

Key Mathematical Formulations for 3D Ligand–Pharmacophore Mapping (DiffPhore)

Problem Definition

$$\hat{G}_l = \text{Model}(G_p, G_l), \quad (1)$$

where G_p denotes the pharmacophore model (graphical 3D representation), G_l is the input ligand conformation, and \hat{G}_l is the generated ligand conformation (same chemistry as G_l , different 3D pose).

The learning goal is to approximate the conditional density

$$P(\hat{G}_l | G_p, G_l), \quad (2)$$

whose score (gradient of log-density) guides denoising/generation.

Score-based Generative Modeling

Langevin dynamics (generic). Given a stepsize $\epsilon > 0$ and Gaussian noise $z_t \sim \mathcal{N}(0, I)$, iterative denoising is

$$\hat{G}_{l,t} = \hat{G}_{l,t-1} + \epsilon \nabla_{\hat{G}_{l,t-1}} \log P(\hat{G}_{l,t-1} | G_p, G_l) + \sqrt{2\epsilon} z_t, \quad 1 \leq t \leq T. \quad (3)$$

Gaussian perturbation at noise level σ . At step t with noise scale σ_t , the perturbed sample is modeled as

$$P_\sigma(G_{l,t} | G_l^*, G_p) = \mathcal{N}(G_{l,t} | G_l^*, \sigma^2 I), \quad (4)$$

with a decreasing schedule $\sigma_1 > \sigma_2 > \dots > \sigma_T$.

Score network training loss. Let $\text{CFGenerator}(G_{l,t}, G_p, \sigma_t)$ estimate the score $\nabla_{G_{l,t}} \log P_{\sigma_t}(G_{l,t} | G_l^*)$. The denoising score matching loss is

$$\mathcal{L} = \frac{1}{T} \sum_{t=1}^T \sigma_t^2 \mathbb{E}_{G_l^* \sim P_{\text{data}}} \mathbb{E}_{G_{l,t} \sim P_{\sigma_t}(\cdot | G_l^*)} \left\| \text{CFGenerator}(G_{l,t}, G_p, \sigma_t) - \nabla_{G_{l,t}} \log P_{\sigma_t}(G_{l,t} | G_l^*) \right\|^2. \quad (5)$$

Generation-time Langevin (with learned score). At inference, replace the true score with the network output:

$$\hat{G}_{l,t} = \hat{G}_{l,t-1} + \epsilon_{t-1} \text{CFGenerator}(\hat{G}_{l,t-1}, G_p, \sigma_{t-1}) + \sqrt{2\epsilon_{t-1}} z_t, \quad 1 \leq t \leq T. \quad (6)$$

Knowledge-guided LPM Representation

Heterogeneous geometric graph. At step t , the LPM encoder builds

$$G_t = \text{LPMEncoder}(G_{l,t}, G_p) = \{ G_{l,t}, G_p, G_{lp} \}, \quad (7)$$

where $G_{l,t}$ is the ligand graph (atoms V_l , coordinates x_t , edges E_l), G_p is the pharmacophore graph (feature points V_p , coordinates x_p , edges E_p plus connections from exclusion spheres), and G_{lp} is a bipartite graph linking ligand atoms to pharmacophore points. The bipartite features include type-matching vectors V_{lp} and direction-matching vectors N_{lp} .

Geometry: Translations, Rotations, and Torsions

Conformation manifold. Let m be the number of rotatable bonds. A ligand conformation lies on an $(m + 6)$ -dimensional product space

$$g = (r, R, \theta) \in \mathcal{P}, \quad (8)$$

$$\mathcal{P} = \mathbb{T}^3 \times \text{SO}(3) \times \text{SO}(2)^m, \quad (9)$$

where $r \in \mathbb{T}^3$ (translation), $R \in \text{SO}(3)$ (rotation), and $\theta \in \text{SO}(2)^m$ (torsion angles).

Applying a pose update. Given coordinates x_t at step t , a pose update $g = (r, R, \theta)$ yields

$$x_{t-\Delta t} = \mathcal{A}(r, R, \theta; x_t) = \mathcal{A}_{\text{tr}}(r) \mathcal{A}_{\text{rot}}(R) \mathcal{A}_{\text{tor}}(\theta) x_t. \quad (10)$$

Predicting change directions (scores). Rather than predicting absolute poses, the generator outputs score-like directions:

$$(\alpha, \beta, \gamma) = \text{CFGGenerator}(G_t, t), \quad (11)$$

interpretable as directions for translation Δr , rotation ΔR , and torsions $\Delta \theta$, respectively.