Week 10:

Revision Lecture (Core Theories and Techniques)

MSIN00180 Quantitative Methods for Business

Calculus

Differentiation Rules

Given *u* and *v* are differentiable functions of *x* and *c* is a constant ...

Power Rule

$$\frac{d}{dx} x^n = n x^{n-1}$$

Constant Multiple Rule

$$\frac{d}{dx}(cu) = c\frac{du}{dx}$$

Sum Rule

$$\frac{d}{dx}(u + v) = \frac{du}{dx} + \frac{dv}{dx}$$

Product Rule

$$\frac{d}{dx}(uv) = u\frac{dv}{dx} + v\frac{du}{dx}$$

Quotient Rule

$$\frac{d}{dx}\left(\frac{u}{v}\right) = \frac{v\frac{du}{dx} - u\frac{dv}{dx}}{v^2}$$

Chain Rule

$$\frac{d}{dx} f(g(x)) = \frac{df(u)}{du} \cdot \frac{dg(x)}{dx}$$

alternatively ... $\frac{dy}{dx} = \frac{dy}{du} \cdot \frac{du}{dx}$ where y = f(u) and u = g(x)

Differential of an Exponential Function

 $\frac{d}{dx} e^u = e^u \frac{du}{dx}$ where u is any differentiable function of x

Find
$$\frac{d}{dx} [(2x-3)(x^2+1)^3]$$
 where $x = 0$

Find
$$\frac{d}{dx} [(2x-3)(x^2+1)^3]$$
 where $x = 0$

Solution

Product rule:

$$(2x-3)\frac{d}{dx}[(x^2+1)^3] + (x^2+1)^3\frac{d}{dx}[(2x-3)]$$

$$(2x-3)\frac{d}{dx}[(x^2+1)^3] + 2(x^2+1)^3$$

Chain rule: $(2x-3)3(x^2+1)^2(2x) + 2(x^2+1)^3$

Factorise: $(x^2 + 1)^2 [(2x - 3) 3(2x) + 2(x^2 + 1)]$

Simplify: $2(x^2 + 1)^2 [7x^2 - 9x + 1]$

When x = 0: $2(0^2 + 1)^2 [7 \times 0^2 - 9 \times 0 + 1] = 2$

Find
$$\frac{d}{dx} \left[\frac{(2 \times -3) (x^2+1)^3}{(x-2)^2} \right]$$
 where $x = 0$

Find
$$\frac{d}{dx} \left[\frac{(2 \times -3) (x^2+1)^3}{(x-2)^2} \right]$$
 where $x = 0$

Solution

Quotient rule:

$$\frac{d}{dx} \left[\frac{(2\,x-3)\left(x^2+1\right)^3}{(x-2)^2} \right] = \frac{(x-2)^2\,\frac{d}{dx} \left[(2\,x-3)\left(x^2+1\right)^3 \right] - (2\,x-3)\left(x^2+1\right)^3\,\frac{d}{dx} \left[(x-2)^2 \right]}{(x-2)^4}$$

Use previous challenge result : $\frac{(x-2)^2 \, 2 \, (x^2+1)^2 \big[\, 7 \, x^2-9 \, x+1 \big] - (2 \, x-3) \, \big(x^2+1\big)^3 \, \frac{d}{dx} \big[(x-2)^2 \big]}{(x-2)^4}$

Chain rule: $\frac{(x-2)^2 \, 2 \left(x^2+1\right)^2 \left[\, 7 \, x^2-9 \, x+1\right] - \left(2 \, x-3\right) \left(x^2+1\right)^3 \, 2 \, (x-2)^1 \, (1)}{(x-2)^4}$

Simplify – divide by (x-2): $\frac{(x-2) 2 (x^2+1)^2 (7 x^2-9 x+1)-(2 x-3) (x^2+1)^3 2}{(x-2)^3}$

Factorise: $\frac{2(x^2+1)^2 \left[(x-2)(7x^2-9x+1)-(2x-3)(x^2+1)\right]}{(x-2)^3}$

When x = 0: $\frac{2(0^2+1)^2 [(0-2)(7\times0^2-9\times0+1)-(2\times0-3)(0^2+1)]}{(0-2)^3} = -\frac{1}{4}$

Implicit Differentiation

Implicit differentiation is used when the dependent variable (typically y) is not the subject of a formula.

eg find
$$\frac{dy}{dx}$$
 where $x^2 + 3yx = (x + 2y)^2$

The key is to always treat the dependent variable as a function of the independent variable (typically x)

$$x^2 + 3 y(x) x = (x + 2 y(x))^2$$

Remember: implicit differentiation requires no new differentiation rules or techniques.

Challenge 3

Find
$$\frac{dy}{dx}$$
 where $x^2 + 3yx = (x + 2y)^2$

Find
$$\frac{dy}{dx}$$
 where $x^2 + 3yx = (x + 2y)^2$

Solution

differentiate both sides by x: $\frac{d}{dx}(x^2 + 3yx) = \frac{d}{dx}((x + 2y)^2)$

use sum rule on LHS & chain rule on RHS: $2x + \frac{d}{dx}3y = 2(x+2y)\frac{d}{dx}(x+2y)$

 $use\ product\ rule\ on\ LHS\ \&\ sum\ rule\ on\ RHS\ : \quad 2x \quad + \quad 3\ (\ y\frac{dx}{dx} \quad + \quad x\frac{dy}{dx}\) \qquad = \qquad 2\ (\ x+2y\) \quad \left(\ 1+2\ \frac{dy}{dx}\ \right)$

expand out RHS: $2x + 3(y + x\frac{dy}{dx}) = 2(x+2y) + 2(x+2y) 2\frac{dy}{dx}$

collect $\frac{dy}{dx}$ terms on the RHS: $2x + 3y - 2(x+2y) = 2(x+2y) 2 \frac{dy}{dx} - 3x \frac{dy}{dx}$

factorise out $\frac{dy}{dx}$: $2x + 3y - 2(x+2y) = \frac{dy}{dx}(4(x+2y) - 3x)$

$$\frac{dy}{dx} = \frac{-y}{(x+8 y)}$$

Partial Differentiation

Partial differentiation is used to differentiate functions of two or more independent variables.

eg find
$$\frac{\partial f}{\partial x}$$
 where $f(x, y) = (x + 2y)^2$

note this time both x and y are independent variables

The key is to treat all other variables (besides the variable being used differentiated with respect to) as constants

Challenge 4

find
$$\frac{\partial f}{\partial x}$$
 where $f(x, y) = (x + 2y)^2$

find
$$\frac{\partial f}{\partial x}$$
 where $f(x, y) = (x + 2y)^2$

Solution

partially differentiate with respect to x:

chain rule:

$$\frac{\partial f}{\partial x} = 2(x + 2y) \frac{\partial}{\partial x}(x + 2y)$$

sum rule:

$$\frac{\partial f}{\partial x} = 2(x + 2y) \left(\frac{\partial}{\partial x} x + \frac{\partial}{\partial x} 2y \right)$$

treat y as a constant when differentiating:

$$\frac{\partial f}{\partial x} = 2(x+2y)(1+0)$$

$$\frac{\partial f}{\partial x} = 2(x + 2y)$$

Successive partial differentials

$$\frac{\partial f}{\partial x \, \partial y} = \frac{\partial}{\partial y} \left(\frac{\partial f}{\partial x} \right)$$
$$= \frac{\partial}{\partial x} \left(\frac{\partial f}{\partial y} \right)$$

Order does not matter!

The same partial differentiation process applies - always treat the other variables as constants $\frac{\partial f}{\partial x \, \partial y}$ is the same as $f_{x \, y}$

Challenge 5

find f_{xy} where $f = e^{xy}$

find f_{xy} where $f = e^{xy}$

Solution

differentiate with respect to x

$$f_x = e^{xy}(y)$$

now differentiate again with respect to \emph{y} using product rule :

$$f_{xy} = e^{xy}(1) + y(e^{xy}x)$$

$$f_{xy} = e^{xy}(1 + xy)$$

The Gradient Vector

The gradient vector of f(x, y) is the vector

 $\nabla f = \frac{\partial f}{\partial x} i + \frac{\partial f}{\partial y} j$ where *i* is the unit vector in the *x* direction and *j* is the unit vector in the *y* direction

- The gradient vector is the vector made up of the partial derivatives with respect to x, y, \dots
- ullet At a given point P_0 the gradient vector points in the direction of maximum upward slope

Challenge 6

Find the gradient vector of the function $f(x, y) = 2 x y - 3 y^2$ at the point $P_0 = (1, 1)$

Find the gradient vector of the function $f(x, y) = 2 x y - 3 y^2$ at the point $P_0 = (1, 1)$

Solution

First find $\frac{\partial f}{\partial x}$ and $\frac{\partial f}{\partial y}$

$$\frac{\partial f}{\partial y} = 2y + 0$$

$$\frac{\partial f}{\partial x} = 2y + 0$$
 so $\left(\frac{\partial f}{\partial x}\right)_{(1,1)} = 2 \times 1 = 2$

$$\frac{\partial f}{\partial x} = 2x - 6y$$

$$\frac{\partial f}{\partial y} = 2 x - 6 y$$
 so $\left(\frac{\partial f}{\partial y}\right)_{(1,1)} = 2 \times 1 - 6 \times 1 = -4$

$$\nabla f_{(1,1)} = 2i - 4j$$

or representing vectors as lists we can write

$$\nabla f_{(1,1)} = \{2, -4\}$$

Directional Derivatives

The directional derivative of the function f(x, y) at the point P_0 in the direction of the vector $u = u_1 i + u_2 j$ is

$$\begin{split} \left(\frac{df}{ds}\right)_{u,P_0} &= (\nabla f)_{P_0} \cdot \frac{u}{|u|} \\ &= \left(\frac{\partial f}{\partial x}\right)_{P_0} \frac{u_1}{|u|} + \left(\frac{\partial f}{\partial y}\right)_{P_0} \frac{u_2}{|u|} \end{split}$$

Challenge 7

Find the directional derivative of the function $f(x, y) = 2 x y - 3 y^2$ at the point $P_0(1, 1)$ in the direction u = 3i + 4j

Find the directional derivative of the function $f(x, y) = 2 xy - 3 y^2$ at the point $P_0(1, 1)$ in the direction u = 3i + 4j

Solution

We have already found in challenge 6 that

$$\nabla f_{(1,1)} = \{2, -4\}$$

So the directional derivative is given by

$$\left(\frac{df}{ds}\right)_{u,(1,1)} = (\nabla f)_{(1,1)} \cdot \frac{u}{|u|}$$

$$\left(\frac{df}{ds}\right)_{u,(1,1)} = (2\,i-4\,j)\cdot\frac{u}{|u|}$$

and
$$|u| = |3i + 4j| = \sqrt{3^2 + 4^2} = 5$$

SO

$$\left(\frac{df}{ds}\right)_{u,(1,1)} = (2i - 4j) \cdot \frac{u}{5}$$

$$= (2i - 4j) \cdot \left(\frac{3}{5}i + \frac{4}{5}j\right)$$

$$= 2 \times \frac{3}{5} - 4 \times \frac{4}{5}$$

$$= -2$$

Extreme values of single variable functions

Critical point exists at an interior point x = c when f'(c) = 0, or where f'(c) does not exist.

- If f''(c) < 0 then a local maximum
- If f''(c) > 0 then a local minimum
- If f''(c) = 0 then an inflection point

For absolute minimum or maximum it is also necessary to test the values of f at the domain end points.

Extreme values of functions of 2 variables

Critical point exists at an interior point (a, b) when $f_x(a, b) = 0$ and $f_y(a, b) = 0$, or where these values are do not exist.

- If $f_{xx} < 0$ and $f_{xx} f_{yy} f_{xy}^2 > 0$ then a local maximum
- If $f_{xx} > 0$ and $f_{xx} f_{yy} f_{xy}^2 > 0$ then a local minimum
- If $f_{xx} f_{yy} f_{xy}^2 < 0$ then a saddle point
- If $f_{xx} f_{yy} f_{xy}^2 = 0$ then test is inconclusive

Challenge 8

Find the local maximums or minimums of $f(x, y) = 2xy - x^2 - 2y^2 + 3x + 4$

Find the local maximums or minimums of $f(x, y) = 2xy - x^2 - 2y^2 + 3x + 4$

Solution

$$f_x = 2y - 2x + 3 = 0$$
(I)
 $f_y = 2x - 4y = 0$ (II)

From (II):
$$x = 2y$$
(III)

Sub into (I):
$$2y - 2(2y) + 3 = 0$$

 $2y = 3 \longrightarrow y = \frac{3}{2}$

From (III):
$$x = 2 \times \frac{3}{2} = 3$$

So there is an extreme point at $(3, \frac{3}{2})$.

Test for type of extreme point:

< 0 so could be a maximum but need to also test discriminant ... $f_{xx} = -2$ $f_{yy} = -4$ $f_{xy} = 2$

discriminant = $f_{xx} f_{yy} - f_{xy}^2 = (-2)(-4) - (2)^2 = 4$ > 0 so $(3, \frac{3}{2})$ confirmed as local maximum

Value of f at $(3, \frac{3}{2})$: $f(3, \frac{3}{2}) = 2 \times 3 \times \frac{3}{2} - 3^2 - 2(\frac{3}{2})^2 + 3 \times 3 + 4 = \frac{17}{2}$

Absolute Maxima and Minima on Closed Bounded Regions

- 1. First find and classify all the critical points in the interior of the region (which we have previously addressed)
- 2. Then consider any end points of boundaries as these may also be candidate points for absolute maxima or minima
- 3. Finally consider any critical points that lie on the boundaries. These need to be determined and classified individually using the equation of each boundary as a **constraint** on the function being analysed.
 - One way to do this is by using the **Lagrange Multiplier** method (next slide)

Lagrange Multiplier Method

To find the local maximum and minimum values of f(x, y, y) subject to the constraint g(x, y, z) = 0 find the values of x, y, z and λ that simultaneously satisfy the equations

$$\nabla f = \lambda \nabla g$$
 and $g(x, y, z) = 0$

Challenge 9

Find the local extreme values of $f(x, y) = x^2 y$ on the line x + y = 3

Find the local extreme values of $f(x, y) = x^2 y$ on the line x + y = 3

Solution

$$f_x = 2xy$$
, $f_y = x^2$
 $\rightarrow \nabla f = \{2xy, x^2\}$

The constraint is given by g(x, y) = x + y - 3 = 0

so
$$g_x = 1$$
, $g_y = 1 \longrightarrow \nabla g = \{1, 1\}$

Using the Lagrange equation we get

$$\nabla f = \lambda \nabla g \longrightarrow \{2xy, x^2\} = \lambda \{1, 1\}$$

Expressed as 2 simultaneous equations:

$$2 x y = \lambda$$

$$x^2 = \lambda$$

$$\rightarrow y = \frac{x}{2} \text{ or } x = 0$$

Consider x = 0:

Substitute this into g(x, y) = x + y - 3 = 0 gives y = 3 when x = 0At this extreme point $f(0, 3) = x^2 y = 0$

Consider $y = \frac{x}{2}$:

Substitute this into g(x, y) = x + y - 3 = 0 gives $x + \frac{x}{2} - 3 = 0 \implies x = 2$ $y = \frac{x}{2} = 1$ when x = 2

At this extreme point $f(2, 1) = x^2 y = 4$

Basic integration formulae

$$\int k \, \mathrm{d} x = k \, x + C$$

$$\int x^n dx = \frac{x^{n+1}}{n+1} + C \qquad n \neq -1$$

$$\int_{-x}^{1} dx = \ln |x| + C$$

$$\int e^x dx = e^x + C$$

$$\int a^x dx = \frac{a^x}{\ln a} + C \qquad a > 0, \ a \neq 1$$

Integration using the Substitution Rule

$$\int f(g(x)) g'(x) dx = \int f(u) du$$
 where $u = g(x)$

Challenge 10

Evaluate
$$\int \frac{2x}{\sqrt{x^2+1}} dx$$

Evaluate $\int \frac{2x}{\sqrt{x^2+1}} dx$ using the substitution method

Solution

Try the substitution $u = x^2 + 1$:

$$du = 2x dx$$

so using the substitution rule:

$$\int \frac{2x}{\sqrt{x^2+1}} dx = \int \frac{1}{\sqrt{u}} du$$
$$= 2u^{\frac{1}{2}} + C$$

$$= 2 \sqrt{x^2 + 1} + C$$

Integration by Parts

$$\int f(x) g'(x) dx = f(x) g(x) - \int f'(x) g(x) dx$$

alternatively this can be expressed as

$$\int u \, dv = u \, v - \int v \, du$$

- Use this method when the second integral is easier to evaluate than the first.
- Various choices may be available for *u* and dv
 - Choose *u* when its differential is simpler
 - Choose dv when its integral is simpler

Challenge 11

Evaluate $\int \ln x \, dx$.

Evaluate $\int \ln x \, dx$.

Solution

Let
$$u = \ln x$$
 \Longrightarrow (differentiate) $du = \frac{1}{x} dx$

Let
$$dv = dx \implies (integrate) v = x$$

Using the "by parts" formula:

$$\int u \, dv = u \, v - \int v \, du$$
$$= (\ln x)x - \int x \, \frac{1}{x} \, dx$$
$$= x \ln x - x + C$$

Solving Separable Differential Equations of the form

$$\frac{\mathrm{d}y}{\mathrm{d}x} = \frac{g(x)}{h(y)}$$

In its differential form we can write

$$h(y) dy = g(x) dx$$

The solution can be then be found by integrating each side

$$\int h(y) dy = \int g(x) dx$$

Challenge 12

The unit price function p(x) decreases the price at the rate of £0.01 per unit order ie

$$\frac{dp}{dx} = -0.01 x$$

Find p(x) if p(100) = 20

The unit price function p(x) decreases the price at the rate of £0.01 per unit order ie

$$\frac{dp}{dx} = -0.01 x$$

Find p(x) if p(100) = 20

Solution

$$\frac{dp}{dx} = -0.01x$$

separating variables and integrating both sides gives :

$$\int dp = \int -0.01 \, x \, dx$$

$$p = -0.01 \frac{x^2}{2} + C$$

Using p(100)=20

$$20 = -0.01 \frac{100^2}{2} + C$$

$$C = 20 + 50 = 70$$

$$p(x) = 70 - \frac{x^2}{200}$$

Solving Linear Differential Equations of the form

$$\frac{\mathrm{d}y}{\mathrm{d}x} + P(x) y = Q(x)$$

- 1. Find the function $v(x) = e^{\int P(x) dx}$
- 2. The solution is then given by $y = \frac{1}{v(x)} \int v(x) Q(x) dx$

Challenge 13

Solve the differential equation

$$e^{x} \frac{dy}{dx} + 2 e^{x} y = 1$$

Solve the differential equation

$$e^x \frac{dy}{dx} + 2 e^x y = 1$$

Solution

Divide throughout by e^x :

$$\frac{dy}{dy} + 2y = e^{-x}$$

$$\frac{dy}{dx} + 2y = e^{-x} \qquad \Longrightarrow P(x) = 2, \ Q(x) = e^{-x}$$

Find the function $v(x) = e^{\int P(x) dx}$

$$v(x) = e^{\int 2 dx} = e^{2x}$$

The solution is then given by $y = \frac{1}{v(x)} \int v(x) Q(x) dx$

$$y = e^{-2x} \int e^{2x} e^{-x} dx$$

$$y = e^{-2x} \int e^x dx$$

$$y = e^{-2x}(e^x + C)$$

$$y = e^{-x} + C e^{-2x}$$

Linearization

The linearization of the function f at the point x = a is given by

$$L(x) = f(a) + f'(a)(x - a)$$

- The linearization of a function is simply the equation of the tangent line at the point x = a
- The linearization is an approximation to f for values of x close to the point x = a

Challenge 14

Find the linearization of the function $f(x) = x^{\frac{1}{3}}$ around the point x = -8.

Use the linearization to estimate $(-6)^{\frac{1}{3}}$ to 2 decimal places.

Find the linearization of the function $f(x) = x^{\frac{1}{3}}$ around the point x = -8.

Use the linearization to estimate $(-6)^{\frac{1}{3}}$ to 2 decimal places.

Solution

$$L(x) = f(a) + f'(a)(x - a)$$

$$= a^{\frac{1}{3}} + \frac{1}{3}a^{\frac{-2}{3}}(x - a)$$

$$= (-8)^{\frac{1}{3}} + \frac{1}{3}(-8)^{\frac{-2}{3}}(x + 8)$$

$$= -2 + \frac{1}{3}(-2)^{-2}(x + 8)$$

$$= -2 + \frac{1}{3} \times \frac{1}{4}(x + 8)$$

$$= \frac{x}{12} - \frac{4}{3}$$

Use the linearization to estimate $(-6)^{\frac{1}{5}}$ to 2 decimal places:

$$L(-6) = \frac{-6}{12} - \frac{4}{3} = \frac{-11}{6} \approx -1.83$$

Taylor Series

The Taylor Series can be used to approximate any differentiable function f(x) about a point $x = x_0$ thus

$$f(x) \approx f(x_0) + f'(x_0) \left(x - x_0\right) + \frac{1}{2!} f''(x_0) \left(x - x_0\right)^2 + \frac{1}{3!} f'''(x_0) \left(x - x_0\right)^3 + \dots$$

alternatively:
$$f(x) \approx f(x_0) + \sum_{n=1}^{\infty} \frac{1}{n!} f^{(n)}(x_0) (x - x_0)^n$$

Setting $x_0 = 0$ gives a special case of the Taylor Series called the Maclaurin Series

$$f(x) \approx f(0) + \sum_{n=1}^{\infty} \frac{1}{n!} f^{(n)}(0) x^n$$

Linear Algebra

Gauss-Jordan elimination method

1. Proceed from equation to equation, top to bottom, until the $i_{\rm th}$ equation is reached of the form $c x_i + ... = b$ where $c \ne 0$.

Divide this i_{th} equation by c: $\mathbf{m}_{\llbracket \mathbf{i} \rrbracket} = \frac{1}{c} \mathbf{m}_{\llbracket \mathbf{i} \rrbracket}$

- **2.** Eliminate x_i from all the other equations, above and below the i_{th} equation by subtracting suitable multiples of the i_{th} equation.
- 3. Repeat from step (1) until all equations have been considered.
- **4.** Finally convert back to normal form to solve each equation for its leading variable.

This may result in no solutions (due to an inconsistent set of equations), a single solution or an infinite set of solutions.

Rank governs the number of solutions

The rank of a matrix A is the number of leading ones in rref(A), denoted rank(A).

A system of equation is said to be **inconsistent** if there are no solutions. A linear system is **inconsistent** if (and only if) the RREF of its augmented matrix contains any row [0 0 ... 0 k] where k≠0.

If a linear system is **consistent**, then it has either:

• infinitely many solutions when there is at least one free variable (rank < number of variables),

• exactly one solution when all the variables are leading (rank=number of variables)

Solve the following simultaneous equations using Gaussian elimination

4a + 7b = 1

5a + 8b = 2

Represent equations in matrix form

$$\begin{pmatrix} 4 & 7 \\ 5 & 8 \end{pmatrix} \begin{pmatrix} a \\ b \end{pmatrix} = \begin{pmatrix} 1 \\ 2 \end{pmatrix}$$

Gaussian elimination process:

Step 1: Express as an augmented matrix

$$\begin{pmatrix} 4 & 7 & 1 \\ 5 & 8 & 2 \end{pmatrix}$$

Step 2: Consider each row in turn

Step 2.1: Change the leading non-zero number to a 1 in row1:

$$row1 = row1/4$$

$$\begin{pmatrix} 1 & \frac{7}{4} & \frac{1}{4} \\ 5 & 8 & 2 \end{pmatrix}$$

Step 2.2: Remove non-zero numbers above and below this new leading 1

$$row2 = row2 - 5 \times row1$$

$$\begin{pmatrix} 1 & \frac{7}{4} & \frac{1}{4} \\ 0 & -\frac{3}{4} & \frac{3}{4} \end{pmatrix}$$

Step 2: Consider next row

Step 2.1: Change the leading non-zero number to a 1 in row2:

$$row2 = row2 / (-\frac{3}{4})$$

$$\begin{pmatrix} 1 & \frac{7}{4} & \frac{1}{4} \\ 0 & 1 & -1 \end{pmatrix}$$

Step 2.2: Remove non-zero numbers above and below this new leading 1

$$row1 = row1 - \frac{7}{4} \times row2$$

$$\begin{pmatrix} 1 & 0 & 2 \\ 0 & 1 & -1 \end{pmatrix}$$

Step 3: Convert the final reduced-row echelon form matrix to a standard matrix equation

$$\begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} \begin{pmatrix} a \\ b \end{pmatrix} = \begin{pmatrix} 2 \\ -1 \end{pmatrix}$$

Step 4: Determine whether there are many, one or no solutions

Step 4.1: No solutions (inconsistent) when zeros on one side and a non-zero number on the other

Step 4.2: **One solution** when the number of leading ones = number of variables (rank = m)

- Each row gives a unique solution for each variable

- In this case: a = 2 and b = -1

Step 4.3: Many solutions when number of leading ones < number of variables (rank < m)

- For variables on all zero rows assign general variable values eg $t, s, r \dots$
- Find the solutions for all other variables in terms of t, s, r ...

Find the inverse using Gaussian elimination

Consider an $n \times n$ matrix A. To find A^{-1} (if it exists):

- 1. Form the augmented matrix $[A : I_n]$
- 2. Apply standard Gaussian elimination until you have $[I_n : A^{-1}]$

Find inverse of $\begin{pmatrix} 4 & 7 \\ 5 & 8 \end{pmatrix}$ using Gaussian elimination

$$\begin{pmatrix} 1 & \frac{7}{4} & \frac{1}{4} & 0 \\ 5 & 8 & 0 & 1 \end{pmatrix} \text{ row1 } / 4$$

$$\begin{pmatrix} 1 & \frac{7}{4} & \frac{1}{4} & 0 \\ 0 & -\frac{3}{4} & \frac{-5}{4} & 1 \end{pmatrix} \text{ row2 } - 5 \times \text{row1}$$

$$\begin{pmatrix} 1 & \frac{7}{4} & \frac{1}{4} & 0 \\ 0 & 1 & \frac{5}{3} & \frac{-4}{3} \end{pmatrix} \text{ row } / \left(\frac{-3}{4} \right)$$

$$\begin{pmatrix} 1 & 0 & -\frac{8}{3} & \frac{7}{3} \\ 0 & 1 & \frac{5}{3} & \frac{-4}{3} \end{pmatrix} \text{ row } 1 & -\frac{7}{4} \times \text{row } 2$$

The inverse is therefore $\begin{pmatrix} -\frac{8}{3} & \frac{7}{3} \\ \frac{5}{3} & \frac{-4}{3} \end{pmatrix}$

Least-squares solution

The normal equation

The least-squares solutions of the system $A \vec{x} = \vec{b}$ are the exact solutions of

$$A^T A \overrightarrow{x}^* = A^T \overrightarrow{b}$$

Find the least-squares solution \vec{x}^* of the system $A \vec{x} = \vec{b}$ where

$$A = \begin{pmatrix} 1 & 3 \\ 2 & 6 \end{pmatrix} \text{ and } \vec{b} = \begin{pmatrix} 5 \\ 0 \end{pmatrix}$$

$$A^T A \overrightarrow{X}^* = A^T \overrightarrow{b}$$

$$\begin{pmatrix} 1 & 2 \\ 3 & 6 \end{pmatrix} \begin{pmatrix} 1 & 3 \\ 2 & 6 \end{pmatrix} \overrightarrow{X}^* = \begin{pmatrix} 1 & 2 \\ 3 & 6 \end{pmatrix} \begin{pmatrix} 5 \\ 0 \end{pmatrix}$$

$$\begin{pmatrix} 5 & 15 \\ 15 & 45 \end{pmatrix} \overrightarrow{x}^* = \begin{pmatrix} 5 \\ 15 \end{pmatrix}$$

Solve by Gaussian elimination:

$$\begin{pmatrix} 5 & 15 & 5 \\ 15 & 45 & 15 \end{pmatrix}$$
 form augmented matrix

$$\begin{pmatrix} 1 & 3 & 1 \\ 15 & 45 & 15 \end{pmatrix} \text{ row } 1/5$$

$$\begin{pmatrix} 1 & 3 & 1 \\ 0 & 0 & 0 \end{pmatrix}$$
 row2 - 15×row1

Let
$$x_2 = t$$

$$\begin{pmatrix} 1 & 3 \\ 0 & 0 \end{pmatrix} \begin{pmatrix} x_1 \\ t \end{pmatrix} = \begin{pmatrix} x_1 + 3t \\ 0 \end{pmatrix} = \begin{pmatrix} 1 \\ 0 \end{pmatrix}$$

$$x_1 = 1 - 3t$$

so
$$\vec{x}^* = \begin{pmatrix} 1 - 3t \\ t \end{pmatrix}$$
 where t is an arbitrary constant

Fitting a straight line using a least-squares approach



We can represent each data point as a separate equation:

$$c_0 + c_1 1 = 0$$
 for point (1,0)
 $c_0 + c_1 2 = 4$ for point (2,4)
 $c_0 + c_1 3 = 6$ for point (3,6)

We can represent these equations in matrix form thus:

$$\begin{pmatrix} 1 & 1 \\ 1 & 2 \\ 1 & 3 \end{pmatrix} \begin{pmatrix} c_0 \\ c_1 \end{pmatrix} = \begin{pmatrix} 0 \\ 4 \\ 6 \end{pmatrix}$$

Now use the **normal equation** to find the least-squares solution for $\begin{pmatrix} c_0 \\ c_1 \end{pmatrix}$

Fit a straight line to the following data points using least-squares

Χ	У
-1	0
0	- 1
1	2

Fit a straight line to the following data points using least-squares

Χ	У
-1	0
0	- 1
1	2

Set up the matrix of equations for each data point for a straight line model

$$\begin{pmatrix} 1 & -1 \\ 1 & 0 \\ 1 & 1 \end{pmatrix} \begin{pmatrix} c_0 \\ c_1 \end{pmatrix} = \begin{pmatrix} 0 \\ -1 \\ 2 \end{pmatrix}$$

Form the normal equation where $A = \begin{pmatrix} 1 & -1 \\ 1 & 0 \\ 1 & 1 \end{pmatrix}$ and $\vec{b} = \begin{pmatrix} 0 \\ -1 \\ 2 \end{pmatrix}$

$$A^T A \overrightarrow{x}^* = A^T \overrightarrow{b}$$

$$\begin{pmatrix} 1 & 1 & 1 \\ -1 & 0 & 1 \end{pmatrix} \begin{pmatrix} 1 & -1 \\ 1 & 0 \\ 1 & 1 \end{pmatrix} \overrightarrow{X}^* = \begin{pmatrix} 1 & 1 & 1 \\ -1 & 0 & 1 \end{pmatrix} \begin{pmatrix} 0 \\ -1 \\ 2 \end{pmatrix}$$

$$\begin{pmatrix} 3 & 0 \\ 0 & 2 \end{pmatrix} \overrightarrow{X}^* = \begin{pmatrix} 1 \\ 2 \end{pmatrix}$$

$$\begin{pmatrix} 3 & 0 \\ 0 & 2 \end{pmatrix} \begin{pmatrix} c_0 \\ c_1 \end{pmatrix} = \begin{pmatrix} 1 \\ 2 \end{pmatrix}$$

$$\begin{pmatrix} c_0 \\ c_1 \end{pmatrix} = \begin{pmatrix} \frac{1}{3} \\ 1 \end{pmatrix}$$

straight line equation therefore:

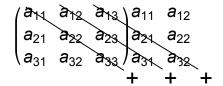
$$\frac{1}{3} + x = y$$

Determinants

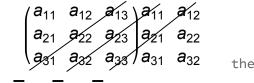
Determinant of a 2×2 matrix

$$\det\begin{pmatrix} a & b \\ c & d \end{pmatrix} = (a d - b c)$$

Determinant of a 3×3 matrix: Sarrus's Rule



add the product of these diagonal elements



subtract the products of these opposite diagonal elements

Find the determinant of
$$A = \begin{pmatrix} 1 & 2 & 3 \\ 3 & 1 & 0 \\ 0 & 2 & 1 \end{pmatrix}$$

$$\begin{pmatrix} 1 & 2 & 3 \\ 3 & 1 & 0 \\ 0 & 2 & 1 \end{pmatrix} \begin{pmatrix} 1 & 2 \\ 3 & 1 \\ 0 & 2 \end{pmatrix}$$

$$\det \begin{pmatrix} 1 & 2 & 3 \\ 3 & 1 & 0 \\ 0 & 2 & 1 \end{pmatrix} = 1 \times 1 \times 1 + 2 \times 0 \times 0 + 3 \times 3 \times 2 - 0 \times 1 \times 3 - 2 \times 0 \times 1 - 1 \times 3 \times 2 = 13$$

Determinant of triangular and diagonal matrices

The determinant of an **upper or lower triangular matrix** or of a **diagonal matrix** is the product of the diagonal elements

$$\operatorname{eg} \operatorname{det} \begin{pmatrix} a_{11} & a_{12} & a_{13} \\ 0 & a_{22} & a_{23} \\ 0 & 0 & a_{33} \end{pmatrix} = \operatorname{det} \begin{pmatrix} a_{11} & 0 & 0 \\ 0 & a_{22} & 0 \\ 0 & 0 & a_{33} \end{pmatrix} = a_{11} a_{22} a_{33}$$

Determinant of block matrix

If M is a **block matrix** such that $M = \begin{pmatrix} A & B \\ 0 & C \end{pmatrix}$ or $M = \begin{pmatrix} A & 0 \\ B & C \end{pmatrix}$ where A and C are **square matrices** then

$$det(M) = det(A) det(C)$$

Find

$$\det\begin{pmatrix}1&0&0&0&0\\2&2&0&0&0\\3&5&1&0&0\\1&2&1&1&2\\3&0&2&3&4\end{pmatrix}$$

$$\det\begin{pmatrix} 1 & 0 & 0 & 0 & 0 \\ 2 & 2 & 0 & 0 & 0 \\ 3 & 5 & 1 & 0 & 0 \\ 1 & 2 & 1 & 1 & 2 \\ 3 & 0 & 2 & 3 & 4 \end{pmatrix} = \det\begin{pmatrix} 1 & 0 & 0 \\ 2 & 2 & 0 \\ 3 & 5 & 1 \end{pmatrix} \det\begin{pmatrix} 1 & 2 \\ 3 & 4 \end{pmatrix} = 1 \times 2 \times 1 \times (1 \times 4 - 3 \times 2) = -4$$

Eigenvalues and eigenvectors

A nonzero vector \vec{v} is called an **eigenvector** of the square matrix A if

$$A \overrightarrow{V} = \lambda \overrightarrow{V}$$

for some scalar λ , called the associated **eigenvalue** of eigenvector \overrightarrow{v} .

Alternatively we can say:

When **diagonalising** a square matrix A to the form $A = SBS^{-1}$

- the **eigenvalues** of A are the scalar values λ_i that form the diagonal elements of B, and
- the **eigenvectors** of *A* are the corresponding column vectors \vec{v}_i of *S*.

Finding Eigenvalues: The Characteristic Equation

We can restate the defining eigenvalue equation $A \vec{v} = \lambda \vec{v}$ as:

$$(A - \lambda I_n) \overrightarrow{V} = \overrightarrow{0}$$

By the definition of the **kernel**, since eigenvectors exist the matrix is **non-invertible**.

And if a matrix is non-invertible its determinant is zero, so

$$det(A - \lambda I_n) = 0$$
 \(\infty\) Characteristic Equation

- a) Find the eigenvalues of $\begin{pmatrix} 5 & -4 \\ 2 & -1 \end{pmatrix}$
- b) Find the eigenvalues of $\begin{pmatrix} -3 & 0 & 4 \\ 0 & -1 & 0 \\ -2 & 7 & 3 \end{pmatrix}$

Challenge 21 (a)

a) Find the eigenvalues of $\begin{pmatrix} 5 & -4 \\ 2 & -1 \end{pmatrix}$

$$\det\begin{pmatrix} 5 - \lambda & -4 \\ 2 & -1 - \lambda \end{pmatrix} = (5 - \lambda)(-1 - \lambda) + 2 \times 4$$
$$= \lambda^2 - 4\lambda - 5 + 8$$
$$= \lambda^2 - 4\lambda + 3$$
$$= (\lambda - 3)(\lambda - 1)$$

The eigenvalues of $\begin{pmatrix} 5 & -4 \\ 2 & -1 \end{pmatrix}$ are $\lambda_1 = 3$, $\lambda_2 = 1$

Challenge 21 (b)

b) Find the eigenvalues of $\begin{pmatrix} -3 & 0 & 4 \\ 0 & -1 & 0 \\ -2 & 7 & 3 \end{pmatrix}$

Use Sarrus's Rule:

$$\begin{pmatrix} -3 - \lambda & 0 & 4 \\ 0 & -1 - \lambda & 0 \\ -2 & 7 & 3 - \lambda \end{pmatrix} \begin{pmatrix} -3 - \lambda & 0 \\ 0 & -1 - \lambda \\ -2 & 7 \end{pmatrix}$$

$$\det\begin{pmatrix} -3 - \lambda & 0 & 4 \\ 0 & -1 - \lambda & 0 \\ -2 & 7 & 3 - \lambda \end{pmatrix} = 0 = (-3 - \lambda)(-1 - \lambda)(3 - \lambda) + 0 + 0 - (-2)(-1 - \lambda)4 - 0 - 0$$
$$= -\lambda^3 - \lambda^2 + 9\lambda + 9 - 8\lambda - 8$$
$$= -\lambda^3 - \lambda^2 + \lambda + 1$$
$$= (1 - \lambda)(\lambda + 1)^2$$

The eigenvalues of $\begin{pmatrix} -3 & 0 & 4 \\ 0 & -1 & 0 \\ -2 & 7 & 3 \end{pmatrix}$ are $\lambda_1 = 1$, $\lambda_2 = -1$ (algebraic multiplicity = 2)

- The $(1 \lambda)(\lambda + 1)^2$ factorisation was possibly difficult to spot.
- However, it should be reasonably clear that 1 and -1 are roots of $-\lambda^3 \lambda^2 + \lambda + 1 = 0$

Finding eigenvectors

We have already seen that

$$A \overrightarrow{v} = \lambda \overrightarrow{v} \implies (A - \lambda I_n) \overrightarrow{v} = \overrightarrow{0}$$

To find eigenvectors solve the matrix equation:
$$(A - \lambda I_n) \overrightarrow{V} = \overrightarrow{0}$$

- a) Find the eigenvectors of $\begin{pmatrix} 5 & -4 \\ 2 & -1 \end{pmatrix}$
- b) Find the eigenvectors of $\begin{pmatrix} -3 & 0 & 4 \\ 0 & -1 & 0 \\ -2 & 7 & 3 \end{pmatrix}$

Challenge 22 (a)

a) Find the eigenvectors of $\begin{pmatrix} 5 & -4 \\ 2 & -1 \end{pmatrix}$

From Challenge 21 we found $\lambda_1 = 3$, $\lambda_2 = 1$

Consider $\lambda_1 = 3$

$$\begin{pmatrix} 5-3 & -4 \\ 2 & -1-3 \end{pmatrix} = \begin{pmatrix} 2 & -4 \\ 2 & -4 \end{pmatrix}$$

let c_1 , c_2 be the column vectors of $\begin{pmatrix} 2 & -4 \\ 2 & -4 \end{pmatrix}$

kernel basis vector $\rightarrow 2 c_1 + 1 c_2 = 0 \rightarrow \begin{pmatrix} 2 \\ 1 \end{pmatrix}$

eigenvector $v_1 = \begin{pmatrix} 2 \\ 1 \end{pmatrix}$

Consider $\lambda_2 = 1$

$$\begin{pmatrix} 5-1 & -4 \\ 2 & -1-1 \end{pmatrix} = \begin{pmatrix} 4 & -4 \\ 2 & -2 \end{pmatrix}$$

kernel basis vector $\rightarrow 1 c_1 + 1 c_2 = 0 \rightarrow \begin{pmatrix} 1 \\ 1 \end{pmatrix}$

eigenvector $v_2 = \begin{pmatrix} 1 \\ 1 \end{pmatrix}$

Challenge 22 (b)

b) Find the eigenvectors of $\begin{pmatrix} -3 & 0 & 4 \\ 0 & -1 & 0 \\ -2 & 7 & 3 \end{pmatrix}$

From Challenge 21 we found $\lambda_1 = 1$, $\lambda_2 = -1$

Consider $\lambda_1 = 1$

$$\begin{pmatrix} -3-1 & 0 & 4 \\ 0 & -1-1 & 0 \\ -2 & 7 & 3-1 \end{pmatrix} = \begin{pmatrix} -4 & 0 & 4 \\ 0 & -2 & 0 \\ -2 & 7 & 2 \end{pmatrix}$$

by observation c_1 , c_2 are independent but c_3 is redundant

kernel basis vector
$$\rightarrow 1c_1 + 0c_2 + 1c_3 = 0 \rightarrow \begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix}$$

eigenvector
$$v_1 = \begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix}$$

Consider $\lambda_2 = -1$

$$\begin{pmatrix} -3+1 & 0 & 4 \\ 0 & -1+1 & 0 \\ -2 & 7 & 3+1 \end{pmatrix} = \begin{pmatrix} -2 & 0 & 4 \\ 0 & 0 & 0 \\ -2 & 7 & 4 \end{pmatrix}$$

by observation c_1 , c_2 are independent but c_3 is redundant

kernel basis vector
$$\rightarrow 2 c_1 + 0 c_2 + 1 c_3 = 0 \rightarrow \begin{pmatrix} 2 \\ 0 \\ 1 \end{pmatrix}$$

eigenvector
$$v_2 = \begin{pmatrix} 2 \\ 0 \\ 1 \end{pmatrix}$$

Discrete linear dynamical systems

General solution in terms of A^t

Consider the dynamical system $\vec{x}(t+1) = A\vec{x}(t)$ with $\vec{x}(0) = \vec{x}_0$

Then:
$$\overrightarrow{X}(t) = A^t \overrightarrow{X}_0$$

Discrete linear dynamical systems

General solution in terms of eigenvectors and eigenvalues

- 1. Find the eigenvectors $\vec{v}_1,...,\vec{v}_n$ for A, and the associated eigenvalues $\vec{\lambda}_1,...,\vec{\lambda}_n$
- 2. Find the coefficients $c_1, ..., c_n$ that form a linear combination of the vector \vec{x}_0 with respect the eigenbasis $\overrightarrow{V}_1,...,\overrightarrow{V}_n$:

$$\vec{X}_0 = c_1 \vec{V}_1 + \dots + c_n \vec{V}_n$$

3. Then:
$$\overrightarrow{X}(t) = c_1 \lambda_1^t \overrightarrow{V}_1 + \ldots + c_n \lambda_n^t \overrightarrow{V}_n$$

The individual rows of this solution are referred to as the "Closed Formula" solutions.

Find the closed formula solutions for $\vec{x}(t) = A^t \vec{x}_0$ where

$$A = \begin{pmatrix} 0.5 & 0.25 \\ 0.5 & 0.75 \end{pmatrix} \overrightarrow{x}_0 = \begin{pmatrix} 1 \\ 0 \end{pmatrix}$$

Find eigenvalues:

$$\det\begin{pmatrix} 0.5 - \lambda & 0.25 \\ 0.5 & 0.75 - \lambda \end{pmatrix} = 0 = (0.5 - \lambda) (0.75 - \lambda) - 0.5 \times 0.25$$

$$= \lambda^2 - 1.25 \lambda + 0.375 - 0.125$$

$$= \lambda^2 - 1.25 \lambda + 0.25$$

$$= 4 \lambda^2 - 5 \lambda + 1$$

$$= (\lambda - 1) (4 \lambda - 1)$$

$$\lambda_1 = 1, \ \lambda_2 = \frac{1}{4}$$

Solution contd.

Find eigenvectors:

Consider $\lambda_1 = 1$:

$$\begin{pmatrix} 0.5 - 1 & 0.25 \\ 0.5 & 0.75 - 1 \end{pmatrix} = \begin{pmatrix} -0.5 & 0.25 \\ 0.5 & -0.25 \end{pmatrix}$$

kernel basis vector $\rightarrow 1 c_1 + 2 c_2 = 0 \rightarrow \begin{pmatrix} 1 \\ 2 \end{pmatrix}$

eigenvector $v_1 = \begin{pmatrix} 1 \\ 2 \end{pmatrix}$

Consider $\lambda_2 = \frac{1}{4}$:

$$\begin{pmatrix} 0.5 - 0.25 & 0.25 \\ 0.5 & 0.75 - 0.25 \end{pmatrix} = \begin{pmatrix} 0.25 & 0.25 \\ 0.5 & 0.5 \end{pmatrix}$$

kernel basis vector $\rightarrow -1$ $c_1 + 1$ $c_2 = 0 \rightarrow \begin{pmatrix} -1 \\ 1 \end{pmatrix}$

eigenvector $v_2 = \begin{pmatrix} -1 \\ 1 \end{pmatrix}$

Solution contd.

Find the coefficients $c_1, ..., c_n$

$$\overrightarrow{x}_0 = c_1 \overrightarrow{v}_1 + c_2 \overrightarrow{v}_n = \begin{pmatrix} 1 & -1 \\ 2 & 1 \end{pmatrix} \begin{pmatrix} c_1 \\ c_2 \end{pmatrix} = \begin{pmatrix} 1 \\ 0 \end{pmatrix}$$

$$\begin{pmatrix} c_1 - c_2 \\ 2 c_1 + c_2 \end{pmatrix} = \begin{pmatrix} 1 \\ 0 \end{pmatrix}$$

Using standard simultaneous equations approach:

$$c_1 - c_2 = 1$$

 $2c_1 + c_2 = 0$

Add equations: $3c_1 = 1 \rightarrow c_1 = \frac{1}{3}$

From equation (1): $c_2 = c_1 - 1 \rightarrow c_2 = -\frac{2}{3}$

Solution contd.

Closed formula solution:

$$\begin{aligned} \overrightarrow{x}(t) &= c_1 \lambda_1^t \overrightarrow{v}_1 + c_2 \lambda_2^t \overrightarrow{v}_2 = \frac{1}{3} \times 1^t \begin{pmatrix} 1 \\ 2 \end{pmatrix} - \frac{2}{3} \left(\frac{1}{4} \right)^t \begin{pmatrix} -1 \\ 1 \end{pmatrix} \\ &= \begin{pmatrix} 1 \times \frac{1}{3} \times 1^t \\ 2 \times \frac{1}{3} \times 1^t \end{pmatrix} - \begin{pmatrix} -1 \times \frac{2}{3} \left(\frac{1}{4} \right)^t \\ 1 \times \frac{2}{3} \left(\frac{1}{4} \right)^t \end{pmatrix} \\ &= \begin{pmatrix} \frac{1}{3} \\ \frac{2}{3} \end{pmatrix} + \begin{pmatrix} \frac{2}{3} \left(\frac{1}{4} \right)^t \\ -\frac{2}{3} \left(\frac{1}{4} \right)^t \end{pmatrix} \end{aligned}$$

$$\vec{X}$$
 (t) = $\begin{pmatrix} x_1 \\ x_2 \end{pmatrix}$ = $\begin{pmatrix} \frac{1}{3} + \frac{2}{3} & (\frac{1}{4})^t \\ \frac{2}{3} - \frac{2}{3} & (\frac{1}{4})^t \end{pmatrix}$

Remember Other Topics May Arise ...

There obviously is not time to cover everything we have learned over this module in this revision lecture.

Other topics <u>may</u> arise in the exam besides those covered today!

Good luck!