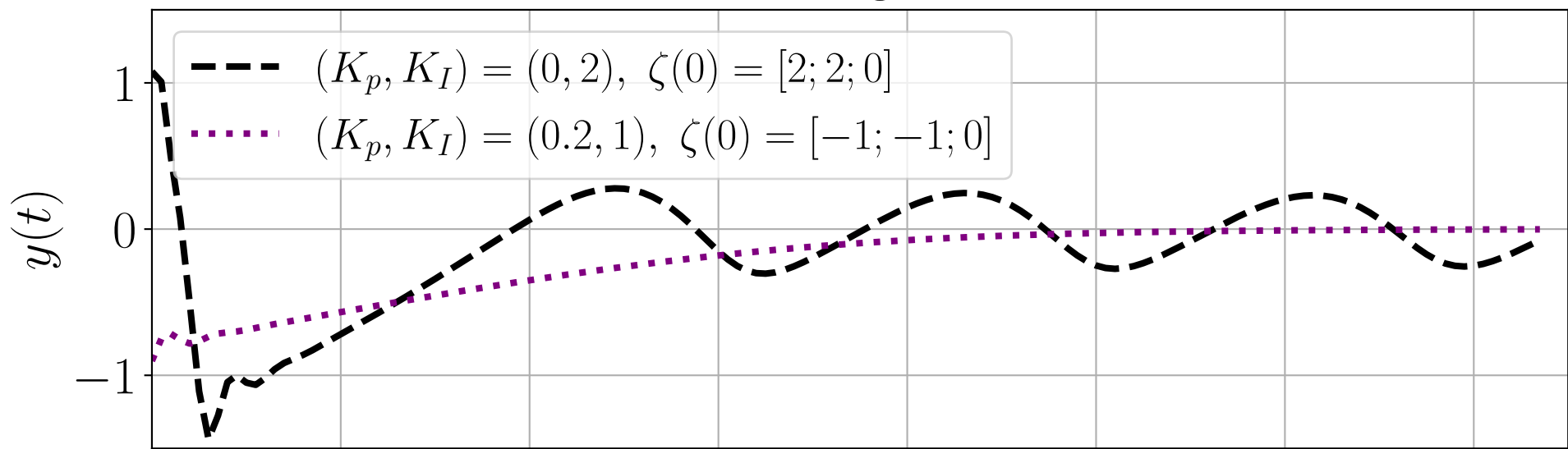
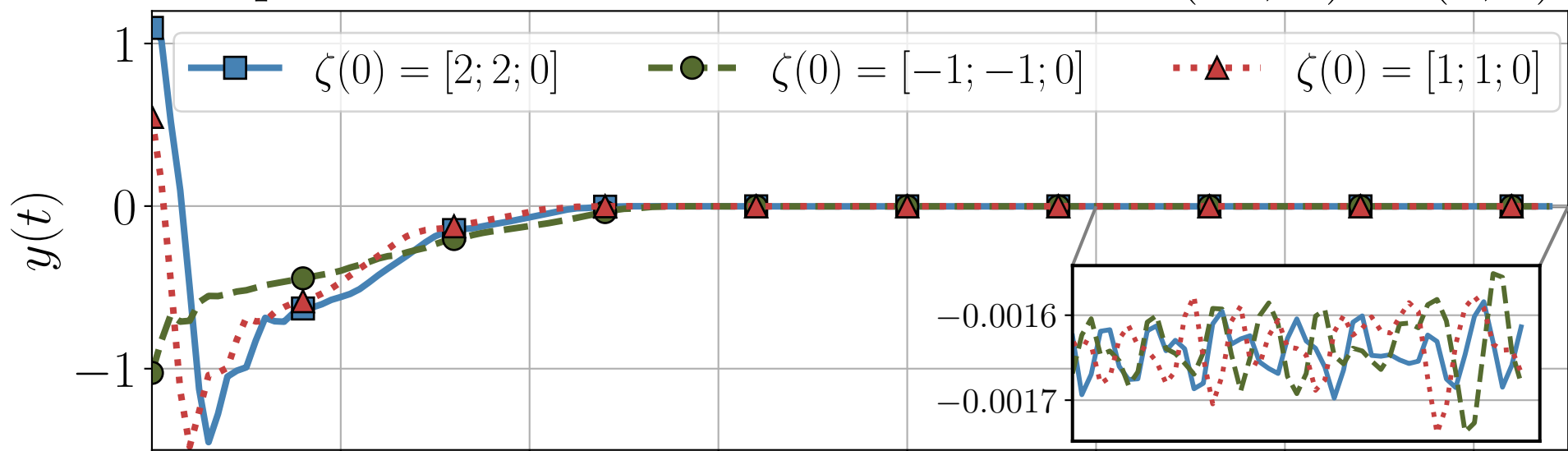


# Training Data



## Proposed Controller With Online Noise $(\sigma^d, \sigma) = (0, 0)$



## Proposed Controller Without Online Noise $(\sigma^d, \sigma) = (0, 0)$

