# Module 11: GLM Estimation

#### **GLM**

A standard GLM can be written:

$$Y = X\beta + \varepsilon$$
  $\varepsilon \sim N(0, V)$ 

where

$$\begin{bmatrix} Y_1 \\ Y_2 \\ \vdots \\ Y_n \end{bmatrix} = \begin{bmatrix} 1 & X_{11} & \cdots & X_{1p} \\ 1 & X_{21} & \cdots & X_{2p} \\ \vdots & \vdots & & \vdots \\ 1 & X_{np} & \cdots & X_{np} \end{bmatrix} \times \begin{bmatrix} \beta_0 \\ \beta_1 \\ \vdots \\ \beta_p \end{bmatrix} + \begin{bmatrix} \varepsilon_1 \\ \varepsilon_2 \\ \vdots \\ \varepsilon_n \end{bmatrix}$$
 V is the covariance matrix whose format depends on the noise model.

Regression coefficients

## **Problem Formulation**

Assume the model:

$$\mathbf{Y} = \mathbf{X}\boldsymbol{\beta} + \boldsymbol{\varepsilon} \qquad \boldsymbol{\varepsilon} \sim N(\mathbf{0}, \mathbf{I}\boldsymbol{\sigma}^2)$$

- The matrices X and Y are assumed to be known, and the noise is considered to be uncorrelated.
- Our goal is to find the value of β that minimizes:

$$(\mathbf{y} - \mathbf{X}\boldsymbol{\beta})^T (\mathbf{y} - \mathbf{X}\boldsymbol{\beta})$$

### **OLS Solution**

#### Ordinary least squares solution

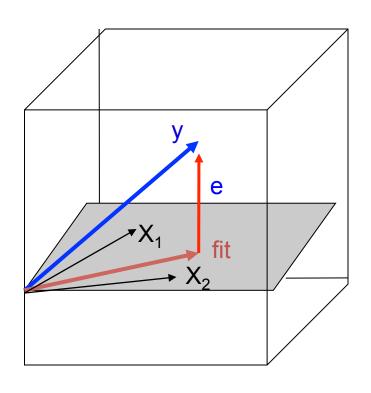
$$\hat{\boldsymbol{\beta}} = (\mathbf{X}^T \mathbf{X})^{-1} \mathbf{X}^T \mathbf{y}$$

#### Properties:

Maximum likelihood estimate

$$E(\hat{eta}) = eta$$

$$E(\hat{\beta}) = \beta$$
$$Var(\hat{\beta}) = \sigma^2 (\mathbf{X}^T \mathbf{X})^{-1}$$



Can we do better?

#### Gauss Markov Theorem

 The Gauss-Markov Theorem states that any other unbiased estimator of β will have a larger variance than the OLS solution.

- Assume  $\tilde{\beta}$  is an unbiased estimator of  $\beta$ .
- Then according to G-M Theorem,

$$Var(\tilde{\beta}) \ge Var(\hat{\beta})$$

•  $\hat{\beta}$  is the best linear unbiased estimator (BLUE) of  $\beta$ .

#### **Estimation**

If ε is i.i.d., then Ordinary Least Square (OLS) estimate is optimal

 $\mathbf{Y} = \mathbf{X}\boldsymbol{\beta} + \boldsymbol{\varepsilon} \qquad \qquad \hat{\boldsymbol{\beta}} = (\mathbf{X}'\mathbf{X})^{-1}\mathbf{X}'\mathbf{Y}$ 

• If  $Var(\varepsilon) = V\sigma^2 \neq I\sigma^2$ , then Generalized Least Squares (GLS) estimate is optimal

 $\mathbf{Y} = \mathbf{X}\boldsymbol{\beta} + \boldsymbol{\epsilon} \qquad \qquad \hat{\boldsymbol{\beta}} = (\mathbf{X}'\mathbf{V}^{-1}\mathbf{X})^{-1}\mathbf{X}'\mathbf{V}^{-1}\mathbf{Y}$ 

# **GLM Summary**

model

$$Y = X\beta + \varepsilon$$

estimate

$$\hat{\boldsymbol{\beta}} = (\mathbf{X}'\mathbf{V}^{-1}\mathbf{X})^{-1}\mathbf{X}'\mathbf{V}^{-1}\mathbf{Y}$$

fitted values

$$\hat{\mathbf{Y}} = \mathbf{X}\hat{\boldsymbol{\beta}}$$

residuals

$$\mathbf{r} = \mathbf{Y} - \hat{\mathbf{Y}}$$

$$= (\mathbf{I} - (\mathbf{X}'\mathbf{V}^{-1}\mathbf{X})^{-1}\mathbf{X}'\mathbf{V}^{-1})\mathbf{Y}$$

$$= \mathbf{R}\mathbf{Y}$$

# Estimating the Variance

• Even if we assume  $\varepsilon$  is i.i.d., we still need to estimate the residual variance,  $\sigma^2$ .

• Our estimate: 
$$\hat{\sigma}^2 = \frac{\mathbf{r}^T \mathbf{r}}{tr(\mathbf{RV})}$$

• For OLS: 
$$\hat{\sigma}^2 = \frac{\mathbf{r}^T \mathbf{r}}{N - p}$$

Estimating V ≠ I more difficult.

## **End of Module**

