

Lecture 12: Classification with Support Vector Machines

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Mathematics for Machine Learning KAIST EE

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Please watch this tutorial video by Luis Serrano on Support Vector Machine.

https://youtu.be/Lpr__X8zuE8

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Roadmap



Roadmap



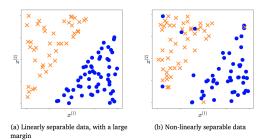
- (1) Story and Separating Hyperplanes
- (2) Primal SVM: Hard SVM
- (3) Primal SVM: Soft SVM
- (4) Dual SVM
- (5) Kernels
- (6) Numerical Solution

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- (Binary) classification vs. regression
- A Classification predictor $f: \mathbb{R}^D \mapsto \{+1, -1\}$, where D is the dimension of features.
- Suppervised learning as in the regression with a given dataset $\{(x_1, y_1), \dots, (x_N, y_N)\}$, where our task is to learn the model parameters which produces the smallest classification errors.
- SVM
 - Geometric way of thinking about supvervised learning
 - · Relying on empirical risk minimization
 - Binary classification = Drawing a separating hyperplane
 - Various interpretation from various perspectives: geometric view, loss function view, the view from convex hulls of data points

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- Hard SVM: Linearly separable, and thus, allow no classification error
- Soft SVM: Non-linearly separable, thus, allow some classification error

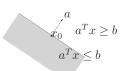
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Separating Hyperplane



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- Hyperplane in \mathbb{R}^D is a set: $\{x \mid a^\mathsf{T} x = b\}$ where $a \in \mathbb{R}^n, a \neq 0, b \in \mathbb{R}$ In other words, $\{x \mid a^\mathsf{T} (x x_0) = 0\}$, where x_0 is any point in the hyperplane, i.e., $a^\mathsf{T} x_0 = b$.
- Divides \mathbb{R}^D into two halfspaces: $\{x|a^\mathsf{T}x\leq b\}$ and $\{x|a^\mathsf{T}x>b\}$



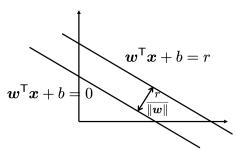
- In our problem, we consider the hyperplane $\mathbf{w}^{\mathsf{T}}\mathbf{x} + b = 0$, where \mathbf{w} and b are the parameters of the model.
- Classification logic

$$\begin{cases} \mathbf{w}^{\mathsf{T}} \mathbf{x}_n + b \geq 0 & \text{when } y_n = +1 \\ \mathbf{w}^{\mathsf{T}} \mathbf{x}_n + b < 0 & \text{when } y_n = -1 \end{cases} \implies y_n (\mathbf{w}^{\mathsf{T}} \mathbf{x}_n + b) \geq 0$$

Distance bertween Two Hyperplanes



- Consider two hyperplanes $\mathbf{w}^{\mathsf{T}}\mathbf{x} b = 0$ and $\mathbf{w}^{\mathsf{T}}\mathbf{x} b = r$, where assume r > 0.
- Question. What is the distance¹ between two hyperplanes? Answer: $\frac{r}{\|w\|}$



¹Shortested distance between two hyperplanes.

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- (1) Story and Separating Hyperplanes
- (2) Primal SVM: Hard SVM
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- Assume that the data points are linearly separable.
- Goal: Find the hyperplane that maximizes the margin between the positive and the negative samples
- Given the training dataset $\{(x_1, y_1), \dots, (x_N, y_N)\}$ and a hyperplane $\mathbf{w}^\mathsf{T} \mathbf{x} + b = 0$, what is the constraint that all data points are $\frac{r}{\|\mathbf{w}\|}$ -away from the hyperplane?

$$y_n(\mathbf{w}^\mathsf{T}\mathbf{x}_n+b)\geq \frac{r}{\|\mathbf{w}\|}$$

• Note that r and ||w|| are scaled together, so if we fix ||w|| = 1, then

$$y_n(\mathbf{w}^\mathsf{T}\mathbf{x}_n+b)\geq r$$

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Hard SVM: Formulation 1



Formulation 2 (1)



• Maximize the margin, such that all the training data points are well-classified into their classes (+ or -)

$$\max_{\boldsymbol{w},b,r} r$$
subject to $y_n(\boldsymbol{w}^{\mathsf{T}}\boldsymbol{x}_n+b) \geq r$, for all $n=1,\ldots,N$, $\|\boldsymbol{w}\|=1$, $r>0$

 $\max_{\boldsymbol{w},b,r} r$

subject to $y_n(\mathbf{w}^\mathsf{T}\mathbf{x}_n + b) \ge r$, for all n = 1, ..., N, $\|\mathbf{w}\| = 1$, r > 0

- Since $\|\mathbf{w}\| = 1$, reformulate \mathbf{w} by \mathbf{w}' as: $y_n\Big(\frac{{\mathbf{w}'}^\mathsf{T}}{\|\mathbf{w}'\|}\mathbf{x}_n + b\Big) \geq r$
- Change the objective from r to r^2 .
- Define \mathbf{w}'' and \mathbf{b}'' by rescaling the constraint:

$$y_n\Big(rac{{oldsymbol w'}^{\mathsf{T}}}{\|{oldsymbol w'}\|}{oldsymbol x}_n + b\Big) \geq r \Longleftrightarrow y_n\Big({oldsymbol w''}^{\mathsf{T}}{oldsymbol x}_n + b''\Big) \geq 1, \quad {oldsymbol w''} = rac{{oldsymbol w''}}{\|{oldsymbol w'}\|} ext{ and } b'' = rac{b}{r}$$



- Note that $\|\mathbf{w}''\| = \frac{1}{r}$
- Thus, we have the following reformulated problem:

$$\begin{aligned} & \max_{\boldsymbol{w}'',b''} & \frac{1}{\left\|\boldsymbol{w}''\right\|^2} \\ & \text{subject to} & y_n \big(\boldsymbol{w}''^\mathsf{T} \boldsymbol{x}_n + b''\big) \geq 1, \text{ for all } n = 1, \dots, N, \end{aligned}$$

=

$$\label{eq:min_wb} \begin{split} \min_{\boldsymbol{w},b} \quad & \frac{1}{2} \, \| \boldsymbol{w} \|^2 \\ \text{subject to} \quad & y_n \big(\boldsymbol{w}^\mathsf{T} \boldsymbol{x}_n + b \big) \geq 1, \text{ for all } n = 1, \dots, N, \end{split}$$

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• Given the training dataset $\{(\mathbf{x}_1, y_1), \dots, (\mathbf{x}_N, y_N)\}$ and a hyperplane $\mathbf{w}^\mathsf{T} \mathbf{x} + b = 0$, what is the constraint that all data points are $\frac{r}{\|\mathbf{w}\|}$ -away from the hyperplane?

$$y_n(\mathbf{w}^\mathsf{T}\mathbf{x}_n+b)\geq \frac{r}{\|\mathbf{w}\|}$$

• Formulation 1. Note that r and ||w|| are scaled together, so if we fix ||w|| = 1, then $y_n(\mathbf{w}^\mathsf{T} \mathbf{x}_n + b) \ge r$.

And, maximize r.

• Formulation 2. If we fix r = 1, then

$$y_n(\mathbf{w}^\mathsf{T}\mathbf{x}_n+b)\geq 1.$$

And, minimize $\| \boldsymbol{w} \|$

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Roadmap



Soft SVM: Geometric View

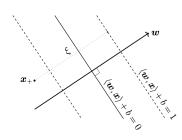


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- it 5 vivi. deometric view
- Now we allow some classification errors, because it's not linearly separable.
- Introduce a slack variable that quantifies how much errors will be allowed in my optimization problem
- $\xi = (\xi_n : n = 1, ..., N)$
- ξ_n : slack for the *n*-th sample (x_n, y_n)

$$\min_{\boldsymbol{w},b} \quad \frac{1}{2} \|\boldsymbol{w}\|^2 + C \sum_{n=1}^{N} \xi_n$$
subject to $y_n(\boldsymbol{w}^\mathsf{T} \boldsymbol{x}_n + b) \ge 1 - \xi_n$, $\xi_n > 0$, for all n

• C: Trade-off between width and slack

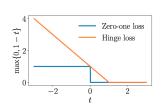




- From the perspective of empirical risk minimizaiton
- Loss function design
 - zero-one loss $1(f(x_n) \neq y_n)$: # of mismatches between the prediction and the label \implies combinatorial optimization (typically NP-hard)
 - hinge loss

$$\ell(t) = \max(0, 1 - t)$$
, where $t = yf(\mathbf{x}) = y(\mathbf{w}^\mathsf{T}\mathbf{x} + b)$

- ▶ If \mathbf{x} is really at the correct side, $t \ge 1$ $\rightarrow \ell(t) = 0$
- ▶ If x is at the correct side, but too close to the boundary, 0 < t < 1 $\rightarrow 0 < \ell(t) = 1 t < 1$
- ▶ If x is at the wrong side, t < 0 $\rightarrow 1 < \ell(t) = 1 - t$



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- $\min_{\boldsymbol{w},b} \text{ (regularizer } + \text{ loss)} = \min_{\boldsymbol{w},b} \quad \frac{1}{2} \|\boldsymbol{w}\|^2 + C \sum_{n=1}^{N} \max\{0, 1 y(\boldsymbol{w}^\mathsf{T}\boldsymbol{x} + b)\}$
- $\frac{1}{2} \| \mathbf{w} \|^2$: L2-regularizer (margin maximization = regularization)
- C: regularization parameter, which moves from the regularization term to the loss term
- Why this loss function view = geometric view? $\min_t \max(0,1-t) \Longleftrightarrow \min_{\xi,t} \xi, \text{ subject to } \xi \geq 0, \ \xi \geq 1-t$

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Roadmap

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Dual SVM: Idea



- (1) Story and Separating Hyperplanes
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- $$\begin{split} \min_{\boldsymbol{w},b} & \ \frac{1}{2} \|\boldsymbol{w}\|^2 + C \sum_{n=1}^N \xi_n \\ \text{subject to} & \ y_n \big(\boldsymbol{w}^\mathsf{T} \boldsymbol{x}_n + b \big) \geq 1 \xi_n, \ \xi_n \geq 0, \quad \text{for all } n \end{split}$$
- The above primal problem is a convex optimization problem.
- Let's apply Lagrange multipliers, find another formulation, and see what other nice properties are shown
- Convert the problem into "\le " constraints, so as to apply min-min-max rule

$$\min_{\mathbf{w},b} \ \frac{1}{2} \|\mathbf{w}\|^2 + C \sum_{n=1}^{N} \xi_n, \text{ s.t. } -y_n (\mathbf{w}^{\mathsf{T}} \mathbf{x}_n + b) \le -1 + \xi_n, \ -\xi_n \le 0, \quad \text{for all } n$$



$$\min_{\boldsymbol{w},b} \ \frac{1}{2} \|\boldsymbol{w}\|^2 + C \sum_{n=1}^{N} \xi_n, \text{ s.t. } -y_n \big(\boldsymbol{w}^\mathsf{T} \boldsymbol{x}_n + b \big) \leq -1 + \xi_n, \ -\xi_n \leq 0, \quad \text{for all } n$$

• Lagrangian with multipliers $\alpha_n \geq 0$ and $\gamma_n \geq 0$

$$\mathcal{L}(\boldsymbol{w}, b, \boldsymbol{\xi}, \boldsymbol{\alpha}, \boldsymbol{\gamma}) = \frac{1}{2} \|\boldsymbol{w}\|^2 + C \sum_{n=1}^{N} \xi_n - \sum_{n=1}^{N} \alpha_n \left[y_n (\boldsymbol{w}^\mathsf{T} \boldsymbol{x}_n + b) - 1 + \xi_n \right] - \sum_{n=1}^{N} \gamma_n \xi_n$$

• Dual function: $\mathcal{D}(\alpha, \gamma) = \inf_{\mathbf{w}, b, \xi} \mathcal{L}(\mathbf{w}, b, \xi, \alpha, \gamma)$ for which the followings should be met:

(D1)
$$\frac{\partial \mathcal{L}}{\partial \mathbf{w}} = \mathbf{w}^{\mathsf{T}} - \sum_{n=1}^{N} \alpha_n y_n \mathbf{x}_n^{\mathsf{T}} = 0$$
, (D2) $\frac{\partial \mathcal{L}}{\partial b} = \sum_{n=1}^{N} \alpha_n y_n = 0$, (D3) $\frac{\partial \mathcal{L}}{\partial \xi_n} = C - \alpha_n - \gamma_n = 0$

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• Dual function $\mathcal{D}(\alpha, \gamma) = \inf_{\mathbf{w}, b, \xi} \mathcal{L}(\mathbf{w}, b, \xi, \alpha, \gamma)$ with (D1) is given by:

$$\mathcal{D}(\boldsymbol{\alpha}, \boldsymbol{\gamma}) = \frac{1}{2} \sum_{i=1}^{N} \sum_{j=1}^{N} y_{i} y_{j} \alpha_{i} \alpha_{j} \langle \mathbf{x}_{i}, \mathbf{x}_{j} \rangle - \sum_{i=1}^{N} y_{i} \alpha_{i} \left\langle \sum_{j=1}^{N} y_{j} \alpha_{j} \mathbf{x}_{j}, \mathbf{x}_{i} \right\rangle - b \sum_{i=1}^{N} y_{i} \alpha_{i}$$

$$+ \sum_{i=1}^{N} \alpha_{i} + \sum_{i=1}^{N} (C - \alpha_{i} - \gamma_{i}) \xi_{i}$$

• From (D2) and (D3), the above is simplified into:

$$\mathcal{D}(\boldsymbol{\alpha}, \boldsymbol{\gamma}) = \frac{1}{2} \sum_{i=1}^{N} \sum_{i=1}^{N} y_i y_j \alpha_i \alpha_j \langle \mathbf{x}_i, \mathbf{x}_j \rangle + \sum_{i=1}^{N} \alpha_i$$

• $\alpha_i, \gamma_i \ge 0$ and $C - \alpha_i - \gamma_i = 0 \implies 0 \le \alpha_i \le C$

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Dual SVM

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• (Lagrangian) Dual Problem: maximize $\mathcal{D}(\alpha, \gamma)$

$$\min_{\alpha} \quad \frac{1}{2} \sum_{i=1}^{N} \sum_{j=1}^{N} y_i y_j \alpha_i \alpha_j \langle \mathbf{x}_i, \mathbf{x}_j \rangle + \sum_{i=1}^{N} \alpha_i$$

subject to $\sum_{i=1}^{N} y_i \alpha_i = 0$, $0 \le \alpha_i \le C$, $\forall i = 1, ..., N$

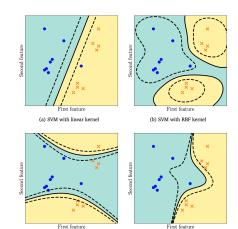
- Primal SVM: the number of parameters scales as the number of features (D)
- Dual SVM
 - \circ the number of parameters scales as the number of training data (N)
 - \circ only depends on the inner products of individual training data points $\langle \pmb{x}_i, \pmb{x}_j \rangle \to \text{allow}$ the application of kernel

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• Modularity: Using the feature transformation $\phi(\mathbf{x})$, dual SVMs can be modularized

$$\langle \mathbf{x}_i, \mathbf{x}_j \rangle \implies \langle \phi(\mathbf{x}_i), \phi(\mathbf{x}_j) \rangle$$

- Similarity function $k: \mathcal{X} \times \mathcal{X} \mapsto \mathbb{R}$, $k(\mathbf{x}_i, \mathbf{x}_j) = \langle \phi(\mathbf{x}_i), \phi(\mathbf{x}_j) \rangle$
- Kernel matrix, Gram matrix: must be symmetric and positive semidifinite
- Examples: polynomial kernel, Gaussian radial basis function, rational quadratic kernel



(c) SVM with polynomial (degree 2) kernel (d) SVM with polynomial (degree 3) kernel

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Review Questions

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Questions?

1)