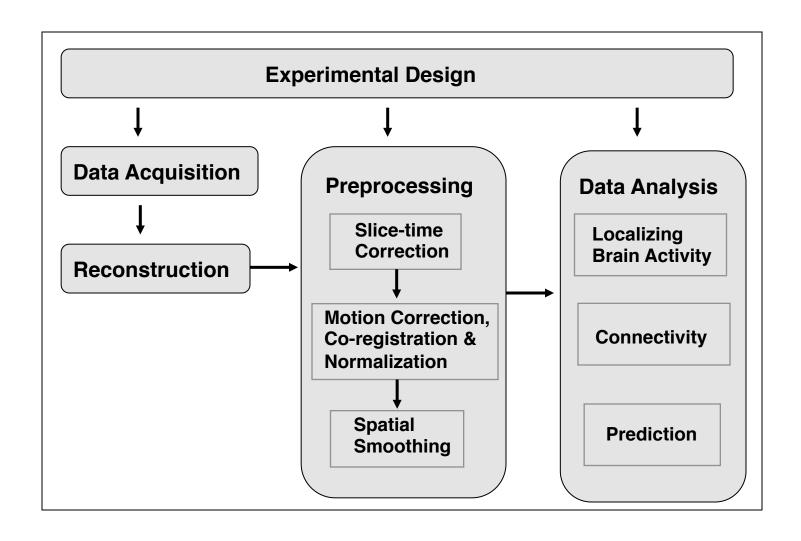
Module 8: Pre-processing I

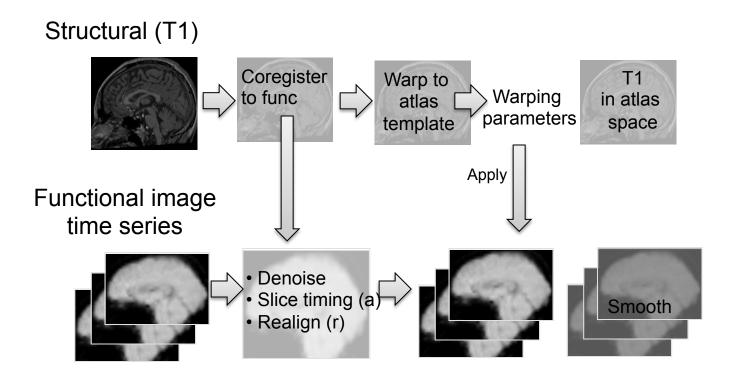
Data Processing Pipeline



Pre-processing

- Prior to analysis, fMRI data undergoes a series of preprocessing steps aimed at identifying and removing artifacts and validating model assumptions.
- The goals of preprocessing are
 - To minimize the influence of data acquisition and physiological artifacts;
 - To check statistical assumptions and transform the data to meet assumptions;
 - To standardize the locations of brain regions across subjects to achieve validity and sensitivity in group analysis.

Pre-processing Pipeline



Preprocessing is performed both on the fMRI data and structural scans collected prior to the experiment.

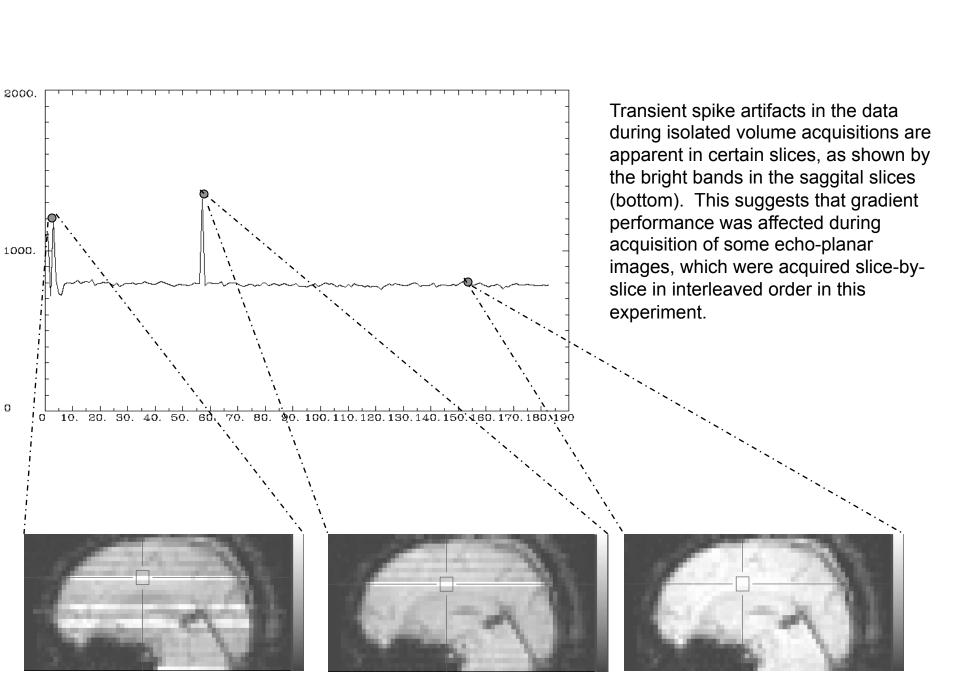
Pre-processing Steps

- Visualization and Artifact Removal
- Slice Time Correction
- Motion Correction
- Physiological Corrections
- Co-registration
- Normalization
- Spatial Filtering
- Temporal Filtering

Visualization & Artifact Removal

- The first part of the preprocessing pipeline is to use exploratory techniques to investigate the raw image data and detect possible problems and artifacts.
- fMRI data often contain transient spike artifacts and slow drift over time.

 An exploratory technique such as principal components analysis (PCA) can be used to look for spike-related artifacts.



Slice Time Correction

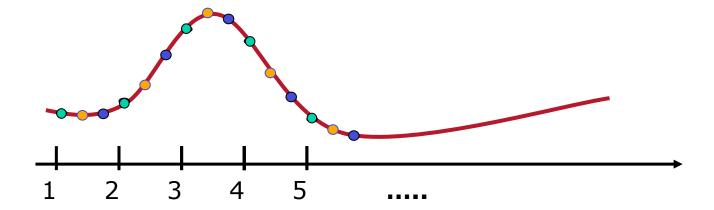
- We often sample multiple slices of the brain during each individual repetition time (TR) to construct a brain volume.
- Typically each slice is sampled at a slightly different time points (i.e., 2D imaging; not 3D).
- Slice time correction shifts each voxel's time series so that they all appear to have been sampled simultaneously.

Slice Time Correction

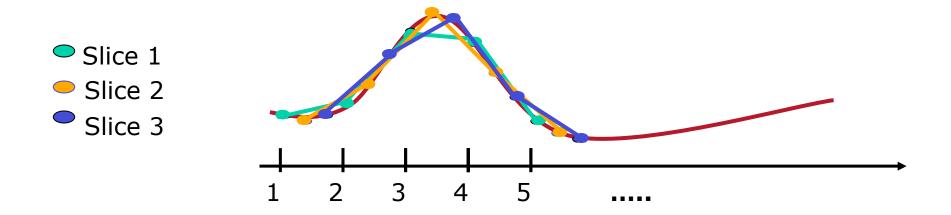


Slice 2

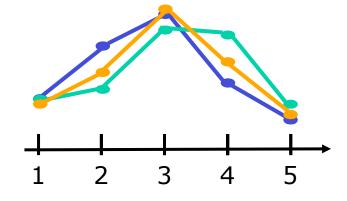
Slice 3



Slice Time Correction



Can be corrected using temporal interpolation.



Temporal Interpolation

- Use information from nearby time points to estimate the amplitude of the MR signal at the onset of the TR.
- Use a linear, spline or sinc function.

Phase Shift

 Slide the time course by applying a phase shift to the Fourier transform of the time course.

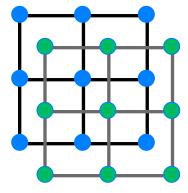
Head Motion

- Very small movements of the head during an experiment can be a major source of error if not treated correctly.
- When analyzing the time series associated with a voxel, we assume that it depicts the same region of the brain at every time point
 - Head motion may make this assumption incorrect.
- Can be corrected using a rigid body transformation.

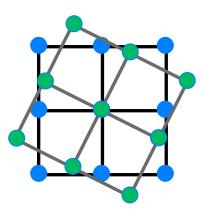
Motion Correction

- The goal is to find the best possible alignment between an input image and some target image.
- To align the two images, one of them needs to be transformed.
- A rigid body transformation is used.
- It involves 6 variable parameters, 3 sets of translations and 3 sets of rotations (6 DOF).

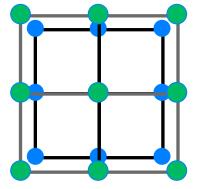
Translation



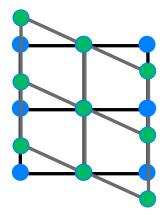
Rotation



Scaling



Shearing



Transformations

Linear transformations

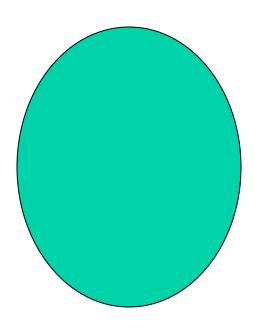
- Rigid body (6 DOF) translation and rotation
- Similarity (7 DOF) translation, rotation and a single global scaling
- Affine (12 DOF) translation, rotation, scaling and shearing.

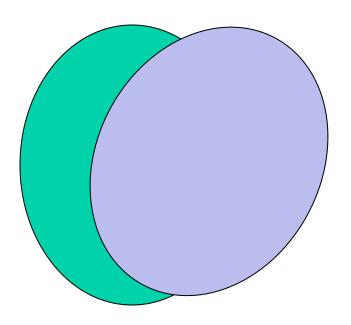
Warping

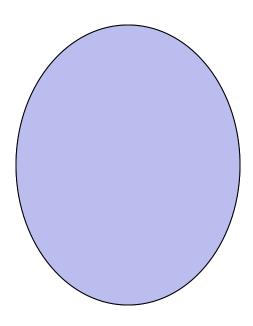
Transformations where the equations relating the coordinates of the images are non-linear.

Motion Correction

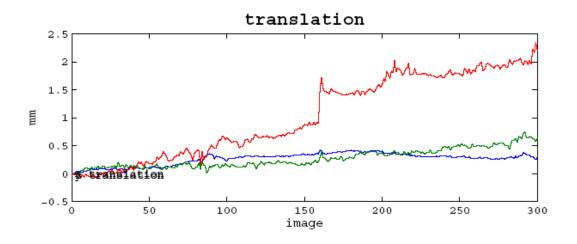
- The target image is usually defined to be the first (or mean) image in the fMRI time series.
- The goal is to find the set of parameters which minimizes some cost function that assesses similarity between the image and the target.
- Examples of cost functions include the sum of squared differences or mutual information.

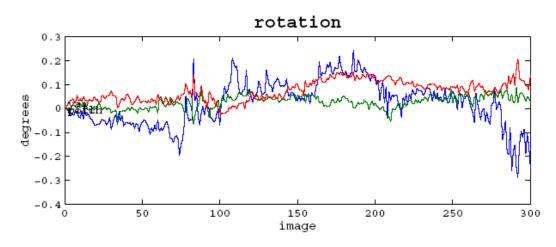






Illustration





Coregistration

- Next, a structural MRI collected in the beginning of the session is registered to the fMRI images in a process referred to as coregistration.
 - Allows one to visualize single-subject task activations overlaid on the individual's anatomical information.
 - Simplifies later transformation of the fMRI images to a standard coordinate system.



Coregistration

- There are certain key differences between coregistration and motion correction.
 - Functional and structural images do not have the same signal intensity in the same areas.
 - They cannot be subtracted.
 - Their shapes may differ.
- Use at least an affine transformation to perform coregistration and the mutual information cost function.

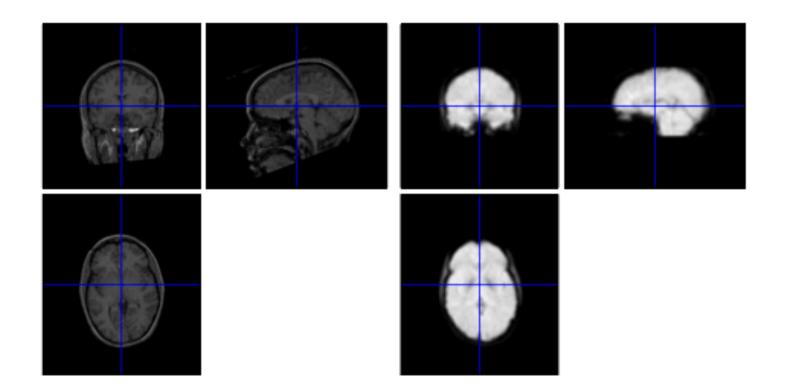
Coregistration

Normalised Mutual Information Coregistration

X1 = 3.492*X + 0.123*Y + 0.266*Z + 6.471

Y1 = -0.041*X +3.269*Y -1.606*Z +40.323

21 = -0.237*X + 1.244*Y + 4.195*Z + 2.370



End of Module

