Advanced Python for Neuroscientists Lecture 6: Neural network II

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Recap

Lecture 5

- Feedforward neural network
- Gradient descent

Outline

- Backpropagation
- Stochastic Gradient Descent
- Application

Cost function of a neural network

$$J(\Theta) = -\frac{1}{m} \sum_{i=1}^{m} \sum_{k=1}^{K} y_k^{(i)} \log(h_{\Theta}^k(x^{(i)})) + (1 - y_k^{(i)}) \log(1 - h_{\Theta}^k(x^{(i)}))$$
$$+ \frac{\lambda}{2m} \sum_{l=1}^{L-1} \sum_{i=1}^{s_l} \sum_{j=1}^{s_{l+1}} (\Theta_{j,i}^{(l)})^2$$

How do we minimize this cost function?

"Backpropagation" in neural network is for minimizing the cost function and finding the optimal set of Θ .

To use gradient descent, we need to compute the partial derivative $\frac{\partial}{\partial \Theta_i^{(l)}} J(\Theta)$.

Forward propagation:

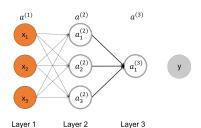
$$a^{(1)} = x$$

$$z^{(2)} = \Theta^{(1)}a^{(1)}$$

$$a^{(2)} = g(z^{(2)})$$

$$z^{(3)} = \Theta^{(2)}a^{(2)}$$

$$a^{(3)} = g(z^{(3)}) = h_{\Theta}(x)$$



Backpropagation: Layer 3 to Layer 2

$$J(\Theta) = -y \log(h_{\Theta}(x)) - (1-y) \log(1-h_{\Theta}(x))$$

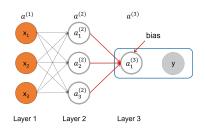
Chain rule

$$h_{\Theta}(x) = g(z^{(3)}) = a^{(3)}$$

$$z^{(3)} = \Theta^{(2)}a^{(2)}$$

$$\frac{\partial J}{\partial \Theta^{(2)}} = \frac{\partial J}{\partial a^{(3)}} \frac{\partial a^{(3)}}{\partial z^{(3)}} \frac{\partial z^{(3)}}{\partial \Theta^{(2)}}$$

$$= (a^{(3)} - y)a^{(2)T}$$



Backpropagation: Layer 2 to Layer 1

$$h_{\Theta}(x) = g(z^{(3)}) = a^{(3)}$$

$$z^{(3)} = \Theta^{(2)}a^{(2)}$$

$$a^{(2)} = g(z^{(2)})$$

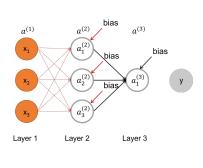
$$z^{(2)} = \Theta^{(1)}a^{(1)}$$

$$\frac{\partial J}{\partial \Theta^{(1)}} = \frac{\partial J}{\partial a^{(3)}} \frac{\partial a^{(3)}}{\partial z^{(3)}} \frac{\partial z^{(3)}}{\partial a^{(2)}}$$

$$\frac{\partial a^{(2)}}{\partial z^{(2)}} \frac{\partial z^{(2)}}{\partial \Theta^{(1)}}$$

$$= \Theta^{(2)T}(a^{(3)} - y)$$

$$(a^{(2)} - a^{(2)2})a^{(1)T}$$



Learning with large datasets

$$J(\Theta) = -\frac{1}{m} \sum_{i=1}^{m} y^{(i)} \log(h_{\theta}(x^{(i)})) + (1 - y^{(i)}) \log(1 - h_{\theta}(x^{(i)}))$$

Gradient descent:

Repeat{

$$\theta_j := \theta_j - \alpha \frac{1}{m} \sum_{i=1}^m (h_{\theta}(x^{(i)}) - y^{(i)}) x_j^{(i)}$$
 for every $j = 0, ..., n$

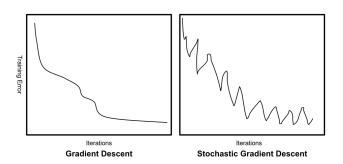
We compute the gradient with all samples and then update θ . This can be very time consuming when m is large.

Instead, we can update θ with gradient contributed by each sample:

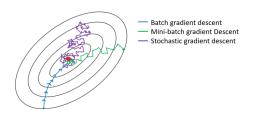
1. Randomly shuffle the training set.

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2. Repeat { for i=1:m { \theta_j := \theta_j - \alpha(h_\theta(x^{(i)}) - y^{(i)})x_j^{(i)}  for every j = 0, ..., n }
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The cost function does not monotonically decrease with SGD.



More often, we use a batch of training samples (between 1 and m) to update θ each time. This is called mini-batch gradient descent.



The batch size is a hyper-parameter for us to determine. The complete pass of the entire training set is called an epoch, whose number is also a hyper-parameter.

Data collection

Explore the open datasets: MNIST, CIFAR-10, SVHN, IMDB Reviews ...

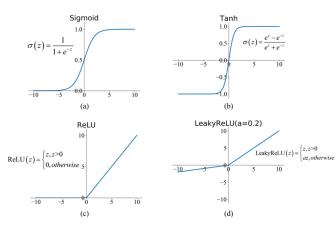




Data split



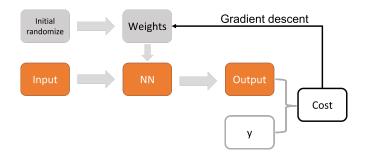
Activation functions



Considerations before training

Goal: e.g. classify neuron vs. non-neuron			
Data	Images	Number?	e.g. 10,000
Input	Image	Size?	e.g. (64,64,3)
Output	Categorical	No. categories?	e.g. y=0 or 1
Architecture	Neural net	Shallow/Deep	e.g. 3 layers
Activation function	Sigmoid, tanh, ReLU,		e.g. ReLU, leakyReLU
Cost function	Cross entropy, MSE, (depending on the goal)		

Train the network



Estimate accuracy in the test set.

Application

Homework

- Make sure you understand all the exercises above
- Run through the codes here that should replicate all the figures https://github.com/yisiszhang/AdvancedPython/ blob/main/colab/Lecture6.ipynb
- Try different neural network layouts
- Try different learning rates