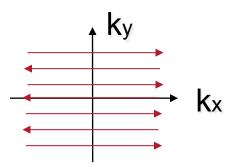
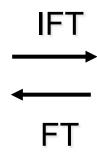
# Module 4: K-space

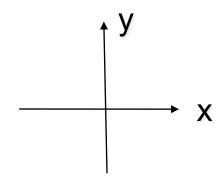
## **Image Formation**

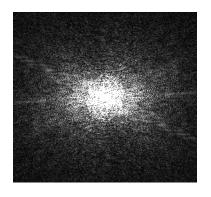
#### k-space

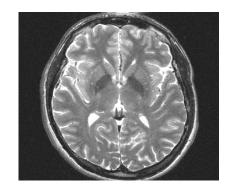






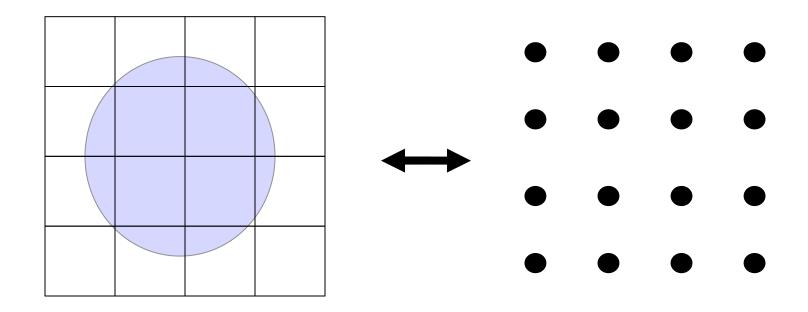






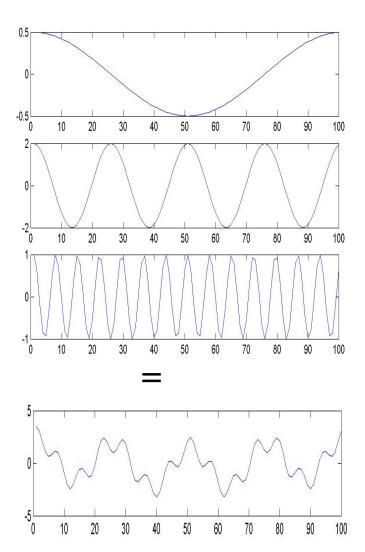
#### K-space

It is important to note that there is not a one-to-one relationship between image and k-space.



Each individual point in image space depends on all of the points contained in the k-space

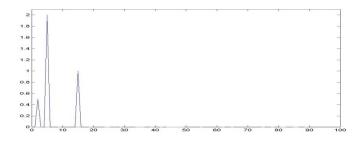
## Superposition of curves



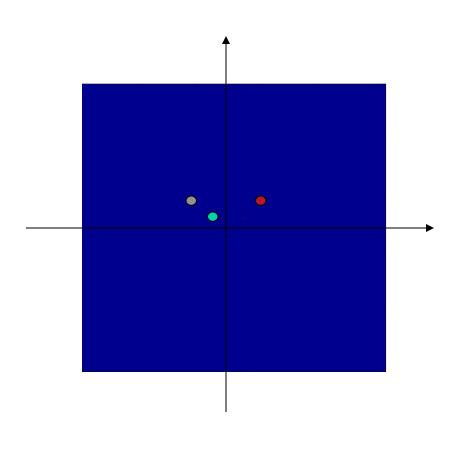
1 Dimension

Period: T

Frequency:  $\omega = T^{-1}$ 

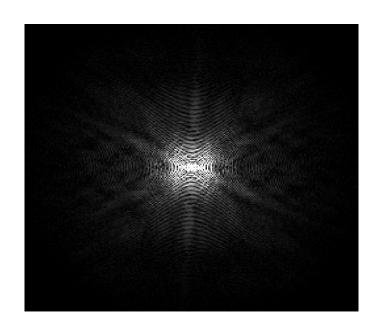


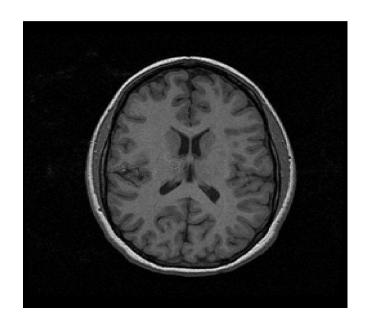
#### 2 Dimensions

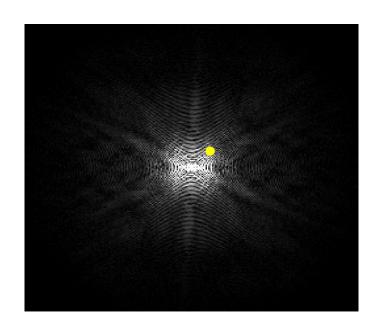


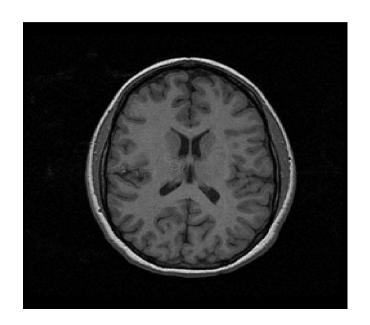
K-space

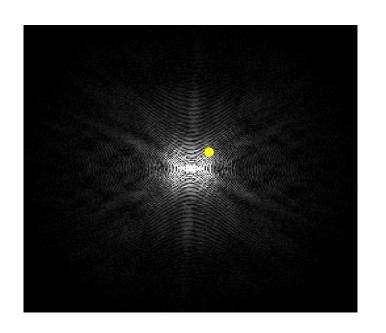


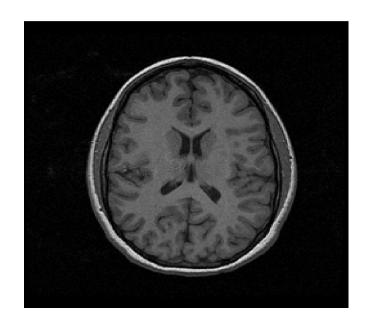


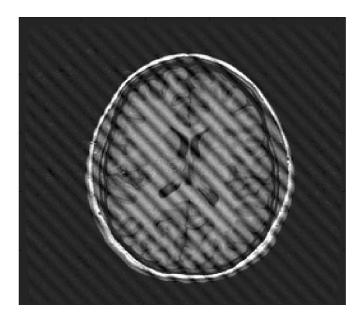


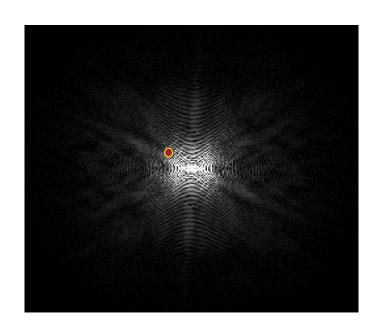


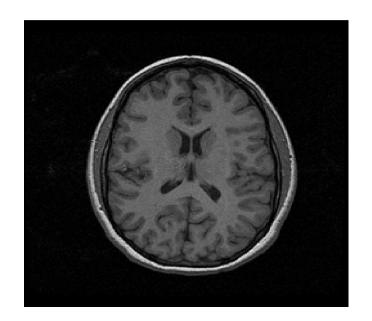


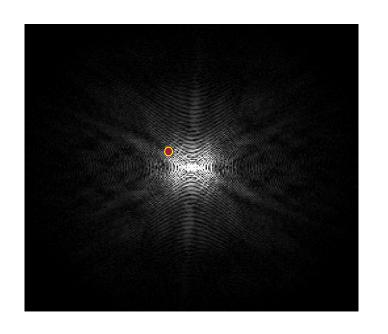


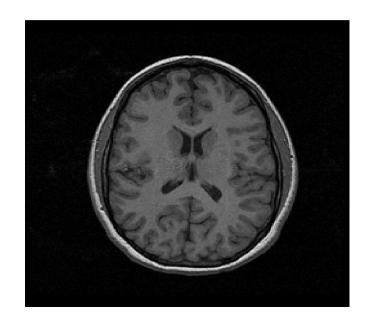


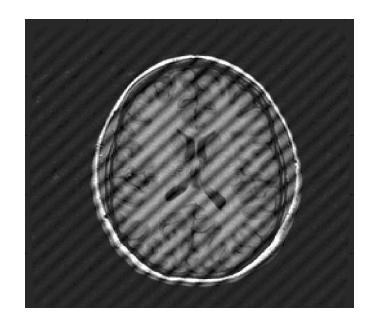


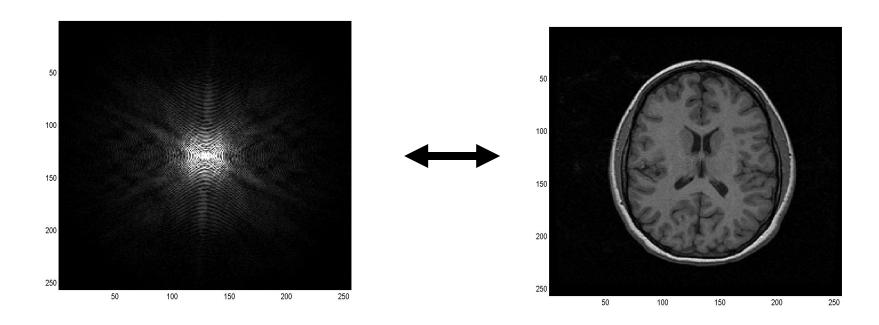


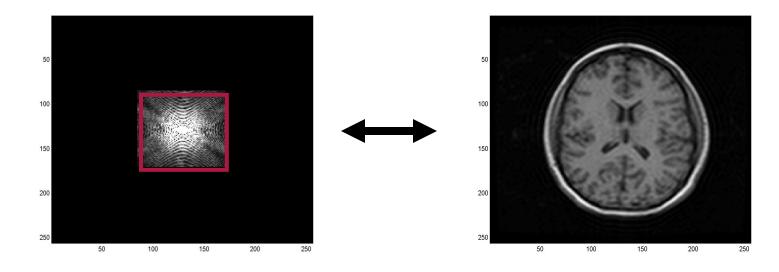


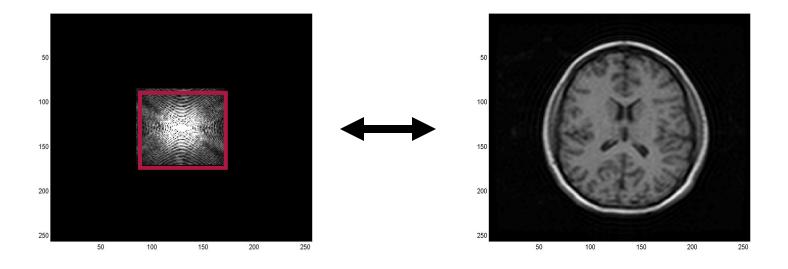


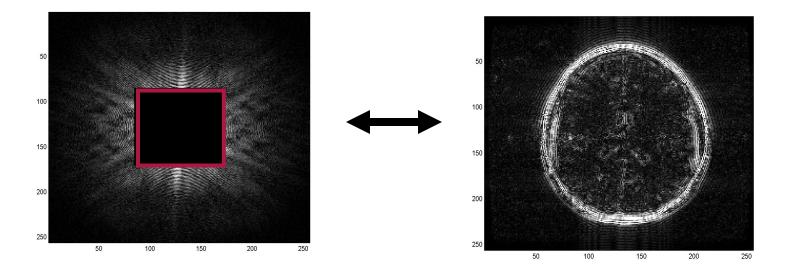










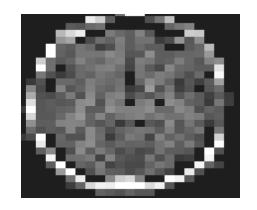


### Information content in k-space

 Low spatial frequencies represent parts of the object that change in a spatially slow manner (Contrast).

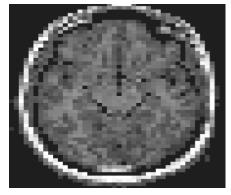
 High spatial frequencies represent small structures whose size is on the same order as the voxel size (Tissue boundaries).

#### **Spatial Resolution**



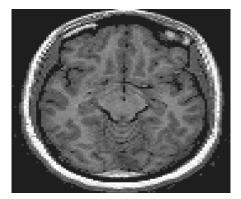
 $32 \times 32$  image

1024 points sampled in k-space



64 × 64 image

4096 points sampled in k-space



128 × 128 image

16,384 points sampled in k-space

#### **End of Module**

