks, MySQL, MS Office

**Certificate:** Completion of Preparation for Scientific and Technological Training