# Advanced Python for Neuroscientists Lecture 7: Convolutional Neural network

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# Recap

#### Lecture 5

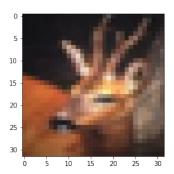
- Feedforward neural network
- Gradient descent

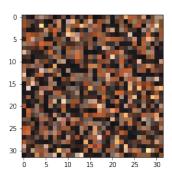
#### Lecture 6

- Backpropagation
- Stochastic Gradient Descent
- Application

## Outline

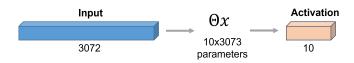
- Motivation & concept
- Overview
- Architectures





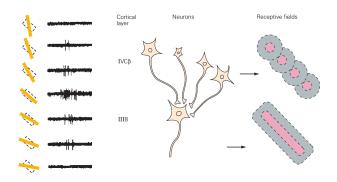
We may want to preserve the spatial structure.

Fully connected layer A CIFAR10 image size  $32x32x3 \rightarrow 3072 \times 1$ 



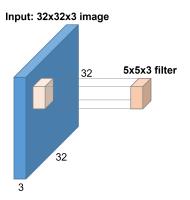
This does not maintain the spatial information.

### Receptive field



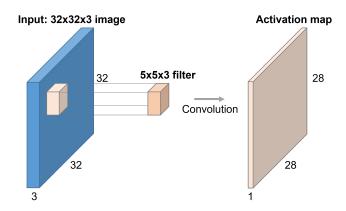
Cite Kandel et al., Principles of neural science. Ed6

Convolutional neural network (ConvNet)



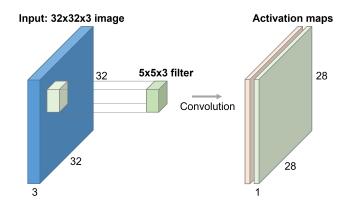
Slide (convolve) the filter over all spatial locations. At each location perform a dot product.

Convolutional neural network (ConvNet)



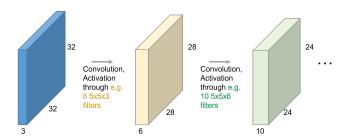
Each filter produces a 2D activation map.

Convolutional neural network (ConvNet)



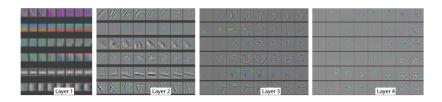
Each filter produces a 2D activation map.

## Convolutional neural network (ConvNet)



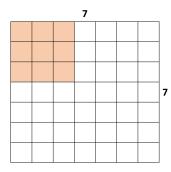
The same logic applied to each layer.

 $\mathsf{Low\text{-}level} \to \mathsf{Mid\text{-}level} \to \mathsf{High\text{-}level} \text{ features} \to \mathsf{linearly} \text{ separable}$   $\mathsf{classifier}$ 



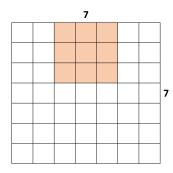
[Zeiler & Fergus 2013]

How does the convolution work?



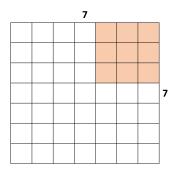
Apply a 3x3 filter to a 7x7 grid with stride 2

How does the convolution work?



Apply a 3x3 filter to a 7x7 grid with stride 2

How does the convolution work?



Apply a 3x3 filter to a 7x7 grid with stride 2

How does the convolution work?

N							
N							

Output size 
$$= (N-F)/stride + 1$$

e.g. 
$$(7-3)/2 + 1 = 3$$

### Common to zero-pad the border

				N+2					
0	0	0	0	0	0	0	0	0	
0			F					0	
0								0	
0	F							0	
0								0	N+2
0								0	
0								0	
0								0	
0	0	0	0	0	0	0	0	0	

If N = 7, F = 3, stride = 3 what is the output size?

$$I[x, y] * F[x, y] = \sum_{m} \sum_{n} I[m, n] F[x - m, y - n]$$

#### Input

					•			
0	0	0	0	0	0	0	0	0
0	1	2	3	4	12	9	8	0
0	5	2	3	4	12	9	8	0
0	5	2	1	4	10	9	8	0
0	7	2	1	4	12	7	8	0
0	7	2	1	4	14	9	8	0
0	5	2	3	4	12	7	8	0
0	5	2	1	1	12	9	8	0
0	0	0	0	0	0	0	0	0

Filte
3x3

1 2 1 2 4 2 1 2 1

# Stride=3 Output

=

 20
 69
 75

 60
 84
 96

 36
 53
 73

How many parameters in this layer (or what are being learned)?

Image: 32x32x3, Filter: 10 of 5x5x3, stride 1, pad 2

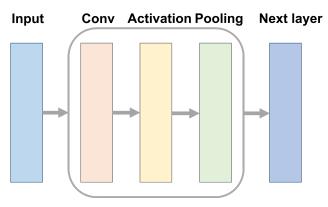
How many parameters in this layer (or what are being learned)?

Image: 32x32x3, Filter: 10 of 5x5x3, stride 1, pad 2 each filter has

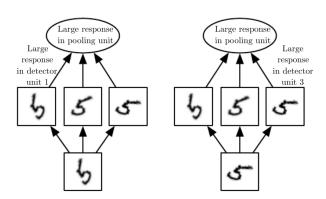
$$5x5x3 + 1 = 76$$
 parameters (+1 for bias) total # parameters =  $76 \times 10 =$ **760**

Consider convolution as  $\Theta x$ 

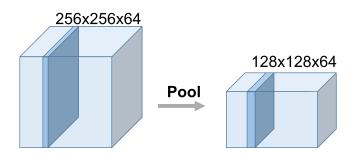
A complex layer consists of Convolution, Activation (e.g. ReLU), Pooling (e.g. Max pooling)



Intuition of pooling: Invariance to local translation



Pooling over individual activation map



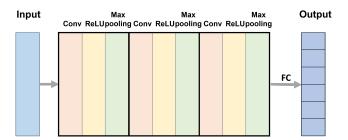
# Max pooling

1	3	3	4
2	5	8	2
3	0	1	0
2	2	1	2

Max-pooling	
with 2x2 filters	
and stride 2	

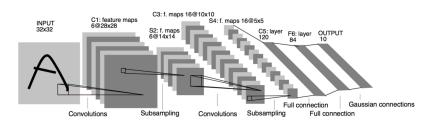
5	8
3	2

## A complete ConvNet for classification



# 7.3 Architectures

#### LeNet-5

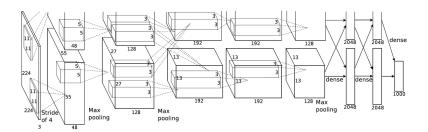


[LeCun et al., 1998]

Conv filters 5x5, stride 1, 2x2 pooling at stride 2

## 7.3 Architectures

#### AlexNet

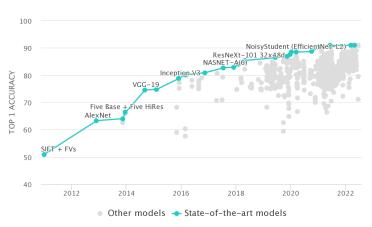


[Krizhevsky et al., 2012]

CONV1→MAX POOL1→ CONV2→MAX POOL2→ CONV3→CONV4→CONV5→ MAX POOL3→FC6→FC7→FC8 Architectures

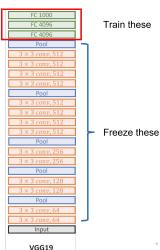
## 7.3 Architectures

ImageNet Large Scale Visual Recognition Challenge (ILSVRC) winners



#### Architectures

# 7.3 Architectures Transfer Learning



## Homework

- Make sure you understand all the exercises above
- Run through the codes here that should replicate all the figures https://github.com/yisiszhang/AdvancedPython/ blob/main/colab/Lecture7.ipynb
- Make sure to understand the inputs to Conv and FC layers
- Try to improve the performance of the ConvNet model