



# Data Fusion of Multi-Fidelity Systems via Latent Variable Gaussian Process for Active Learning

**Yi-Ping Chen\*, Liwei Wang, Yigitcan Comlek, Wei Chen**

*Department of Mechanical Engineering, Northwestern University*

*Integrated DEsign Automation Laboratory (IDEAL)*

2<sup>nd</sup> MMLDE-CSET, Sep. 25, 2023, El Paso, TX



# Outline



1

Introduction

2

LVGP & MF-LVGP

3

Multi-Fidelity Adaptive Sampling

4

Case Studies

5

Closure

# Outline



1

Introduction

2

LVGP & MF-LVGP

3

Multi-Fidelity Adaptive Sampling

4

Case Studies

5

Closure

# Why do We Need Multi-Fidelity Adaptive Sampling?

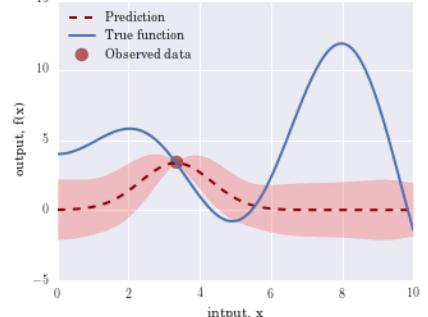


- Simulation cost of complex engineering system is expensive
- Building a surrogate model is a solution, while collecting sufficient data is a challenging task

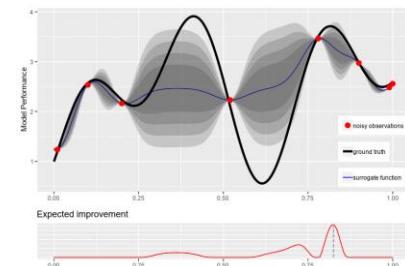
## Adaptive Sampling

### Global Fitting (GF)

Approximating true function with more data



### Bayesian Optimization (BO)



## Multi-Fidelity (MF) Data Fusion

(LF)

Low-fidelity  
models



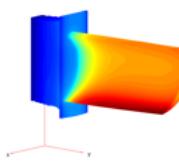
- Coarse physical resolutions



- Fast runtime

(HF)

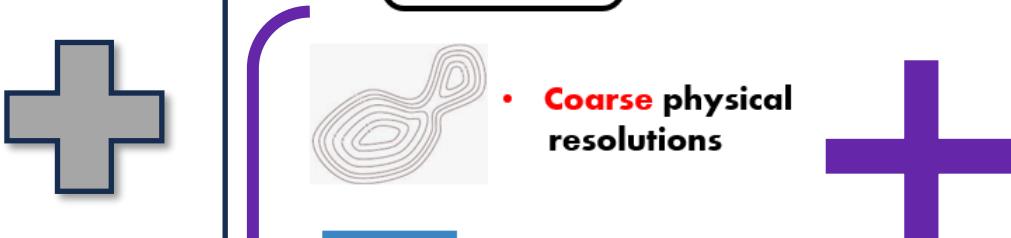
High-fidelity  
models



- Fine physical resolutions



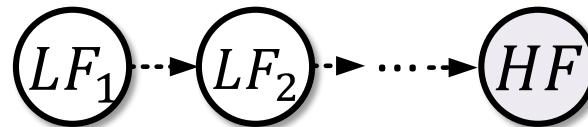
- Slow runtime



# Categorizing MF Methods via Architecture



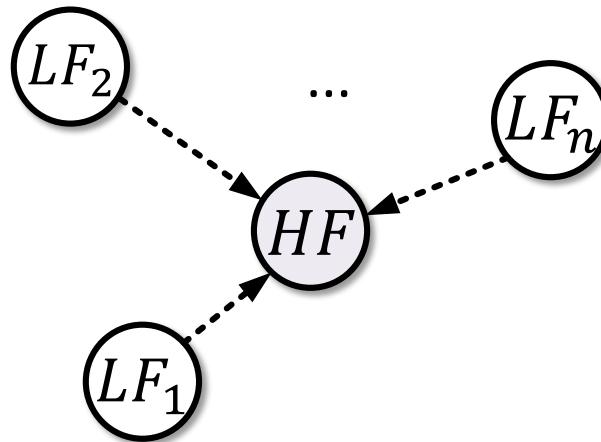
$$HF = HF | LF_n | \dots | LF_2 | LF_1$$



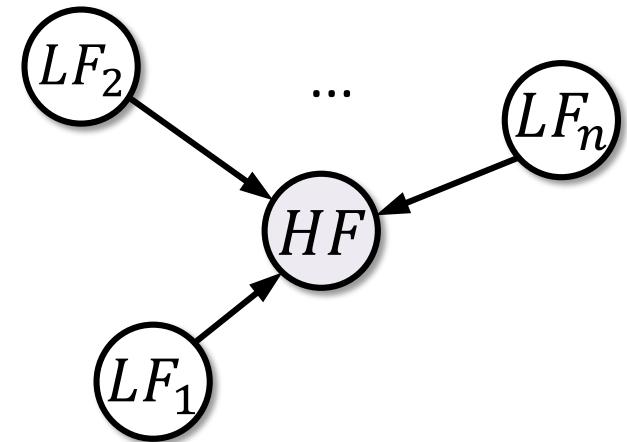
(a) Hierarchical Architecture

- Ranking fidelity models may not be practical
- Uncertainty propagation, not desirable for adaptive sampling

$$HF = HF | (LF_n, \dots, LF_2, LF_1)$$



(b) Non-hierarchical architecture with implicit use of correlation



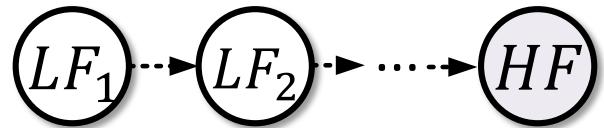
(c) Non-hierarchical architecture with explicit use of correlation

- **Implicit:** The correlation is only used for *response/uncertainty* prediction via *existing* data
- **Explicit:** The correlation is to quantify the *benefit* of the *future* samples as the sampling criteria

# MF Methods with Hierarchical Architecture

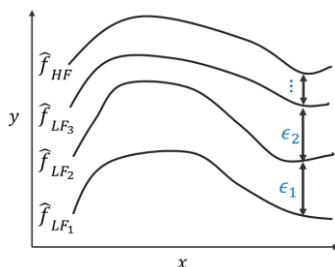


$$HF = HF | LF_n | \dots | LF_2 | LF_1$$



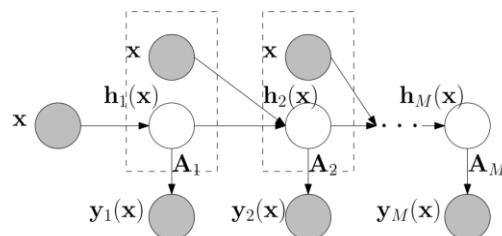
- The surrogate of the higher-fidelity models are conditioning on the information of the lower-fidelity models.
- Fidelity levels should be clearly ranked.
- Uncertainty propagates while the MF model is trained sequentially.

## Kennedy & O'Hagan



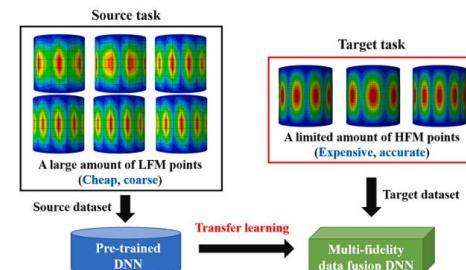
Kennedy,, and O'Hagan, A.. *Biometrika* 87.1 (2000)

## Deep Neural Network



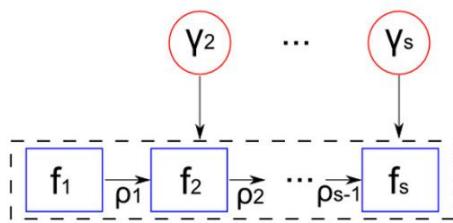
Li, S., Kirby, R. M., & Zhe, S., *Deep Multi-Fidelity Active Learning of High-dimensional Outputs*, 2020.

## Transfer Learning



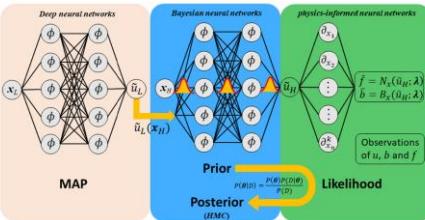
Li, Z., Zhang, S., Li, H., Tian, K., Cheng, Z., Chen, Y., & Wang, B. *Advanced Engineering Informatics*, 2022

## CoKriging



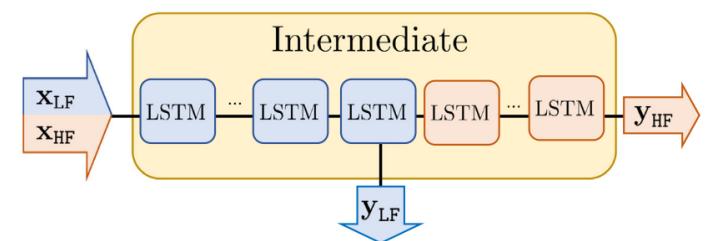
Le Gratiet, L., & Cannamela, C. *Technometrics*, 57(3), 2015.

## Bayesian Neural Network



Meng, X., Babaei, H., & Karniadakis, G. E., *Journal of Computational Physics*, 2021.

## LSTM

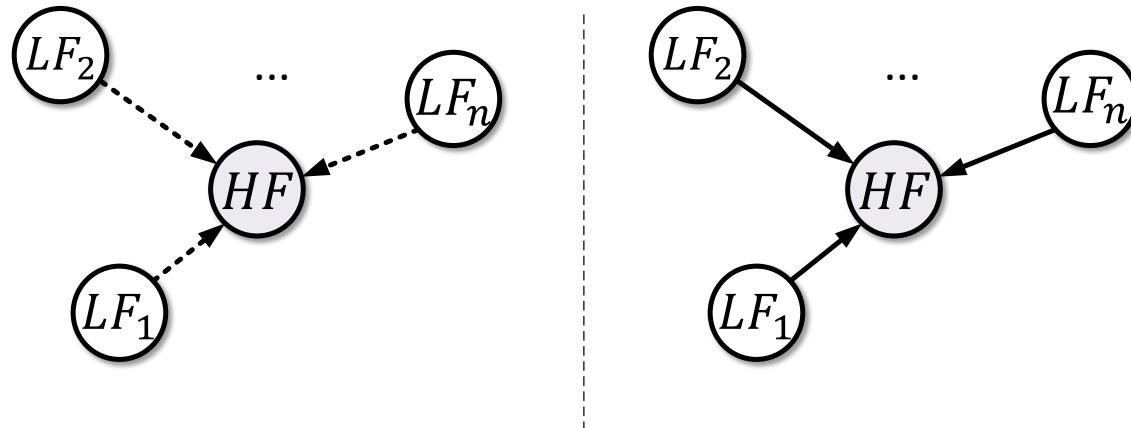


Conti, P., Guo, M., Manzoni, A., & Hesthaven, J. S., *CMAME*, 2022

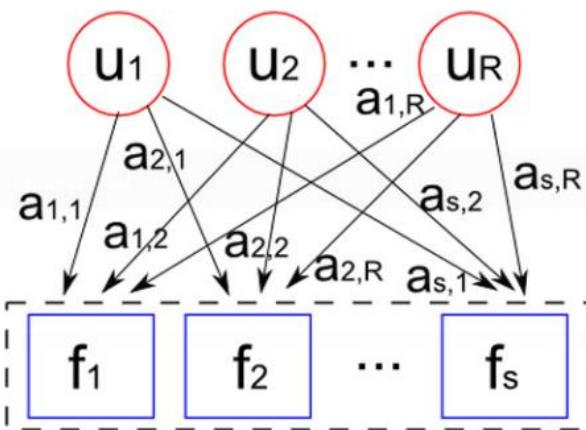
# Non-Hierarchical Architecture – MF Data Fusion



$$HF = HF | (LF_n, \dots, LF_2, LF_1)$$

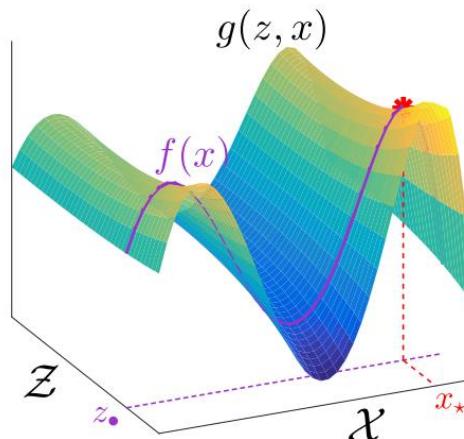


## Multi-Response Gaussian Process

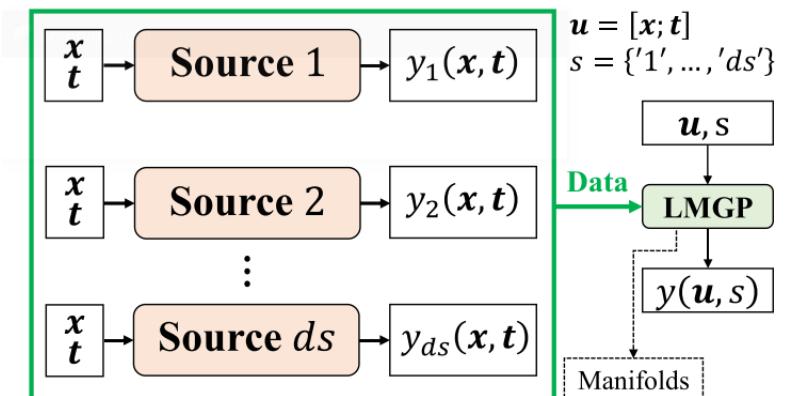


Brevault, L., Balesdent, M., & Hebbal, A., *Aerospace Science and Technology*, 2020

## Latent Representation



Kandasamy, K., Dasarathy, G., Schneider, J., & Póczos, B., 2017 *ICML*.

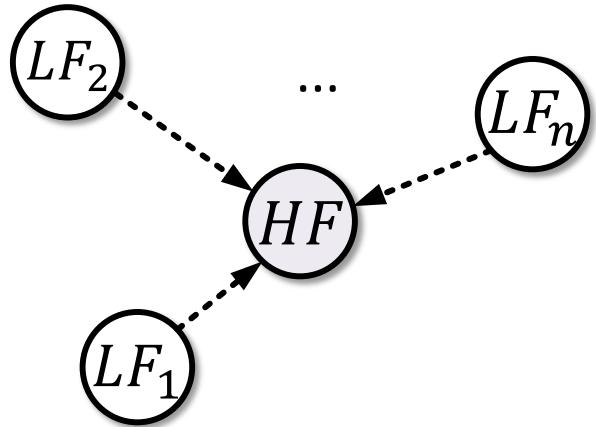


Zanjani Foumani, Z., Shishehbor, M., Yousefpour, A., & Bostanabad, R. *CMAME*, 2023.

# Non-Hierarchical Architecture – Infill Sampling

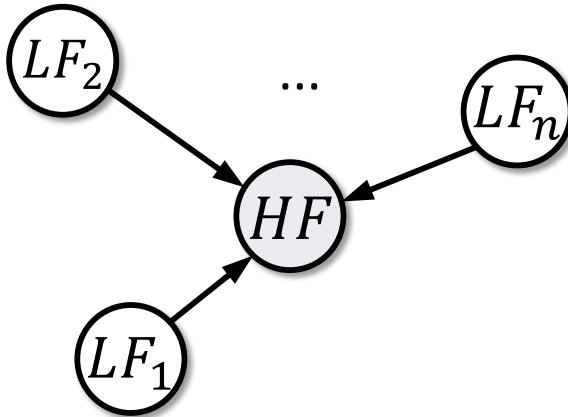


## Implicit use of Correlation



- Assign separate acquisition function to different source, *neglect the interaction* between HF and LF models.
- The *contribution/benefit* of the infill LF samples to HF model is *unknown*.
- Less efficient resource allocation and robustness.

## Explicit use of Correlation



- Treat fidelity sources as the subregion of the same MF model and *include the interaction* between fidelities.
- *Quantify the benefit* before querying the infill sample.
- Allocate resource only for improving the performance of HF surrogate.

# Objectives of This Work



- Perform a non-hierarchical, interpretable MF data fusion methods.

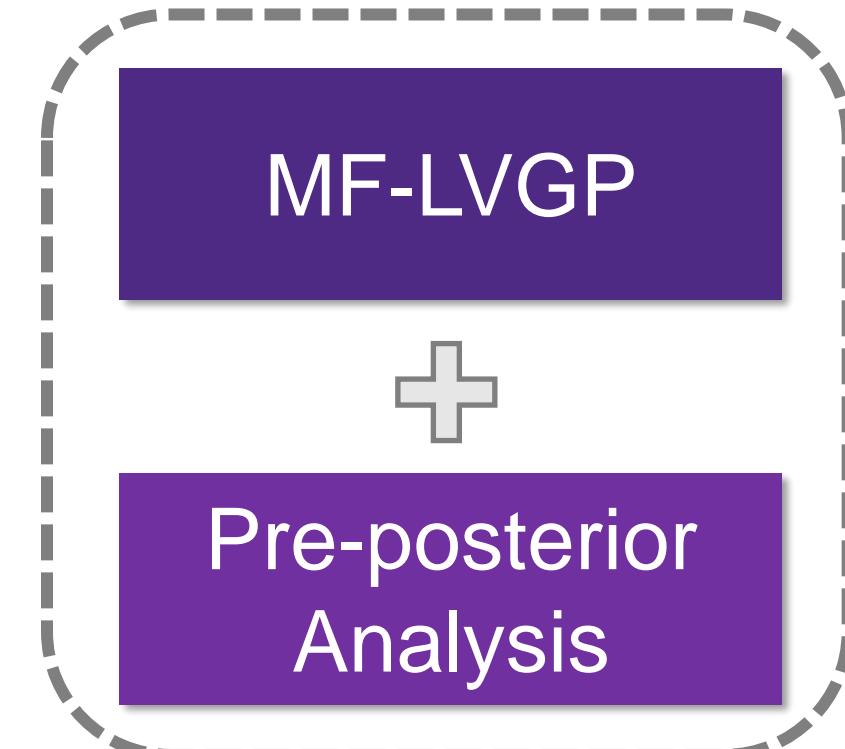
*We perform MF data fusion with Latent Variable Gaussian Process (LVGP)*

- Quantify the future benefit of the candidate samples.

*We implement the pre-posterior analysis on MF-LVGP to quantify the benefit*

- Propose an adaptive sampling framework that explicitly utilize the correlation.

*We proposed a flexible, benefit & cost-aware adaptive sampling framework*



# Outline



1

Introduction

2

LVGP & MF-LVGP

3

Multi-Fidelity Adaptive Sampling

4

Case Studies

5

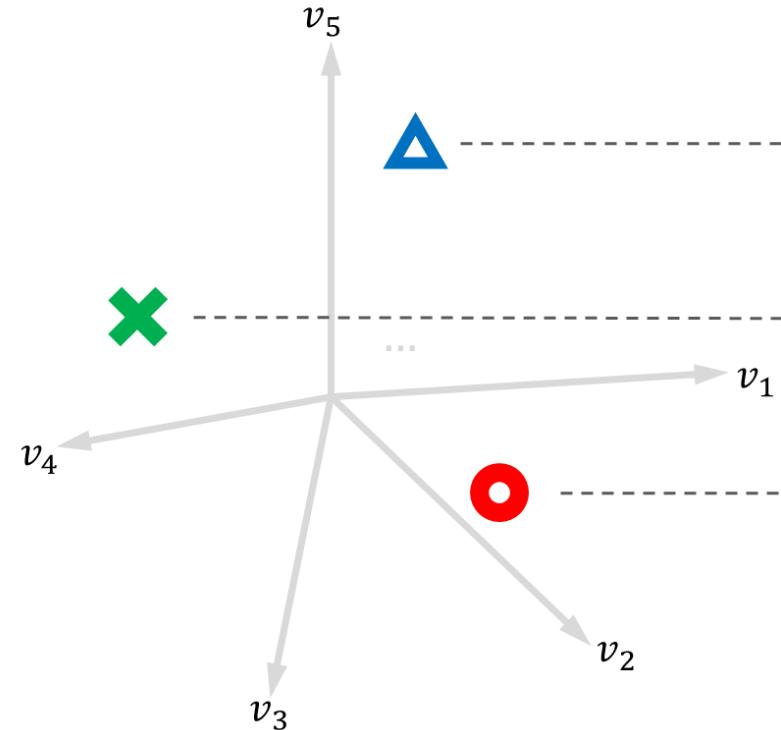
Closure

# **Lightning Introduction of Latent Variable Gaussian Process (LVGP)**

# Visualization of LVGP



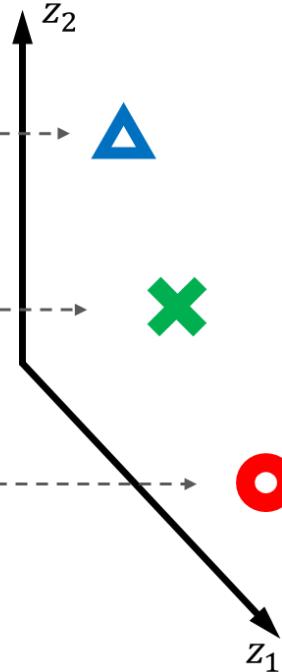
## Underlying Quantitative Space



### Qualitative Variables:

It is known that every qualitative variable has an underlying, possibly high dimensional quantitative representation that influences the response.

## Low Dimensional Latent Space



### What LVGP does:

Through physics-based dimension reduction, the numerical space can be reduced to lower latent spaces.

# Consider an example...



$$f(\textcolor{red}{x}_1, \textcolor{green}{x}_2) = \left( \textcolor{green}{x}_2 - \frac{5.1}{4\pi^2} \textcolor{red}{x}_1^2 + \frac{5}{\pi} \textcolor{red}{x}_1 - 6 \right)^2 + 10 \left( 1 - \frac{1}{8\pi} \right) \cos \textcolor{red}{x}_1 + 10$$

Quantitative Variable

$$\textcolor{red}{x}_1 = [-5, 10]$$

Qualitative Variable

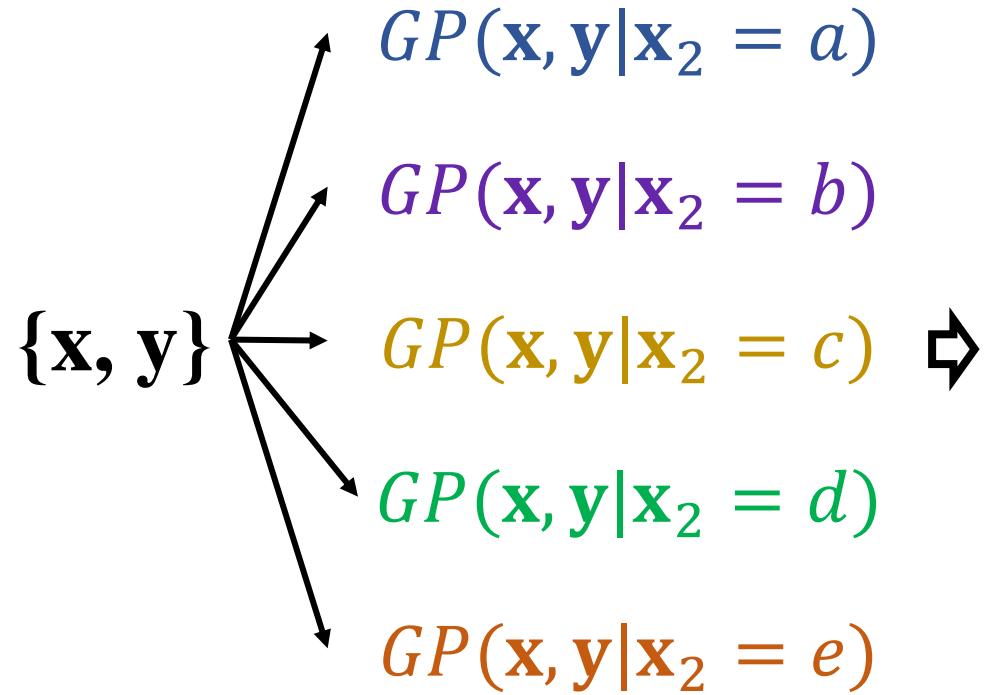
$$\textcolor{green}{x}_2 = \{a, b, c, d, e\}$$

Training samples be like...

$$\mathbf{x}^1 = (3, a), \mathbf{x}^2 = (-1, b) \dots$$

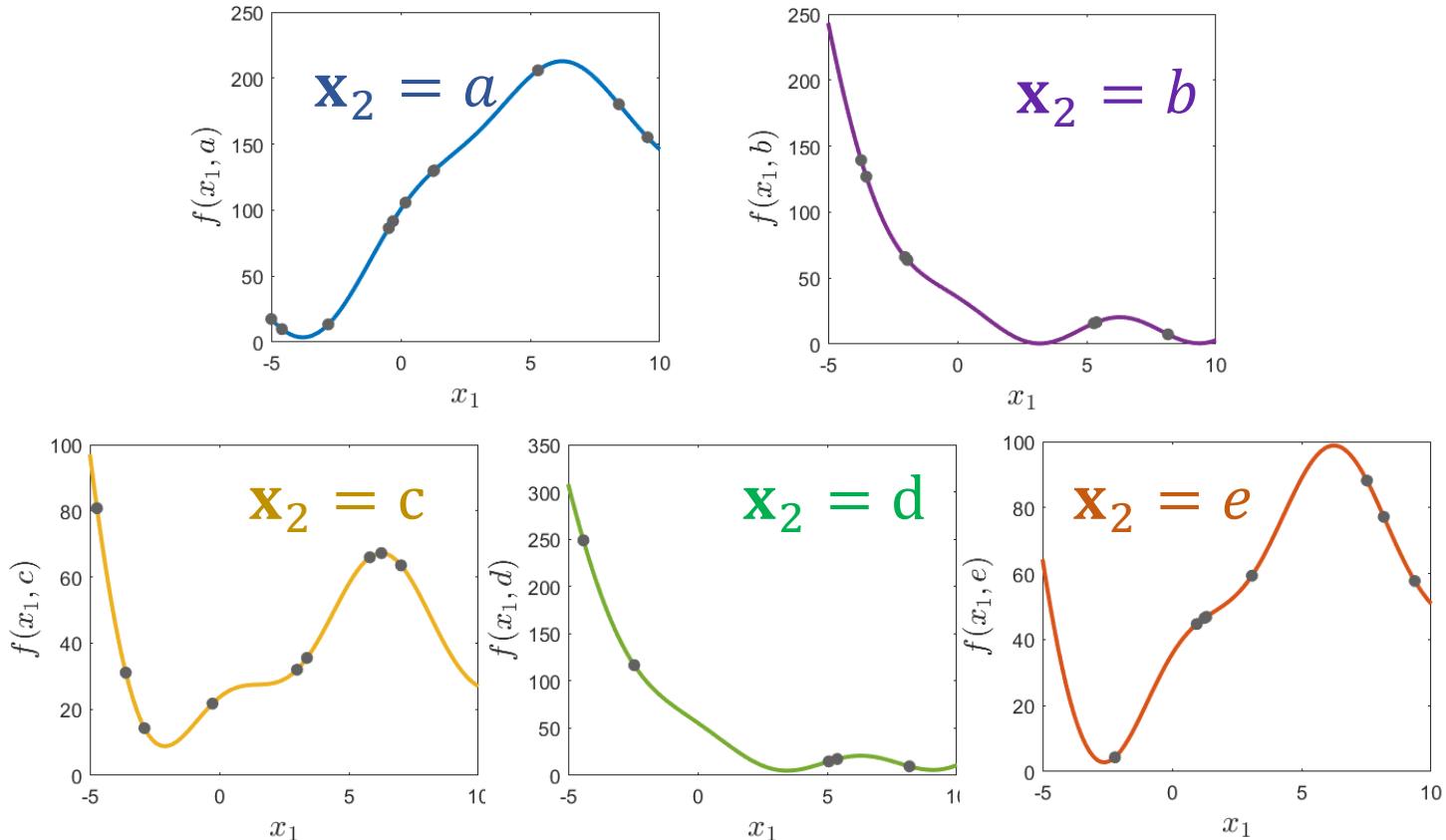


# Training with Ordinary Gaussian Process



Training  
Samples

Fit separate GP model  
for each category

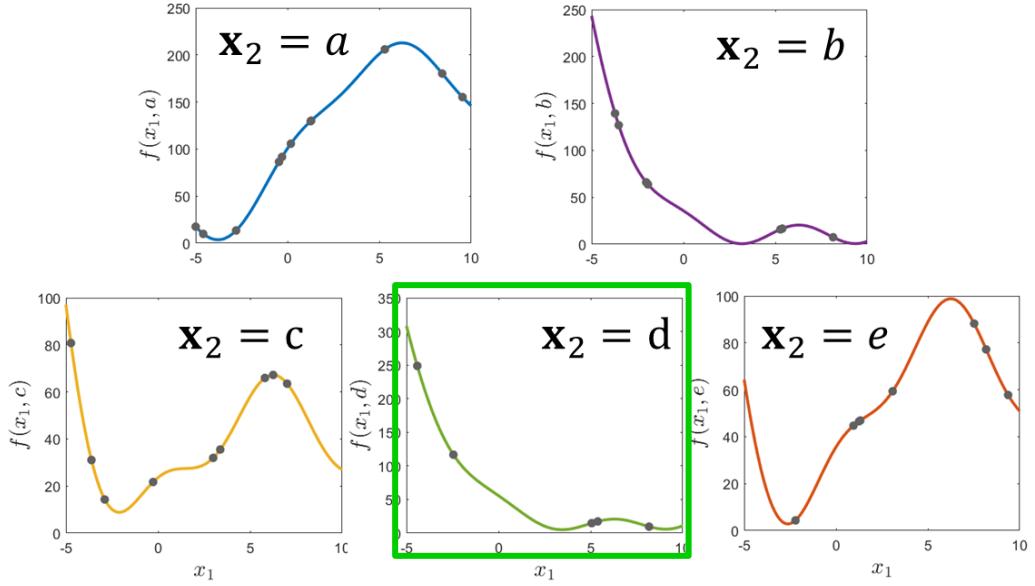


Response for each category

# Predicting with Ordinary Gaussian Process

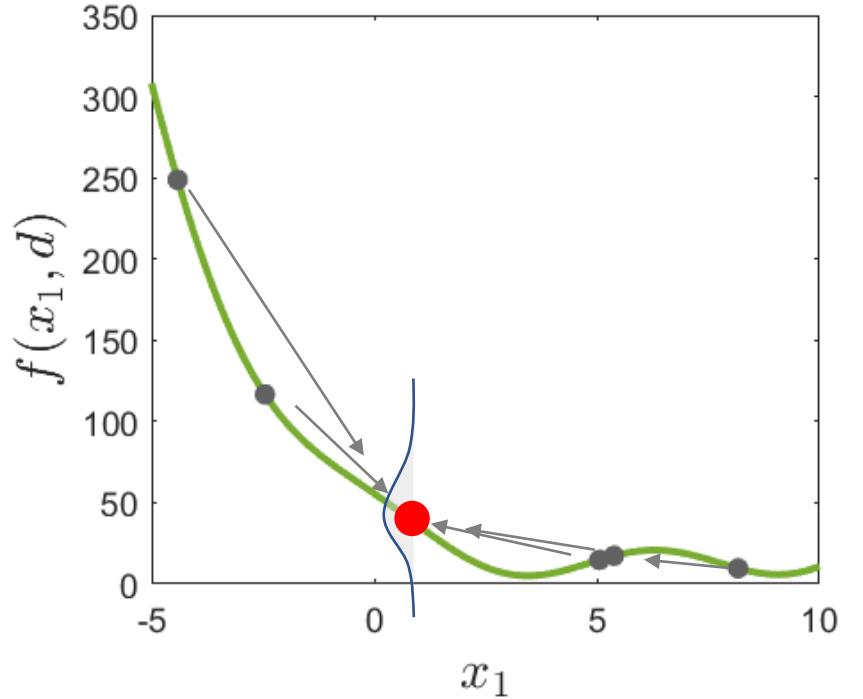


$f(1, d)$



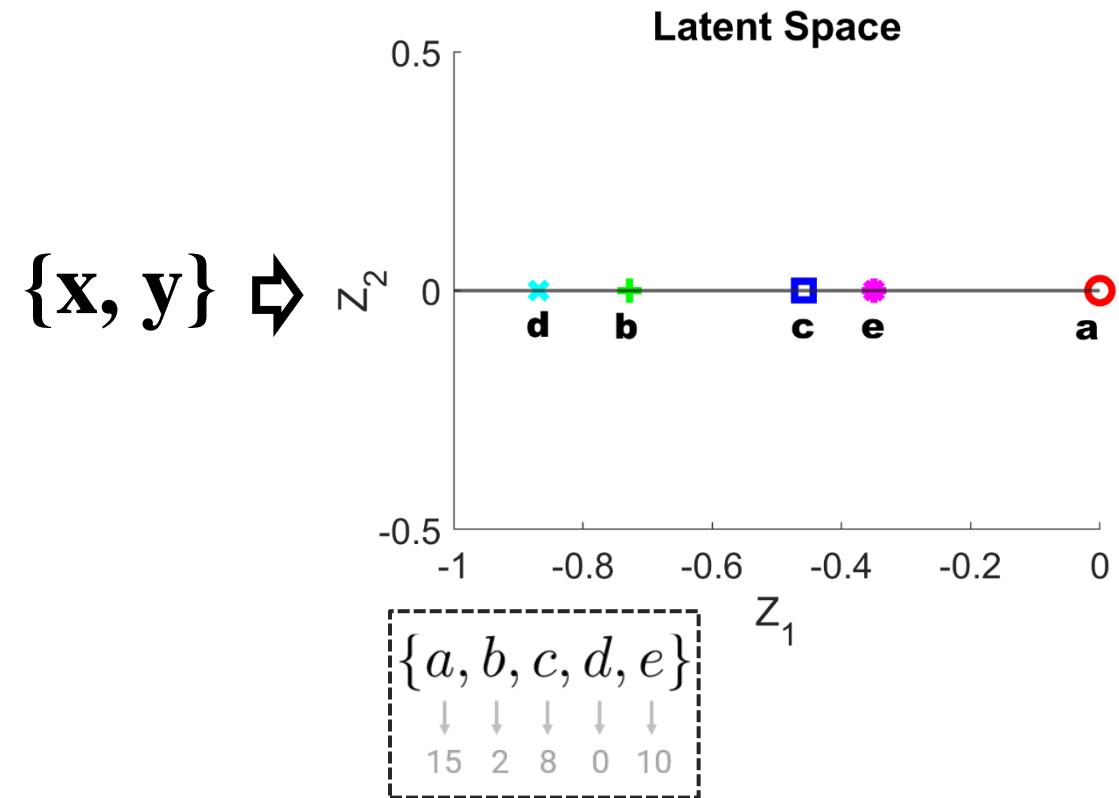
Predicting  
Target

Select corresponding  
response model

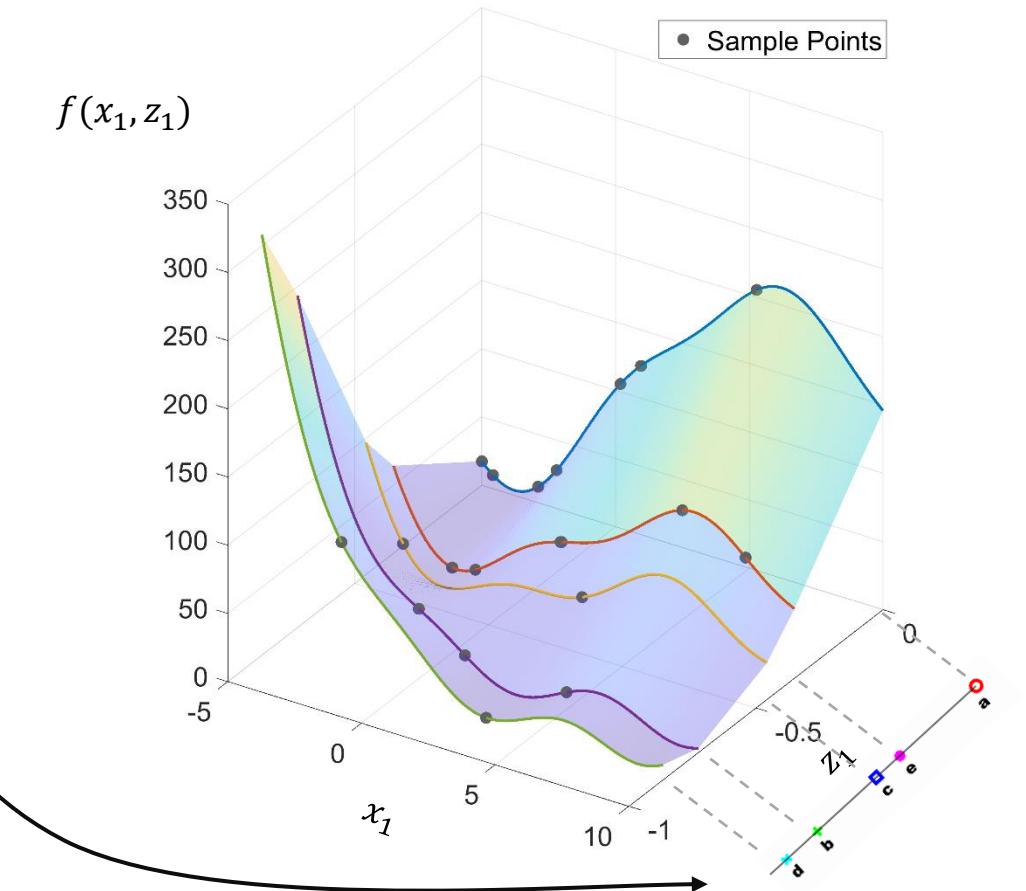


Response prediction is  
conditioned to the samples within  
the *same category*

# Training with LVGP



Map qualitative variables  
into latent space



Generate an output space with  
quantitative variables and latent variables

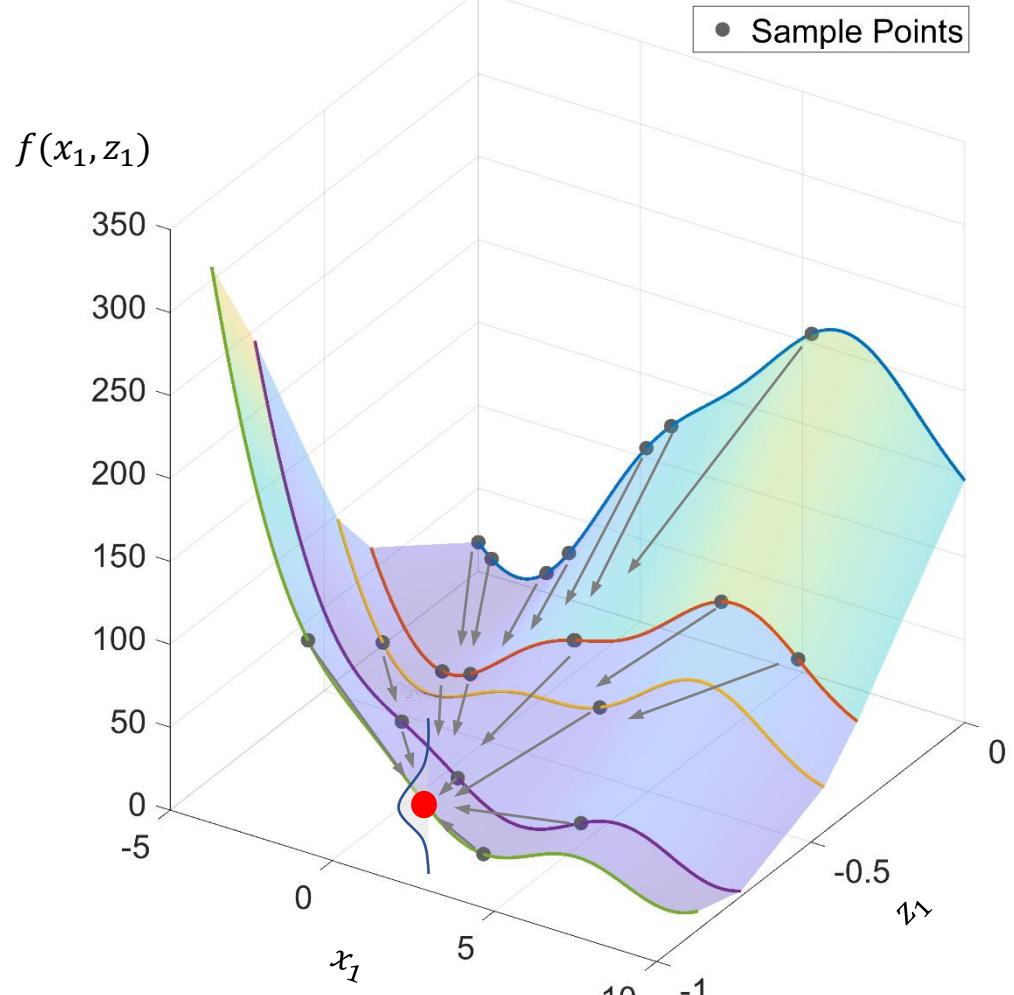
# Predicting with LVGP



$f(1, d)$



Predicting  
Target

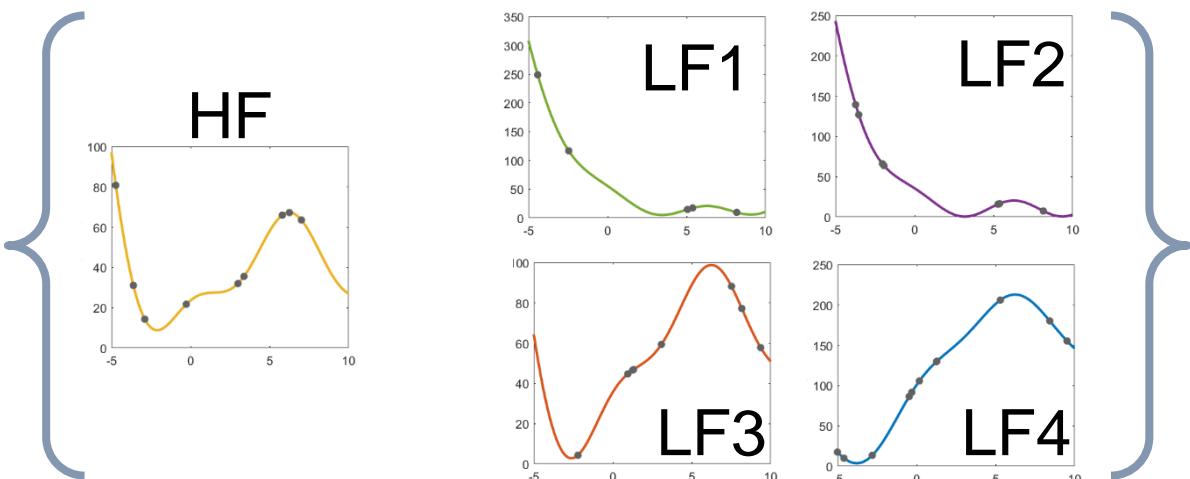


The prediction is  
conditioned to all the  
training samples

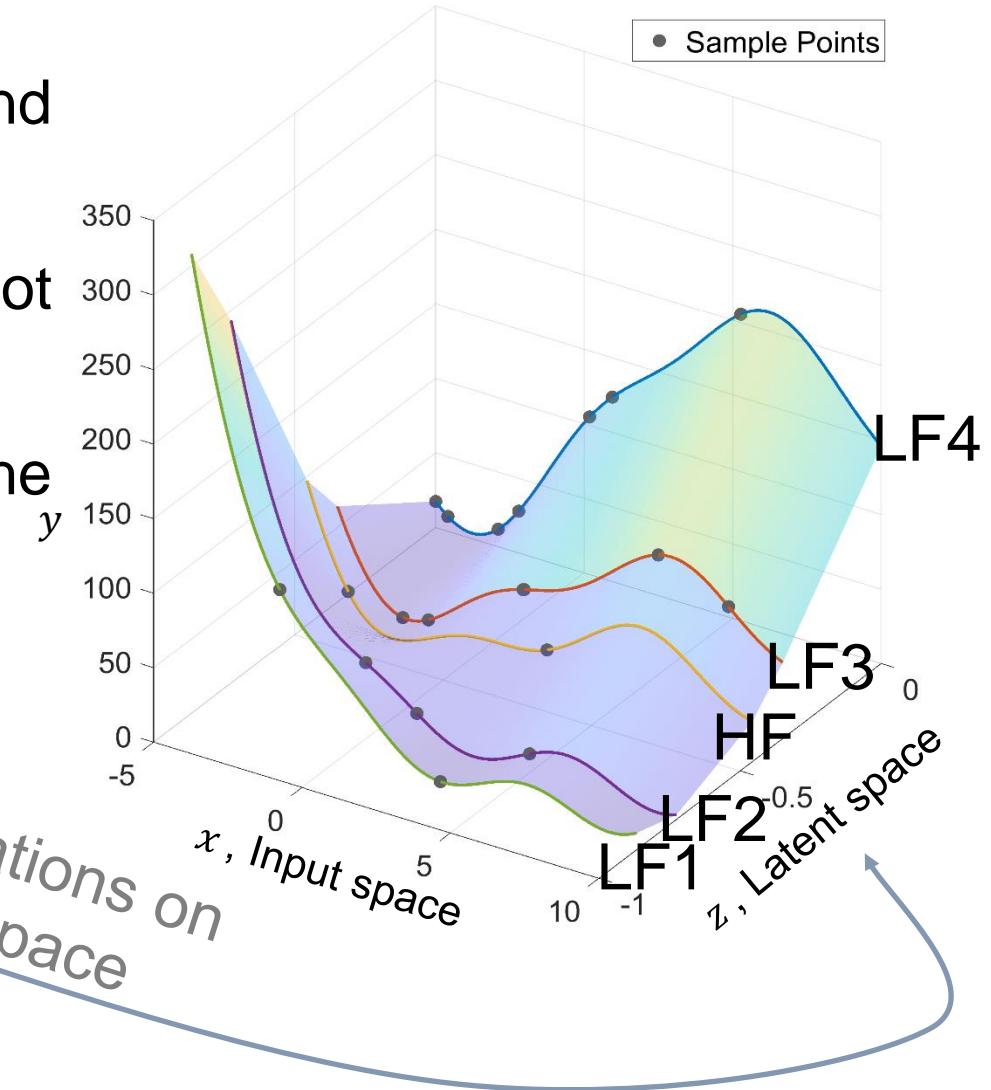
# LVGP for Multi-fidelity Modeling (MF-LVGP)



- Assigning the fidelity level as a qualitative variable
- Mapping different fidelity models into latent space and capturing their correlations
- Prior knowledge about the hierarchy of fidelity is not required
- Predicting HF response with information from all the fidelity samples



Learn correlations on latent space



# Outline



1

Introduction

2

LVGP & MF-LVGP

3

Multi-Fidelity Adaptive Sampling

4

Case Studies

5

Closure

# The Main Questions We Encountered



*Q: How to determine “Which Fidelity Model” and “Where to Sample”?*

*A: Infill the sample that provides the highest benefit-to-cost ratio.*

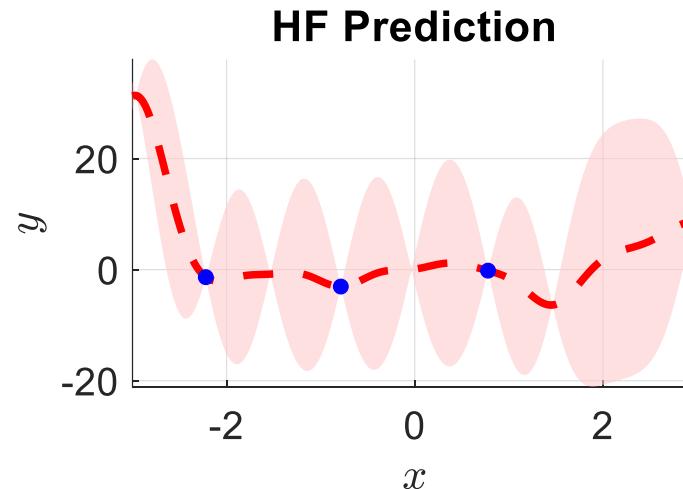
*Q: What is the “benefit” and how do we quantify it?*

*A: We define the benefit as the potential reduction of the acquisition.*

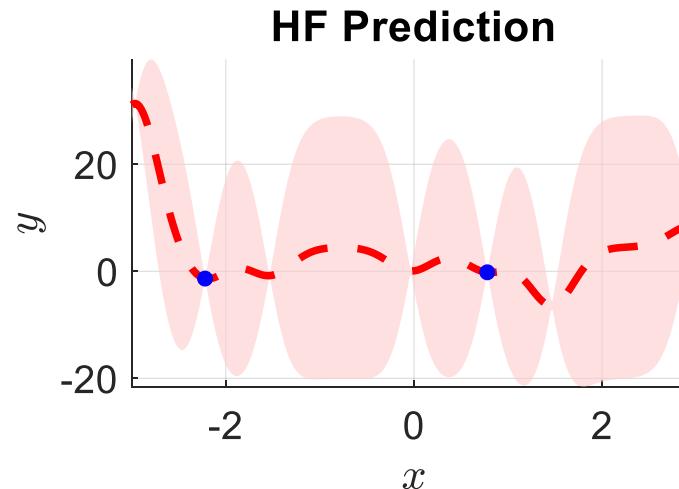
# Reduction of Acquisition (MSE) with Infill Samples (GF)



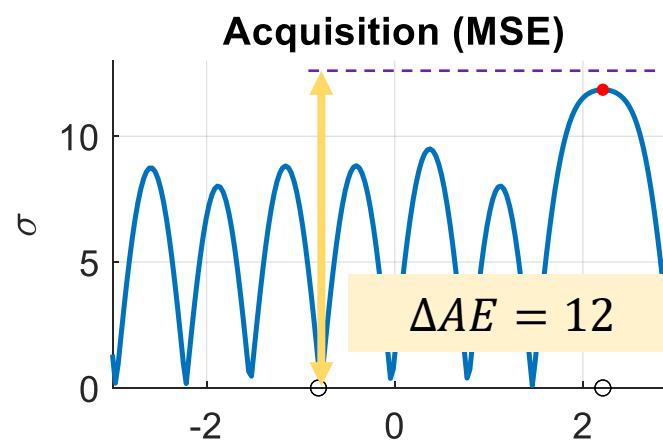
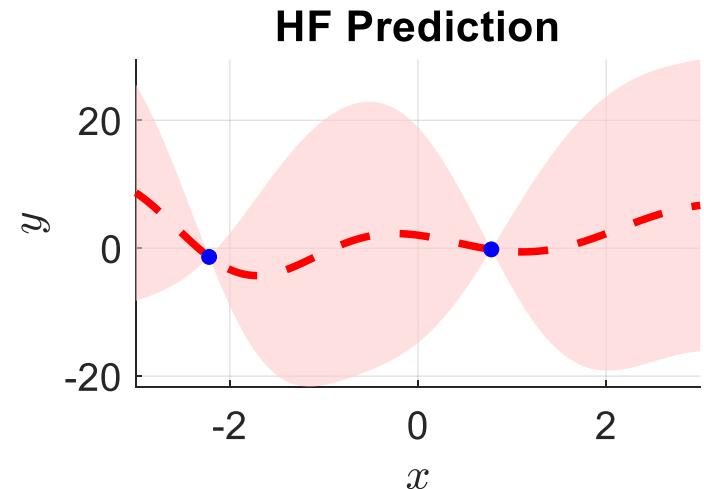
Infill on HF (cost = 1000)



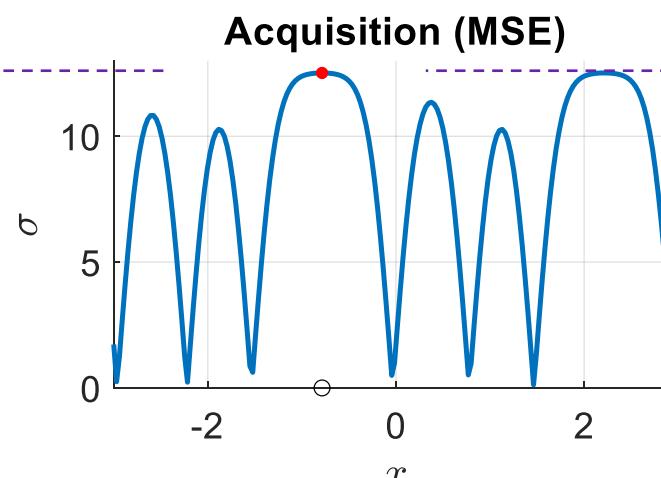
Current MF-LVGP



Infill on LF (cost = 1)



$$\frac{\Delta AE}{cost} = 0.012$$

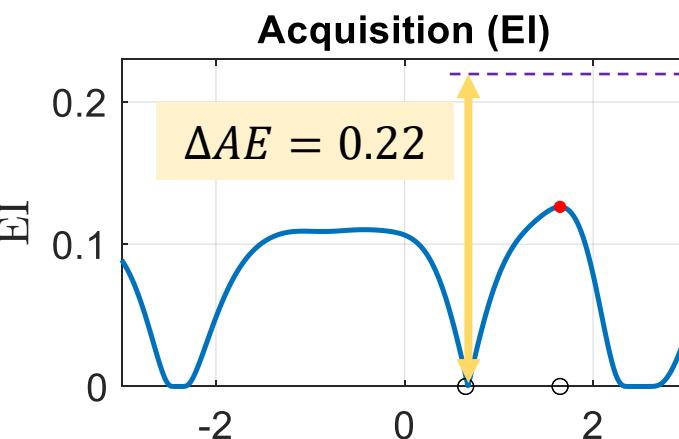
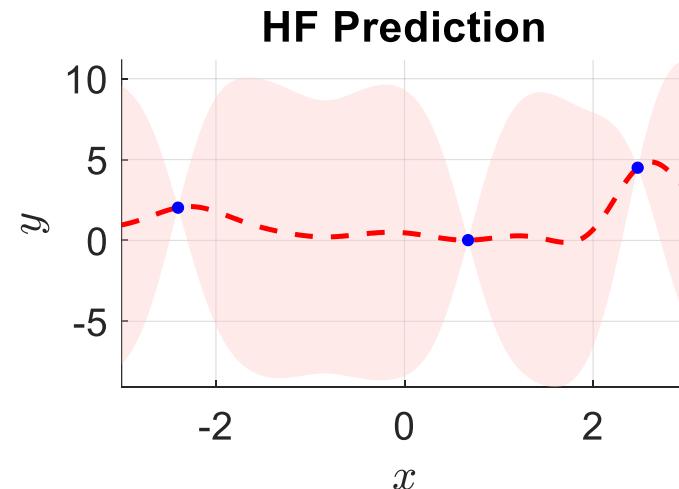


$$\frac{\Delta AE}{cost} = 1.65$$

# Reduction of Acquisition (EI) with Infill Samples (BO)

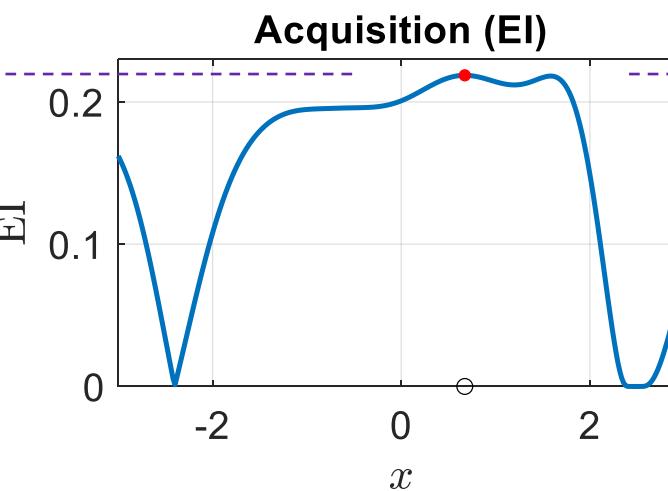
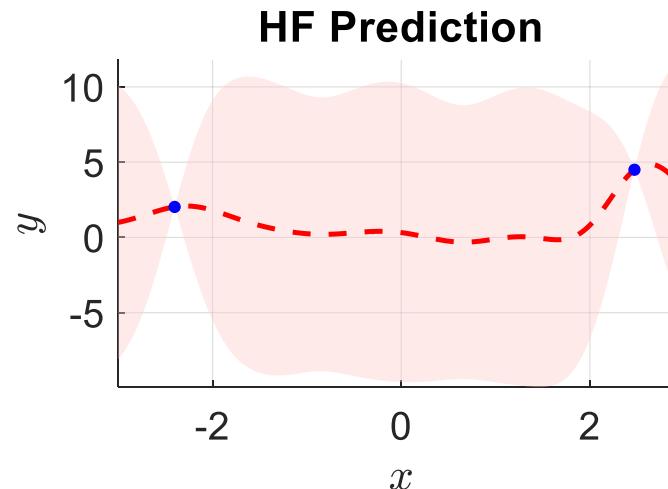


Infill on HF (cost = 1000)

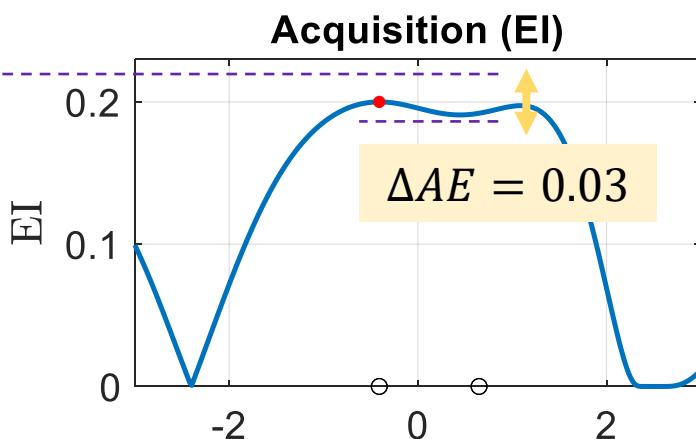
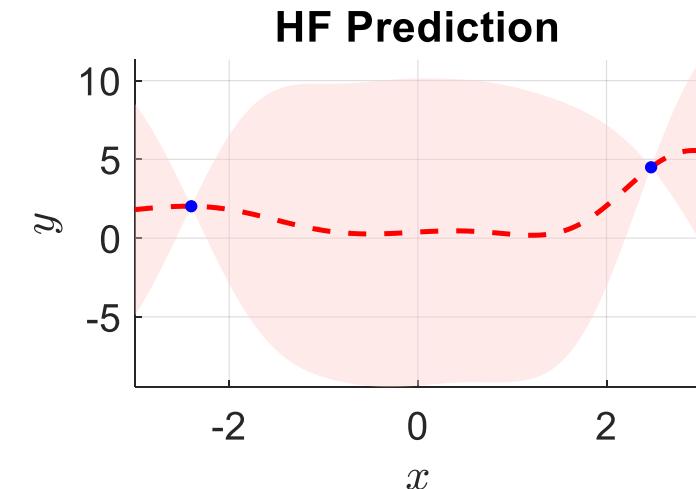


$$\frac{\Delta AE}{cost} = 0.00022$$

Current MF-LVGP



Infill on LF (cost = 1)

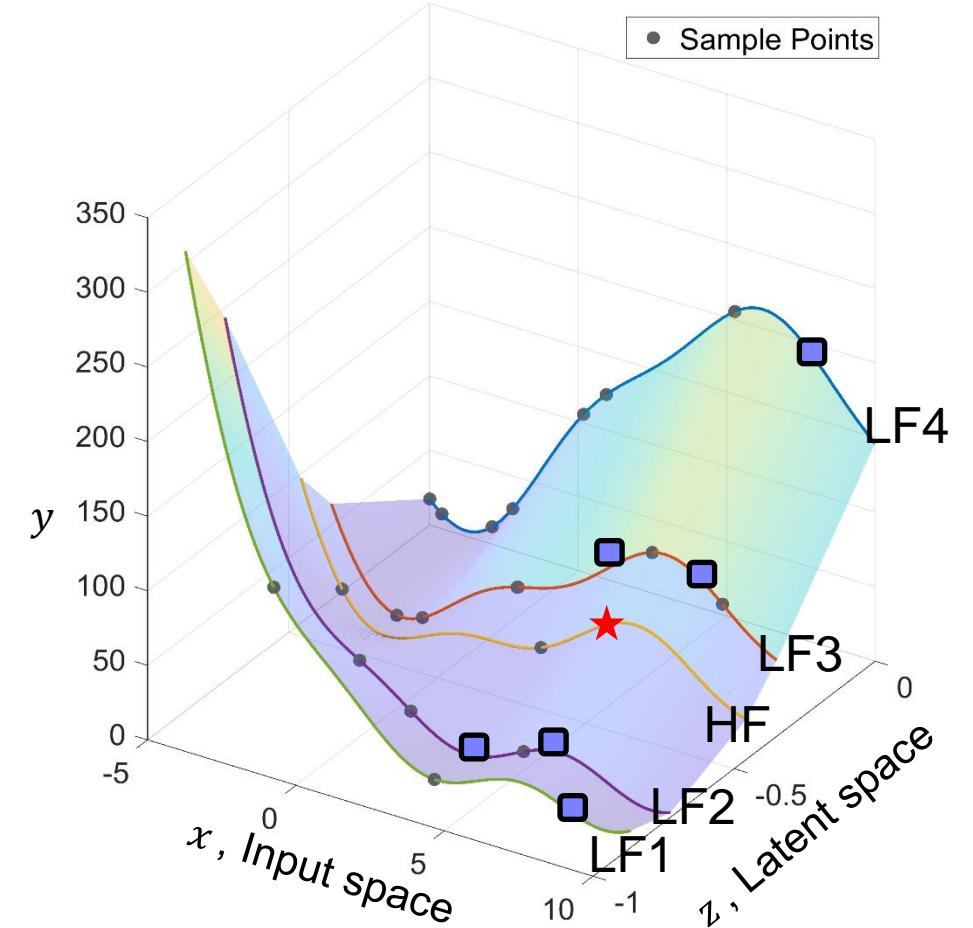
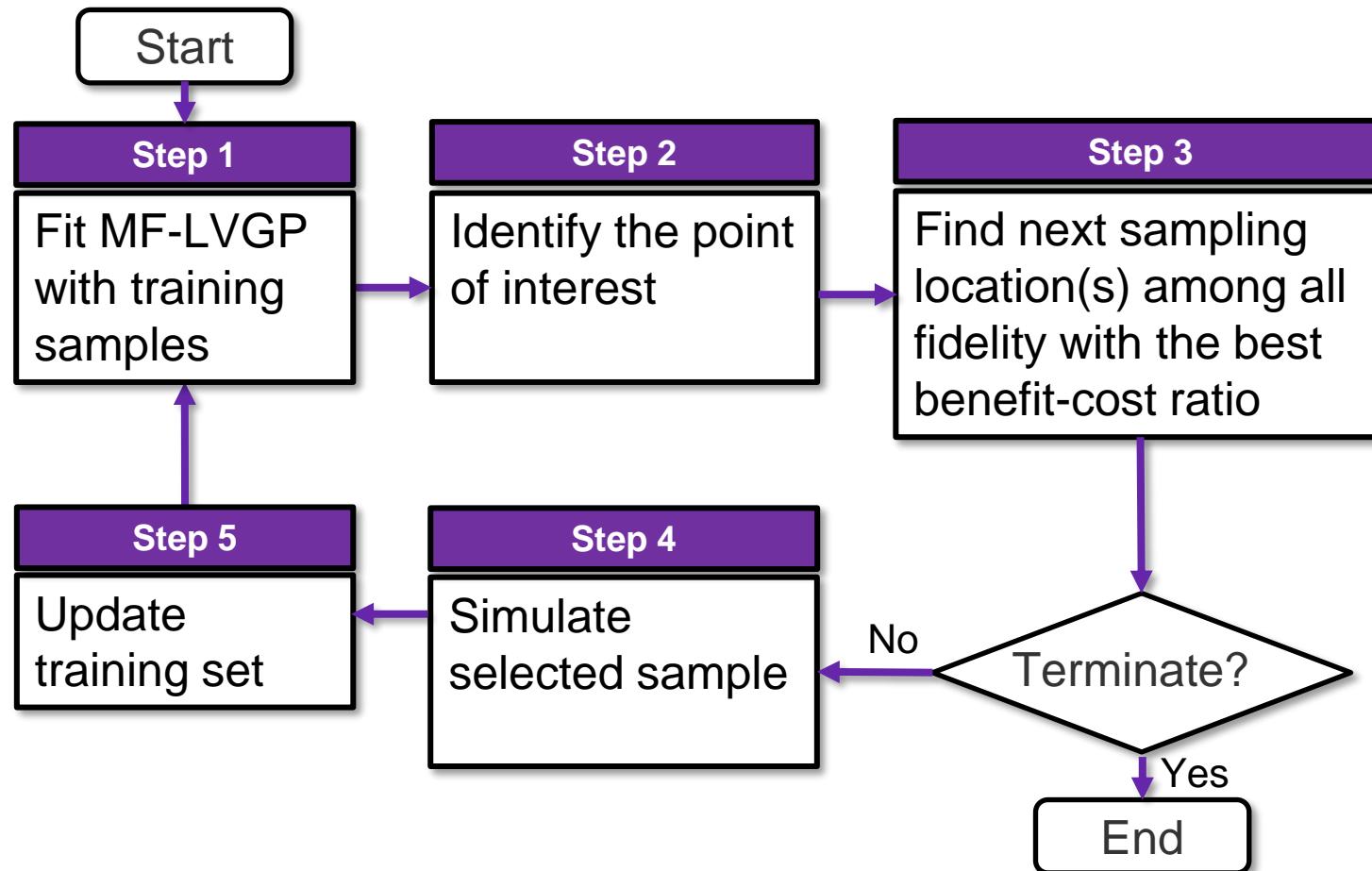


$$\frac{\Delta AE}{cost} = 0.03$$

# MF Adaptive Sampling Method: MuFASa



## Multi-Fidelity Adaptive Sampling (MuFASa)



★ Point of interest on HF subregion

■ Potential sampling location on LF subregions

# Two-Stage Optimization



## First Stage:

Determine the location of interest on the design space of HF model

$$x_{HF}^* = \arg \max(AF(x))$$

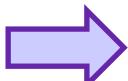
$AF(x)$  can be substituted by the common acquisition function for active learning.

### Global Fitting: Maximum MSE

$$x_{HF}^* = \arg \max \hat{s}^2(x_{HF})$$

### Bayesian Optimization: EI

$$EI(x) = (\hat{y}(x) - y^*)\Phi\left(\frac{\hat{y}(x) - y^*}{\hat{s}(x)}\right) + \hat{s}(x)\varphi\left(\frac{\hat{y}(x) - y^*}{\hat{s}(x)}\right)$$



## Second Stage:

Identify the infill sample with the best benefit-cost ratio

$$x_{next} = \arg \max \frac{AF(x_i) - \widehat{AF}(x_i)}{cost(i)}$$

$\widehat{AF}(x) \rightarrow$  Pre-posterior analysis

### Global Fitting: Maximum MSE

$$\Delta \widehat{AF}(x_{HF}^*, x_{next}) = \hat{s}^2(x_{HF}^*) - \hat{s}^2(x_{HF}^*, x_{next})$$

### Bayesian Optimization: EI

$$\Delta \widehat{AF}(x_{HF}^*, x_{next}) = EI^2(x_{HF}^*) - \widehat{EI}^2(x_{HF}^*, x_{next})$$

# Pre-posterior Analysis of LVGP



- candidate LF infill sample  $x_{next}$ .
- let  $\hat{y} = LVGP(x_{next})$
- Update parameters  $\hat{\mathbf{R}}_{new} = \begin{bmatrix} \mathbf{R} & r(x_{next}, \mathbf{x})^T \\ r(x_{next}, \mathbf{x}) & r(x_{next}, x_{next}) \end{bmatrix}$ ,  $\hat{\mathbf{y}}_{new} = [\mathbf{y}, \hat{y}]^T$

## Parameters in pre-posterior LVGP

$$\hat{\mu}_{new} = (\mathbf{1}^T (\hat{\mathbf{R}}_{new})^{-1} \mathbf{1})^{-1} \mathbf{1}^T (\hat{\mathbf{R}}_{new})^{-1} \hat{\mathbf{y}}_{new}$$

$$\hat{\sigma}^2_{new} = \frac{1}{n} (\hat{\mathbf{y}}_{new} - \hat{\mu}_{new} \mathbf{1})^T (\hat{\mathbf{R}}_{new})^{-1} (\hat{\mathbf{y}}_{new} - \hat{\mu}_{new} \mathbf{1})$$

## Prediction of arbitrary input of pre-posterior LVGP

$$\hat{y}(x_{HF}^*) = \hat{\mu}_{new} + \mathbf{r}(x^*) (\hat{\mathbf{R}}_{new})^{-1} (\hat{\mathbf{y}}_{new} - \hat{\mu}_{new} \mathbf{1})$$

$$\hat{s}^2(x_{HF}^*) = \hat{\sigma}^2_{new} (\mathbf{r}(x^*) - \mathbf{r}(x^*) \hat{\mathbf{R}}_{new}^{-1} \mathbf{r}(x^*)^T)$$

## Parameters in LVGP

$$\hat{\mu} = (\mathbf{1}^T \mathbf{R}^{-1} \mathbf{1})^{-1} \mathbf{1}^T \mathbf{R}^{-1} \mathbf{y}$$

$$\hat{\sigma}^2 = \frac{1}{n} (\mathbf{y} - \hat{\mu} \mathbf{1})^T \mathbf{R}^{-1} (\mathbf{y} - \hat{\mu} \mathbf{1}).$$

## Prediction of arbitrary input in LVGP

$$\hat{y}(\mathbf{x}^*) = \hat{\mu} + \mathbf{r}(\mathbf{x}^*) \mathbf{R}^{-1} (\mathbf{y} - \hat{\mu} \mathbf{1})$$

$$\hat{s}^2(\mathbf{x}^*) = \hat{\sigma}^2 (\mathbf{r}(\mathbf{x}^*) - \mathbf{r}(\mathbf{x}^*) \mathbf{R}^{-1} \mathbf{r}(\mathbf{x}^*)^T)$$

# Two-Stage Optimization



## First Stage:

Determine the location of interest on the design space of HF model

$$x_{HF}^* = \arg \max(AF(x))$$

$AF(x)$  can be substituted by the common acquisition function for active learning.

### Global Fitting: Maximum MSE

$$x_{HF}^* = \arg \max \hat{s}^2(x_{HF})$$

### Bayesian Optimization: EI

$$EI(x) = (\hat{y}(x) - y^*)\Phi\left(\frac{\hat{y}(x) - y^*}{\hat{s}(x)}\right) + \hat{s}(x)\varphi\left(\frac{\hat{y}(x) - y^*}{\hat{s}(x)}\right)$$



## Second Stage:

Identify the infill sample with the best benefit-cost ratio

$$x_{next} = \arg \max \frac{AF(x_i) - \widehat{AF}(x_i)}{cost(i)}$$

$\widehat{AF}(x) \rightarrow$  Pre-posterior analysis

### Global Fitting: Maximum MSE

$$\Delta \widehat{AF}(x_{HF}^*, x_{next}) = \hat{s}^2(x_{HF}^*) - \hat{s}^2(x_{HF}^*, x_{next})$$

### Bayesian Optimization: EI

$$\Delta \widehat{AF}(x_{HF}^*, x_{next}) = EI^2(x_{HF}^*) - \widehat{EI}^2(x_{HF}^*, x_{next})$$

# Outline



1

Introduction

2

LVGP & MF-LVGP

3

Multi-Fidelity Adaptive Sampling

4

Case Studies

5

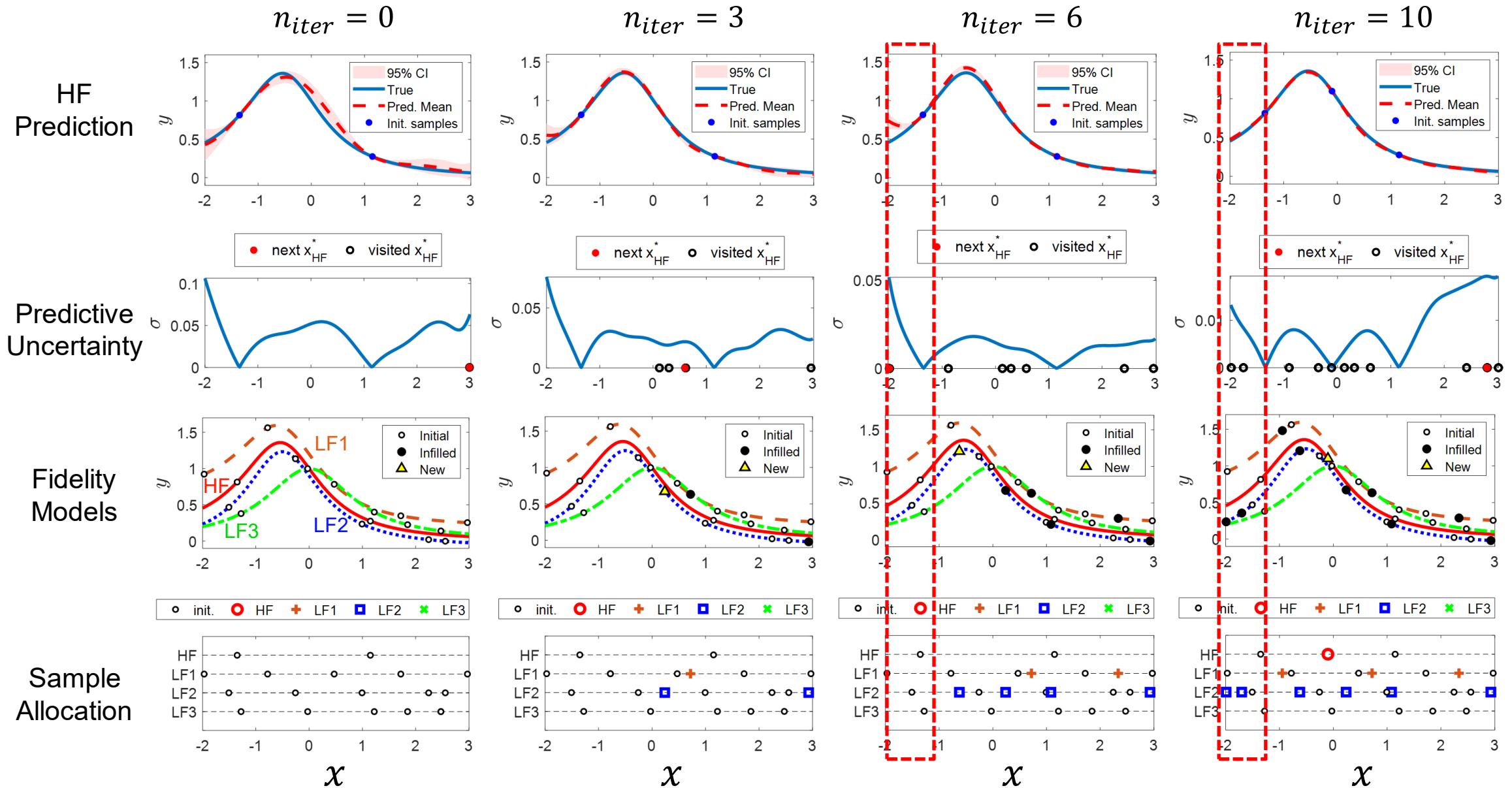
Closure

# 1D Illustrative Example with Multiple Fidelities (GF)



	<b>Model</b> ( $-2 \leq x \leq 3$ )	<b>Cost</b>	<b>Initi. Sample</b>
HF	$y_{HF}(x) = \frac{1}{0.1x^3 + x^2 + x + 1}$	100	2
LF1	$y_{LF1}(x) = \frac{1}{0.2x^3 + x^2 + x + 1} + 0.2$	10	5
LF2	$y_{LF2}(x) = \frac{1}{x^2 + x + 2} - 0.1$	10	5
LF3	$y_{LF3}(x) = \frac{1}{x + 1}$	10	5

# 1D Illustrative Example with Multiple Fidelities (GF)

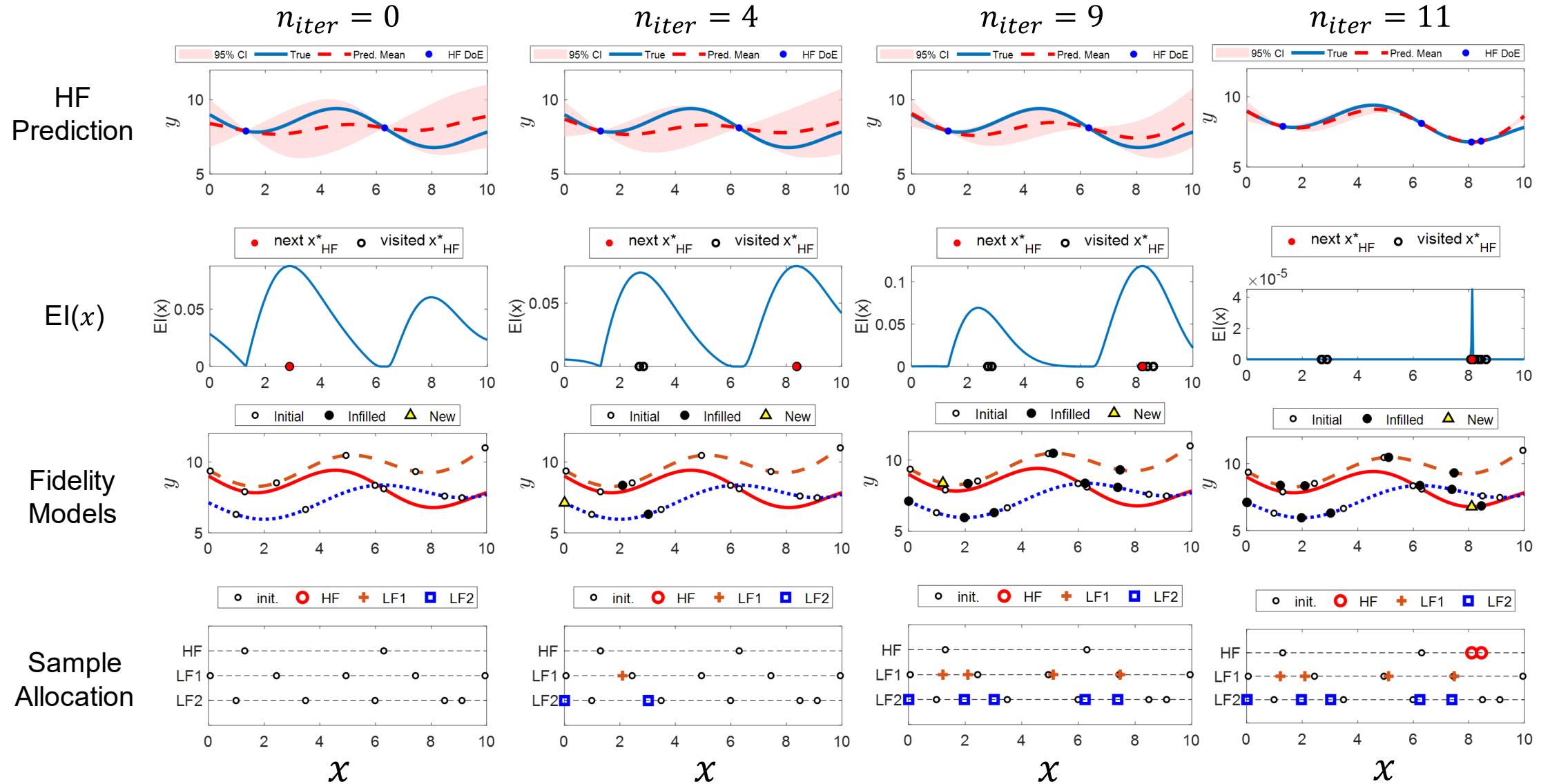


# 1D Illustrative Example with Multiple Fidelities (BO)

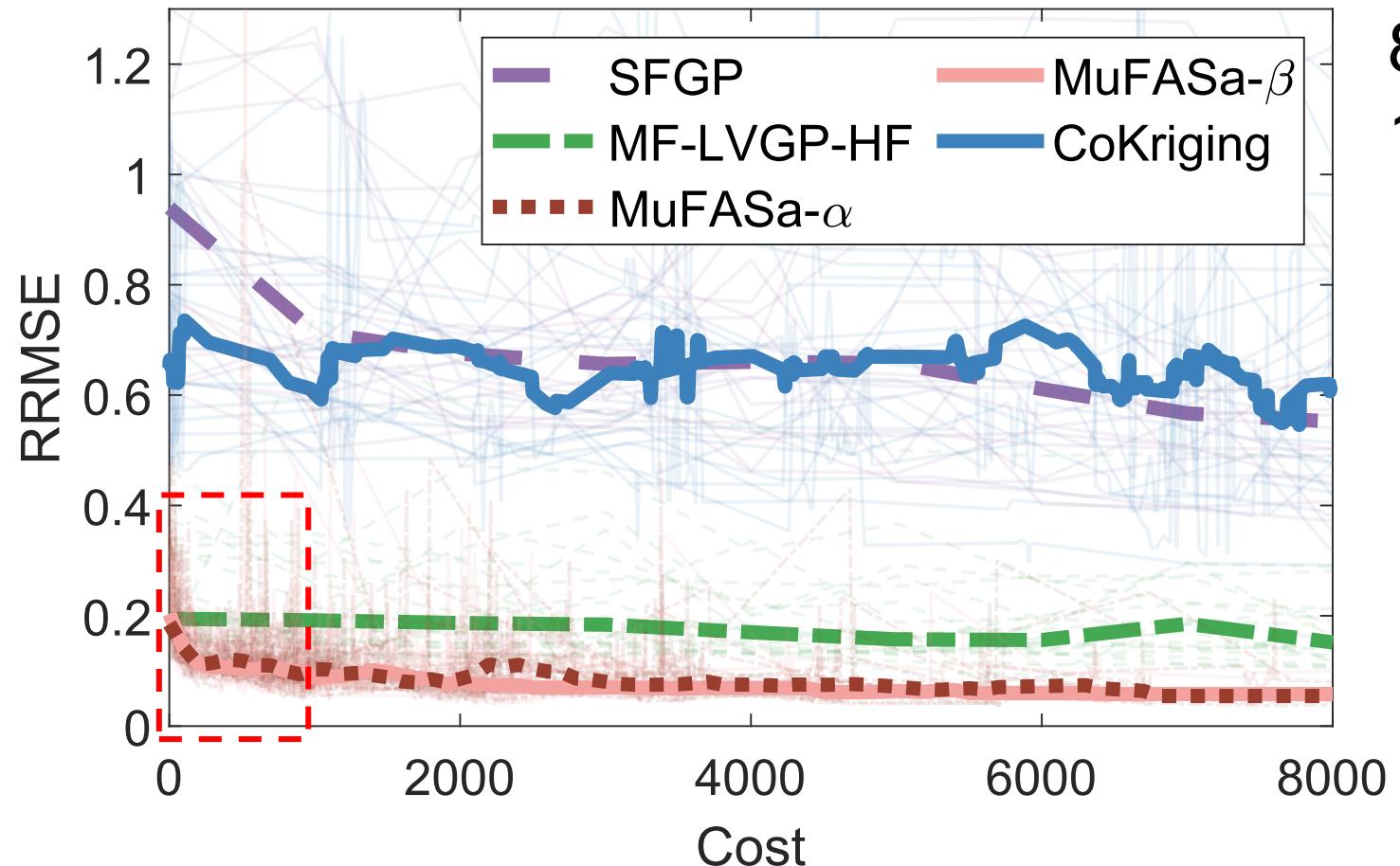


	<b>Model</b> ( $0 \leq x \leq 10$ )	<b>Cost</b>	<b>Init. Sample</b>
HF	$y_{HF}(x) = -\sin x - \exp\left(\frac{x}{10}\right) + 10$	1000	2
LF1	$y_{LF1}(x) = -\sin(0.95x) - \exp\left(\frac{x}{50}\right) + 0.03(x - 2)^2 + 10.3$	1	5
LF2	$y_{LF2}(x) = -\sin(0.8x) - \exp\left(\frac{x}{50}\right) + 0.03(x - 2)^2 + 8$	1	5

# 1D Illustrative Example with Multiple Fidelities (BO)



# Convergence History for Borehole (GF)



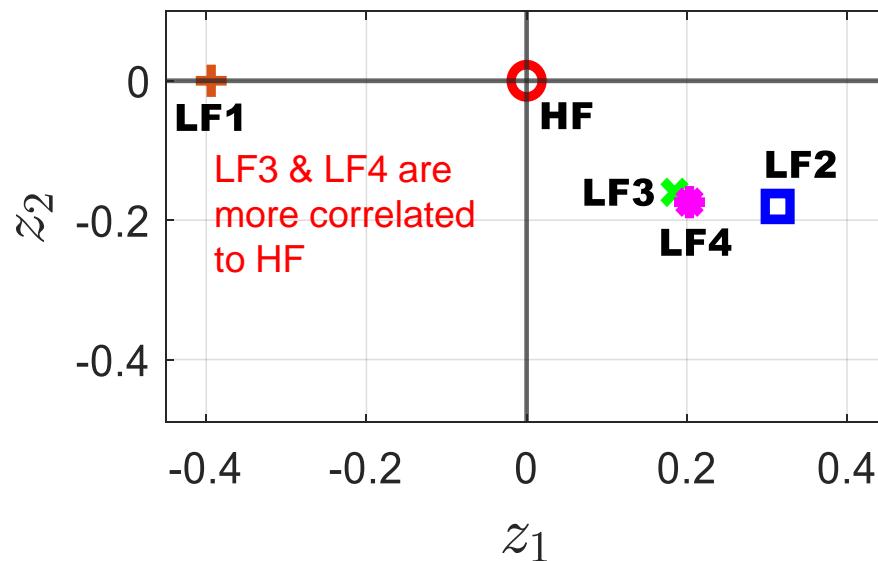
8 inputs,  
1 HF + 4 LF

- MF-LVGP & MuFASa outperforms the CoKriging and SFGP in accuracy, even before adaptive sampling, RRMSE drops dramatically before the HF samples are infilled, mostly contributed by LF infill samples.
- RRMSE curves have several jumps due to the variation of the scaling factors via MLE.

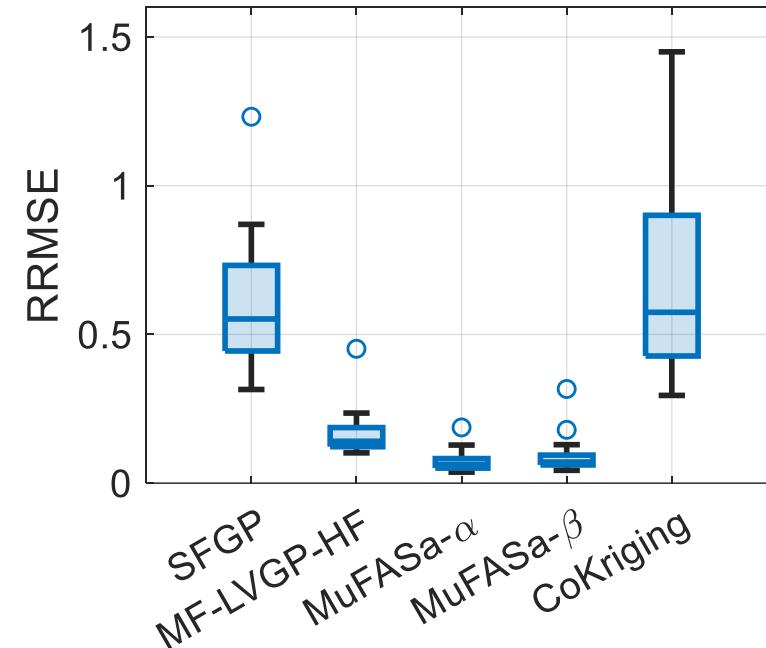
# Replicate Tests for High-D Test Cases (GF)



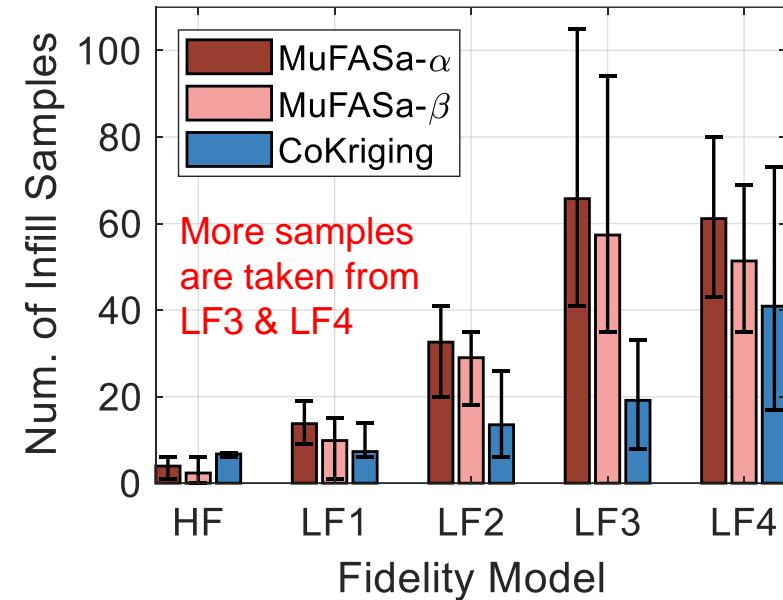
**Latent space of fidelity level**



**Termination RRMSE**

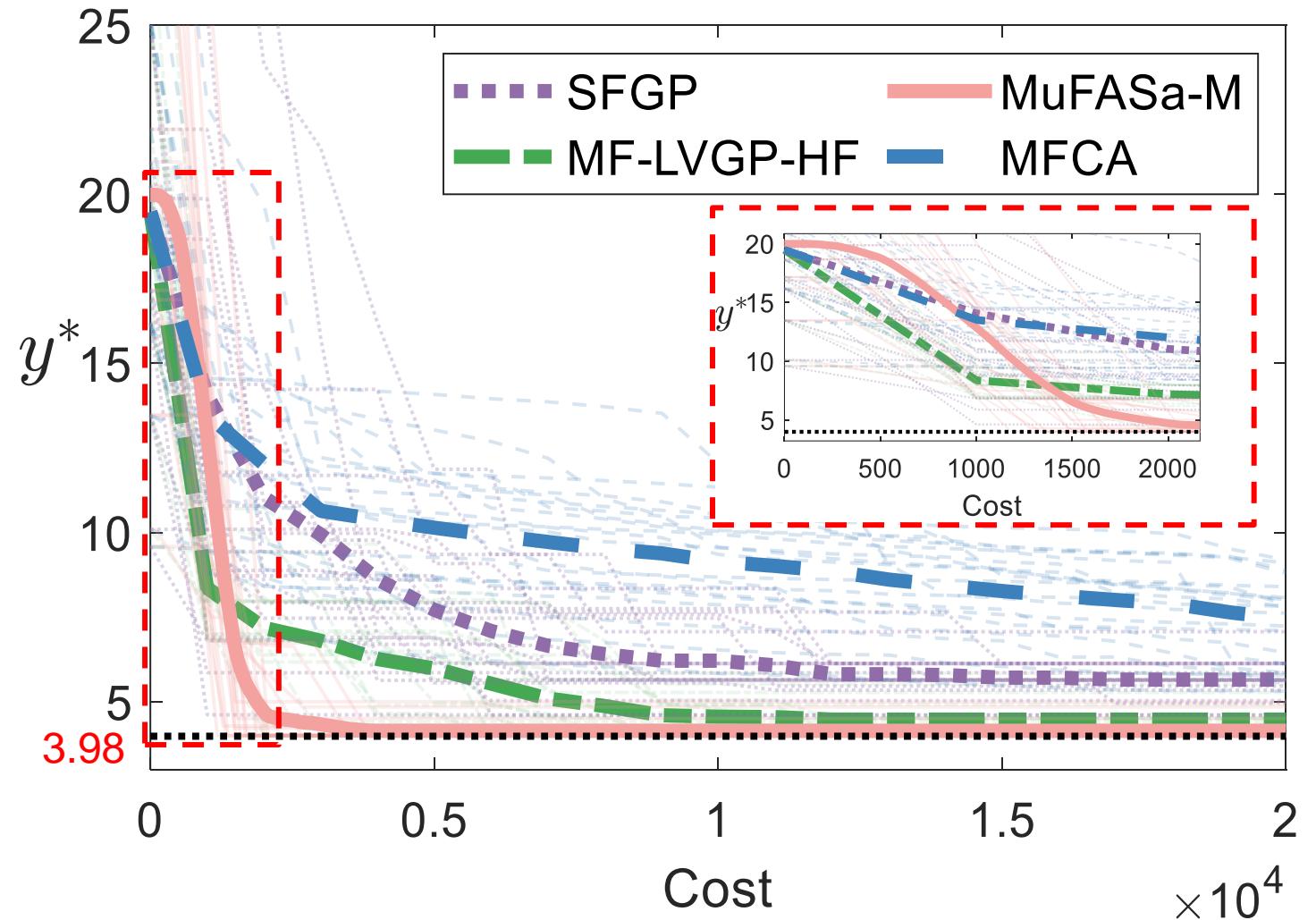


**Sample allocation**



ID	HF	LF1	LF2	LF3	LF4
Cost	1000	10	10	10	10
Ini. DoE	4	10	10	10	10

# Convergence History for Borehole (BO)



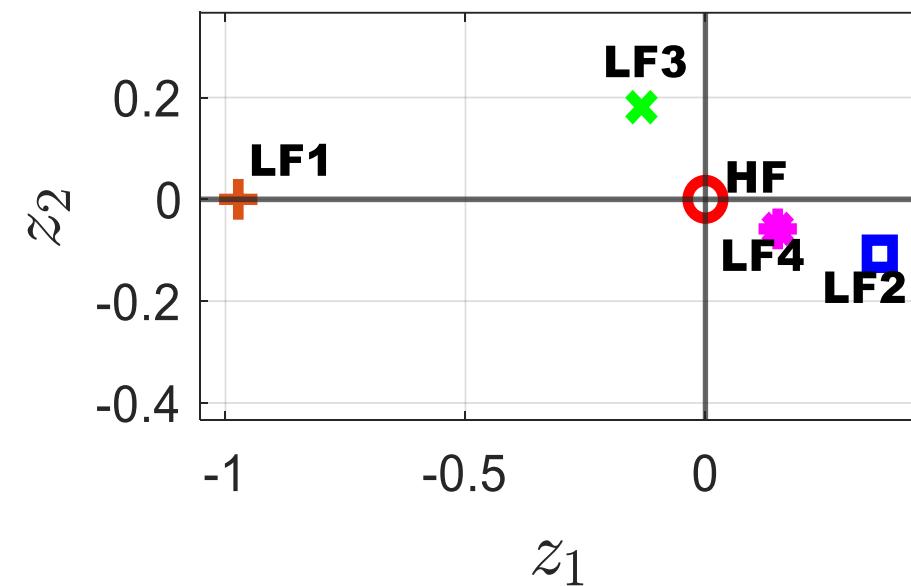
8 inputs,  
1 HF + 4 LF

- MuFASa outperforms benchmark methods in both convergence rate and robustness.
- The optimal values do not drop immediately as the BO starts: more LF samples are taken to improve the model, then HF samples are infilled near the ground true optimum.

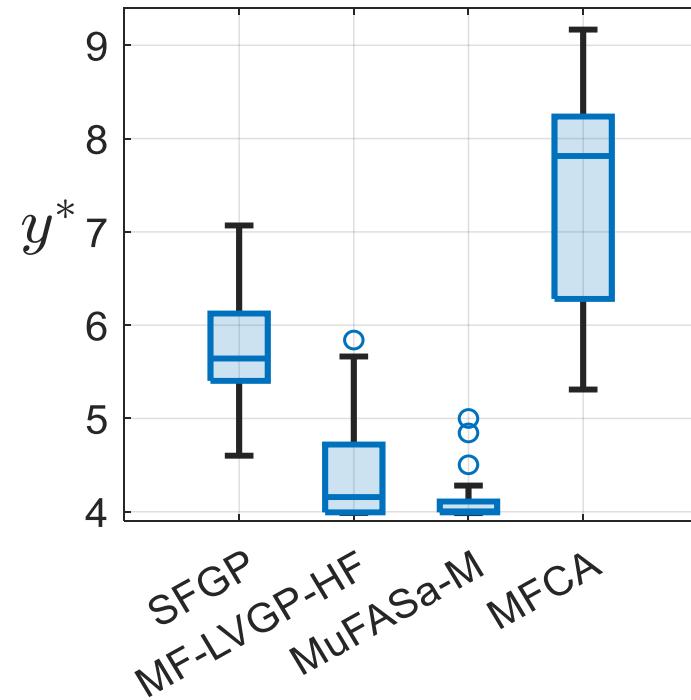
# Replicate Tests for Borehole (BO)



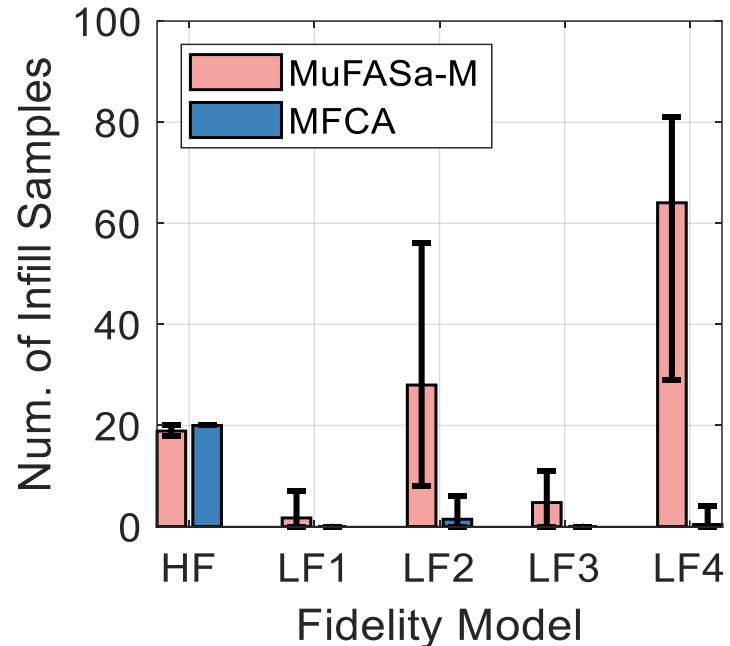
Latent space of fidelity level



Optimal Solution



Sample Allocation



ID	HF	LF1	LF2	LF3	LF4
Cost	1000	100	10	100	10
Ini. DoE	5	5	25	5	25

# Outline



1

Introduction

2

LVGP & MF-LVGP

3

Multi-Fidelity Adaptive Sampling

4

Case Studies

5

Closure

# Closure



## Remarks

- **MF-LVGP:** non-hierarchical, interpretable MF data fusion.
- **Pre-posterior Analysis:** **Quantify the future benefit** of the candidate samples.
- **MuFASa:** a benefit & cost-aware adaptive sampling framework.
- Address **GF** and **BO** with the same framework.
- Outperform benchmark methods with better convergence rate and robustness.

## Future Works

- *Scalable techniques* → accommodate big dataset.
- *Model-reduction techniques* → accommodate higher-dimensional cases.
- *greedy sampling/dynamic programming* → batch sampling, look multiple steps ahead.

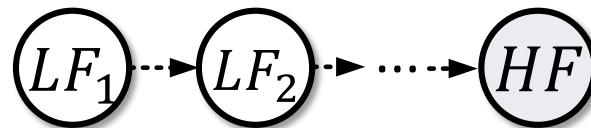
Thank you & Appreciate for the attentions!



# Categorize MF Methods via Architecture



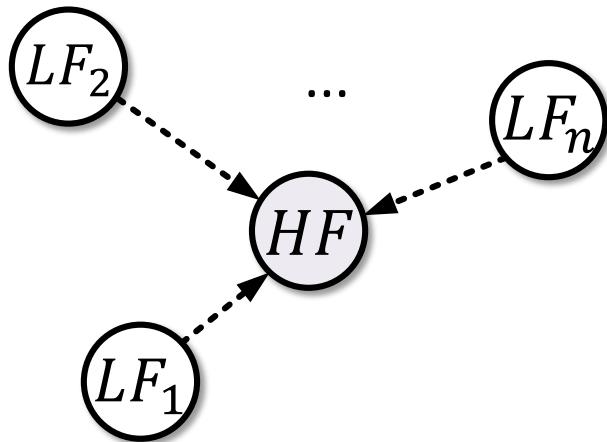
$$HF = HF | LF_n | \dots | LF_2 | LF_1$$



(a) Hierarchical Architecture

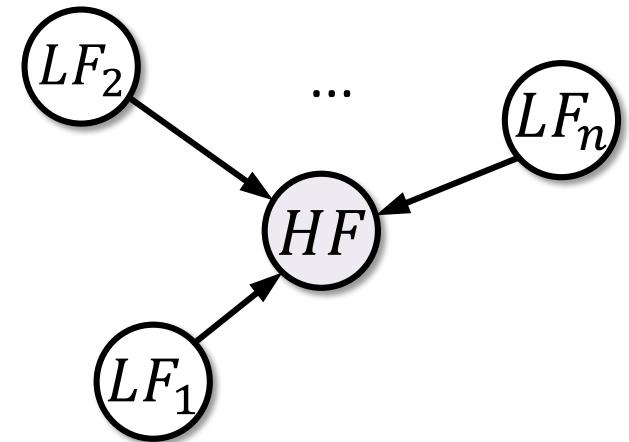
- Ranking fidelity models may not be practical
- Uncertainty propagation, not desirable for adaptive sampling

$$HF = HF | (LF_n, \dots, LF_2, LF_1)$$



(b) Non-hierarchical architecture with implicit use of correlation

- The contribution of the LF samples are unknown.
- Treat LF and HF source as independent sources and neglect their interplay.



(c) Non-hierarchical architecture with explicit use of correlation

- Focus on improving HF surrogate only as the objective.
- Approximate the future benefit as the sampling criteria is the key.

# Borehole Function for Bayesian Optimization



	<b>Model</b>	<b>Cost</b>	<b>Ini. samples</b>
HF	$y_{HF} = \frac{2\pi T_u (H_u - H_l)}{\ln\left(\frac{r}{rw}\right) (1 + \frac{2LT_u}{\ln\left(\frac{r}{rw}\right) r_w^2 k_w} + \frac{T_u}{T_l})}$	1000	5
LF 1	$y_{LF1} = \frac{2\pi T_u (H_u - 0.8H_l)}{\ln\left(\frac{r}{rw}\right) (1 + \frac{1LT_u}{\ln\left(\frac{r}{rw}\right) r_w^2 k_w} + \frac{T_u}{T_l})}$	100	5
LF 2	$y_{LF2} = \frac{2\pi T_u (H_u - H_l)}{\ln\left(\frac{r}{rw}\right) (1 + \frac{8LT_u}{\ln\left(\frac{r}{rw}\right) r_w^2 k_w} + 0.75 \frac{T_u}{T_l})}$	10	25
LF 3	$y_{LF3} = \frac{2\pi T_u (1.09H_u - H_l)}{\ln\left(\frac{4r}{rw}\right) (1 + \frac{3LT_u}{\ln\left(\frac{r}{rw}\right) r_w^2 k_w} + \frac{T_u}{T_l})}$	100	5
LF 4	$y_{LF4} = \frac{2\pi T_u (1.05H_u - H_l)}{\ln\left(\frac{4r}{rw}\right) (1 + \frac{3LT_u}{\ln\left(\frac{r}{rw}\right) r_w^2 k_w} + \frac{T_u}{T_l})}$	10	25

Input space:

$$100 \leq T_u \leq 1000$$

$$990 \leq H_u \leq 1110$$

$$700 \leq H_l \leq 820$$

$$100 \leq r \leq 10000$$

$$0.05 \leq r_w \leq 0.15$$

$$10 \leq T_l \leq 500$$

$$1000 \leq L \leq 2000$$

$$6000 \leq K_w \leq 12000$$

Ground Truth  
Optimum: 3.98

Zanjani Foumani, Z., Shishehbor, M., Yousefpour, A., & Bostanabad, R. (2023). Multi-fidelity cost-aware Bayesian optimization. *Computer Methods in Applied Mechanics and Engineering*, 407, 115937.