Computer Vision Homework 9 Report

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1 Introduction

In this homework assignment, we're going to do **General Edge Detection**. I use *Python* as my programming language and *Pillow* as my image library. It is a fork of *PIL*, which is the original image library of *Python*. And I use *Pillow* for reading input image, and transfering image data into a *List* of *Python*.



Figure 1: lena.bmp as Benchmark Image

2 General Edge Detection

To do edge detection, I apply each kernel and calculate the gradient magnitude g for each operator. When the kernel reach the boundary of the image, I use a function to flip the inward pixels to the outward.

```
1 def flip(p, boundary):
2    if p < 0:
3        return -p -1
4    elif p >= boundary:
5        return 2 * boundary - p - 1
6    else:
7    return p
```

2.1 Robert's Operator

Gradient magnitude of this operator is $g = \sqrt{r_1^2 + r_2^2}$.

```
def roberts operator (data, hei, wid):
     r1 = [ \]
3
       (0, 0, -1), (1, 0, 0), \
       (0, 1, 0), (1, 1, 1)
4
     r2 = [ \]
6
       (0, 0, 0), (1, 0, -1), \
7
       (0, 1, 1), (1, 1, 0)
8
     ret = []
9
     for y in range (hei):
10
       for x in range (wid):
11
         r1val = 0
12
         for rx, ry, val in r1:
13
           px = flip(x + rx, wid)
           py = flip(y + ry, hei)
14
           r1val += data[py * wid + px] * val
15
         r2val = 0
16
17
         for rx, ry, val in r2:
18
           px = flip(x + rx, wid)
           py = flip(y + ry, hei)

r2val += data[py * wid + px] * val
19
20
         val = sqrt(r1val^{***} 2 + r2val^{***} 2)
21
         ret.append(0 if val >= 12 else 255)
22
     return ret
```



Figure 2: Robert's operator with threshold = 12

2.2 Prewitt's Edge Detector

```
\begin{array}{l} p1 = [ \\ 2 \\ (-1,-1,-1), ( & 0,-1,-1), ( & 1,-1,-1), \\ 3 \\ (-1, & 0, & 0), ( & 0, & 0, & 0), ( & 1, & 0, & 0), \\ 4 \\ (-1, & 1, & 1), ( & 0, & 1, & 1), ( & 1, & 1, & 1) ] \\ 5 \\ p2 = [ \\ 6 \\ (-1,-1,-1), ( & 0,-1, & 0), ( & 1,-1, & 1), \\ 7 \\ (-1, & 0,-1), ( & 0, & 0, & 0), ( & 1, & 0, & 1), \\ 8 \\ (-1, & 1,-1), ( & 0, & 1, & 0), ( & 1, & 1, & 1) ] \end{array}
```



Figure 3: Prewitt's edge detector with threshold = 24

2.3 Sobel's Edge Detector

The method to calculate gradient magnitude of this operator is the same as previous one, and the kernel of this operator is,

```
\begin{array}{l} \mathbf{1} \\ \mathbf{1} \\ \mathbf{2} \\ (-1,-1,-1) \,, ( \ 0,-1,-2) \,, ( \ 1,-1,-1) \,, \backslash \\ (-1,\ 0,\ 0) \,, ( \ 0,\ 0,\ 0) \,, ( \ 1,\ 0,\ 0) \,, \backslash \\ (-1,\ 1,\ 1) \,, ( \ 0,\ 1,\ 2) \,, ( \ 1,\ 1,\ 1) \,] \\ \mathbf{5} \\ \mathbf{5} \\ \mathbf{2} \\ = [ \backslash \\ (-1,-1,-1) \,, ( \ 0,-1,\ 0) \,, ( \ 1,-1,\ 1) \,, \backslash \\ (-1,\ 0,-2) \,, ( \ 0,\ 0,\ 0) \,, ( \ 1,\ 0,\ 2) \,, \backslash \\ (-1,\ 1,-1) \,, ( \ 0,\ 1,\ 0) \,, ( \ 1,\ 1,\ 1) \,] \end{array}
```



Figure 4: Sobel's edge detector with threshold = 38

2.4 Frei and Chen's Gradient Operator

```
 \begin{array}{l} f1 = [ \\ (-1,-1,-1), ( \ 0,-1,-\operatorname{sqrt}(2)), ( \ 1,-1,-1), \\ (-1,\ 0,\ 0), ( \ 0,\ 0,\ \ 0), ( \ 1,\ 0,\ 0), \\ (-1,\ 1,\ 1), ( \ 0,\ 1,\ \operatorname{sqrt}(2)), ( \ 1,\ 1,\ 1) ] \\ f2 = [ \\ (-1,-1,\ \ -1), ( \ 0,-1,\ 0), ( \ 1,-1,\ \ 1), \\ (-1,\ 0,-\operatorname{sqrt}(2)), ( \ 0,\ 0,\ 0), ( \ 1,\ 0,\ \operatorname{sqrt}(2)), \\ 8 \\ \end{array}
```



Figure 5: Frei and Chen's gradient operator with threshold = 30

2.5 Kirsch's Compass Operator

Gradient magnitude of this operator is $g = \max_{n,n=0,\dots,7} k_n$.

```
def kirsch operator (data, hei, wid):
 2
     k = [
 3
        (-1,-1,-3), (0,-1,-3), (1,-1,5),
 5
       (-1, 0, -3), (0, 0, 0), (1, 0, 5), 
 6
        7
8
       (-1,-1,-3), (0,-1,5), (1,-1,5),
       (-1, 0, -3), (0, 0, 0), (1, 0, 5), (
9
       (-1, 1, -3), (0, 1, -3), (1, 1, -3), (
10
11
       (-1,-1, 5), (0,-1, 5), (1,-1, 5), 
12
13
       (-1, 0, -3), (0, 0, 0), (1, 0, -3), 
14
        (-1, 1, -3), (0, 1, -3), (1, 1, -3), \langle 1, 1, -3 \rangle
15
       (-1,-1, 5), (0,-1, 5), (1,-1,-3), 
16
       (-1, 0, 5), (0, 0, 0), (1, 0, -3), 
17
        (-1, 1, -3), (0, 1, -3), (1, 1, -3)], \setminus
18
19
       \left(\,-1,-1\,,\  \, 5\,\right)\,,\left(\  \  \, 0\,,-1\,,-3\,\right)\,,\left(\  \  \, 1\,,-1\,,-3\,\right)\,,\left\backslash
20
21
        (-1, 0, 5), (0, 0, 0), (1, 0, -3), 
22
        (-1, 1, 5), (0, 1, -3), (1, 1, -3), \langle
23
       (-1,-1,-3), (0,-1,-3), (1,-1,-3),
24
       (-1, 0, 5), (0, 0, 0), (1, 0, -3), 
25
        (-1, 1, 5), (0, 1, 5), (1, 1, -3), (
26
27
       (-1,-1,-3), (0,-1,-3), (1,-1,-3),
28
29
       (-1, 0, -3), (0, 0, 0), (1, 0, -3), 
30
       (-1, 1, 5), (0, 1, 5), (1, 1, 5), \langle
31
32
        (-1,-1,-3), (0,-1,-3), (1,-1,-3),
       (-1, 0, -3), (0, 0, 0), (1, 0, 5), 
33
```

```
34
       (-1, 1, -3), (0, 1, 5), (1, 1, 5)]
35
36
     ret = []
37
     for y in range(hei):
38
       for x in range (wid):
39
         maxval = -float('Inf')
40
         for kernel in k:
           tmpval = 0
41
42
           for rx, ry, val in kernel:
             px = flip(x + rx, wid)
43
             py = flip(y + ry, hei)
44
45
             tmpval += data[py * wid + px] * val
           maxval = tmpval if tmpval > maxval else maxval
46
47
         ret.append(0 if maxval \geq 135 else 255)
48
     return ret
```



Figure 6: Kirsch's compass operator with threshold = 135

2.6 Robinson's Compass Operator

```
k = [
 2
 3
     (-1,-1,-1), (0,-1,0), (1,-1,1),
 4
     (-1, 0, -2), (0, 0, 0), (1, 0, 2), 
 5
     (-1, 1, -1), (0, 1, 0), (1, 1, 1)], \setminus
 6
 7
     (-1,-1, 0), (0,-1, 1), (1,-1, 2), 
     (-1, 0, -1), (0, 0, 0), (1, 0, 1), (-1, 1, -2), (0, 1, -1), (1, 1, 0)],
8
9
10
     (-1,-1, 1), (0,-1, 2), (1,-1, 1), 
11
12
     (-1, 0, 0), (0, 0, 0), (1, 0, 0), 
     (-1, 1, -1), (0, 1, -2), (1, 1, -1), \langle
13
     (-1,-1, 2), (0,-1, 1), (1,-1, 0), 
15
```

```
16
     (-1, 0, 1), (0, 0, 0), (1, 0, -1), 
17
     (-1, 1, 0), (0, 1, -1), (1, 1, -2), \langle
18
19
     (-1,-1, 1), (0,-1, 0), (1,-1,-1), 
20
     (-1, 0, 2), (0, 0, 0), (1, 0, -2), 
21
     (-1, 1, 1), (0, 1, 0), (1, 1, -1)], \setminus
22
23
     (-1,-1, 0), (0,-1,-1), (1,-1,-2), 
     (-1, 0, 1), (0, 0, 0), (1, 0, -1), (
24
     (-1, 1, 2), (0, 1, 1), (1, 1, 0), (
25
26
27
     (-1,-1,-1), (0,-1,-2), (1,-1,-1),
28
     (-1, 0, 0), (0, 0, 0), (1, 0, 0), 
29
     (-1, 1, 1), (0, 1, 2), (1, 1, 1), 
30
31
     (-1,-1,-2), (0,-1,-1), (1,-1,0),
     (-1, 0, -1), (0, 0, 0), (1, 0, 1), (
32
33
     (-1, 1, 0), (0, 1, 1), (1, 1, 2)]
```



Figure 7: Robinson's compass operator with threshold = 43

2.7 Nevatia-Babu 5×5 Operator

```
k = [
1
2
3
    (-2,-2, 100), (-1,-2, 100), (0,-2, 100), (1,-2, 100), (2,-2, 100), (
    (-2,-1, 100), (-1,-1, 100), (0,-1, 100), (1,-1, 100), (2,-1, 100),
    \begin{array}{l} (-2,\ 0,\ 0)\ , (-1,\ 0,\ 0)\ , (\ 0,\ 0,\ 0)\ , (\ 1,\ 0,\ 0)\ , (\ 2,\ 0,\ 0)\ , \\ (-2,\ 1,-100)\ , (-1,\ 1,-100)\ , (\ 0,\ 1,-100)\ , (\ 1,\ 1,-100)\ , (\ 2,\ 1,-100)\ , \end{array}
5
6
    7
8
9
    (-2,-2, 100), (-1,-2, 100), (0,-2, 100), (1,-2, 100), (2,-2, 100), (
    (-2,-1, 100), (-1,-1, 100), (0,-1, 100), (1,-1, 78), (2,-1, -32),
    (-2, 0, 100), (-1, 0, 92), (0, 0, 0), (1, 0, -92), (2, 0, -100),
```

```
(-2, 1, 32), (-1, 1, -78), (0, 1, -100), (1, 1, -100), (2, 1, -100),
12
13
                           (-2, 2, -100), (-1, 2, -100), (0, 2, -100), (1, 2, -100), (2, 2, -100)],
14
                           (-2,-2,\ 100),(-1,-2,\ 100),(\ 0,-2,\ 100),(\ 1,-2,\ 32),(\ 2,-2,-100),
15
16
                           (-2,-1, 100), (-1,-1, 100), (0,-1, 92), (1,-1, -78), (2,-1,-100), 
17
                           (-2, 0, 100), (-1, 0, 100), (0, 0, 0), (1, 0, -100), (2, 0, -100), (
18
                           (-2, 1, 100), (-1, 1, 78), (0, 1, -92), (1, 1, -100), (2, 1, -100), (
                           (-2, 2, 100), (-1, 2, -32), (0, 2, -100), (1, 2, -100), (2, 2, -100)], 
19
20
21
                           (-2, -2, -100), (-1, -2, -100), (0, -2,
                                                                                                                                                                                                                               0)\ , (\quad 1, -2\,, \quad 100)\ , (\quad 2\,, -2\,, \quad 100)\ , \backslash
                                                                                                                                                                                                                               0) , (1,-1, 100) , (2,-1, 100) ,
22
                           (-2,-1,-100),(-1,-1,-100),(0,-1,
23
                           (-2, 0, -100), (-1, 0, -100), (0, 0, 
                                                                                                                                                                                                                               0), (1, 0, 100), (2, 0, 100),
24
                           (-2, 1, -100), (-1, 1, -100), (0, 1, 1)
                                                                                                                                                                                                                               0), (1, 1, 100), (2, 1, 100),
25
                                                                                                                                                                                                                               0), (1, 2, 100), (2, 2, 100), \langle
                           (-2, 2, -100), (-1, 2, -100), (0, 2, 
26
                           \left(-2,-2,-100\right),\left(-1,-2,-32\right),\left(-0,-2,-100\right),\left(-1,-2,-100\right),\left(-2,-2,-100\right),\left(-2,-2,-100\right)
27
                          (-2,-1,-100),(-1,-1,-78),(-1,-1,-92),(-1,-1,-100),(-2,-1,-100),(-1,-1,-100),(-1,-1,-100),(-1,-1,-100),(-1,-1,-100),(-1,-1,-100),(-1,-1,-100),(-1,-1,-100),(-1,-1,-100),(-1,-1,-100),(-1,-1,-100),(-1,-1,-100),(-1,-1,-100),(-1,-1,-100),(-1,-1,-100),(-1,-1,-100),(-1,-1,-100),(-1,-1,-100),(-1,-1,-100),(-1,-1,-100),(-1,-1,-100),(-1,-1,-100),(-1,-1,-100),(-1,-1,-100),(-1,-1,-100),(-1,-1,-100),(-1,-1,-100),(-1,-1,-100),(-1,-1,-100),(-1,-1,-100),(-1,-100),(-1,-100),(-1,-100),(-1,-100),(-1,-100),(-1,-100),(-1,-100),(-1,-100),(-1,-100),(-1,-100),(-1,-100),(-1,-100),(-1,-100),(-1,-100),(-1,-100),(-1,-100),(-1,-100),(-1,-100),(-1,-100),(-1,-100),(-1,-100),(-1,-100),(-1,-100),(-1,-100),(-1,-100),(-1,-100),(-1,-100),(-1,-100),(-1,-100),(-1,-100),(-1,-100),(-1,-100),(-1,-100),(-1,-100),(-1,-100),(-1,-100),(-1,-100),(-1,-100),(-1,-100),(-1,-100),(-1,-100),(-1,-100),(-1,-100),(-1,-100),(-1,-100),(-1,-100),(-1,-100),(-1,-100),(-1,-100),(-1,-100),(-1,-100),(-1,-100),(-1,-100),(-1,-100),(-1,-100),(-1,-100),(-1,-100),(-1,-100),(-1,-100),(-1,-100),(-1,-100),(-1,-100),(-1,-100),(-1,-100),(-1,-100),(-1,-100),(-1,-100),(-1,-100),(-1,-100),(-1,-100),(-1,-100),(-1,-100),(-1,-100),(-1,-100),(-1,-100),(-1,-100),(-1,-100),(-1,-100),(-1,-100),(-1,-100),(-1,-100),(-1,-100),(-1,-100),(-1,-100),(-1,-100),(-1,-100),(-1,-100),(-1,-100),(-1,-100),(-1,-100),(-1,-100),(-1,-100),(-1,-100),(-1,-100),(-1,-100),(-1,-100),(-1,-100),(-1,-100),(-1,-100),(-1,-100),(-1,-100),(-1,-100),(-1,-100),(-1,-100),(-1,-100),(-1,-100),(-1,-100),(-1,-100),(-1,-100),(-1,-100),(-1,-100),(-1,-100),(-1,-100),(-1,-100),(-1,-100),(-1,-100),(-1,-100),(-1,-100),(-1,-100),(-1,-100),(-1,-100),(-1,-100),(-1,-100),(-1,-100),(-1,-100),(-1,-100),(-1,-100),(-1,-100),(-1,-100),(-1,-100),(-1,-100),(-1,-100),(-1,-100),(-1,-100),(-1,-100),(-1,-100),(-1,-100),(-1,-100),(-1,-100),(-1,-100),(-1,-100),(-1,-100),(-1,-100),(-1,-100),(-1,-100),(-1,-100),(-1,-100),(-1,-100),(-1,-100),(-1,-100),(-1,-100),(-1,-100),(-1,-100),(-1,-100),(-1,-100),(-1,-100),(-1,-100),(-1,-100),(-1,-100),(-100),(-100),
28
                          (-2, 0, -100), (-1, 0, -100), (0, 0, 0), (1, 0, 100), (2, 0, 100), (2, 0, 100), (3, 0, 100), (3, 0, 100), (3, 0, 100), (3, 0, 100), (3, 0, 100), (3, 0, 100), (3, 0, 100), (3, 0, 100), (3, 0, 100), (3, 0, 100), (3, 0, 100), (3, 0, 100), (3, 0, 100), (3, 0, 100), (3, 0, 100), (3, 0, 100), (3, 0, 100), (3, 0, 100), (3, 0, 100), (3, 0, 100), (3, 0, 100), (3, 0, 100), (3, 0, 100), (3, 0, 100), (3, 0, 100), (3, 0, 100), (3, 0, 100), (3, 0, 100), (3, 0, 100), (3, 0, 100), (3, 0, 100), (3, 0, 100), (3, 0, 100), (3, 0, 100), (3, 0, 100), (3, 0, 100), (3, 0, 100), (3, 0, 100), (3, 0, 100), (3, 0, 100), (3, 0, 100), (3, 0, 100), (3, 0, 100), (3, 0, 100), (3, 0, 100), (3, 0, 100), (3, 0, 100), (3, 0, 100), (3, 0, 100), (3, 0, 100), (3, 0, 100), (3, 0, 100), (3, 0, 100), (3, 0, 100), (3, 0, 100), (3, 0, 100), (3, 0, 100), (3, 0, 100), (3, 0, 100), (3, 0, 100), (3, 0, 100), (3, 0, 100), (3, 0, 100), (3, 0, 100), (3, 0, 100), (3, 0, 100), (3, 0, 100), (3, 0, 100), (3, 0, 100), (3, 0, 100), (3, 0, 100), (3, 0, 100), (3, 0, 100), (3, 0, 100), (3, 0, 100), (3, 0, 100), (3, 0, 100), (3, 0, 100), (3, 0, 100), (3, 0, 100), (3, 0, 100), (3, 0, 100), (3, 0, 100), (3, 0, 100), (3, 0, 100), (3, 0, 100), (3, 0, 100), (3, 0, 100), (3, 0, 100), (3, 0, 100), (3, 0, 100), (3, 0, 100), (3, 0, 100), (3, 0, 100), (3, 0, 100), (3, 0, 100), (3, 0, 100), (3, 0, 100), (3, 0, 100), (3, 0, 100), (3, 0, 100), (3, 0, 100), (3, 0, 100), (3, 0, 100), (3, 0, 100), (3, 0, 100), (3, 0, 100), (3, 0, 100), (3, 0, 100), (3, 0, 100), (3, 0, 100), (3, 0, 100), (3, 0, 100), (3, 0, 100), (3, 0, 100), (3, 0, 100), (3, 0, 100), (3, 0, 100), (3, 0, 100), (3, 0, 100), (3, 0, 100), (3, 0, 100), (3, 0, 100), (3, 0, 100), (3, 0, 100), (3, 0, 100), (3, 0, 100), (3, 0, 100), (3, 0, 100), (3, 0, 100), (3, 0, 100), (3, 0, 100), (3, 0, 100), (3, 0, 100), (3, 0, 100), (3, 0, 100), (3, 0, 100), (3, 0, 100), (3, 0, 100), (3, 0, 100), (3, 0, 100), (3, 0, 100), (3, 0, 100), (3, 0, 100), (3, 0, 100), (3, 0, 100), (3, 0, 100), (3, 0, 100), (3, 0, 100), (3, 0, 100), (3, 0, 100), (
29
30
                          (-2, 1, -100), (-1, 1, -100), (0, 1, -92), (1, 1, 78), (2, 1, 100), (
31
                           (-2, 2, -100), (-1, 2, -100), (0, 2, -100), (1, 2, -32), (2, 2, 100), (
32
33
                          (-2,-2, 100), (-1,-2, 100), (0,-2, 100), (1,-2, 100), (2,-2, 100),
                         (-2,-1, -32), (-1,-1, 78), (0,-1, 100), (1,-1, 100), (2,-1, 100),
34
                          \begin{array}{l} (-2,\ 1,\ 02), (-1,\ 1,\ 10), (-1,\ 1,\ 100), (-1,\ 1,\ 100), (-1,\ 1,\ 100), (-1,\ 1,\ 100), (-1,\ 1,\ 100), (-1,\ 1,\ 100), (-1,\ 1,\ 100), (-1,\ 1,\ 100), (-1,\ 1,\ 100), (-1,\ 1,\ 100), (-1,\ 1,\ 100), (-1,\ 1,\ 100), (-1,\ 1,\ 100), (-1,\ 1,\ 100), (-1,\ 1,\ 100), (-1,\ 1,\ 100), (-1,\ 1,\ 100), (-1,\ 1,\ 100), (-1,\ 1,\ 100), (-1,\ 1,\ 100), (-1,\ 1,\ 100), (-1,\ 1,\ 100), (-1,\ 1,\ 100), (-1,\ 1,\ 100), (-1,\ 1,\ 100), (-1,\ 1,\ 100), (-1,\ 1,\ 100), (-1,\ 1,\ 100), (-1,\ 1,\ 100), (-1,\ 1,\ 100), (-1,\ 1,\ 100), (-1,\ 1,\ 100), (-1,\ 1,\ 100), (-1,\ 1,\ 100), (-1,\ 1,\ 100), (-1,\ 1,\ 100), (-1,\ 1,\ 100), (-1,\ 1,\ 100), (-1,\ 1,\ 100), (-1,\ 1,\ 100), (-1,\ 1,\ 100), (-1,\ 1,\ 100), (-1,\ 1,\ 100), (-1,\ 1,\ 100), (-1,\ 1,\ 100), (-1,\ 1,\ 100), (-1,\ 1,\ 100), (-1,\ 1,\ 100), (-1,\ 1,\ 100), (-1,\ 1,\ 100), (-1,\ 1,\ 100), (-1,\ 1,\ 100), (-1,\ 1,\ 100), (-1,\ 1,\ 100), (-1,\ 1,\ 100), (-1,\ 1,\ 100), (-1,\ 1,\ 100), (-1,\ 1,\ 100), (-1,\ 100), (-1,\ 100), (-1,\ 100), (-1,\ 100), (-1,\ 100), (-1,\ 100), (-1,\ 100), (-1,\ 100), (-1,\ 100), (-1,\ 100), (-1,\ 100), (-1,\ 100), (-1,\ 100), (-1,\ 100), (-1,\ 100), (-1,\ 100), (-1,\ 100), (-1,\ 100), (-1,\ 100), (-1,\ 100), (-1,\ 100), (-1,\ 100), (-1,\ 100), (-1,\ 100), (-1,\ 100), (-1,\ 100), (-1,\ 100), (-1,\ 100), (-1,\ 100), (-1,\ 100), (-1,\ 100), (-1,\ 100), (-1,\ 100), (-1,\ 100), (-1,\ 100), (-1,\ 100), (-1,\ 100), (-1,\ 100), (-1,\ 100), (-1,\ 100), (-1,\ 100), (-1,\ 100), (-1,\ 100), (-1,\ 100), (-1,\ 100), (-1,\ 100), (-1,\ 100), (-1,\ 100), (-1,\ 100), (-1,\ 100), (-1,\ 100), (-1,\ 100), (-1,\ 100), (-1,\ 100), (-1,\ 100), (-1,\ 100), (-1,\ 100), (-1,\ 100), (-1,\ 100), (-1,\ 100), (-1,\ 100), (-1,\ 100), (-1,\ 100), (-1,\ 100), (-1,\ 100), (-1,\ 100), (-1,\ 100), (-1,\ 100), (-1,\ 100), (-1,\ 100), (-1,\ 100), (-1,\ 100), (-1,\ 100), (-1,\ 100), (-1,\ 100), (-1,\ 100), (-1,\ 100), (-1,\ 100), (-1,\ 100), (-1,\ 100), (-1,\ 100), (-1,\ 100), (-1,\ 100), (-1,\ 100), (-1,\ 100), (-1,\ 100), (-1,\ 100), (-1,\ 100), (-1,\ 100), (-1,\ 100), 
35
36
37
```



Figure 8: Nevatia-Babu 5x5 operator with threshold = 12500

3 How to Use

There's only one program edge_detection.py, to use it, just type command "./edge_detection.py --operator=[operator] [input file]".