

Analysis and Synthesis Sparse Representation Models for Image Modeling

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Outline

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 - Image Restoration and Enhancement
 - Synthesis & Analysis Sparsity Models
- Convolutional sparse coding for image super-resolution
 - Convolutional Sparse Coding v.s. Sparse Coding
 - The Proposed Method
- Guided Image Enhancement via Weighted Analysis Sparsity Model
 - Dependency Modeling for Guided Enhancement
 - Learning dynamic guidance for guided depth enhancement
- Ongoing and Future Works
 - Image Separation without Training Data
 - Image Restoration with Deep Denoisers
 - Optimization Inspired Network Structure Design

Introduction

Image restoration and enhancement problems

Image Denoising



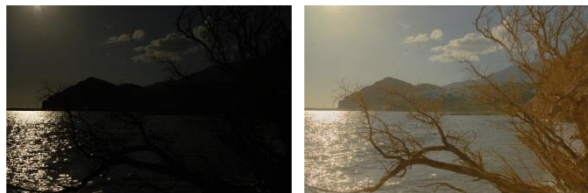
$$y = x + n$$

Image Deconvolution



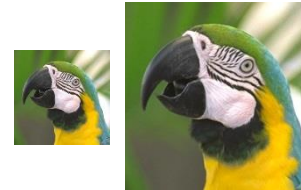
$$y = k \otimes x + n$$

Contrast Enhancement



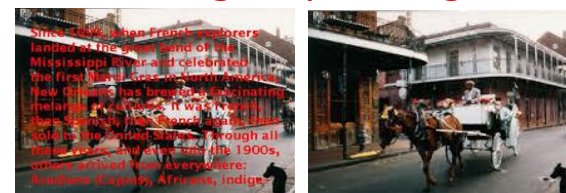
?

Image Super-resolution



$$y = D(k \otimes x) + n$$

Image Inpainting



$$y = M \odot x + n$$

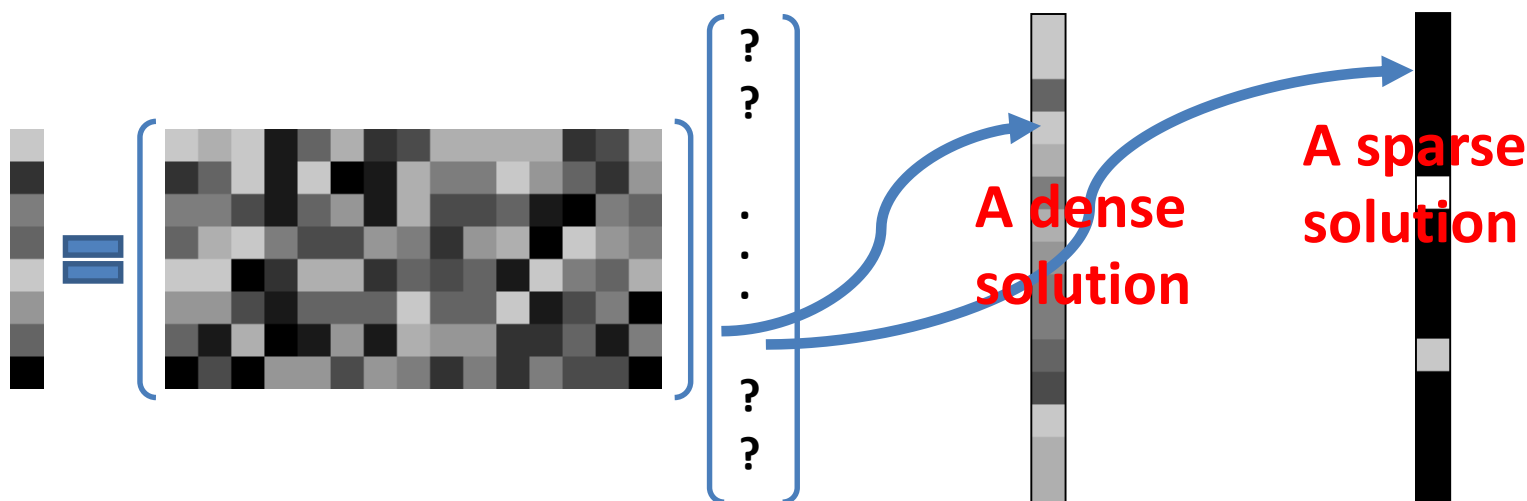
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Synthesis & Analysis sparsity models

- Synthesis representation models

Synthesis based sparse representation model assumes that a signal x can be represented as a linear combination of a **small number** of atoms chosen out of a dictionary D :

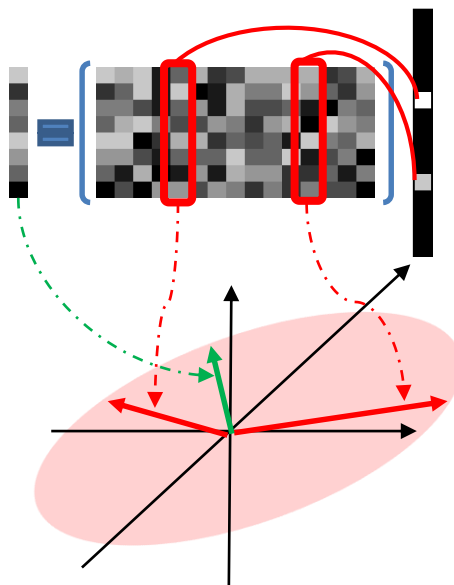
$$x = D\alpha, \text{ s.t. } \|\alpha\|_0 < \varepsilon$$



Synthesis & Analysis sparsity models

- Synthesis representation models

Synthesis based sparse representation model assumes that a signal x can be represented as a linear combination of a **small number** of atoms chosen out of a dictionary D :

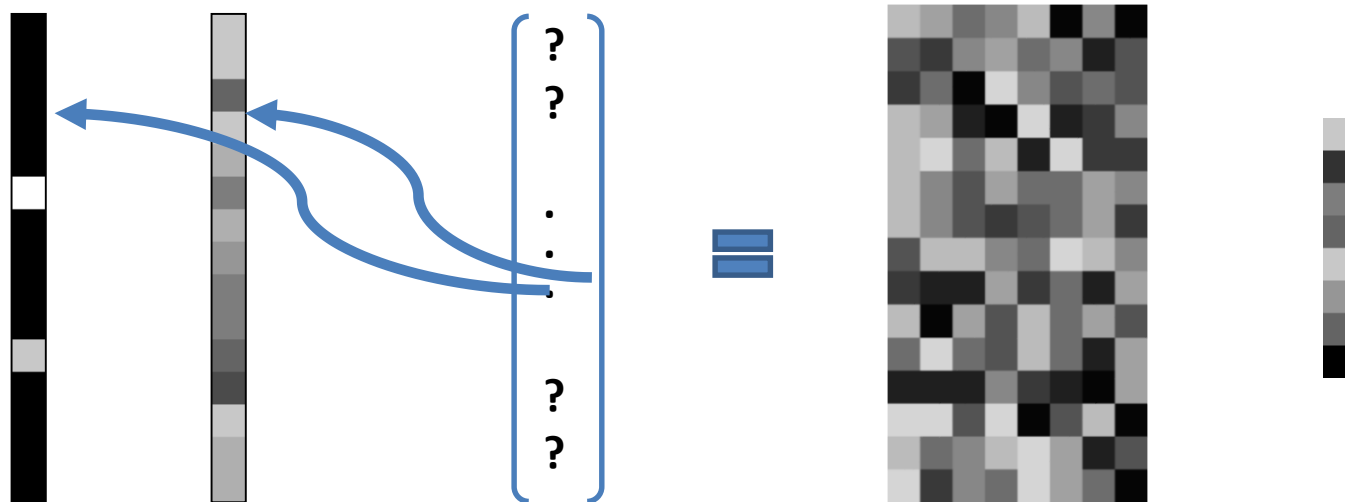


Synthesis & Analysis sparsity models

- Analysis representation models

Analysis model generate representation coefficients by a simple multiplication operation, and assumes the coefficients are sparse:

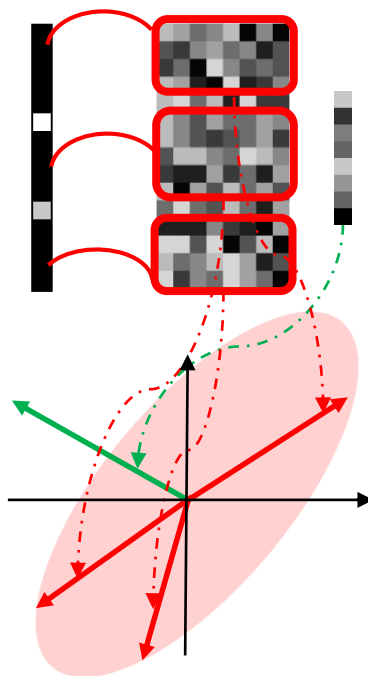
$$\|Px\|_0 < \varepsilon$$



Synthesis & Analysis sparsity models

- Analysis representation models

Analysis model generate representation coefficients by a simple multiplication operation, and assumes the coefficients are sparse:



Synthesis & Analysis sparsity models

Synthesis model

$$\min_{\alpha} \frac{1}{2} \|y - D\alpha\|_F^2 + \psi(\alpha)$$
$$x = D\alpha$$

- Representative methods
KSVD, BM3D, LSSC, NCSR, et. al.
- Pros
 - Synthesis model can be more sparse
- Cons
 - Patch prior modeling needs aggregation
 - Time consuming

Analysis model

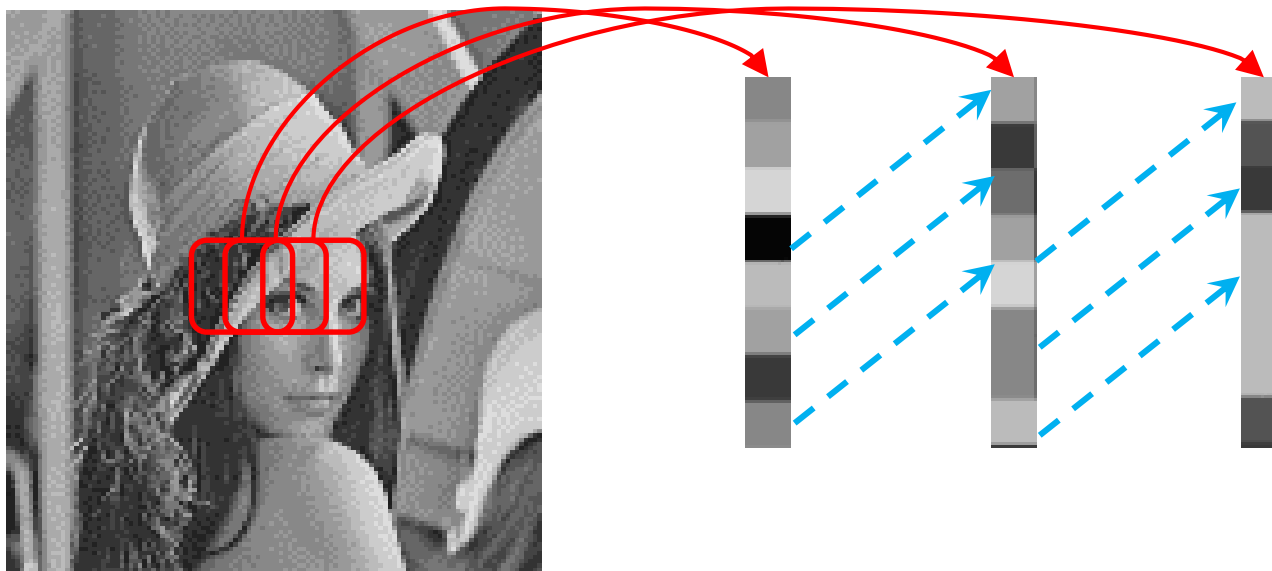
$$\min_x \frac{1}{2} \|y - x\|_F^2 + \phi(Px)$$

- Representative methods
TV, wavelet methods, FRAME, FOE, CSF, TRD et. al.
- Pros
 - Patch divide free
 - Efficient in the inference phase
- Cons
 - Not as sparse as synthesis model, limited capacity in modeling image prior.

Convolutional sparse coding for image super-resolution

Convolutional Sparse Coding v.s. Sparse Coding

Consistency constraint



Convolutional Sparse Coding v.s. Sparse Coding

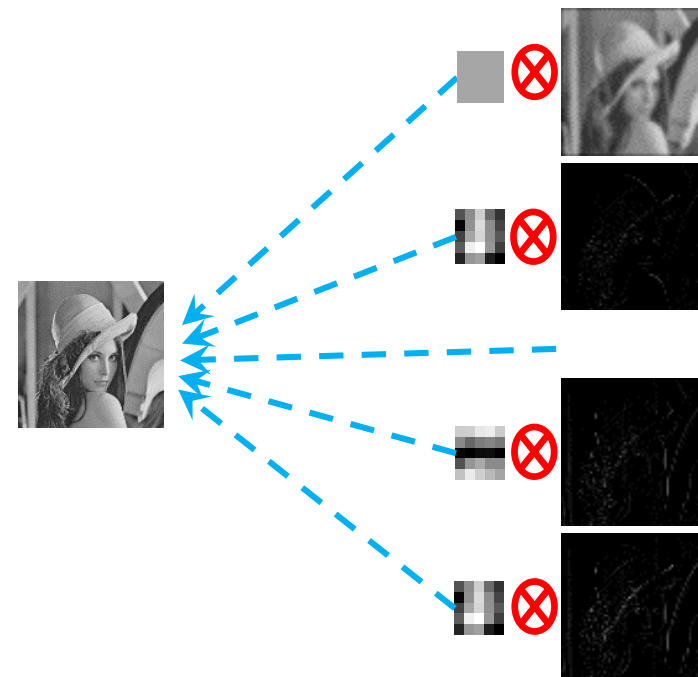
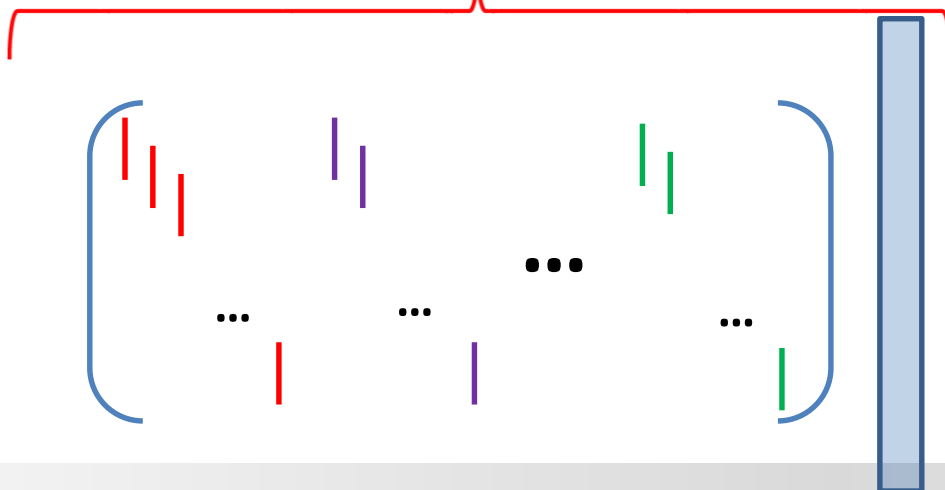
Sparse coding

$$\min_{\alpha} ||y - D\alpha||_F^2 + \phi(\alpha)$$

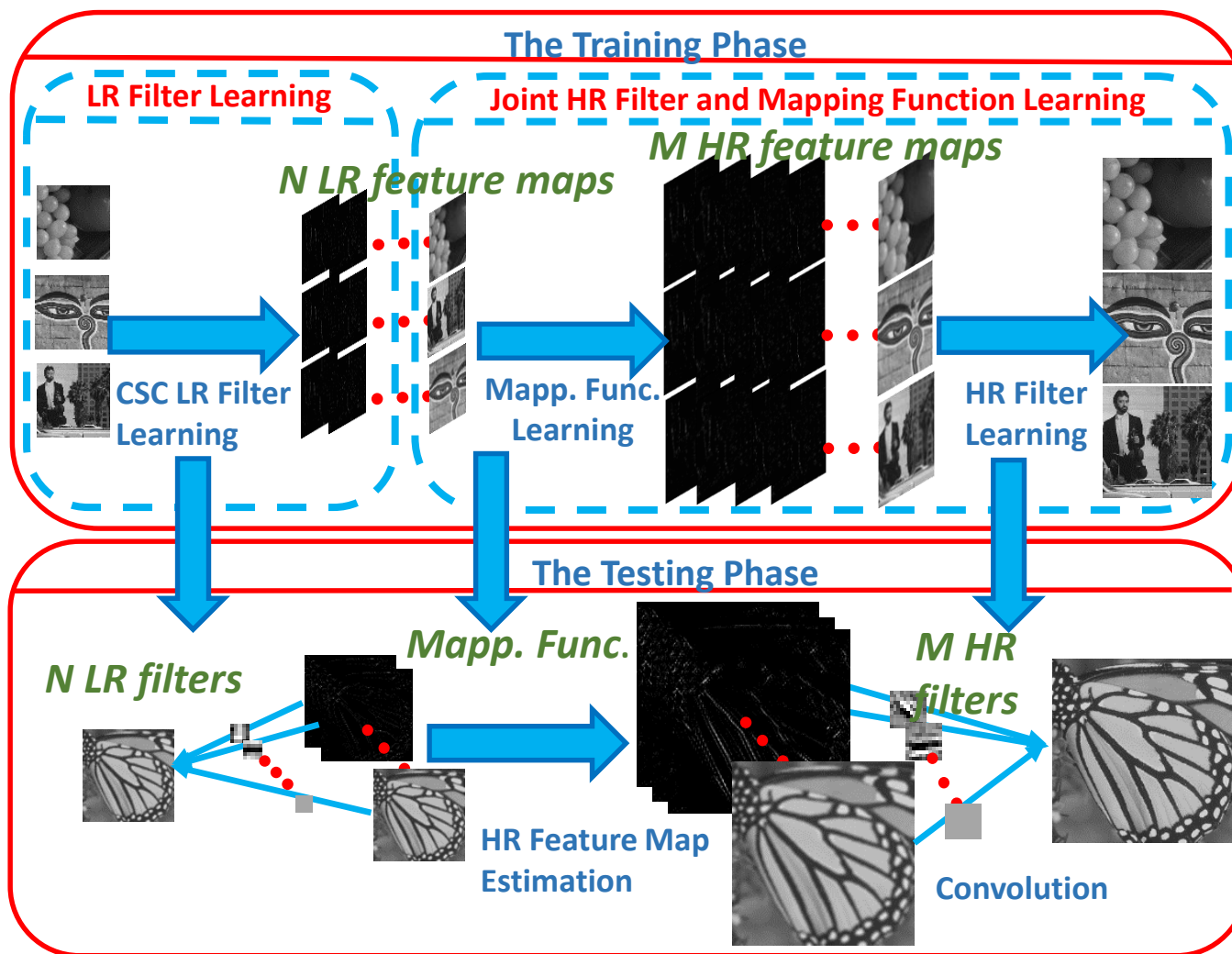
Convolutional sparse coding

$$\min_{\mathbf{z}} ||\mathbf{Y} - \sum \mathbf{f}_i \otimes \mathbf{z}_i||_F^2 + \sum \varphi(\mathbf{z}_i)$$

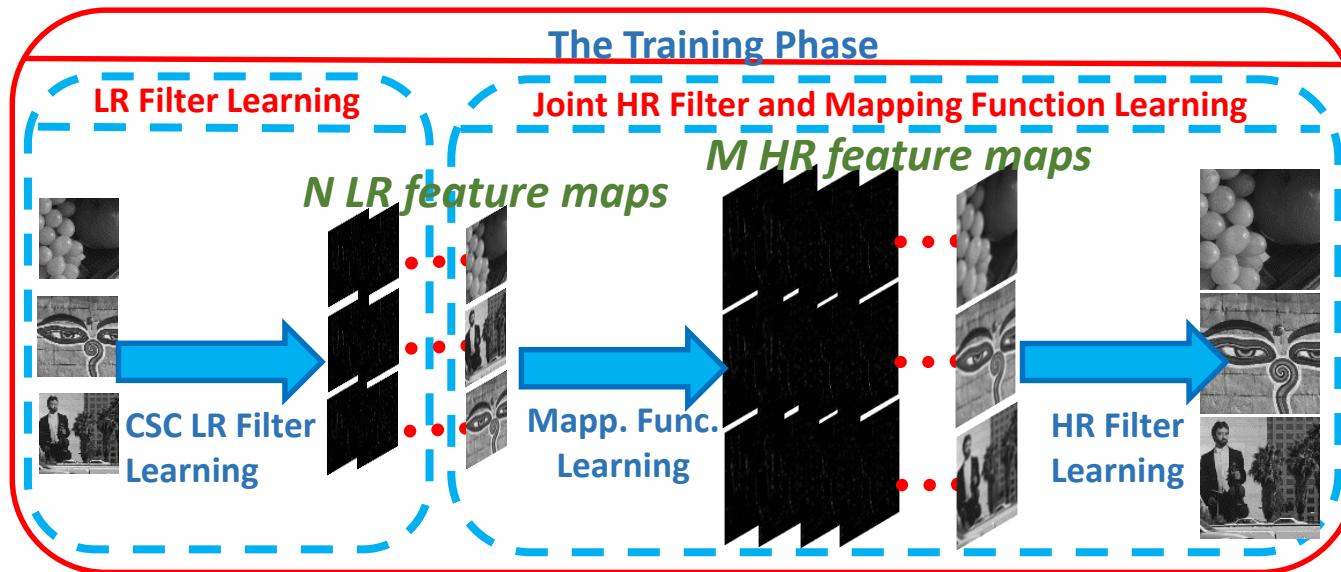
Matrix Form



Convolutional sparse coding for image SR



Convolutional sparse coding for image SR

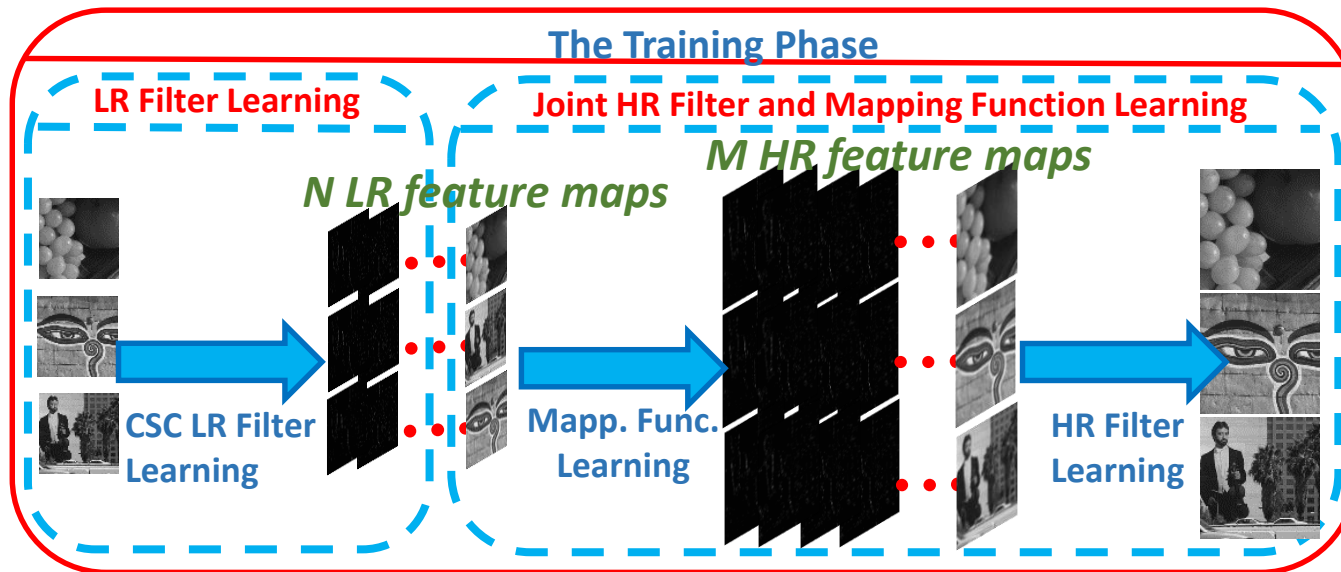


– LR filter training

$$\min_{\mathbf{Z}, \mathbf{f}} \left\| \mathbf{Y} - \sum_{i=1}^N \mathbf{f}_i^l \otimes \mathbf{Z}_i^l \right\|_F^2 + \lambda \sum_{i=1}^N \left\| \mathbf{Z}_i^l \right\|_1$$

$$s.t. \left\| \mathbf{f}_i^l \right\|_F^2 \leq 1$$

Convolutional sparse coding for image SR

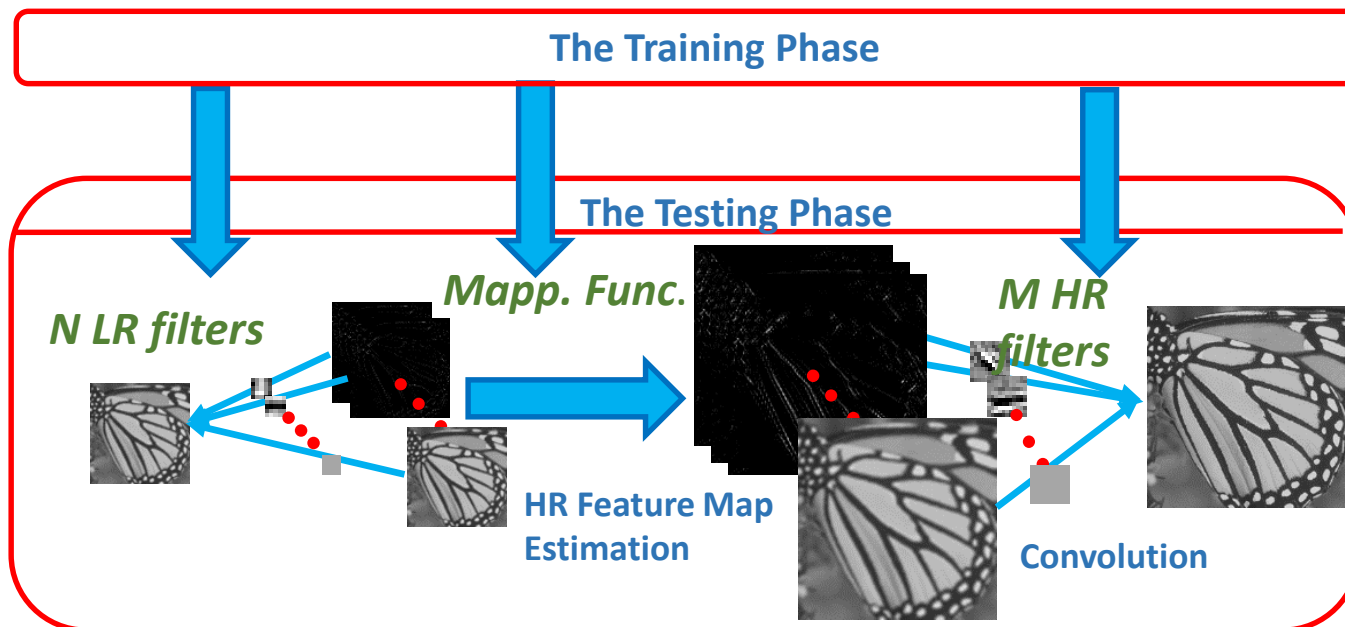


- Joint HR filter and mapping function learning

$$\{\mathbf{f}^h, \mathbf{W}\} = \min_{\mathbf{f}, \mathbf{w}} \left\| \mathbf{X} - \sum_{j=1}^M \mathbf{f}_j^h \otimes g(\mathbf{Z}^l; \mathbf{w}_j) \right\|_F^2$$

$$s.t. \quad \|\mathbf{f}_j^h\|_F^2 \leq e; \quad \mathbf{w}_j \succeq 0, |\mathbf{w}_j|_1 = 1$$

Convolutional sparse coding for image SR



Convolutional sparse coding for image SR

Optimization: SA-ADMM

$$\{\mathbf{W}\} = \arg \min_{\mathbf{W}} \sum_{k=1}^K \left\| \mathbf{X}_k - \sum_{j=1}^M \mathbf{f}_j^h \otimes g(\mathbf{Z}_{k,:}^l; \mathbf{w}_j) \right\|_F^2, \quad s.t. \quad \mathbf{w}_j \succeq 0, |\mathbf{w}_j|_1 = 1.$$

Denote by $\tilde{\mathbf{Z}}_i^l$ the upsampling of LR feature map

$$\tilde{\mathbf{Z}}_{k,i}^l(x', y') = \begin{cases} \mathbf{Z}_{k,i}^l(x, y) & \text{if } \text{mod}(x', \text{factor}) = 0 \text{ and } \text{mod}(y', \text{factor}) = 0 \\ 0 & \text{otherwise} \end{cases},$$

then we have

$$[\text{vec}(\mathbf{Z}_{k,1}^h), \text{vec}(\mathbf{Z}_{k,2}^h), \dots, \text{vec}(\mathbf{Z}_{k,M}^h)] = [\text{vec}(\tilde{\mathbf{Z}}_{k,1}^l), \text{vec}(\tilde{\mathbf{Z}}_{k,2}^l), \dots, \text{vec}(\tilde{\mathbf{Z}}_{k,N}^l)] * \mathbf{W},$$

The original problem can be write as:

$$\{\mathbf{W}\} = \sum_{k=1}^K \arg \min_{\mathbf{W}} \left\| \text{vec}(\mathbf{X}) - [\mathbf{F}_1^h, \dots, \mathbf{F}_M^h] * \begin{bmatrix} [\text{vec}(\tilde{\mathbf{Z}}_{k,1}^l), \dots, \text{vec}(\tilde{\mathbf{Z}}_{k,N}^l)] \\ \dots \\ [\text{vec}(\tilde{\mathbf{Z}}_{k,1}^l), \dots, \text{vec}(\tilde{\mathbf{Z}}_{k,N}^l)] \end{bmatrix} * \text{vec}(\mathbf{W}) \right\|_F^2$$

$s.t. \quad \mathbf{w}_j \succeq 0, |\mathbf{w}_j|_1 = 1.$

Convolutional sparse coding for image SR

Optimization: SA-ADMM

$$\{\mathbf{W}\} = \sum_{k=1}^K \arg \min_{\mathbf{W}} \|\text{vec}(\mathbf{X}) - [\mathbf{F}_1^h, \dots, \mathbf{F}_M^h] * \begin{bmatrix} [\text{vec}(\tilde{\mathbf{Z}}_{k,1}^l), \dots, \text{vec}(\tilde{\mathbf{Z}}_{k,N}^l)] \\ \dots \\ [\text{vec}(\tilde{\mathbf{Z}}_{k,1}^l), \dots, \text{vec}(\tilde{\mathbf{Z}}_{k,N}^l)] \end{bmatrix} * \text{vec}(\mathbf{W})\|_F^2$$

$s.t. \mathbf{w}_j \succeq 0, |\mathbf{w}_j|_1 = 1.$

➡
$$\{\mathbf{W}\} = \sum_{k=1}^K \arg \min_{\mathbf{W}} \|\text{vec}(\mathbf{X}) - \mathbf{A} * \text{vec}(\mathbf{W})\|_F^2 \quad s.t. \mathbf{w}_j \succeq 0, |\mathbf{w}_j|_1 = 1.$$

SA-ADMM

$$\text{vec}(\mathbf{W})_{t+1} = [L\text{vec}(\bar{\mathbf{W}})_t - \rho(\mathbf{T}_t - \mathbf{S}_t) - \frac{1}{K} \sum_{k=1}^K \mathbf{A}_k^T (\mathbf{A}_k \text{vec}(\mathbf{W}_{\tau_j(t)}) - \mathbf{X}_k)] / (\rho + L)$$

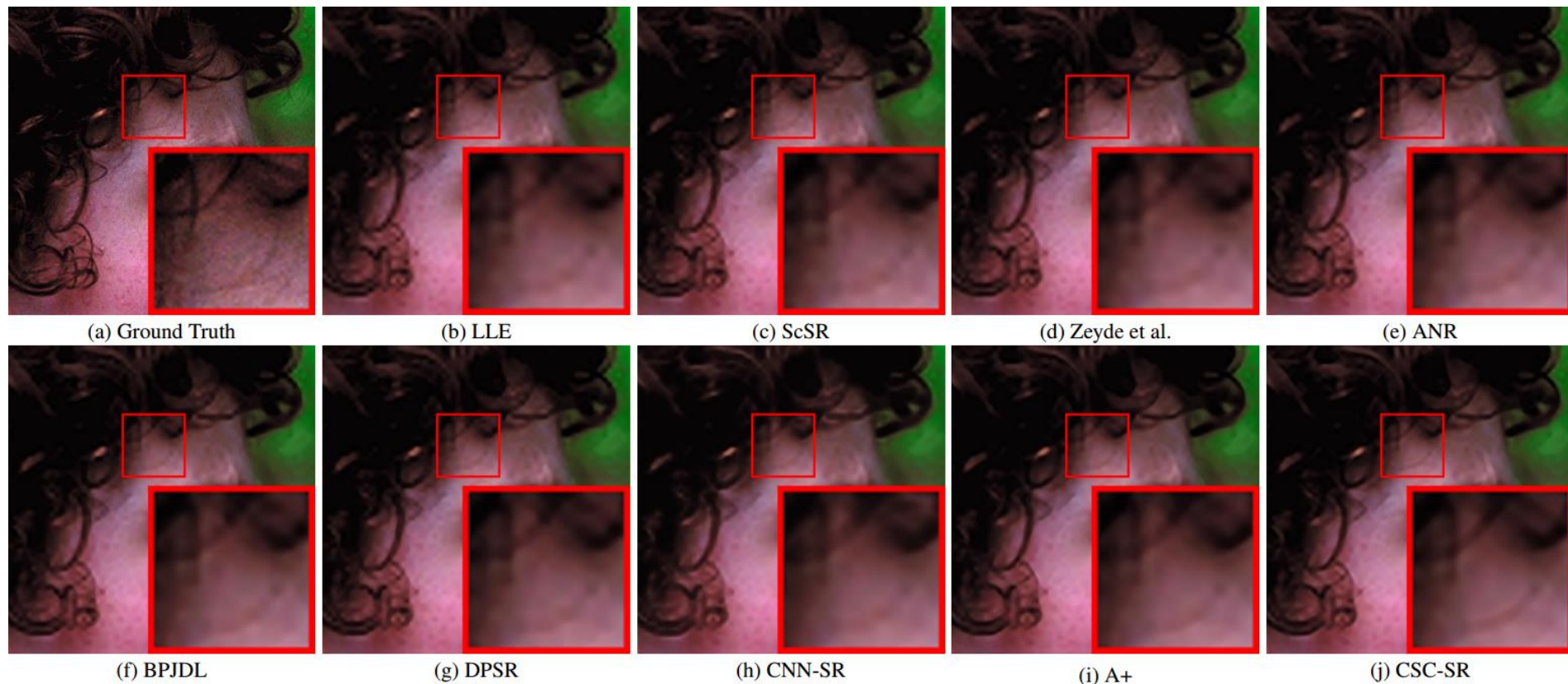
$$\mathbf{S}_{t+1} = \arg \min_{\mathbf{S}} \frac{\rho}{2} \|\mathbf{W}_{t+1} + \mathbf{T}_t - \mathbf{S}\|^2, \quad s.t. \mathbf{s}_j \succeq 0, \sum \mathbf{s}_j = 1$$

$$\mathbf{T}_{t+1} = \mathbf{T}_t + \mathbf{W}_{t+1} - \mathbf{S}_{t+1}$$

Convolutional sparse coding for image SR



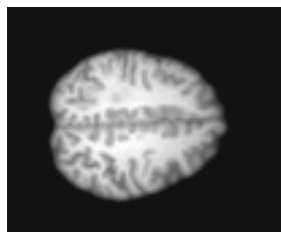
Convolutional sparse coding for image SR



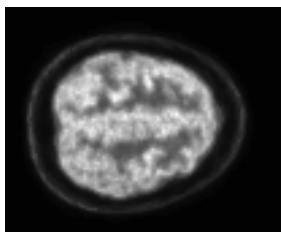
Guided Image Enhancement via Weighted Analysis Sparsity

Dependency Modeling

- Dependent image data



MRI



PET



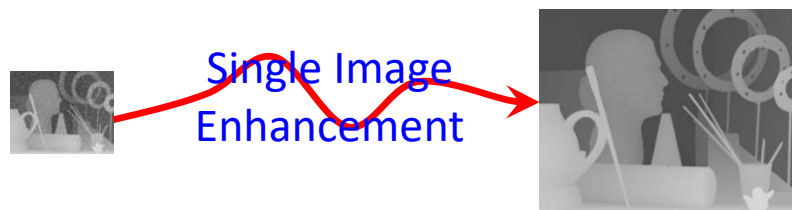
Depth



RGB

...

- Guided enhancement



Dependency Modeling

- Previous Arts
 - 1st order method: co-different

$$\sum_i \sum_{j \in S(i)} (x_i - x_j)^2 \varphi(g_i - g_j)$$

$$\sum_i \sum_{j \in S(i)} (1 - \rho(x_i - x_j)) \varphi(g_i - g_j)$$

- 2nd order method: TGV
- Other priors: Non-local mean
- Data-driven method: joint dictionary learning



Dependency Modeling

- Weighted Analysis Sparse Representation Model

$$\sum_i \sum_{j \in S(i)} (x_i - x_j)^2 \varphi(g_i - g_j)$$

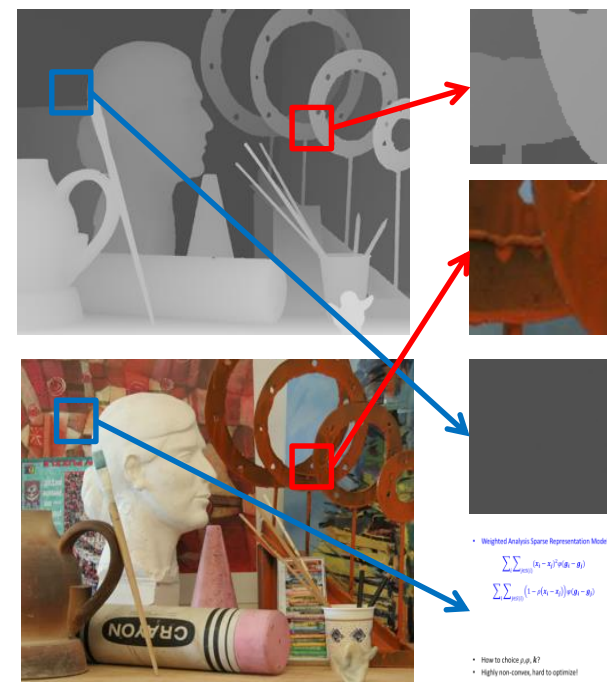
$$\sum_i \sum_{j \in S(i)} (1 - \rho(x_i - x_j)) \varphi(g_i - g_j)$$

Generalize the model: from one-order point-wise relationship to high-order local prior.



$$\hat{x} = \operatorname{argmin}_x f(x, y) + \sum \rho(k_x^i * x) \odot \varphi(k_g^i * g)$$


- How to choice ρ, φ, k ?
- Highly non-convex, hard to optimize!



Guided image enhancement via weighted analysis sparsity

- Task-driven training of stage-wise parameters
 - Solving weighted analysis sparse representation model with gradient descent, we have:

$$\hat{x} = \operatorname{argmin}_x f(x, y) + \sum \rho(k_x^i * x) \odot \varphi(k_g^i * g)$$



$$x^{t+1} = x^t - \tau \left(\Delta f(x^t, y) + \sum k_x^{iT} \rho^{i'}(k_x^i * x) \odot \varphi(k_g^i * g) \right)$$

- Stage-wise parameter training

$$\min_{k_x, k_g, \rho, \varphi} \operatorname{loss}(x^{t+1}(x^t; k_x, k_g, \rho, \varphi) - x^{gt})$$

$$\text{s.t.} \quad x^{t+1}(x^t; k_x, k_g, \rho, \varphi) = x^t - \tau \left(\Delta f(x^t, y) + \sum k_x^{iT} \rho^{i'}(k_x^i * x) \odot \varphi(k_g^i * g) \right)$$

Guided image enhancement via weighted analysis

sparsity

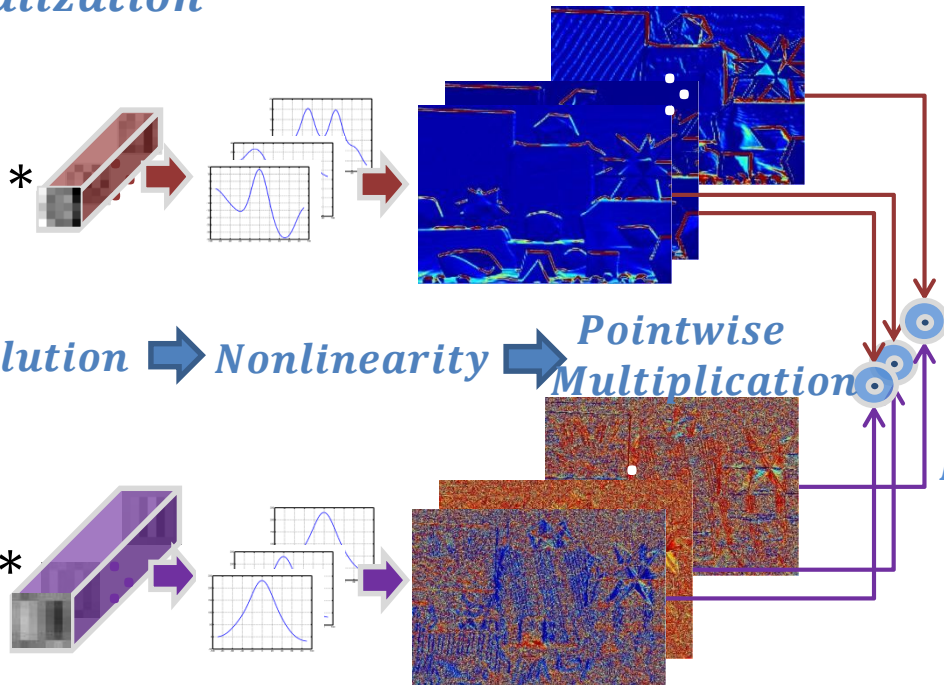
Low quality
depth map

Initialization
 x^0



High quality
color image

Convolution → **Nonlinearity** → **Pointwise Multiplication**



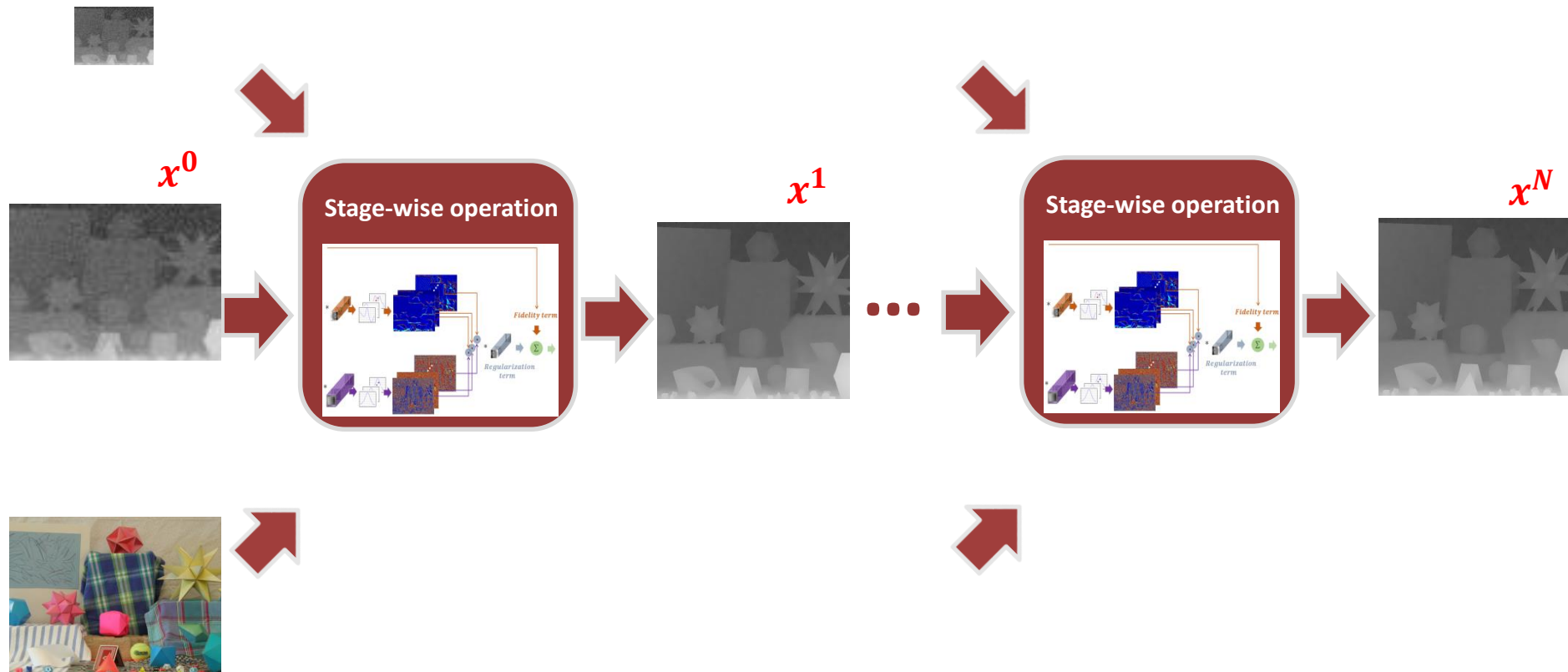
Fidelity term

x^1

Regularization term

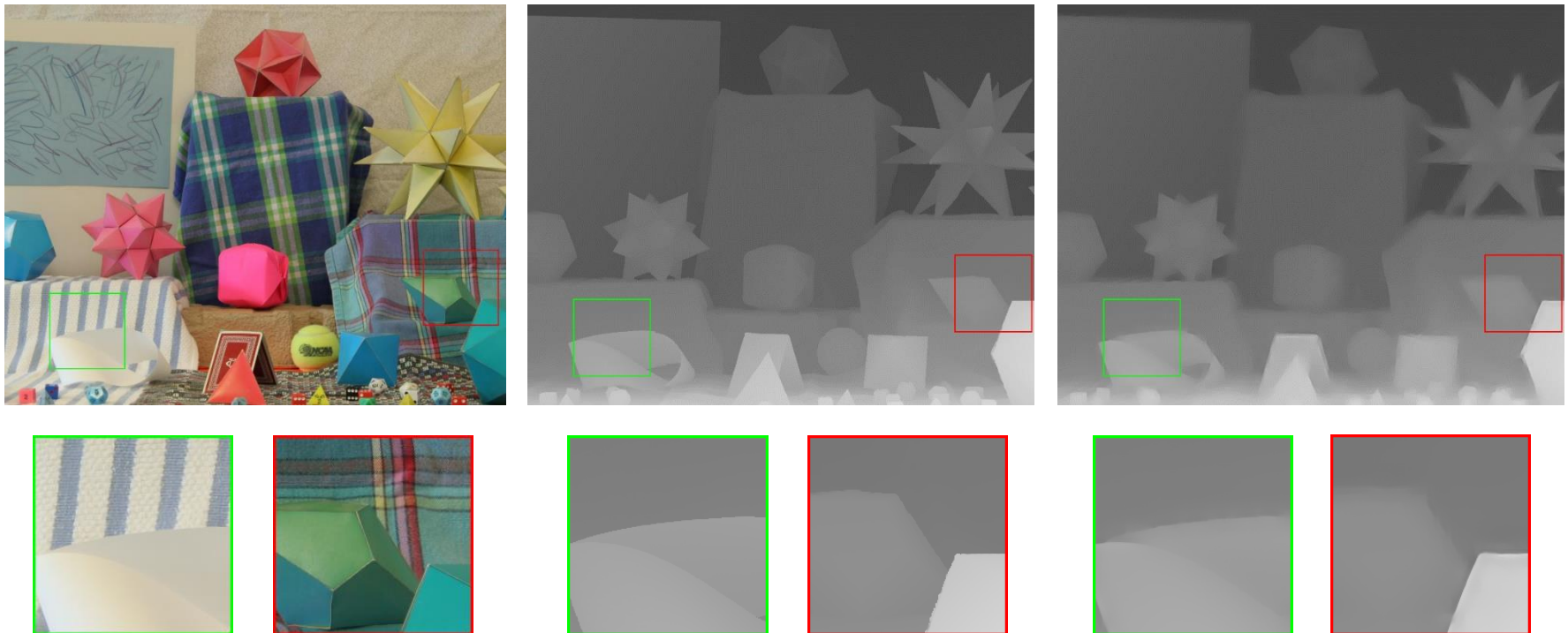
Enhanced
depth map

Guided image enhancement via weighted analysis sparsity



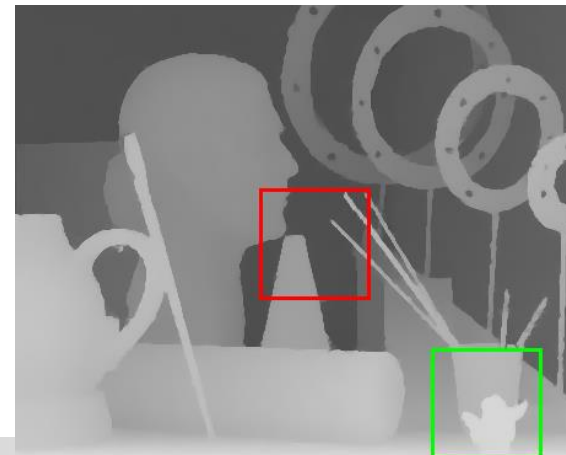
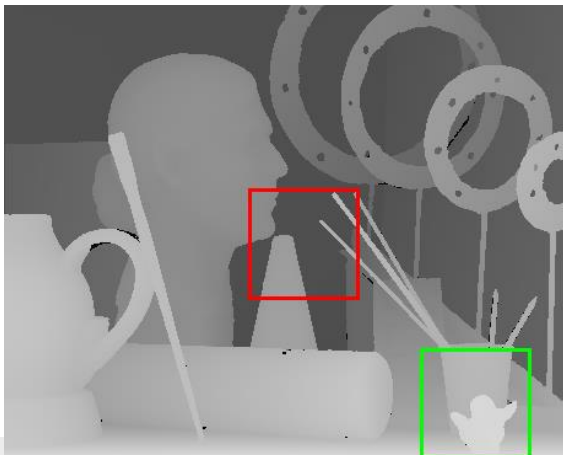
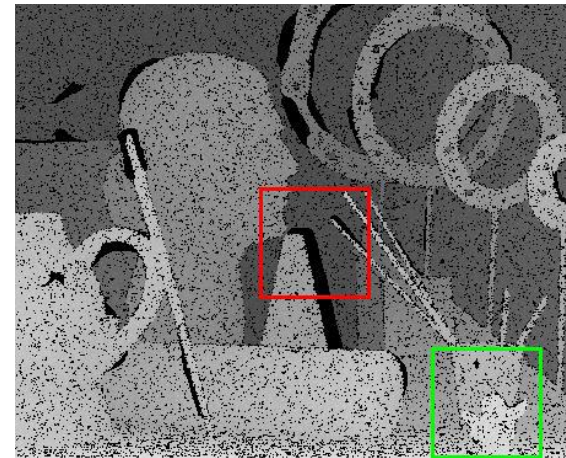
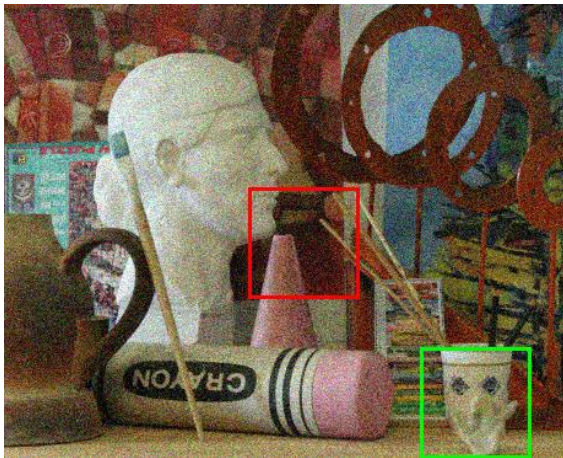
Guided Image Enhancement via Weighted Analysis Sparsity

- Experimental results



Guided Image Enhancement via Weighted Analysis Sparsity

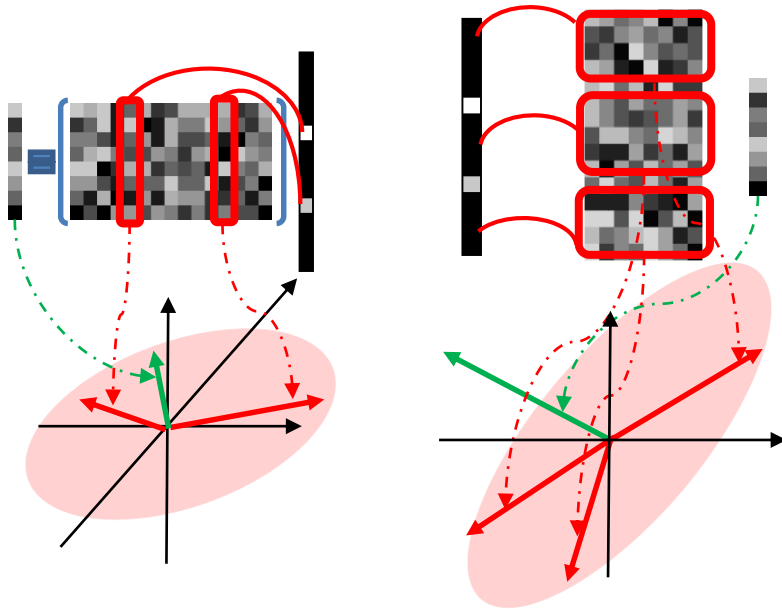
- Experimental results



Ongoing and Future Works

Image Separation without Training Data

- Complementary Property of ASR and SSR



- Layer Separation

$$\min_{u,v} f(y - u - v) + \rho_s(u) + \rho_A(v)$$



Image Restoration with Deep Denoisers

- Half Quadratic Splitting

$$\min_x f(\mathbf{y}, \mathbf{x}) + \rho(\mathbf{x})$$

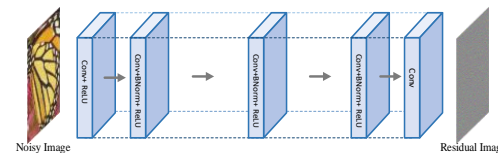
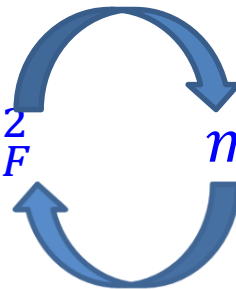
Half Quadratic Splitting



$$\min_{\mathbf{x}, \mathbf{s}} f(\mathbf{y}, \mathbf{x}) + \lambda \|\mathbf{x} - \mathbf{s}\|_F^2 + \rho(\mathbf{s})$$

$$\min_{\mathbf{x}} f(\mathbf{y}, \mathbf{x}) + \lambda \|\mathbf{x} - \mathbf{s}\|_F^2$$

$$\min_{\mathbf{s}} \lambda \|\mathbf{x} - \mathbf{s}\|_F^2 + \rho(\mathbf{s})$$



Deep Denoiser

Optimization Inspired Network Structure Design

- State-of-the-art Performance Has been Achieved by Deep Models
 - Non-blind Super-Resolution
 - Gaussian Denoising
 - Non-blind Deblur
- More Complex Restoration problems
 - Blind Deblur, SR, Denoising?

Related Publications and References

Related Publication

- **S. Gu**, W. Zuo, Q. Xie, D. Meng, X. Feng, L. Zhang. "Convolutional Sparse Coding for Image Super-resolution," In **ICCV 2015**.
- **S. Gu**, W. Zuo, S. Guo, Y. Chen, C. Chen and L. Zhang, "Learning Dynamic Guidance for Depth Image Enhancement," **To appear in CVPR 2017**.
- K. Zhang, W. Zuo, **S. Gu** and L. Zhang, "Learning Deep CNN Denoiser Prior for Image Restoration," **To appear in CVPR 2017**.
- **S. Gu**, et. al. Joint Convolutional Analysis and Synthesis Sparse Representation for Single Image Layer Separation. **Submitted**.

Related Publications and References

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Related Publications and References

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- B. Ham, M. Cho, and J. Ponce. Robust image filtering using joint static and dynamic guidance. In CVPR, 2015.
- D. Ferstl, C. Reinbacher, R. Ranftl, M. Ruther, and H. Bischof. Image guided depth upsampling using anisotropic total generalized variation. In ICCV, 2013.
- J. Park, H. Kim, Y.-W. Tai, M. S. Brown, and I. Kweon. High quality depth map upsampling for 3d-tof cameras. In ICCV, 2011.

THANKS!