

# Time Series Analysis

## Lecture 2 Basic Concepts

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## 自协方差函数

## 自相关函数

- ① Mean, Autocovariance function (ACVF) and Autocorrelation function (ACF) 平稳性
- ② Stationarity 鞅差分序列
- ③ I.I.D. sequence, Martingale difference sequence (MDS), White noise sequence 白噪声序列
- ④ Time Series Decomposition 时间序列分解

# Mean, Autocovariance and Autocorrelation

Suppose  $\{Y_t\}$  is a time series

- Mean function:

$$\mu_t = E(Y_t).$$

- Autocovariance function:

$$\begin{aligned}\gamma_Y(s, t) &= \text{Cov}(Y_s, Y_t) \\ &= E[(Y_s - \mu_s)(Y_t - \mu_t)].\end{aligned}$$

- Autocorrelation function (ACF):

$$\rho_Y(s, t) = \frac{\text{Cov}(Y_s, Y_t)}{\sqrt{\text{Var}(Y_t, Y_t) \text{Var}(Y_s, Y_s)}}$$

# Examples

- ①  $Y_t = \mu + \varepsilon_t$  where  $\varepsilon_t$  is a i.i.d  $N(0, \sigma^2)$ . 独立同分布

**Solution:**

$$\mu_t = E(Y_t) = E(\mu + \varepsilon_t) = \mu$$

$$\gamma_Y(s, t) = \text{Cov}(Y_s, Y_t) = E[(Y_s - \mu)(Y_t - \mu)]$$

因为独立同分布.  $= E(\varepsilon_s \varepsilon_t) = \begin{cases} 0, & \text{if } s \neq t \\ \sigma^2, & \text{if } s = t \end{cases}$

所以  $E(\varepsilon_s \varepsilon_t) \xrightarrow{s \neq t} E(\varepsilon_s)E(\varepsilon_t)$

- ② How about  $Y_t = \beta t + \varepsilon_t$ ?

$$\overbrace{E(Y_t) = \beta t} \quad \text{Cov}(Y_t, Y_s) = \begin{cases} 0, & s \neq t \\ \sigma^2, & s = t \end{cases}$$

# Stationarity: I. Weakly(Covariance) Stationary

协方差平稳

弱平稳

- A time series  $\{Y_t\}$  is **Covariance stationary** or **weakly stationary** if

$$E(Y_t) = \mu_t = \mu \quad \text{for all } t$$

$$\text{Var}(Y_t) = \sigma^2 < \infty$$

$$\text{Cov}(Y_{t+j}, Y_t) = \gamma_Y(t+j, t) = \gamma_j \quad \text{for all } t \text{ and } j.$$

它的“平均水平”“波动幅度”“不同时刻的关联程度”都具有时间平移不变性

- In other words, both  $\mu_t$  and  $\gamma_Y(t+j, t)$  are **time invariant**.

- For a weakly stationary process,

t与t+j的相关程度和t+j与t的相关程度是一样的

$$\begin{aligned} \text{Corr}(Y_{t+j}, Y_t) &= \frac{\text{Cov}(Y_{t+j}, Y_t)}{\sqrt{\text{Var}(Y_{t+j})} \sqrt{\text{Var}(Y_t)}} \\ &= \rho_Y(j) = \rho_Y(-j) \quad \text{symmetric and time invariant} \end{aligned}$$

# Example 1

- **White Noise (WN)**:  $Y_t$  is defined as a white noise process if

$$E(Y_t) = 0 \quad \text{and} \quad \gamma_Y(t-j, t) = \begin{cases} 0, & \text{if } j \neq 0 \\ \sigma^2, & \text{if } j = 0 \end{cases}$$

- In a short, white noise process is a uncorrelated sequence with **zero mean**.
- Obviously, **White Noise process is weakly stationary**.

## Example 2

- **Random Walk:**  $Y_t = \sum_{i=1}^t e_i$ , where  $e_i$  is a i.i.d. process with mean 0 and variance  $\sigma^2$ . ( $Y_t = Y_{t-1} + e_t$ )

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$$\begin{aligned} E(Y_t) &= 0 \\ E(Y_t^2) &= t\sigma^2 \\ \gamma_Y(t-j, t) &= \text{Cov}(Y_{t-j}, Y_t) \\ &= \text{Cov}(Y_{t-j}, Y_{t-j}) + \text{Cov}(Y_{t-j}, \sum_{i=t-j+1}^t e_i) \\ &= \text{Cov}(Y_{t-j}, Y_{t-j}) \\ &= (t-j)\sigma^2. \end{aligned}$$

- Thus, **Random Walk is not weakly stationary.**

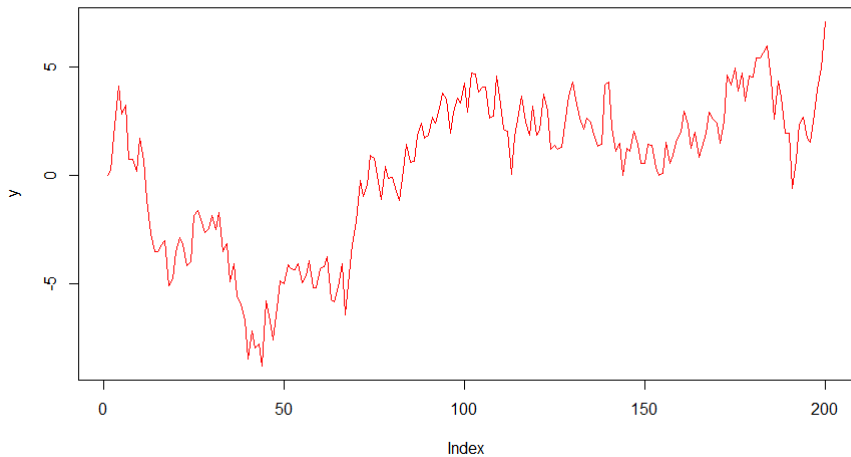


Figure: Random walk



## Stationarity: II. Strictly Stationary

- $Y_t$  is **strictly stationary** if for all  $k, t_1, \dots, t_k, y_1, \dots, y_k$  and  $h$ , the probability

$$\Pr(Y_{t_1} \leq y_1, \dots, Y_{t_k} \leq y_k) = \Pr(Y_{t_1+h} \leq y_1, \dots, Y_{t_k+h} \leq y_k);$$

- In other words, the **joint distribution**  $F(Y_{t_1}, \dots, Y_{t_k})$  depends **only on the intervals** separating the dates  $(t_1, \dots, t_k)$ , **not on the date itself**.

只依赖时间的间隔，不依赖时间数据其本身

# weakly stationary $\neq$ strictly stationary

不是弱平稳，但是在合适的时刻是弱平稳的

- Strictly stationary **does not** imply weakly stationary, **but** a strict stationary process with *finite second moments* is weakly stationary;
- Weakly stationary **does not** imply strictly stationary **because** the third order moment could be time-varying, even the first and second moments are constant.
- An i.i.d. sequence is definitely strictly stationary.
- **Question:** Is an i.i.d. sequence definitely weakly stationary?

# weakly stationary = strictly stationary?

- **Gaussian process:**  $Y_t$  is a Gaussian process, if the joint distribution of  $(Y_{t_1}, \dots, Y_{t_k})$  for any  $k, t_1, \dots, t_k$ , is joint Gaussian distribution.
- If  $\{X_t\}$  is a Gaussian process, under this situation,

weakly stationary  $\Leftrightarrow$  strictly stationary.

高斯过程由“任意有限维联合分布都是高斯”

# Weakly Stationary/Strictly Stationary

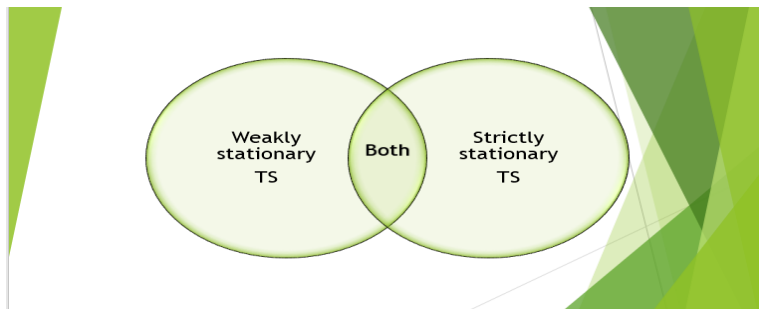


Figure: The relationship between weak stationarity and strict stationarity

From now on, stationarity in this course means weakly stationary.

过去的事儿再怎么分析，也没法预判这次意外是“该赚还是该亏”

Assume innovations  $\{\varepsilon_t\}$ . Four situations:

- ① independent and identically distributed,  $\varepsilon_t \sim i.i.d.(0, \sigma^2)$ ;
- ② **Martingale difference sequence (MDS):**

$$E(\varepsilon_t | \mathfrak{F}_{t-1}) = 0.$$

- ③ White noise:  $E\varepsilon_t = 0$ ,  $Var(\varepsilon_t) = \sigma^2 < \infty$  and  $Corr(\varepsilon_t, \varepsilon_s) = 0$  for all  $t \neq s$ .
- ④ Stationary process:  $E(\varepsilon_t) = \mu$  and  $\rho_\varepsilon(t+j, t) = \rho_\varepsilon(j)$ .

# Graphic demonstration

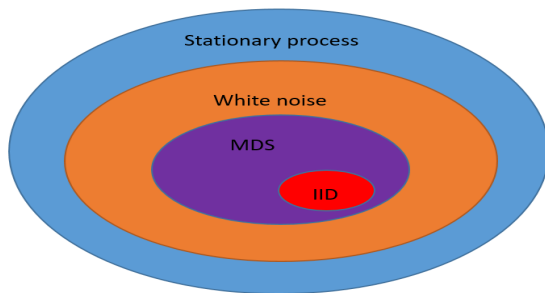


Figure: The classification of stochastic process

# Time Series Component

- Time series: a systematic part + a non-systematic part.
- The systematic part : **Level**, **Trend**, **Seasonality**.
  - 等级 • **Level**: describes the average value of the series;
  - 趋势 • **Trend**: the change in the series from one period to the next (commonly approximated by linear, exponential and other mathematical functions);
  - 季节性 • **Seasonality**: describes a short-term cyclical behavior that can be observed several times within the given series.
- The nonsystematic part: Noise.

# Time Series Decomposition

- Two decompositions: either **additive** or **multiplicative**.
- **Additive**:  $Y_t = Level + Trend + Seasonality + Noise$
- **Multiplicative**:  $Y_t = Level \times Trend \times Seasonality \times Noise$
- The systematic part: for generating **point forecasts** The noise level : for assessing the **uncertainty associated with the point forecasts**).



# Time series patterns

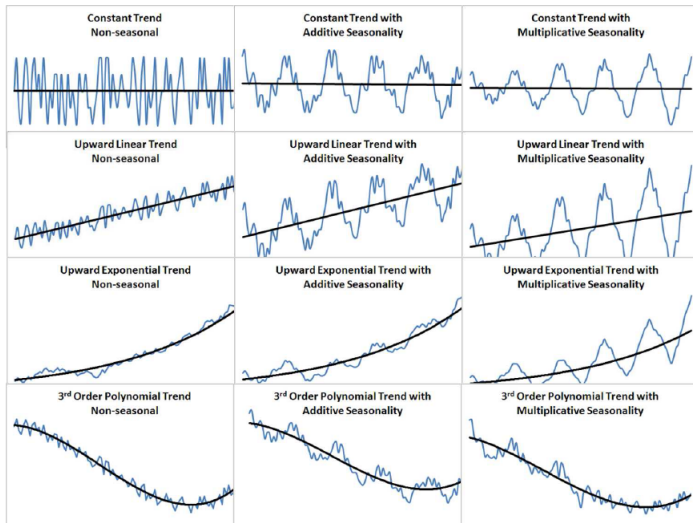


Figure: Illustrations of common trend and seasonality patterns

Discuss the stationarity of the following time series:

- (1)  $\{X_t : t \in \mathcal{T}\} = \{\varepsilon, \eta, \varepsilon, \eta, \dots\}$ , i.e.,  $X_{2t-1} = \varepsilon$ ,  $X_{2t} = \eta$ , where  $\varepsilon \sim \mathcal{N}(0, 1)$ ,  $\eta \sim \mathcal{U}(-\sqrt{3}, \sqrt{3})$ , and  $\varepsilon$  and  $\eta$  are independent.
- (2)  $\{Y_t : t \in \mathcal{T}\}$  is an i.i.d. standard Cauchy distributed sequence with density  $f(x) = \frac{1}{\pi(1+x^2)}$ .
- (3)  $\{Y_t : t \in \mathcal{T}\}$  is i.i.d. with  $Y_t \sim \mathcal{N}(0, 1)$ .
- (4)  $\{\varepsilon, \eta, \xi_3, \xi_4, \dots\}$ , where  $\varepsilon \sim \mathcal{N}(0, 1)$ ,  $\eta \sim t_1$  (Student  $t$ -distribution with degree of freedom 1), and  $\{\xi_j : j = 3, 4, \dots\}$  is i.i.d.  $\sim \text{Exp}(1)$ .