

## Lecture 9: Linear Regression

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Mathematics for Machine Learning

<https://yung-web.github.io/home/courses/mathml.html>

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### Roadmap

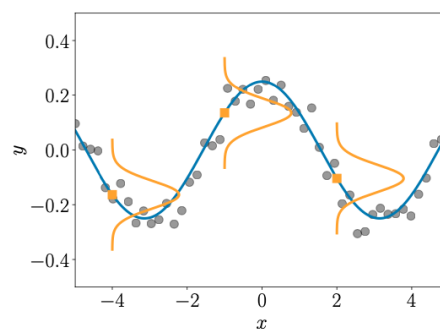
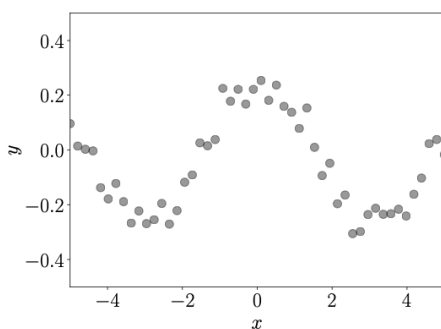
- Problem Formulation
- Parameter Estimation: ML
- Parameter Estimation: MAP
- Bayesian Linear Regression
- Maximum Likelihood as Orthogonal Projection

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## Regression Problem



- For some input values  $x_n$ , we observe noisy function values  $y_n = f(x_n) + \epsilon$
- Goal: infer the function  $f$  that generalizes well to function values at new inputs
- Applications: time-series analysis, control and robotics, image recognition, etc.

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- Linear regression, Gaussian noise
- Notation for simplification (this is how the textbook uses)

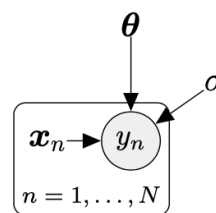
$$p(y|\mathbf{x}) = p_{Y|\mathbf{X}}(y|\mathbf{x}), \quad Y \sim \mathcal{N}(\mu, \sigma^2) \xrightarrow{\text{simplifies}} \mathcal{N}(y | f(\mathbf{x}), \sigma^2)$$

- Likelihood: for  $\mathbf{x} \in \mathbb{R}^D$  and  $y \in \mathbb{R}$ ,  $p(y | \mathbf{x}) = \mathcal{N}(y | f(\mathbf{x}), \sigma^2)$
- $y = f(\mathbf{x}) + \epsilon$ , where  $\epsilon \sim \mathcal{N}(0, \sigma^2)$
- Linear regression with the parameter  $\boldsymbol{\theta} \in \mathbb{R}^D$

$$p(y | \mathbf{x}) = \mathcal{N}(y | \mathbf{x}^\top \boldsymbol{\theta}, \sigma^2) \iff y = \mathbf{x}^\top \boldsymbol{\theta} + \epsilon, \quad \epsilon \sim \mathcal{N}(0, \sigma^2)$$

Prior with Gaussian noise:  $p(y | \mathbf{x}) = \mathcal{N}(y | \mathbf{x}^\top \boldsymbol{\theta}, \sigma^2)$

- Training set  $\mathcal{D} = \{(\mathbf{x}_1, y_1), \dots, (\mathbf{x}_N, y_N)\}$



- Assuming iid of  $N$  data, the likelihood is factorized into:

$$p(\mathcal{Y} | \mathcal{X}, \boldsymbol{\theta}) = \prod_{n=1}^N p(y_n | \mathbf{x}_n, \boldsymbol{\theta}) = \prod_{n=1}^N \mathcal{N}(y_n | \mathbf{x}_n^\top \boldsymbol{\theta}, \sigma^2),$$

where  $\mathcal{X} = \{\mathbf{x}_1, \dots, \mathbf{x}_n\}$  and  $\mathcal{Y} = \{y_1, \dots, y_n\}$

- ML and MAP

- Problem Formulation
- **Parameter Estimation: ML**
- Parameter Estimation: MAP
- Bayesian Linear Regression
- Maximum Likelihood as Orthogonal Projection

## MLE (Maximum Likelihood Estimation) (1)

- $\theta_{\text{ML}} = \arg \max_{\theta} p(\mathcal{Y} \mid \mathcal{X}, \theta) = \arg \min_{\theta} \left( -\log p(\mathcal{Y} \mid \mathcal{X}, \theta) \right)$
- For Gaussian noise with  $\mathbf{X} = [\mathbf{x}_1, \dots, \mathbf{x}_n]^T$  and  $\mathbf{y} = [y_1, \dots, y_n]^T$ ,

$$\begin{aligned} -\log p(\mathcal{Y} \mid \mathcal{X}, \theta) &= -\log \prod_{n=1}^N p(y_n \mid \mathbf{x}_n, \theta) = -\sum_{n=1}^N \log p(y_n \mid \mathbf{x}_n, \theta) \\ &= \frac{1}{2\sigma^2} \sum_{n=1}^N (y_n - \mathbf{x}_n^T \theta)^2 + \text{const} = \frac{1}{2\sigma^2} \|\mathbf{y} - \mathbf{X}\theta\|^2 + \text{const} \end{aligned}$$

Negative-log likelihood for  $f(\mathbf{x}) = \mathbf{x}^T \theta + \mathcal{N}(0, \sigma^2)$ :

$$-\log p(\mathcal{Y} \mid \mathcal{X}, \theta) = \frac{1}{2\sigma^2} \|\mathbf{y} - \mathbf{X}\theta\|^2 + \text{const}$$

- For Gaussian noise with  $\mathbf{X} = [\mathbf{x}_1, \dots, \mathbf{x}_n]^T$  and  $\mathbf{y} = [y_1, \dots, y_n]^T$ ,

$$\theta_{\text{ML}} = \arg \min_{\theta} \frac{1}{2\sigma^2} \|\mathbf{y} - \mathbf{X}\theta\|^2, \quad L(\theta) = \frac{1}{2\sigma^2} \|\mathbf{y} - \mathbf{X}\theta\|^2$$

- In this special case of Gaussian noise, finding MLE is equivalent to finding  $\theta$  that minimizes the empirical risk with squared loss function
  - Models as functions = Model as probabilistic models
- We find  $\theta$  such that  $\frac{dL}{d\theta} = 0$

$$\frac{dL}{d\theta} = \frac{1}{2\sigma^2} \left( -2(\mathbf{y} - \mathbf{X}\theta)^T \mathbf{X} \right) = \frac{1}{\sigma^2} \left( -\mathbf{y}^T \mathbf{X} + \theta^T \mathbf{X}^T \mathbf{X} \right) = 0$$

$$\iff \theta_{\text{ML}}^T \mathbf{X}^T \mathbf{X} = \mathbf{y}^T \mathbf{X}$$

$$\iff \theta_{\text{ML}}^T = \mathbf{y}^T \mathbf{X} (\mathbf{X}^T \mathbf{X})^{-1} \quad (\mathbf{X}^T \mathbf{X} \text{ is positive definite if } \text{rk}(\mathbf{X}) = D)$$

$$\iff \theta_{\text{ML}} = (\mathbf{X}^T \mathbf{X})^{-1} \mathbf{X}^T \mathbf{y}$$

## MLE with Features

- Linear regression: Linear in the parameters
  - $\phi(\mathbf{x})^T \theta$  is also fine, where  $\phi(\mathbf{x})$  can be non-linear (we will cover this later)
  - $\phi(\mathbf{x})$  are the features
- Linear regression with the parameter  $\theta \in \mathbb{R}^K$ ,  $\phi(\mathbf{x}) : \mathbb{R}^D \mapsto \mathbb{R}^K$ :

$$p(y | \mathbf{x}) = \mathcal{N}(y | \phi(\mathbf{x})^T \theta, \sigma^2) \iff y = \phi(\mathbf{x})^T \theta + \epsilon = \sum_{k=0}^{K-1} \theta_k \phi_k(\mathbf{x}) + \epsilon$$

- Example. Polynomial regression.** For  $x \in \mathbb{R}$  and  $\theta \in \mathbb{R}^K$ , we lift the original 1-D input into  $K$ -D feature space with monomials  $x^k$ :

$$\phi(x) = \begin{pmatrix} \phi_0(x) \\ \vdots \\ \phi_{K-1}(x) \end{pmatrix} = \begin{pmatrix} 1 \\ \vdots \\ x^{K-1} \end{pmatrix} \in \mathbb{R}^K \implies f(x) = \sum_{k=0}^{K-1} \theta_k x^k$$

- Now, for the entire training set  $\{\mathbf{x}_1, \dots, \mathbf{x}_N\}$ ,

$$\Phi := \begin{pmatrix} \phi^T(\mathbf{x}_1) \\ \vdots \\ \phi^T(\mathbf{x}_N) \end{pmatrix} = \begin{pmatrix} \phi_0(\mathbf{x}_1) & \cdots & \phi_{K-1}(\mathbf{x}_1) \\ \vdots & \cdots & \vdots \\ \phi_0(\mathbf{x}_N) & \cdots & \phi_{K-1}(\mathbf{x}_N) \end{pmatrix} \in \mathbb{R}^{N \times K}, \quad \Phi_{ij} = \phi_j(\mathbf{x}_i), \quad \phi_j : \mathbb{R}^D \mapsto \mathbb{R}$$

- Negative log-likelihood: Similarly to the case of  $\mathbf{y} = \mathbf{X}\boldsymbol{\theta}$ ,

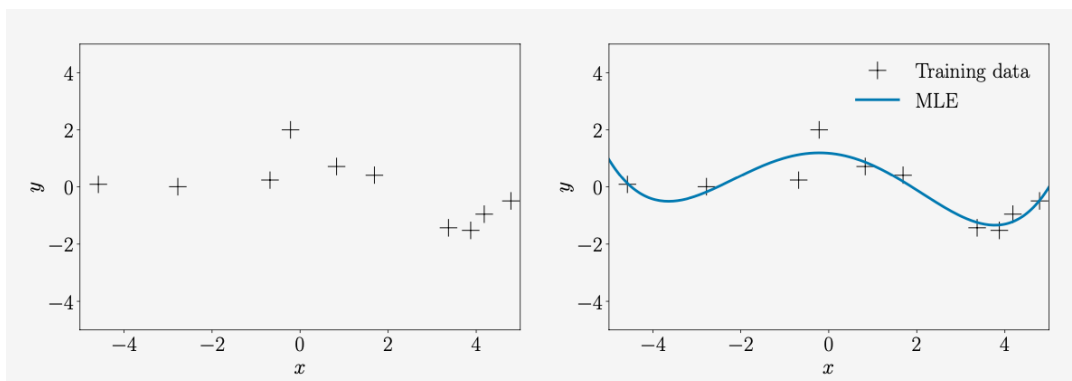
- $p(\mathcal{Y}|\mathcal{X}, \boldsymbol{\theta}) = \mathcal{N}(\mathbf{y} | \Phi\boldsymbol{\theta}, \sigma^2 \mathbf{I})$
- Negative-log likelihood for  $f(\mathbf{x}) = \phi^T(\mathbf{x})\boldsymbol{\theta} + \mathcal{N}(0, \sigma^2)$ :

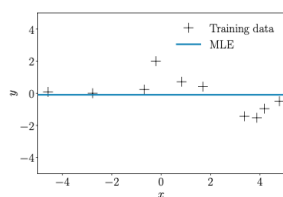
$$-\log p(\mathcal{Y} | \mathcal{X}, \boldsymbol{\theta}) = \frac{1}{2\sigma^2} \|\mathbf{y} - \Phi\boldsymbol{\theta}\|^2 + \text{const}$$

- MLE:  $\boldsymbol{\theta}_{\text{ML}} = (\Phi^T \Phi)^{-1} \Phi^T \mathbf{y}$

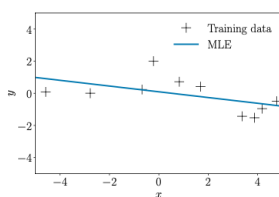
## Polynomial Fit

- $N = 10$  data, where  $x_n \sim \mathcal{U}[-5, 5]$  and  $y_n = -\sin(x_n/5) + \cos(x_n) + \epsilon$ ,  $\epsilon \sim \mathcal{N}(0, 0.2^2)$
- Fit with polynomial with degree 4 using ML

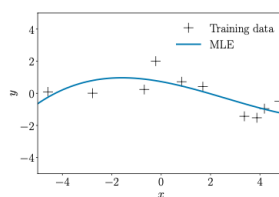




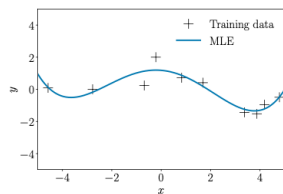
(a)  $M = 0$



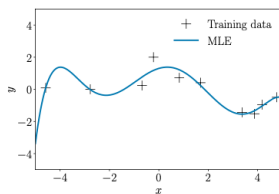
(b)  $M = 1$



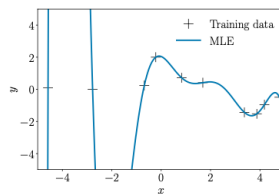
(c)  $M = 3$



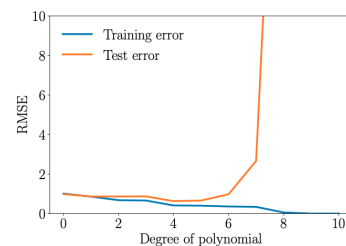
(d)  $M = 4$



(e)  $M = 6$



(f)  $M = 9$



- Higher polynomial degree is better (training error always decreases)
- Test error increases after some polynomial degree

- Problem Formulation
- Parameter Estimation: ML
- **Parameter Estimation: MAP**
- Bayesian Linear Regression
- Maximum Likelihood as Orthogonal Projection

- MLE: prone to overfitting, where the magnitude of the parameters becomes large.
- a prior distribution  $p(\theta)$  helps: what  $\theta$  is plausible
- MAPE and Bayes' theorem

$$p(\theta | \mathcal{X}, \mathcal{Y}) = \frac{p(\mathcal{Y} | \mathcal{X}, \theta)p(\theta)}{p(\mathcal{Y} | \mathcal{X})} \implies \theta_{\text{MAP}} \in \arg \min_{\theta} \left( -\log p(\mathcal{Y} | \mathcal{X}, \theta) - \log p(\theta) \right)$$

- Gradient

$$-\frac{d \log p(\theta | \mathcal{X}, \mathcal{Y})}{d\theta} = -\frac{d \log p(\mathcal{Y} | \mathcal{X}, \theta)}{d\theta} - \frac{d \log p(\theta)}{d\theta}$$

- **Example.** A (conjugate) Gaussian prior  $p(\theta) \sim \mathcal{N}(0, b^2 I)$ 
  - For Gaussian likelihood, Gaussian prior  $\implies$  Gaussian posterior
- Negative log-posterior

Negative-log posterior for  $f(\mathbf{x}) = \phi^T(\mathbf{x})\theta + \mathcal{N}(0, \sigma^2)$  and  $p(\theta) \sim \mathcal{N}(0, b^2 I)$ :

$$-\log p(\theta | \mathcal{X}, \mathcal{Y}) = \frac{1}{2\sigma^2}(\mathbf{y} - \Phi\theta)^T(\mathbf{y} - \Phi\theta) + \frac{1}{2b^2}\theta^T\theta + \text{const}$$

- Gradient

$$-\frac{d \log p(\theta | \mathcal{X}, \mathcal{Y})}{d\theta} = \frac{1}{\sigma^2}(\theta^T \Phi^T \Phi - \mathbf{y}^T \Phi) + \frac{1}{b^2}\theta^T$$



- MAP vs. ML

$$\theta_{\text{MAP}} = \underbrace{\left( \Phi^T \Phi + \frac{\sigma^2}{b^2} I \right)}_{(*)}^{-1} \Phi^T \mathbf{y}, \quad \theta_{\text{ML}} = (\Phi^T \Phi)^{-1} \Phi^T \mathbf{y}$$

- The term  $\frac{\sigma^2}{b^2} I$ 
  - Ensures that  $(*)$  is symmetric, strictly positive definite
  - Role of regularizer

- **Example.** A (conjugate) Gaussian prior  $p(\theta) \sim \mathcal{N}(\mathbf{m}_0, \mathbf{S}_0)$
- Negative log-posterior

Negative-log posterior for  $f(\mathbf{x}) = \phi^T(\mathbf{x})\theta + \mathcal{N}(0, \sigma^2)$  and  $p(\theta) \sim \mathcal{N}(\mathbf{m}_0, \mathbf{S}_0)$ :

$$-\log p(\theta | \mathcal{X}, \mathcal{Y}) = \frac{1}{2\sigma^2} (\mathbf{y} - \Phi\theta)^T (\mathbf{y} - \Phi\theta) + \frac{1}{2} (\theta - \mathbf{m}_0)^T \mathbf{S}_0^{-1} (\theta - \mathbf{m}_0) + \text{const}$$

- We will use this later for computing the parameter posterior distribution in Bayesian linear regression.

- Explicit regularizer in regularized least squares (RLS)

$$\|\mathbf{y} - \Phi\boldsymbol{\theta}\|^2 + \lambda \|\boldsymbol{\theta}\|^2$$

- MAPE with Gaussian prior  $p(\boldsymbol{\theta}) \sim \mathcal{N}(0, b^2 \mathbf{I})$ 
  - Negative log-Gaussian prior

$$-\log p(\boldsymbol{\theta}) = \frac{1}{2b^2} \boldsymbol{\theta}^T \boldsymbol{\theta} + \text{const}$$

- $\lambda = 1/2b^2$  is the regularization term
- Not surprising that we have

$$\boldsymbol{\theta}_{\text{RLS}} = \left( \Phi^T \Phi + \lambda \mathbf{I} \right)^{-1} \Phi^T \mathbf{y}$$

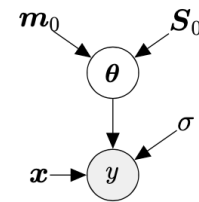
- Problem Formulation
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- Earlier, ML and MAP. Now, **fully Bayesian**
- Model

prior  $p(\boldsymbol{\theta}) \sim \mathcal{N}(\mathbf{m}_0, \mathbf{S}_0)$

likelihood  $p(y|\mathbf{x}, \boldsymbol{\theta}) \sim \mathcal{N}(y | \boldsymbol{\phi}^\top(\mathbf{x})\boldsymbol{\theta}, \sigma^2)$

joint  $p(y, \boldsymbol{\theta}|\mathbf{x}) = p(y | \mathbf{x}, \boldsymbol{\theta})p(\boldsymbol{\theta})$



- Goal: For an input  $\mathbf{x}_*$ , we want to compute the following **posterior predictive distribution** of  $y_*$ :

$$p(y_*|\mathbf{x}_*, \mathcal{X}, \mathcal{Y}) = \int \overbrace{p(y_*|\mathbf{x}_*, \boldsymbol{\theta})}^{\text{likelihood}} \overbrace{p(\boldsymbol{\theta}|\mathcal{X}, \mathcal{Y})}^{(*)} d\boldsymbol{\theta}$$

- $(*)$ : parameter posterior distribution that needs to be computed

## Parameter Posterior Distribution (1)

- **Parameter posterior distribution**

$$p(\boldsymbol{\theta} | \mathcal{X}, \mathcal{Y}) = \mathcal{N}(\boldsymbol{\theta} | \mathbf{m}_N, \mathbf{S}_N), \quad \text{where}$$

$$\mathbf{S}_N = (\mathbf{S}_0^{-1} + \sigma^2 \boldsymbol{\Phi}^\top \boldsymbol{\Phi})^{-1}, \quad \mathbf{m}_N = \mathbf{S}_N (\mathbf{S}_0^{-1} \mathbf{m}_0 + \sigma^{-2} \boldsymbol{\Phi}^\top \mathbf{y})$$

(Proof of Sketch)

- From the negative-log posterior for general Gaussian prior,

$$-\log p(\boldsymbol{\theta}|\mathcal{X}, \mathcal{Y}) = \frac{1}{2\sigma^2} (\mathbf{y} - \boldsymbol{\Phi}\boldsymbol{\theta})^\top (\mathbf{y} - \boldsymbol{\Phi}\boldsymbol{\theta}) + \frac{1}{2} (\boldsymbol{\theta} - \mathbf{m}_0)^\top \mathbf{S}_0^{-1} (\boldsymbol{\theta} - \mathbf{m}_0) + \text{const}$$

$$\begin{aligned}
 &= \frac{1}{2} \left( \sigma^{-2} \mathbf{y}^T \mathbf{y} - 2\sigma^{-2} \mathbf{y}^T \Phi \boldsymbol{\theta} + \boldsymbol{\theta}^T \sigma^{-2} \Phi^T \Phi \boldsymbol{\theta} + \boldsymbol{\theta}^T \mathbf{S}_0^{-1} \boldsymbol{\theta} - 2\mathbf{m}_0^T \mathbf{S}_0^{-1} \boldsymbol{\theta} + \mathbf{m}_0^T \mathbf{S}_0^{-1} \mathbf{m}_0 \right) \\
 &= \frac{1}{2} \left( \boldsymbol{\theta}^T (\sigma^{-2} \Phi^T \Phi + \mathbf{S}_0^{-1}) \boldsymbol{\theta} - 2(\sigma^{-2} \Phi^T \mathbf{y} + \mathbf{S}_0^{-1} \mathbf{m}_0)^T \boldsymbol{\theta} \right) + \text{const}
 \end{aligned}$$

- cyan color: quadratic term, orange color: linear term
- $p(\boldsymbol{\theta}|\mathcal{X}, \mathcal{Y}) \propto \exp(\text{quadratic in } \boldsymbol{\theta}) \implies$  Gaussian distribution
- Assume that  $p(\boldsymbol{\theta}|\mathcal{X}, \mathcal{Y}) = \mathcal{N}(\boldsymbol{\theta}|\mathbf{m}_N, \mathbf{S}_N)$ , and find  $\mathbf{m}_N$  and  $\mathbf{S}_N$ .

$$\begin{aligned}
 -\log \mathcal{N}(\boldsymbol{\theta}|\mathbf{m}_N, \mathbf{S}_N) &= \frac{1}{2} (\boldsymbol{\theta} - \mathbf{m}_N)^T \mathbf{S}_N^{-1} (\boldsymbol{\theta} - \mathbf{m}_N) + \text{const} \\
 &= \frac{1}{2} \left( \boldsymbol{\theta}^T \mathbf{S}_N^{-1} \boldsymbol{\theta} - 2\mathbf{m}_N^T \mathbf{S}_N^{-1} \boldsymbol{\theta} + \mathbf{m}_N^T \mathbf{S}_N^{-1} \mathbf{m}_N \right) + \text{const}
 \end{aligned}$$

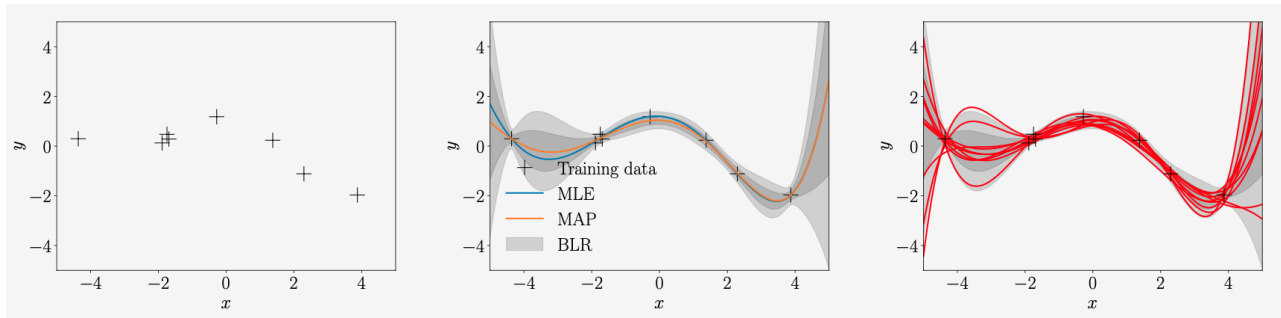
Thus,

$$\mathbf{S}_N^{-1} = \sigma^{-2} \Phi^T \Phi + \mathbf{S}_0^{-1} \quad \text{and} \quad \mathbf{m}_N^T \mathbf{S}_N^{-1} = (\sigma^{-2} \Phi^T \mathbf{y} + \mathbf{S}_0^{-1} \mathbf{m}_0^T)$$

- Posterior predictive distribution

$$\begin{aligned}
 p(y_*|\mathbf{x}_*, \mathcal{X}, \mathcal{Y}) &= \int p(y_*|\mathbf{x}_*, \boldsymbol{\theta}) p(\boldsymbol{\theta}|\mathcal{X}, \mathcal{Y}) d\boldsymbol{\theta} \\
 &= \int \mathcal{N}(y_*|\phi^T(\mathbf{x}_*)\boldsymbol{\theta}, \sigma^2) \mathcal{N}(\boldsymbol{\theta}|\mathbf{m}_N, \mathbf{S}_N) d\boldsymbol{\theta} \\
 &= \mathcal{N}(y_*|\phi^T(\mathbf{x}_*)\mathbf{m}_N, \phi^T(\mathbf{x}_*)\mathbf{S}_N\phi(\mathbf{x}_*) + \sigma^2)
 \end{aligned}$$

- The mean  $\phi^T(\mathbf{x}_*)\mathbf{m}_N$  coincides with the MAP estimate



- BLR: Bayesian Linear Regression

- Likelihood:  $p(\mathcal{Y}|\mathcal{X}, \theta)$ , **Marginal likelihood**:  $p(\mathcal{Y}|\mathcal{X}) = \int p(\mathcal{Y}|\mathcal{X}, \theta)p(\theta)d\theta$
- Recall that the marginal likelihood is important for model selection via Bayes factor:

$$(\text{Posterior odds}) = \frac{\mathbb{P}(M_1 | \mathcal{D})}{\mathbb{P}(M_2 | \mathcal{D})} = \frac{\frac{\mathbb{P}(\mathcal{D}|M_1)\mathbb{P}(M_1)}{\mathbb{P}(\mathcal{D})}}{\frac{\mathbb{P}(\mathcal{D}|M_2)\mathbb{P}(M_2)}{\mathbb{P}(\mathcal{D})}} = \underbrace{\frac{\mathbb{P}(M_1)}{\mathbb{P}(M_2)}}_{\text{Prior odds}} \underbrace{\frac{\mathbb{P}(\mathcal{D} | M_1)}{\mathbb{P}(\mathcal{D} | M_2)}}_{\text{Bayes factor}}$$

$$\begin{aligned} p(\mathcal{Y}|\mathcal{X}) &= \int p(\mathcal{Y}|\mathcal{X}, \theta)p(\theta)d\theta = \int \mathcal{N}(\mathbf{y}|\Phi\theta, \sigma^2\mathbf{I})\mathcal{N}(\theta|\mathbf{m}_0, \mathbf{S}_0) d\theta \\ &= \mathcal{N}(\mathbf{y} | \Phi\mathbf{m}_0, \Phi\mathbf{S}_0\Phi^\top + \sigma^2\mathbf{I}) \end{aligned}$$

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## ML as Orthogonal Projection

- For  $f(\mathbf{x}) = \mathbf{x}^T \boldsymbol{\theta} + \mathcal{N}(0, \sigma^2)$ ,  $\boldsymbol{\theta}_{\text{ML}} = (\mathbf{X}^T \mathbf{X})^{-1} \mathbf{X}^T \mathbf{y} = \frac{\mathbf{X}^T \mathbf{y}}{\mathbf{X}^T \mathbf{X}} \in \mathbb{R}$

$$\mathbf{X} \boldsymbol{\theta}_{\text{ML}} = \frac{\mathbf{X} \mathbf{X}^T}{\mathbf{X}^T \mathbf{X}} \mathbf{y}$$

- Orthogonal projection of  $\mathbf{y}$  onto the one-dimensional subspace spanned by  $\mathbf{X}$

- For  $f(\mathbf{x}) = \boldsymbol{\phi}^T(\mathbf{x}) \boldsymbol{\theta} + \mathcal{N}(0, \sigma^2)$ ,  $\boldsymbol{\theta}_{\text{ML}} = (\boldsymbol{\Phi}^T \boldsymbol{\Phi})^{-1} \boldsymbol{\Phi}^T \mathbf{y} = \frac{\boldsymbol{\Phi}^T \mathbf{y}}{\boldsymbol{\Phi}^T \boldsymbol{\Phi}} \in \mathbb{R}$

$$\boldsymbol{\Phi} \boldsymbol{\theta}_{\text{ML}} = \frac{\boldsymbol{\Phi} \boldsymbol{\Phi}^T}{\boldsymbol{\Phi}^T \boldsymbol{\Phi}} \mathbf{y}$$

- Orthogonal projection of  $\mathbf{y}$  onto the  $K$ -dimensional subspace spanned by columns of  $\boldsymbol{\Phi}$

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- Linear regression for Gaussian likelihood and conjugate Gaussian priors. Nice analytical results and closed forms
- Other forms of likelihoods for other applications (e.g., classification)
- GLM (generalized linear model):  $y = \sigma \circ f$  ( $\sigma$ : activation function)
  - No longer linear in  $\theta$
  - Logistic regression:  $\sigma(f) = \frac{1}{1 + \exp(-f)} \in [0, 1]$  (interpreted as the probability of becoming 1)
  - Building blocks of (deep) feedforward neural nets
  - $\mathbf{y} = \sigma(\mathbf{Ax} + \mathbf{b})$ .  $\mathbf{A}$ : weight matrix,  $\mathbf{b}$ : bias vector
  - $K$ -layer deep neural nets:  $\mathbf{x}_{k+1} = f_k(\mathbf{x}_k)$ ,  $f_k(\mathbf{x}_k) = \sigma_k(\mathbf{A}_k \mathbf{x}_k + \mathbf{b}_k)$

- Gaussian process
  - A distribution over parameters  $\rightarrow$  a distribution over functions
  - Gaussian process: distribution over functions without detouring via parameters
  - Closely related to BLR and support vector regression, also interpreted as Bayesian neural network with a single hidden layer and the infinite number of units
- Gaussian likelihood, but non-Gaussian prior
  - When  $N \ll D$  (small training data)
  - Prior that enforces sparsity, e.g., Laplace prior
  - A linear regression with the Laplace prior = linear regression with LASSO (L1 regularization)

Questions?

Review Questions

1)