

# Time Series Analysis

## Lecture 4 ARIMA modelling

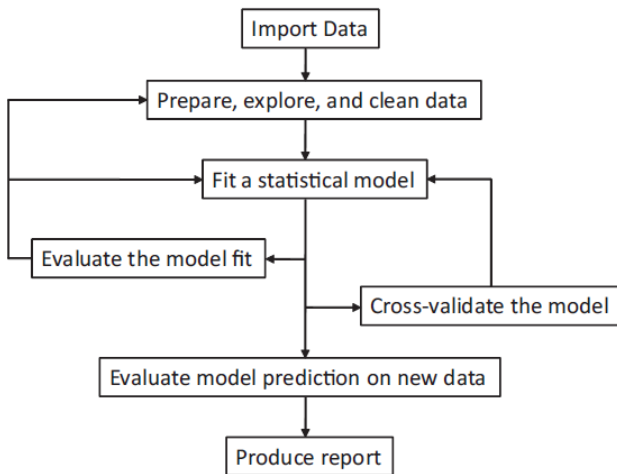
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- Model Steps
- Model Specification
- Model Estimation
- Model Checking
- Model Selection

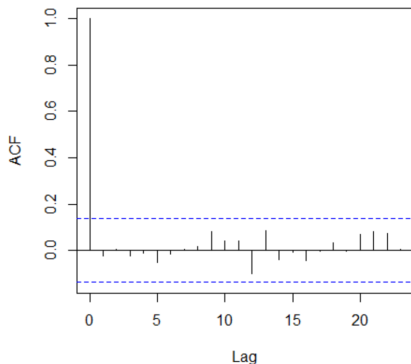
# Modeling Steps

All models are wrong, but some are useful—George, E.P.Box

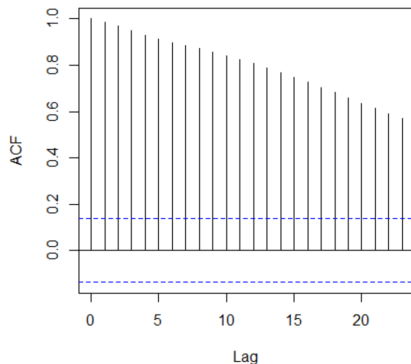


# Illustrations of Simulated Time Series

White Noise

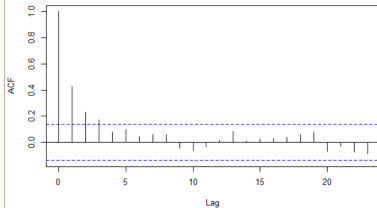


Random Walk

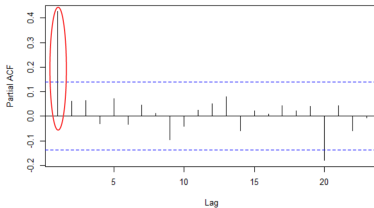


# Illustrations of Simulated Time Series

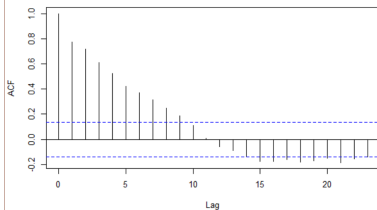
AR(1),  $\phi_1 = 0.5$



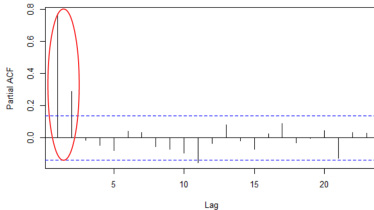
AR(1),  $\phi_1 = 0.5$



AR(2),  $\phi_1 = 0.5, \phi_2 = 0.3$

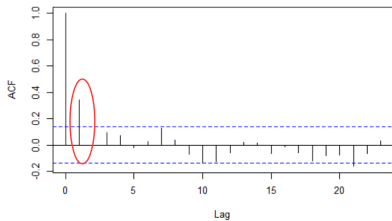


AR(2),  $\phi_1 = 0.5, \phi_2 = 0.3$

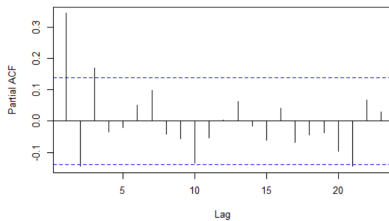


# Illustrations of Simulated Time Series

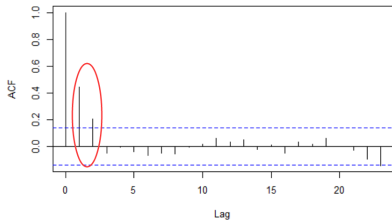
MA(1):  $\theta_1 = 0.5$



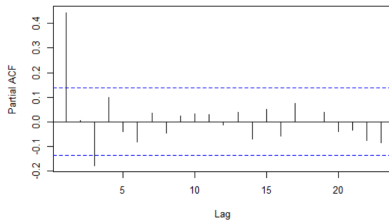
MA(1):  $\theta_1 = 0.5$



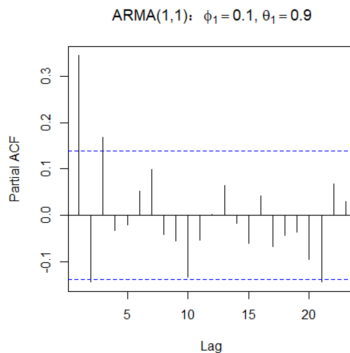
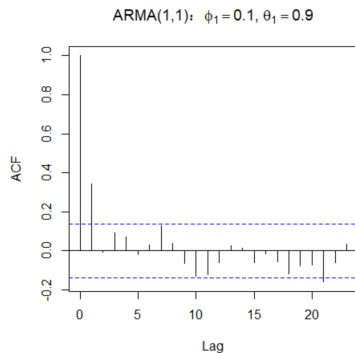
MA(2):  $\theta_1 = 0.6, \theta_2 = 0.3$



MA(2):  $\theta_1 = 0.6, \theta_2 = 0.3$



# Illustrations of Simulated Time Series



# Model Specification

1. If the sample ACF  $\hat{\rho}_k$  are close to 1 for all small  $k$  and decay slowly, difference the data first. 存在非平稳结构
2. For the sample ACF  $\hat{\rho}_k$ , we have

$$\sqrt{T} \hat{\rho}_k \xrightarrow{d} N(0, 1 + 2 \sum_{j=1}^{k-1} \rho_j^2),$$

hence if it is bounded by  $\frac{1.96}{\sqrt{T}} \left[ 1 + 2 \sum_{j=1}^{k-1} \hat{\rho}_j^2 \right]^{1/2}$  for any  $k > q$ , we can try an MA( $q$ ) model to the data.

3. For the sample PACF  $\hat{\pi}_k$ ,

$$\sqrt{T} \hat{\pi}_k \xrightarrow{d} N(0, 1),$$

hence, if it is bounded by  $1.96/\sqrt{T}$  for any  $k > p$ , we can try an AR( $p$ ) model to the data.

4. In general, the correct  $(p, q)$  is not unique. We can select the best one by AIC/BIC.



## Ordinary Least Square of AR( $p$ ) Model

- Consider an AR( $p$ ) model,

$$y_t = \phi_0 + \phi_1 y_{t-1} + \phi_2 y_{t-2} + \cdots + \phi_p y_{t-p} + e_t.$$

The parameter space  $\theta = (\phi', \sigma^2)$ ,  $\phi = (\phi_0, \phi_1, \dots, \phi_p)'$ .

- The **OLS** estimates of coefficients:

$$\begin{aligned}(\hat{\phi}_0, \hat{\phi}_1, \dots, \hat{\phi}_p) &= \underset{t=p+1}{\operatorname{argmin}} \sum^T (y_t - \phi_0 - \phi_1 y_{t-1} - \cdots - \phi_p y_{t-p})^2 \\ &= \underset{t=p+1}{\operatorname{argmin}} S_C(\phi_0, \phi_1, \dots, \phi_p)\end{aligned}$$

# OLS of AR( $p$ )

- Let  $x_t = (1, y_{t-1}, y_{t-2}, \dots, y_{t-p})'$  and  $\phi = (\phi_0, \phi_1, \dots, \phi_p)'$ . Then,

$$\begin{aligned}\hat{\phi}_{OLS} &= \left( \sum_{t=p+1}^T x_t x_t' \right)^{-1} \sum_{t=p+1}^T x_t y_t \\ &= \phi + \left( \sum_{t=p+1}^T x_t x_t' \right)^{-1} \sum_{t=p+1}^T x_t e_t.\end{aligned}$$

- $$\hat{\sigma}_e^2 = \frac{1}{T-p} S_C(\hat{\phi}_0, \hat{\phi}_1, \dots, \hat{\phi}_p).$$

# MLE for $AR(p)$ Model

- Consider the following  $AR(p)$  process:

$$Y_t = \phi_0 + \phi_1 Y_{t-1} + \phi_2 Y_{t-2} + \dots + \phi_p Y_{t-p} + \varepsilon_t,$$

where  $\varepsilon_t$  is i.i.d  $N(0, \sigma^2)$ .

- The **parameter vector** is  $\theta = \{\phi_0, \phi_1, \phi_2, \dots, \phi_p, \sigma^2\}$ .
- For  $Y_t$ ,  $t > p$ , the conditional distribution is

$$(Y_t | Y_{t-1}, Y_{t-2}, \dots, Y_{t-p}) \sim N(\phi_0 + \phi_1 y_{t-1} + \phi_2 y_{t-2} \dots + \phi_p y_{t-p}, \sigma^2)$$

- the conditional density is

$$\begin{aligned} & f_{Y_t | Y_{t-1}, Y_{t-2}, \dots, Y_{t-p}}(y_t | y_{t-1}, y_{t-2}, \dots, y_{t-p}, \theta) \\ &= \frac{1}{\sqrt{2\pi}\sigma} \exp\left(-\frac{(y_t - \phi_0 - \phi_1 y_{t-1} - \phi_2 y_{t-2} \dots - \phi_p y_{t-p})^2}{2\sigma^2}\right). \end{aligned}$$

# MLE for $AR(p)$ process

- Assume  $\mathbf{y}_p = (y_1, y_2, \dots, y_p)$ .
- Conditional MLE: assume  $\mathbf{y}_p$  to be deterministic.
- The conditional likelihood function

$$\begin{aligned} L(\theta) &= \sum_{t=p+1}^T \log(f_{Y_t|Y_{t-1}, Y_{t-2}, \dots, Y_{t-p}}(y_t | y_{t-1}, y_{t-2}, \dots, y_{t-p}, \theta)) \\ &= -(T-p)/2 \log(2\pi\sigma^2) - \sum_{t=p+1}^T \frac{(y_t - \phi_0 - \phi_1 y_{t-1} - \dots - \phi_p y_{t-p})^2}{2\sigma^2}. \end{aligned}$$

# MLE of AR( $p$ ) model

- Unconditional MLE: assume  $\mathbf{y}_p$  to be random vector
- the log likelihood function is

$$\begin{aligned} L(\theta) &= \log(f_{Y_T, Y_{T-1}, Y_{T-2}, \dots, Y_1}(y_T, y_{T-1}, \dots, y_1, \theta)) \\ &= -T/2 \log(2\pi) - T/2 \log(\sigma^2) + \\ &\quad \frac{1}{2\sigma^2} \log |V_p^{-1}| - \frac{1}{2\sigma^2} (\mathbf{y}_P - \mu_P)' V_p^{-1} (\mathbf{y}_P - \mu_P) \\ &\quad - \sum_{t=p+1}^T \frac{(y_t - \phi_0 - \phi_1 y_{t-1} - \phi_2 y_{t-2} \dots - \phi_p y_{t-p})^2}{2\sigma^2} \end{aligned}$$

# Conditional MLE for AR(1)

Consider AR(1) model:  $y_t = \phi_0 + \phi_1 y_{t-1} + e_t$ ,  $e_t \sim i.i.d.(0, \sigma^2)$ .

- Assume  $y_1$  be given as deterministic.

$$y_2|y_1 = y_1 \sim N(\phi_0 + \phi_1 y_1, \sigma^2)$$

- The conditional density function is

$$f(y_2|y_1, \phi) = \frac{1}{\sqrt{2\pi}\sigma} \exp\left(\frac{-(y_2 - \phi_0 - \phi_1 y_1)^2}{2\sigma^2}\right).$$

- The conditional joint density is

$$f(y_T, y_{T-1}, \dots, y_2|y_1, \theta) = \prod_{t=2}^T f(y_t|y_{t-1}, \theta)$$

# Conditional MLE for AR(1)

- The conditional log likelihood function

$$\begin{aligned} L(\theta) &= \sum_{t=2}^T \log(f(y_t|y_{t-1}, \theta)) \\ &= -\left(\frac{T-1}{2}\right) \log(2\pi\sigma^2) - \sum_{t=2}^T \frac{(y_t - \phi_0 - \phi y_{t-1})^2}{2\sigma^2}. \end{aligned}$$

- The conditional MLE for  $\theta$  is defined as

$$\hat{\theta} = \arg \max_{\theta} L(\theta).$$

# Conditional MLE for AR(1)

For  $\hat{\sigma}^2$ , the first order condition is

$$-\frac{T-1}{2\sigma^2} + \sum_{t=2}^T \frac{(y_t - \phi_0 - \phi y_{t-1})^2}{2\sigma^4} = 0.$$

and the solution is

$$\hat{\sigma}^2 = \sum_{t=2}^T \frac{(y_t - \hat{\phi}_0 - \hat{\phi} y_{t-1})^2}{T-1}.$$



## Testing for residual autocorrelations



$$H_0 : \rho_1 = \rho_2 = \dots = 0 \leftrightarrow H_1 : \exists j, \text{ such that } \rho_j \neq 0.$$

- Joint significance test of the first  $m$  residual autocorrelations.
- Ljung-Box typed test statistics:

$$T_m = n(n+2) \sum_{k=1}^m \frac{\rho_k^2(\hat{e})}{n-k} \sim \chi_{m-K}^2.$$

where

$$\rho_k(\hat{e}) = \frac{\sum_{t=k+1}^n \hat{e}_t \hat{e}_{t-k}}{\sum_{t=k+1}^n \hat{e}_t^2}$$

and  $K$  is the number of unknown parameters.

## Testing for Normality

- The skewness and kurtosis of  $\hat{e}_t$  can be calculated as

$$\widehat{SK}_{\hat{e}} = \frac{\hat{m}_3}{\sqrt{\hat{m}_2^3}}, \quad \text{and} \quad \widehat{K}_{\hat{e}} = \frac{\hat{m}_4}{\hat{m}_2^2}.$$

where  $\hat{m}_j = \frac{1}{n} \sum_{t=1}^n \hat{e}_t^j$ ,

- Under the null hypothesis of normality,

$$\sqrt{n/6} \cdot \widehat{SK}_{\hat{e}} \sim \mathcal{N}(0, 1), \quad \sqrt{n/24} \cdot (\widehat{K}_{\hat{e}} - 3) \sim \mathcal{N}(0, 1).$$

- A joint test for normality (Jarque and Bera, 1987):

$$JB = \frac{n}{6} \widehat{SK}_{\hat{e}}^2 + \frac{n}{24} (\widehat{K}_{\hat{e}} - 3)^2 \sim \chi^2_2.$$

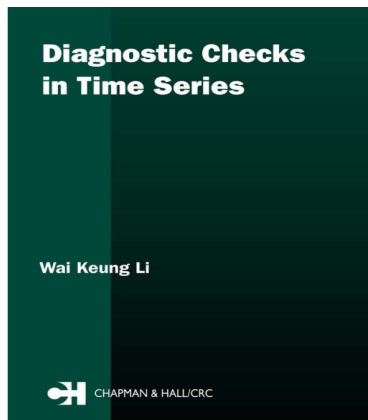


Figure 1: Li,WaiKeung.(2004). Diagnostic Checks in Time Series. Chapman& Hall/CRC

# Model Selection: Order Determination

- Akaike information criterion (AIC):  $-2L(\hat{\theta}) + 2k$
- Bayesian information criterion (BIC):  $-2L(\hat{\theta}) + \ln(T)k$
- Compared to the AIC, the BIC counteracts the overfitting tendency of the AIC.
- Other information criterions.