

Lecture 12: Classification with Support Vector Machines

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Mathematics for Machine Learning
<https://yung-web.github.io/home/courses/mathml.html>
KAIST EE

April 7, 2021

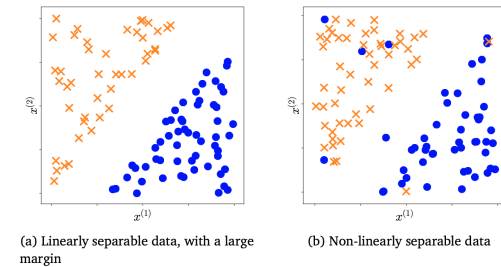
Please watch this tutorial video by Luis Serrano on Support Vector Machine.

https://youtu.be/Lpr__X8zuE8

- (1) Story and Separating Hyperplanes
- (2) Primal SVM: Hard SVM
- (3) Primal SVM: Soft SVM
- (4) Dual SVM
- (5) Kernels
- (6) Numerical Solution

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- (Binary) classification vs. regression
- A Classification predictor $f : \mathbb{R}^D \mapsto \{+1, -1\}$, where D is the dimension of features.
- Supervised learning as in the regression with a given dataset $\{(\mathbf{x}_1, y_1), \dots, (\mathbf{x}_N, y_N)\}$, where our task is to learn the model parameters which produces the smallest classification errors.
- SVM
 - Geometric way of thinking about supervised learning
 - Relying on empirical risk minimization
 - Binary classification = Drawing a separating hyperplane
 - Various interpretation from various perspectives: geometric view, loss function view, the view from convex hulls of data points



- Hard SVM: Linearly separable, and thus, allow no classification error
- Soft SVM: Non-linearly separable, thus, allow some classification error

L12(1)

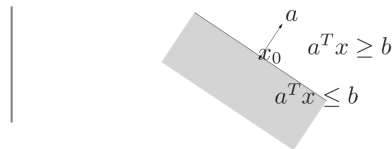
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Separating Hyperplane

- **Hyperplane** in \mathbb{R}^D is a set: $\{x \mid a^T x = b\}$ where $a \in \mathbb{R}^n, a \neq 0, b \in \mathbb{R}$ L7(3)
In other words, $\{x \mid a^T(x - x_0) = 0\}$, where x_0 is any point in the hyperplane, i.e., $a^T x_0 = b$.



- Divides \mathbb{R}^D into two **halfspaces**: $\{x \mid a^T x \leq b\}$ and $\{x \mid a^T x > b\}$
- In our problem, we consider the hyperplane $\mathbf{w}^T \mathbf{x} + b = 0$, where \mathbf{w} and b are the parameters of the model.
- Classification logic

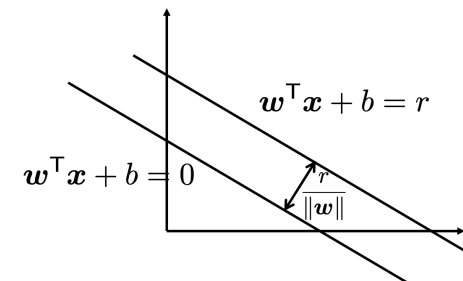
$$\begin{cases} \mathbf{w}^T \mathbf{x}_n + b \geq 0 & \text{when } y_n = +1 \\ \mathbf{w}^T \mathbf{x}_n + b < 0 & \text{when } y_n = -1 \end{cases} \implies y_n(\mathbf{w}^T \mathbf{x}_n + b) \geq 0$$

L12(1)

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Distance between Two Hyperplanes

- Consider two hyperplanes $\mathbf{w}^T \mathbf{x} - b = 0$ and $\mathbf{w}^T \mathbf{x} - b = r$, where assume $r > 0$.
- **Question**. What is the distance¹ between two hyperplanes? Answer: $\frac{r}{\|\mathbf{w}\|}$



¹Shortest distance between two hyperplanes.

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- (1) Story and Separating Hyperplanes
- (2) **Primal SVM: Hard SVM**
- (3) Primal SVM: Soft SVM
- (4) Dual SVM
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- Assume that the data points are linearly separable.
- Goal: Find the hyperplane that maximizes the margin between the positive and the negative samples
- Given the training dataset $\{(\mathbf{x}_1, y_1), \dots, (\mathbf{x}_N, y_N)\}$ and a hyperplane $\mathbf{w}^T \mathbf{x} + b = 0$, what is the constraint that all data points are $\frac{r}{\|\mathbf{w}\|}$ -away from the hyperplane?

$$y_n(\mathbf{w}^T \mathbf{x}_n + b) \geq \frac{r}{\|\mathbf{w}\|}$$

- Note that r and $\|\mathbf{w}\|$ are scaled together, so if we fix $\|\mathbf{w}\| = 1$, then

$$y_n(\mathbf{w}^T \mathbf{x}_n + b) \geq r$$

Hard SVM: Formulation 1

- Maximize the margin, such that all the training data points are well-classified into their classes (+ or -)

$$\begin{aligned} & \max_{\mathbf{w}, b, r} \quad r \\ & \text{subject to} \quad y_n(\mathbf{w}^T \mathbf{x}_n + b) \geq r, \text{ for all } n = 1, \dots, N, \quad \|\mathbf{w}\| = 1, \quad r > 0 \end{aligned}$$

Formulation 2 (1)

$$\begin{aligned} & \max_{\mathbf{w}, b, r} \quad r \\ & \text{subject to} \quad y_n(\mathbf{w}^T \mathbf{x}_n + b) \geq r, \text{ for all } n = 1, \dots, N, \quad \|\mathbf{w}\| = 1, \quad r > 0 \end{aligned}$$

- Since $\|\mathbf{w}\| = 1$, reformulate \mathbf{w} by \mathbf{w}' as: $y_n\left(\frac{\mathbf{w}'^T}{\|\mathbf{w}'\|} \mathbf{x}_n + b\right) \geq r$
- Change the objective from r to r^2 .
- Define \mathbf{w}'' and b'' by rescaling the constraint:

$$y_n\left(\frac{\mathbf{w}'^T}{\|\mathbf{w}'\|} \mathbf{x}_n + b\right) \geq r \iff y_n(\mathbf{w}''^T \mathbf{x}_n + b'') \geq 1, \quad \mathbf{w}'' = \frac{\mathbf{w}'}{\|\mathbf{w}'\| r} \text{ and } b'' = \frac{b}{r}$$

- Note that $\|\mathbf{w}''\| = \frac{1}{r}$
- Thus, we have the following reformulated problem:

$$\begin{aligned} \max_{\mathbf{w}'', b''} \quad & \frac{1}{\|\mathbf{w}''\|^2} \\ \text{subject to} \quad & y_n(\mathbf{w}''^T \mathbf{x}_n + b'') \geq 1, \text{ for all } n = 1, \dots, N, \end{aligned}$$

=

$$\begin{aligned} \min_{\mathbf{w}, b} \quad & \frac{1}{2} \|\mathbf{w}\|^2 \\ \text{subject to} \quad & y_n(\mathbf{w}^T \mathbf{x}_n + b) \geq 1, \text{ for all } n = 1, \dots, N, \end{aligned}$$

L12(2)

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- Given the training dataset $\{(\mathbf{x}_1, y_1), \dots, (\mathbf{x}_N, y_N)\}$ and a hyperplane $\mathbf{w}^T \mathbf{x} + b = 0$, what is the constraint that all data points are $\frac{r}{\|\mathbf{w}\|}$ -away from the hyperplane?

$$y_n(\mathbf{w}^T \mathbf{x}_n + b) \geq \frac{r}{\|\mathbf{w}\|}$$

- **Formulation 1.** Note that r and $\|\mathbf{w}\|$ are scaled together, so if we fix $\|\mathbf{w}\| = 1$, then

$$y_n(\mathbf{w}^T \mathbf{x}_n + b) \geq r.$$

And, maximize r .

- **Formulation 2.** If we fix $r = 1$, then

$$y_n(\mathbf{w}^T \mathbf{x}_n + b) \geq 1.$$

And, minimize $\|\mathbf{w}\|$

L12(2)

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L12(3)

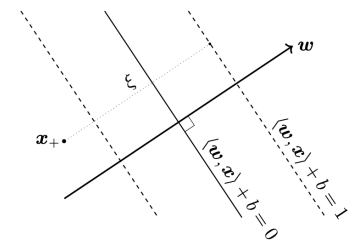
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- Now we allow some classification errors, because it's not linearly separable.
- Introduce a slack variable that quantifies how much errors will be allowed in my optimization problem

- $\xi = (\xi_n : n = 1, \dots, N)$
- ξ_n : slack for the n -th sample (\mathbf{x}_n, y_n)

$$\begin{aligned} \min_{\mathbf{w}, b} \quad & \frac{1}{2} \|\mathbf{w}\|^2 + C \sum_{n=1}^N \xi_n \\ \text{subject to} \quad & y_n(\mathbf{w}^T \mathbf{x}_n + b) \geq 1 - \xi_n, \\ & \xi_n \geq 0, \quad \text{for all } n \end{aligned}$$

- C : Trade-off between width and slack



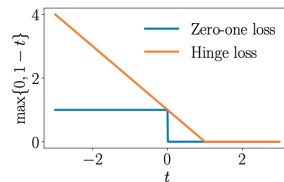
L12(3)

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- From the perspective of empirical risk minimization
- Loss function design
 - zero-one loss** $1(f(x_n) \neq y_n)$: # of mismatches between the prediction and the label
 \Rightarrow combinatorial optimization (typically NP-hard)
 - hinge loss**

$$\ell(t) = \max(0, 1 - t), \text{ where } t = yf(\mathbf{x}) = y(\mathbf{w}^T \mathbf{x} + b)$$

- If \mathbf{x} is really at the correct side, $t \geq 1$
 $\rightarrow \ell(t) = 0$
- If \mathbf{x} is at the correct side, but too close to the boundary, $0 < t < 1$
 $\rightarrow 0 < \ell(t) = 1 - t < 1$
- If \mathbf{x} is at the wrong side, $t < 0$
 $\rightarrow 1 < \ell(t) = 1 - t$



L12(3)

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$$\min_{\mathbf{w}, b} (\text{regularizer} + \text{loss}) = \min_{\mathbf{w}, b} \frac{1}{2} \|\mathbf{w}\|^2 + C \sum_{n=1}^N \max\{0, 1 - y(\mathbf{w}^T \mathbf{x} + b)\}$$

- $\frac{1}{2} \|\mathbf{w}\|^2$: L2-regularizer (margin maximization = regularization)
- C : regularization parameter, which moves from the regularization term to the loss term
- Why this loss function view = geometric view?
 $\min_t \max(0, 1 - t) \iff \min_{\xi, t} \xi, \text{ subject to } \xi \geq 0, \xi \geq 1 - t$

L12(3)

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L12(4)

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$$\min_{\mathbf{w}, b} \frac{1}{2} \|\mathbf{w}\|^2 + C \sum_{n=1}^N \xi_n$$

subject to $y_n(\mathbf{w}^T \mathbf{x}_n + b) \geq 1 - \xi_n, \xi_n \geq 0, \text{ for all } n$

- The above primal problem is a convex optimization problem.
- Let's apply Lagrange multipliers, find another formulation, and see what other nice properties are shown **L7(2), L7(4)**
- Convert the problem into " \leq " constraints, so as to apply **min-min-max** rule

$$\min_{\mathbf{w}, b} \frac{1}{2} \|\mathbf{w}\|^2 + C \sum_{n=1}^N \xi_n, \text{ s.t. } -y_n(\mathbf{w}^T \mathbf{x}_n + b) \leq -1 + \xi_n, -\xi_n \leq 0, \text{ for all } n$$

L12(4)

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$$\min_{\mathbf{w}, b} \frac{1}{2} \|\mathbf{w}\|^2 + C \sum_{n=1}^N \xi_n, \text{ s.t. } -y_n(\mathbf{w}^T \mathbf{x}_n + b) \leq -1 + \xi_n, \quad -\xi_n \leq 0, \quad \text{for all } n$$

- Lagrangian with multipliers $\alpha_n \geq 0$ and $\gamma_n \geq 0$

$$\mathcal{L}(\mathbf{w}, b, \xi, \alpha, \gamma) = \frac{1}{2} \|\mathbf{w}\|^2 + C \sum_{n=1}^N \xi_n - \sum_{n=1}^N \alpha_n [y_n(\mathbf{w}^T \mathbf{x}_n + b) - 1 + \xi_n] - \sum_{n=1}^N \gamma_n \xi_n$$

- Dual function: $\mathcal{D}(\alpha, \gamma) = \inf_{\mathbf{w}, b, \xi} \mathcal{L}(\mathbf{w}, b, \xi, \alpha, \gamma)$ for which the followings should be met:

$$(D1) \frac{\partial \mathcal{L}}{\partial \mathbf{w}} = \mathbf{w}^T - \sum_{n=1}^N \alpha_n y_n \mathbf{x}_n^T = 0, \quad (D2) \frac{\partial \mathcal{L}}{\partial b} = \sum_{n=1}^N \alpha_n y_n = 0, \quad (D3) \frac{\partial \mathcal{L}}{\partial \xi_n} = C - \alpha_n - \gamma_n = 0$$

L12(4)

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- Dual function $\mathcal{D}(\alpha, \gamma) = \inf_{\mathbf{w}, b, \xi} \mathcal{L}(\mathbf{w}, b, \xi, \alpha, \gamma)$ with (D1) is given by:

$$\begin{aligned} \mathcal{D}(\alpha, \gamma) &= \frac{1}{2} \sum_{i=1}^N \sum_{j=1}^N y_i y_j \alpha_i \alpha_j \langle \mathbf{x}_i, \mathbf{x}_j \rangle - \sum_{i=1}^N y_i \alpha_i \left\langle \sum_{j=1}^N y_j \alpha_j \mathbf{x}_j, \mathbf{x}_i \right\rangle - b \sum_{i=1}^N y_i \alpha_i \\ &\quad + \sum_{i=1}^N \alpha_i + \sum_{i=1}^N (C - \alpha_i - \gamma_i) \xi_i \end{aligned}$$

- From (D2) and (D3), the above is simplified into:

$$\mathcal{D}(\alpha, \gamma) = \frac{1}{2} \sum_{i=1}^N \sum_{j=1}^N y_i y_j \alpha_i \alpha_j \langle \mathbf{x}_i, \mathbf{x}_j \rangle + \sum_{i=1}^N \alpha_i$$

- $\alpha_i, \gamma_i \geq 0$ and $C - \alpha_i - \gamma_i = 0 \implies 0 \leq \alpha_i \leq C$

L12(4)

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- (Lagrangian) Dual Problem: maximize $\mathcal{D}(\alpha, \gamma)$

$$\begin{aligned} \min_{\alpha} \quad & \frac{1}{2} \sum_{i=1}^N \sum_{j=1}^N y_i y_j \alpha_i \alpha_j \langle \mathbf{x}_i, \mathbf{x}_j \rangle + \sum_{i=1}^N \alpha_i \\ \text{subject to} \quad & \sum_{i=1}^N y_i \alpha_i = 0, \quad 0 \leq \alpha_i \leq C, \quad \forall i = 1, \dots, N \end{aligned}$$

- Primal SVM: the number of parameters scales as the number of features (D)
- Dual SVM
 - the number of parameters scales as the number of training data (N)
 - only depends on the inner products of individual training data points $\langle \mathbf{x}_i, \mathbf{x}_j \rangle \rightarrow$ allow the application of kernel

L12(4)

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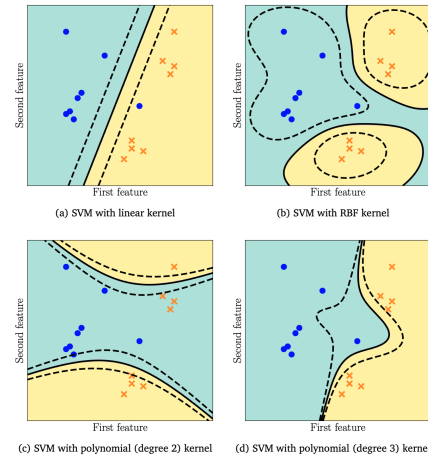
L12(5)

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- Modularity: Using the feature transformation $\phi(\mathbf{x})$, dual SVMs can be modularized

$$\langle \mathbf{x}_i, \mathbf{x}_j \rangle \implies \langle \phi(\mathbf{x}_i), \phi(\mathbf{x}_j) \rangle$$

- Similarity function $k : \mathcal{X} \times \mathcal{X} \mapsto \mathbb{R}$, $k(\mathbf{x}_i, \mathbf{x}_j) = \langle \phi(\mathbf{x}_i), \phi(\mathbf{x}_j) \rangle$
- Kernel matrix, Gram matrix: must be symmetric and positive semidefinite
- Examples: polynomial kernel, Gaussian radial basis function, rational quadratic kernel



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Questions?

1)

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