

## Counterclockwise Rotation

If you want to rotate a vector  $r$  with coordinates  $(x, y)$  and angle  $\alpha$  counterclockwise over an angle  $\beta$  to get vector  $r'$  with coordinates  $(x', y')$  then the following holds:

$$x = r * \cos(\alpha)$$

$$y = r * \sin(\alpha)$$

$$x' = r' * \cos(\alpha + \beta)$$

$$y' = r' * \sin(\alpha + \beta)$$

Trigonometric addition gives us:

$$\cos(\alpha + \beta) = \cos(\alpha)\cos(\beta) - \sin(\alpha)\sin(\beta)$$

$$\sin(\alpha + \beta) = \cos(\alpha)\sin(\beta) + \sin(\alpha)\cos(\beta)$$

As the length of the vector stays the same,

$$x' = r * \cos(\alpha)\cos(\beta) - r * \sin(\alpha)\sin(\beta)$$

$$y' = r * \cos(\alpha)\sin(\beta) + r * \sin(\alpha)\cos(\beta)$$

This equates to:

$$x' = x * \cos(\beta) - y * \sin(\beta)$$

$$y' = x * \sin(\beta) + y * \cos(\beta)$$

Written as matrix multiplication with row vectors, this becomes,

$$[x', y'] = [x, y] \cdot \begin{bmatrix} \cos(\beta) & \sin(\beta) \\ -\sin(\beta) & \cos(\beta) \end{bmatrix}$$

with the rotation matrix equal to,

$$R = \begin{bmatrix} \cos(\beta) & \sin(\beta) \\ -\sin(\beta) & \cos(\beta) \end{bmatrix}$$

Written as matrix multiplication with column vectors, this becomes,

$$\begin{bmatrix} x' \\ y' \end{bmatrix} = \begin{bmatrix} \cos(\beta) & -\sin(\beta) \\ \sin(\beta) & \cos(\beta) \end{bmatrix} \cdot \begin{bmatrix} x \\ y \end{bmatrix}$$

with the rotation matrix equal to,

$$R = \begin{bmatrix} \cos(\beta) & -\sin(\beta) \\ \sin(\beta) & \cos(\beta) \end{bmatrix}$$

Note that the position of  $-\sin(\beta)$  in the rotation matrix has changed.

### **Clockwise Rotation**

If rotation is clockwise, then the rotation matrix for multiplication with row vectors becomes,

$$R = \begin{bmatrix} \cos(-\beta) & \sin(-\beta) \\ -\sin(-\beta) & \cos(-\beta) \end{bmatrix}$$

As  $\sin(-\beta) = -\sin(\beta)$  and  $\cos(-\beta) = \cos(\beta)$

this equates to

$$R = \begin{bmatrix} \cos(\beta) & -\sin(\beta) \\ \sin(\beta) & \cos(\beta) \end{bmatrix}$$

So clockwise rotation of a vector  $[x, y]$  can be expressed as,

$$[x', y'] = [x, y] \cdot \begin{bmatrix} \cos(\beta) & -\sin(\beta) \\ \sin(\beta) & \cos(\beta) \end{bmatrix}$$

So clockwise rotation of a vector  $[x, y]$  can be expressed as,

$$[x', y'] = [x, y] \cdot \begin{bmatrix} \cos(\beta) & -\sin(\beta) \\ \sin(\beta) & \cos(\beta) \end{bmatrix}$$

The rotation matrix for multiplication with column vectors becomes,

$$R = \begin{bmatrix} \cos(-\beta) & -\sin(-\beta) \\ \sin(-\beta) & \cos(-\beta) \end{bmatrix}$$

which equates to,

$$R = \begin{bmatrix} \cos(\beta) & \sin(\beta) \\ -\sin(\beta) & \cos(\beta) \end{bmatrix}$$

So clockwise rotation of a vector  $\begin{bmatrix} x \\ y \end{bmatrix}$  can be expressed as,

$$\begin{bmatrix} x' \\ y' \end{bmatrix} = \begin{bmatrix} \cos(\beta) & \sin(\beta) \\ -\sin(\beta) & \cos(\beta) \end{bmatrix} \cdot \begin{bmatrix} x \\ y \end{bmatrix}$$

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