



High

Accuracy ...

## High Accuracy CMOS Capacitance Multiplier

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### ABSTRACT

This paper presents a CMOS circuit suitable to magnify the value of a grounded unit capacitance. The multiplication factor is achieved through the gain of current mirrors and its maximum value is solely limited by power consumption constraints. Circuit solutions are then developed to reduce power dissipation and to enable the detection of small unit capacitances. Thanks to its inherent simplicity, the circuit is also characterized by wide-band operations. An on-chip tuning technique is also included which allows the value of the obtained capacitance to be adjusted by about 270%. Simulations of a design example are provided.

### 1. INTRODUCTION

In short, you need big capacitance. Analog integrated systems often require the implementation of high-valued capacitors characterized by good accuracy and linearity. This is however an onerous task since linear capacitors -realized with two polysilicon layers- exhibit a relatively small specific capacitance. Furthermore, in some sensor applications it can be useful to deal with capacitance values higher than those normally given by the capacitive sensors. In all these circumstances, a circuit behaving as a capacitance multiplier becomes very useful.

Active capacitive multipliers have been developed in the past, employing both voltage- or current-mode techniques [1-3]. Solutions using voltage amplifiers as active elements (exploiting the well-known Miller effect) can achieve high multiplication factors but are limited in frequency since the voltage gain includes a relatively low frequency pole, moreover they require the availability of both capacitive terminals. Current-mode techniques provide high-frequency performance but, as will be clear later, with reduced values of multiplication factors. In this last case, negative Current Conveyors (CCII-) [4], current mirrors and current amplifiers [5] have been used as active elements. To explain the operating principle of current-mode capacitive multiplication, consider the feedback configuration which uses a common-drain (or common-collector) transistor and a current mirror with current ratio equal to  $k$ , schematically illustrated in Fig. 1.

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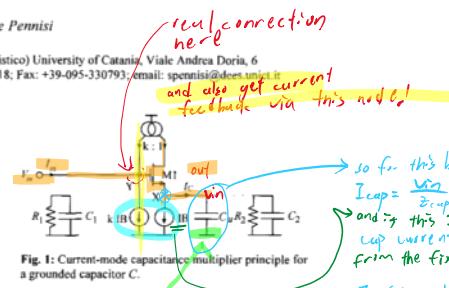


Fig. 1: Current-mode capacitance multiplier principle for a grounded capacitor  $C$ .

In our discussions we assume that the capacitor to be multiplied is grounded, as this situation is the most general one.

Considering an ideally unity voltage gain between the gate and source terminals of the transistor, simple analysis shows that the input impedance,  $Z_{in} = V_{in} / I_{in}$ , is equal to  $1/kC_1$ . Thus, the value of the capacitance connected between the source terminal and ground is effectively multiplied by the current gain  $k$ . The main advantage of this scheme (and of many of the current-mode ones) relies on its simplicity. Moreover, the linearity and the high bandwidth of the current transfer gain, measured with current effects, is reflected on the obtained capacitance value. Of course, unavoidable nonidealities affect the circuit behavior. Basically, we have to consider the finite impedance at the gate of  $M_1$  due to the generator  $I_B$  and the output of the current mirror (that we model with a resistor  $R_1$  in parallel with a parasitic capacitance  $C_1$ ), the output resistance of the source follower transistor ( $V_{out}$ ), and the output impedance of the current generator  $I_B$  ( $R_2$  in parallel with  $C_2$ ). Moreover, the pole in the current mirror transferfunction,  $\omega_k$ , limits the high-frequency operations. After considering these nonidealities we get

$$Z_{in} = \frac{1 + s/\omega_k}{k} \frac{1 + sC_1/g_m}{1 + s(C_1 + C_2)} // \frac{1}{sC_1} // R_1 \quad (1)$$

and the equivalent circuit of this impedance is modeled in Fig. 2. It is seen that resistances  $R_1$  and  $R_2$  affect the low-frequency circuit behaviour. However, since  $R_2$  is divided by  $k$  its effect is usually the dominating one and can dramatically reduce the operating frequency bandwidth.

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for large values of  $k$ . At high frequencies the limitation is due to the lowest pole among those introduced by the voltage and current transfers ( $\omega_k/C_1$  and  $\omega_k$ , respectively). Moreover, the minimum usable value of  $C_1$  is limited by capacitor  $C_2$ , while  $C_1$  causes an offset error. Finally, it is apparent that any error of the current mirror ratio turns directly into a gain error.

In order to improve the above solution, we propose in this paper a novel implementation of capacitance multiplier which reduces the effects of many of the nonidealities discussed above, thus allowing the detection and amplification of smaller unit capacitors and enhancing the frequency performance. To improve flexibility, an electronic tuning technique is also added enabling the on-chip variation of the multiplication factor. This last property is, for instance, essential to compensate for process tolerances in continuous-time filters or integrated sensor applications.

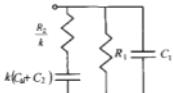


Fig. 2: Low-frequency equivalent circuit of the input impedance of circuit in Fig. 1.

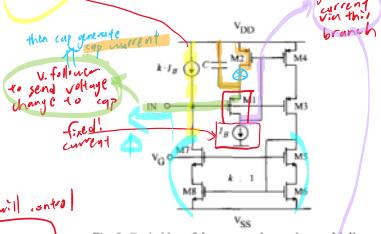


Fig. 3: Basic idea of the proposed capacitor multiplier.

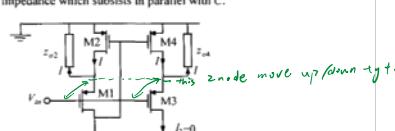


Fig. 4: A schematic of the input section of the proposed circuit (removing the unit capacitor  $C$ ).

It can be noticed that, without using this technique, the finite output impedance of  $M_2$  would strongly limit circuit operations at low frequency. Indeed, being the current on a capacitor proportional to the frequency, for angular frequencies much lower than  $1/(z_{ds}C)$  the current through  $C$  would be much lower than that flowing through  $z_{ds}$  and therefore its contribution to  $I_1$  would be hardly

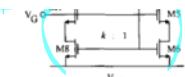


Fig. 3: Basic idea of the proposed capacitor multiplier.

## 2. THE PROPOSED SOLUTION

The proposed circuit is shown in Fig. 3. The input transistor  $M_1$  acts as a voltage follower and at its source terminal, the grounded unit capacitor  $C$ , is connected. Since the current through  $M_1$  is constant (it is set by the bias current generator  $I_b$ ) the current flowing through  $C$  is sensed by transistor  $M_2$ , it is then mirrored through  $M_4$  and delivered to the current mirror  $M_5-M_7$ . The capacitance factor is set by the transistor aspect ratios of  $M_4$  and  $M_5$ , mathematically:

$I_o = k \frac{W}{L} (V_{GS} - V_{th})$   
but why this branch?  
lower tones part of the current (voltage changes)  
control  $V_{GS}$   
maybe this work similar too  
 $I_{DSM1} = 0.2V$  get shifted up and down due to varying  $Z_B$  in  $M_2$

It can be noticed that, without using this technique, the finite output impedance of  $M_2$  would strongly limit circuit operations at low frequency. Indeed, being the current on a capacitor proportional to the frequency, for angular frequencies much lower than  $1/(Z_o C)$  the current through  $Z_o$  would be much lower than that flowing through  $C$  and therefore its contribution to  $I_o$  would be hardly detectable. On the other hand, the equivalent output resistance at the drain of  $M_7$  can be made very large using cascading techniques, thereby minimizing its adverse effect at low frequencies.

Another attractive feature of the circuit is its very small resistance exhibited at the source of  $M_1$ , whose expression is approximately  $1/g_m^2 r_d$ . This, as already stated, improves the high-frequency performance.

The circuit main drawback is the high power dissipation that is proportional to the multiplication factor. Indeed, the small-signal multiplication factor,  $k$ , applies also to the quiescent current of the mirror  $M_5-M_8$ .

Drop need  $k$  times DC current

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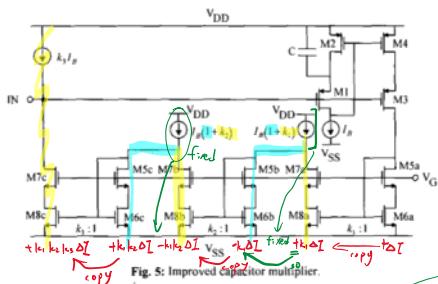


Fig. 5: Improved capacitor multiplier.

When a large factor  $k$  is needed, this constitutes a serious problem. To avoid the above limitation, we adopt the solution in Fig. 5, where the small-signal current gain is obtained through the cascade of three current mirrors (staged  $(M_5a-M_7a)$ ,  $(M_5b-M_7b)$ , and  $(M_5c-M_7c)$ ). The  $j$ th current mirror provides a current gain equal to  $k_j$  so that the overall multiplication factor is  $k = k_1 k_2 k_3$ , but the quiescent current of the input section of each current mirror (i.e., transistors  $M_5-M_6$ ) is always the same and equal to  $I_b$ . Therefore, the total current dissipation of the circuit is  $I_{Diss} = (k_1 + k_2 + k_3) I_b$ . If  $k_1 = k_2 = k_3$  (i.e., if all three current mirrors have the same gain), then the total current dissipation of the circuit is  $I_{Diss} = (3 + k_1) I_b$ . Finally, a tuning subsection can be incorporated in the circuit. The most simple is perhaps the one which exploits triode-biased transistors ( $M_{T1}-M_{T2}$ ) as source degeneration of a generic unitary current mirror ( $M_5-M_6$ ), as illustrated in Fig. 6 [6]. If the tuning voltage,  $V_{TUNE}$ , is zero, the mirror operates under balanced conditions, because the conductance of  $M_{T2}$  equals that of  $M_{T1}$ , and  $I_{out}$  equals  $I_{in}$ . If  $V_{TUNE}$  is negative (positive) the conductance of  $M_{T2}$  is lower (greater) than that of  $M_{T1}$  and  $I_{out}$  is lower (greater) than  $I_{in}$ ; therefore, their current ratio can be varied by means of  $V_{TUNE}$ :

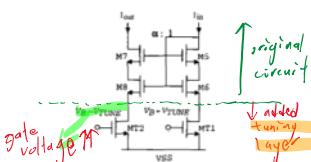


Fig. 6: Tuning technique using triode-biased transistors  $M_{T1}-M_{T2}$ .

Note that the achieved current ratio, also applies to the quiescent currents in addition the small signal component. Therefore, we have to vary the bias current of the output branch according to the tuning voltage applied [6]. For this reason it is convenient to apply this technique to the last current mirror in Fig. 5,  $M_5c-M_6c$ , and consequently only to its bias current generator  $k_3 I_b$ .

## 3. SIMULATIONS

The circuit in Fig. 5 was simulated with SPICE and using the models of a 0.8- $\mu$ m CMOS process. Transistor dimensions and bias settings are summarized in Table I. A typical behavior of the module and phase of the input impedance is plotted in Fig. 7 curves  $a$ , where we set  $C=1pF$  and  $k=8$  ( $k_1=k_2=k_3=2$ ). It can be noticed that the impedance is predominantly capacitive within a limited frequency range. Note that this range is strongly reduced if the gate of  $M_3$  is connected to a constant voltage as shown by curves  $b$  in the same figure (and using the same other settings).

A quantification of the frequency range where the capacitance multiplication occurs and the related accuracy, can be made by considering the three parameters defined below. The first two are related to the bandwidth at  $-1^\circ$  with respect to  $-90^\circ$  and are respectively the lower,  $f_{RL}$ , and higher,  $f_{RH}$  limit frequencies. The second parameter is defined as

$$C_M = \left[ Z_{in}(f') / 2\pi f' \right]^{-1} \quad (3)$$

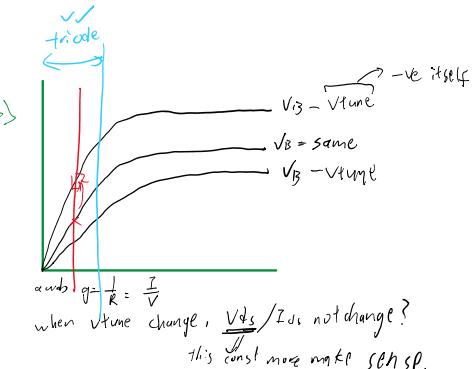
where  $f'$  is an arbitrary frequency internal to the  $-1^\circ$  bandwidth. Equation (3) gives a capacitance value which is nominally equal to  $kC$ . For instance, the curves  $a$  in Fig. 7 yield  $f_{RL}=4.40$  kHz,  $f_{RH}=132$  kHz and  $C_M=7.85$  pF, with a percentage error compared to the ideal capacitance value (8 pF) of -1.9%. As already noted, the circuit may

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→ add cascode current mirr. why?  
→ go both get 4 layers!

→ rox already connected to cap there and if  $f$  is small  
the pole will be at high freq.



when  $V_{tune}$  change,  $|Z_{in}|/I_{in}$  not change?  
this const make sch sch

be useful in two different contexts. The first concerns the realization of high capacitance values, otherwise impractical to be fabricated, and the second is to detect and amplify very small capacitances, like those provided by integrated sensors. To examine the circuit performances within these two frameworks and to understand their fundamental limitations we set different unit capacitors ranging from 50 fF to 10 pF and four different multiplication factors, all obtained using  $k_1=k_2=k_3$ . These results are summarized in Table II, and the case for  $C=10$  pF is also illustrated in Fig. 8. It is seen that there is an offset and a gain error. Offset is caused by the parasitic capacitance in parallel to  $Z_m$  (about 25fF) and its effect becomes negligible for large values of  $kC$ . The gain error is constant (about -2.5%) and is due to the transfer gain of the current mirrors. We see that increasing  $k$  reduces the  $-1^{\text{st}}$ -bandwidth. Moreover, increasing  $C$  by a factor of 10 produces approximately the same decrease in  $f_{T_1}$ . In conclusion, we can obtain an accurate magnification of unit capacitances as low as 100fF and the easy realization of equivalent capacitances in the range of several nanofarads. The tuning technique was finally applied. In brief, by varying  $V_{\text{TUNE}}$  from +0.3V to -0.4V,  $C_x$  modifies by about 270%.

Component	Value
M1, M3	10/0.8
M2, M4	4/0.8
M5abc, M6abc	20/1.2
M7a, M8a	$k_1=20/1.2$
M7b, M8b	$k_2=20/1.2$
M7c, M8c	$k_3=20/1.2$
$I_B$	2 $\mu\text{A}$
VDD-VSS	3 V
VG	1.5 V
VB	1.6 V

Table 1. Transistors dimensions and bias settings.

$C$	$k$	$f_{T_1}$ (kHz)	$f_{T_{\text{BW}}}$ (kHz)	$C_M$	$E\% (C_M)$
50fF	1	11.7	333	75.6fF	+51
	8	58.4	219	449fF	+12
	125	59.7	118	6.15pF	-1.6
	1000	44.5	67.0	47.3pF	-5.4
100fF	1	7.10	263	124fF	+24
	8	34.3	179	839fF	-4.9
	125	36.5	92.2	12.2pF	-2.1
	1000	28.6	51.3	96.1pF	-3.9
1pF	1	0.864	199	1.00pF	0.0
	8	4.40	132	7.85pF	-1.9
	125	5.56	59.1	122pF	-2.4
	1000	5.22	27.3	972pF	-2.8
10pF	1	0.088	120	10.2pF	+2.0
	8	0.459	92.1	78.0pF	-2.6
	125	0.609	46.4	1.22nF	-2.6
	1000	0.621	21.5	9.73nF	-2.7

Table 2. Circuit performance under different settings.

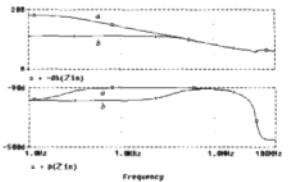


Fig. 7: Module and phase of the input impedance ( $Z_m$ ) of the proposed circuit in Fig.5 (curves a) and with the gate of M3 biased at constant voltage (curves b).  $C = 1\text{pF}$  and  $k = 8$  were set in both cases.

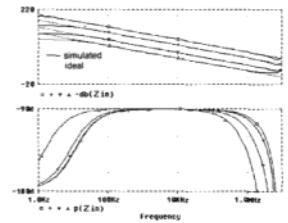


Fig. 8: Magnitude and phase of the input impedance ( $Z_m$ ) of the circuit in Fig.5 with  $C=10\text{pF}$  and  $k = 1, 8, 125, 1000$ .

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