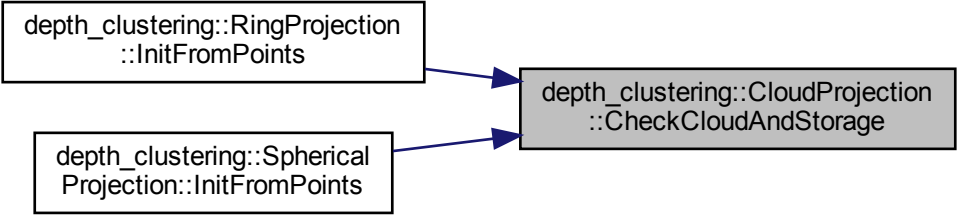


depth_clustering::RingProjection
::InitFromPoints

depth_clustering::Spherical
Projection::InitFromPoints

depth_clustering::CloudProjection
::CheckCloudAndStorage



```
graph LR; A[depth_clustering::RingProjection::InitFromPoints] --> C[depth_clustering::CloudProjection::CheckCloudAndStorage]; B[depth_clustering::Spherical Projection::InitFromPoints] --> C;
```