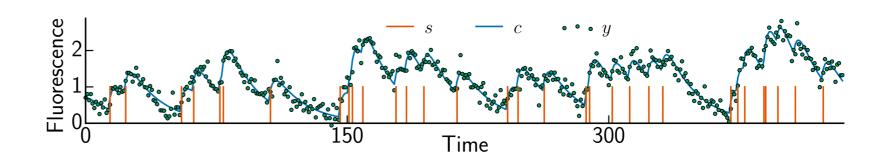
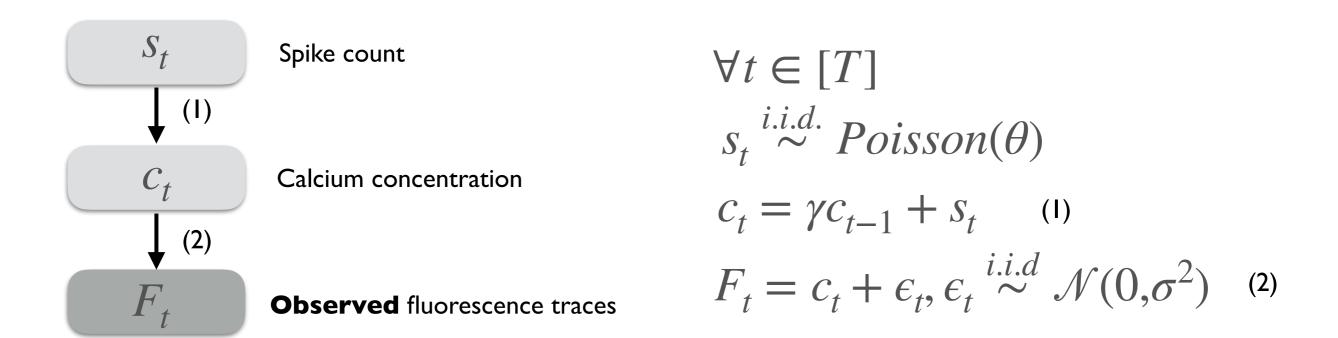
Exact spike train inference via ℓ_0 optimization

Yiqun Chen, 572 methodology presentation 05/07/2019





What you missed from the last season of my presentation...



Wait - how did we cast this as an optimization problem?

MAP estimator with **Poisson** prior for the spikes:

$$\begin{split} \hat{s}_t &= \operatorname{argmax}_{s_t \in \mathbb{N}} P(s_1, \cdots, s_T | F) \\ &= \operatorname{argmax}_{s_t \in \mathbb{N}, c_{1:T}} \sum_{t=1}^T -\frac{1}{2\sigma^2} (F_t - c_t)^2 + s_t \log \theta - \log s_t! \end{split}$$

MAP estimator with **Exponential** prior for the spikes:

$$\begin{split} \hat{s}_t &= \operatorname{argmax}_{s_t > 0} \sum_{t=1}^T -\frac{1}{2\sigma^2} (F_t - c_t)^2 - s_t \cdot \theta \\ &\stackrel{equiv}{=} \operatorname{argmax}_{c_1, \cdots, c_T; c_t - \gamma c_{t-1} > 0} \sum_{t=1}^T -\frac{1}{2\sigma^2} (F_t - c_t)^2 + (c_t - \gamma c_{t-1}) \\ &\approx \operatorname{argmin}_{c_1, \cdots, c_T} \frac{1}{2} \sum_{t=1}^T \left(F_t - c_t \right)^2 + \underline{\lambda \left| c_t - \gamma c_{t-1} \right|} \end{split}$$

Some post-thresholding is usually performed

Wait - how did we cast this as an optimization problem?

MAP estimator with **Poisson** prior but **indicator** St:

$$\begin{split} \hat{s}_t &= \text{argmax}_{s_t \in \{0,1\}} P(s_1, \cdots, s_T | F) \\ &= \text{argmax}_{s_t \in \{0,1\}} \sum_{t=1}^T -\frac{1}{2\sigma^2} (F_t - c_t)^2 + s_t \log \theta - \log s_t! \\ &= \text{argmin}_{s_t \in \{0,1\}} \frac{1}{2} \sum_{t=1}^T (F_t - c_t)^2 + \lambda \cdot s_t \end{split}$$

$$\hat{s}_t = \hat{c}_t - \gamma \hat{c}_{t-1} \stackrel{equiv}{=} \operatorname{argmin}_{c_1, \cdots, c_T; c_t - \gamma c_{t-1} > 0} \frac{1}{2} \sum_{t=1}^T (F_t - c_t)^2 + \lambda \cdot \mathbf{1} \{ c_t \neq \gamma c_{t-1} \}$$

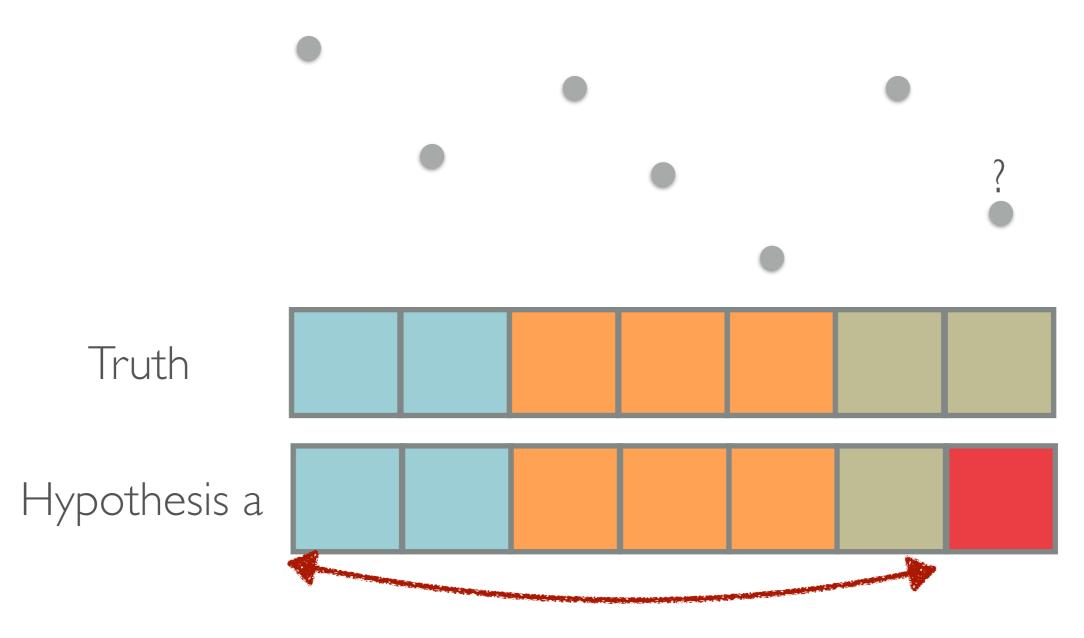
$$\approx \operatorname{argmax}_{c_1, \dots, c_T} \frac{1}{2} \sum_{t=1}^{T} (F_t - c_t)^2 + \lambda \cdot \mathbf{1} \{ c_t \neq \gamma c_{t-1} \}$$



Presence of spikes should only **increase** the Ca²⁺ concentration

Observation: spikes **partition** the observed fluorescence

Given the occurrence of most recent spike, what happened after does not affect what happened before the spike



Same objective value

Algo in real-time

Algo in real-time

? ?

We computed Algo in real-time at time point 2! Min {

Dynamic programming:

$$\min_{c_1, \dots, c_T} \frac{1}{2} \sum_{t=1}^{T} (F_t - c_t)^2 + \lambda \sum_{t=2}^{T} \mathbf{1} \{ c_t \neq \gamma c_{t-1} \}$$

$$= \min_{|\mathcal{P}|=K\in\mathbb{N}} \min_{\forall t\in[T]\setminus\mathcal{P}, c_t=\gamma c_{t-1}} \frac{1}{2} \sum_{t=1}^{T} (F_t - c_t)^2 + \lambda \sum_{t=2}^{T} \mathbf{1}\{c_t \neq \gamma c_{t-1}\}$$

$$= \min_{K \in \mathbb{N}} \min_{0 < \tau_0 < \dots < \tau_K < \tau_{K+1} = T, c_{\tau_1} : c_{\tau_K}} \frac{1}{2} \sum_{j=0}^K \left[(F_{\tau_j + 1} - c_{\tau_j + 1})^2 + \sum_{l=1}^{\tau_{j+1} - \tau_j} (F_{\tau_{j+1} + l} - \gamma^l \cdot c_{\tau_{j+1}})^2 \right] + \lambda \cdot K$$

Right after a spike the fluorescence can increase by an unspecified amount

Otherwise we have **exponential decay**...

Dynamic programming:

$$G(T) = \min_{0 < \tau_0 < \dots < \tau_K < \tau_{K+1} = T, K \in \mathbb{N}} \sum_{j=0}^K \left\{ \frac{1}{2} \min_{c_{\tau_j} + 1} \left[\sum_{t = \tau_j + 1}^{\tau_{j+1}} (y_t - \gamma^{t - (\tau_j + 1)} \cdot c_{\tau_j + 1})^2 \right] \right\} + \lambda \cdot K$$

Too much effort to type - let's abbreviate it as $\mathbf{D}(y_{\tau_i}:y_{\tau_{i+1}})$

$$G(T) = \min_{0 < \tau_0 < \dots < \tau_K < \tau_{K+1} = T, K \in \mathbb{N}} \sum_{j=0}^{K} \left\{ \mathbf{D}(y_{\tau_j} : y_{\tau_{j+1}}) + \lambda \cdot K \right\}$$

$$= \min_{s < T} \left\{ \min_{0 < \tau_0 < \dots < \tau_K = s < T, K-1 \in \mathbb{N}} \left[\sum_{j=0}^{K-1} \mathbf{D}(y_{\tau_j} : y_{\tau_{j+1}}) + \lambda \cdot (K-1) \right] + D(y_{\tau_K} : T) + \lambda \right\}$$

$$= \min_{s < T} \left\{ G(s) + \mathbf{D}(s:T) + \lambda \right\}$$
Obs:
1. Min is taking over **T** different things
2. G(s) values can be **memoized**/stored

- D(s:T) can be computed in O(1)

$$G(t) = \min_{s < t} \left\{ G(s) + \mathbf{D}(s:t) + \lambda \right\}$$
 takes $O(t)$ steps to compute

Unroll this for loop (aka DP):

$$G(0) = -\lambda$$

$$G(1) = G(0) + \mathbf{D}(y_1) + \lambda$$

$$G(2) = \min\{G(0) + \mathbf{D}(y_{1:2}) + \lambda, G(1) + \mathbf{D}(y_2) + \lambda\}$$

Time complexity:
$$\sum_{t=1}^{T} t = O(T^2)$$

Pruning of the active sets

$$G(t) = \min_{s < t} \left\{ G(s) + \mathbf{D}(s:t) + \lambda \right\}$$

Maybe we don't need to do it for all t possible candidates...

$$\mathcal{E}_{s+1} = \{ \tau \in \{ \mathcal{E}_s \cup s \} : G(\tau) + \mathbf{D}(y_{\tau+1:s}) < G(s) \}$$

It's mathematically impossible to have the most recent change point to have occurred before: lower cost with not putting a spike there!

In practice we can often eliminate some s: under some mild assumptions; **expected** time complexity is $\tilde{O}(T)$

$$c_t = \gamma c_{t-1} + s_t$$

$$F_t = c_t + \epsilon_t, \epsilon_t \stackrel{i.i.d}{\sim} \mathcal{N}(0, \sigma^2)$$

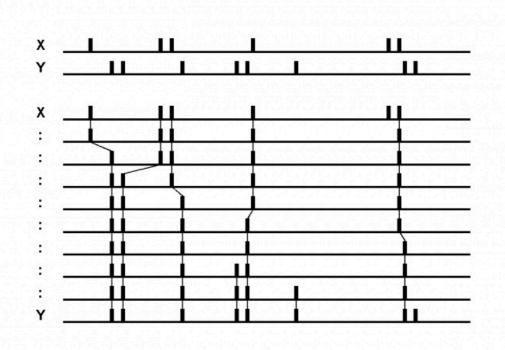
- 1. How to estimate γ ?
- a. Estimate from a segment of exponentially decaying data (eye-ball test)
- b. (Follow-up paper) $\gamma = 1 \frac{\Delta_t}{\phi}$
- 2. How to choose λ ?

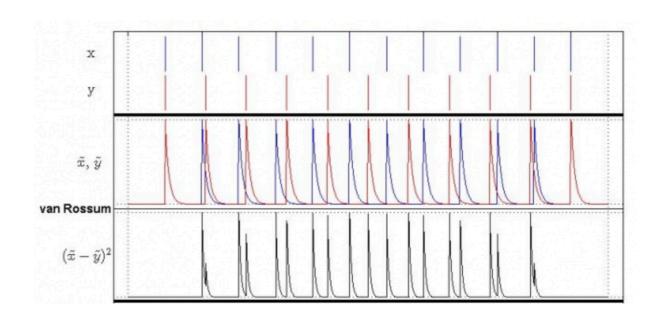
2-fold CV to minimize MSE of estimated Ca²⁺,e.g., $\hat{c}_2 = \frac{1}{2}(\hat{c}_1 + \hat{c}_3)$

3. In reality, $F_t = \beta_1 c_t + \beta_0 + \epsilon_t$ or $F_t = c_t + \beta_{0,t} + \epsilon_t$

Try a grid of intercept values via CV and pick the best fit

Almost there - metrics for evaluating spike sequences





Victor-Purpura distance

Van Rossum distance

Thanks!!!

Next steps:

- I. Real data application
- 2. Wrap up the report



