# **Qspice KSKelvin Symbol Explanation**

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# **Ideal Opamp**

**Qspice**: Opamp\_Ideal.qsym

#### **Ideal Operation Amplifier - Overview**

Qspice : ComptrOD\_Ideal.qsym

- Ideal Opamp Sub-Circuit
  - opamp.sub in LTspice library

\* Copyright © Linear Technology Corp. 1998, 1999, 2000. All rights reserved. subckt opamp 1 2 3

G1 0 3 2 1 {Aol}

R3 3 0 1.

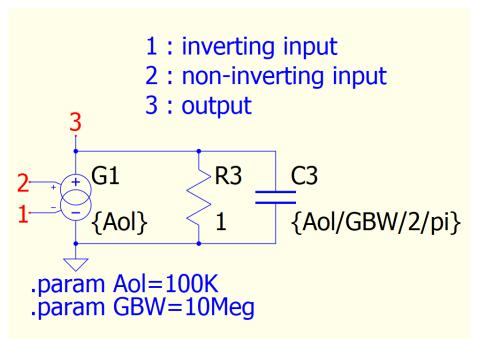
C3 3 0 {Aol/GBW/6.28318530717959}

.ends opamp

#### Opamp equivalent formula

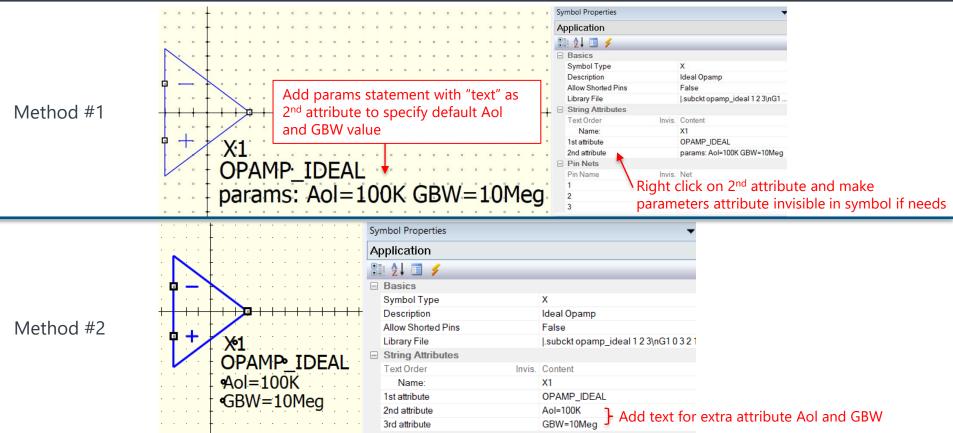
$$V_{output} = Z(R_3, C_3) \times Aol \times I_{G1}$$
  
 $V_{output} = (R_3 / / \frac{1}{j\omega C_3}) \times Aol \times (V_p - V_n)$ 

#### Opamp.sub Equivalent Schematic



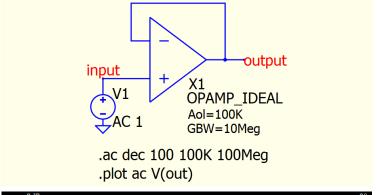
#### Ideal Operation Amplifier – Parameters of Symbol

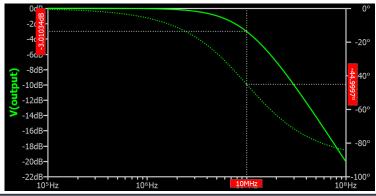
**Qspice**: ComptrOD\_Ideal.qsym



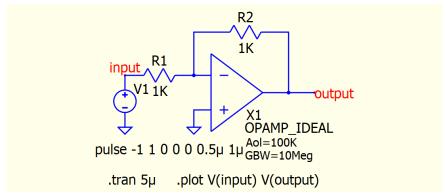
# **Ideal Operation Amplifier - Simulation Example**

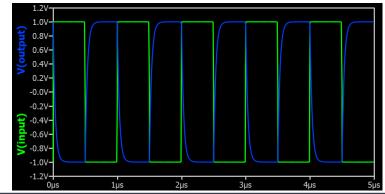
## Parent - opamp\_ideal (.ac).qsch





# Parent - opamp\_ideal (.tran).qsch





#### **Ideal Comparator**

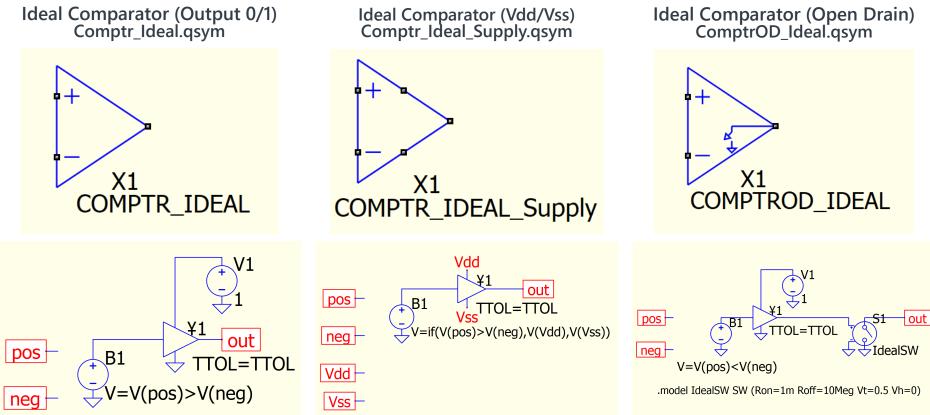
**Qspice**: Comptr\_Ideal.qsym

**Qspice**: ComptrOD\_Ideal.qsym

Qspice : Comptr\_Ideal\_Supply.qsym

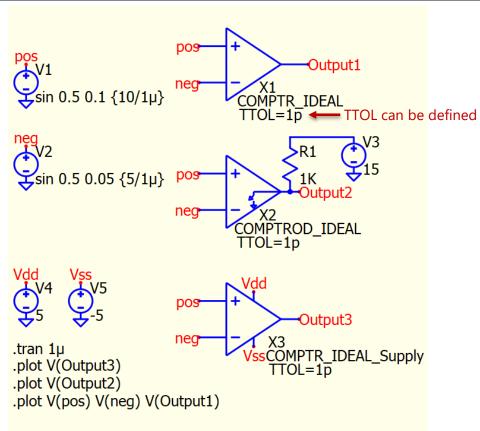
#### 3 type of Ideal Comparators Overview

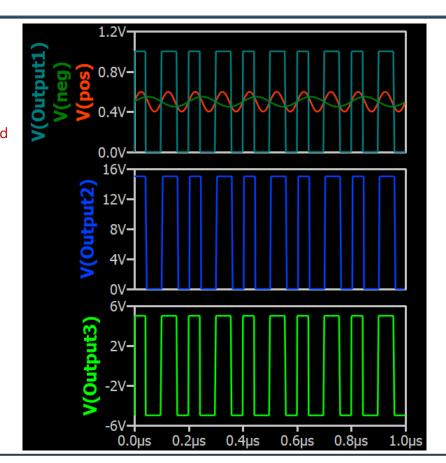
Qspice : Comptr\_Ideal.qsym / Comptr\_Ideal\_Supply.qsym / ComptrOD\_Ideal.qsym



#### 3 type of Ideal Comparators – Simulation Results

**Qspice**: Parent - Comparator.qsch





#### **Control System**

# Gain, Different, PID and Signal Limiter

**Qspice**: Gain.qsym

**Qspice**: Different.qsym

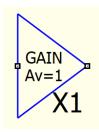
**Qspice**: PID.qsym

**Qspice**: Signal\_Limiter.qsym

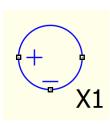
#### **Gain and Different**

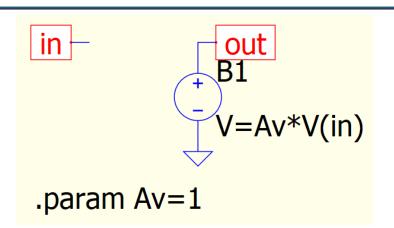
Qspice : Gain.qsym / Difference.qsym

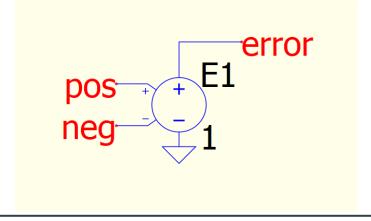
- Gain
  - $V_{out} = Av \times V_{input}$



- Difference
  - $V_{out} = V_{+} V_{-}$







## PID Controller and Signal Limiter

Qspice: PID.qsym / Signal\_Limiter.qsym

- PID Controller
  - $V_{out} = K_p V_{error} + K_i \int V_{error} dt + K_d \frac{dV_{error}}{dt}$ X1

    PID

    err

    Kp=1

    Ki=1

    Kd=1
- error

  Out

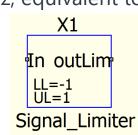
  V=Kp\*V(error)+Ki\*idt(V(error),0)+Kd\*ddt(V(error))

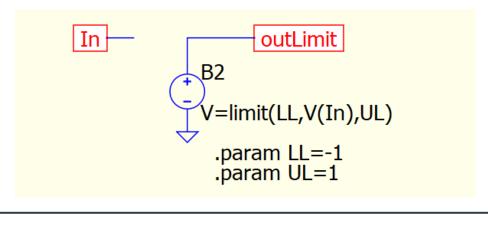
  .param Kp = 1

  .param Ki = 0

  .param Kd = 0

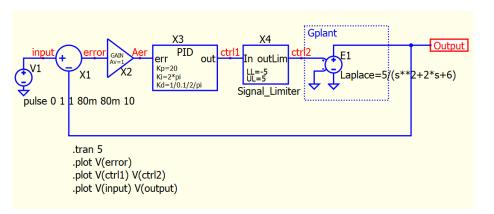
- Signal Limiter
  - limit(x,y,z) | intermediate value of x, y, and z, equivalent to min(max(x,y),z)

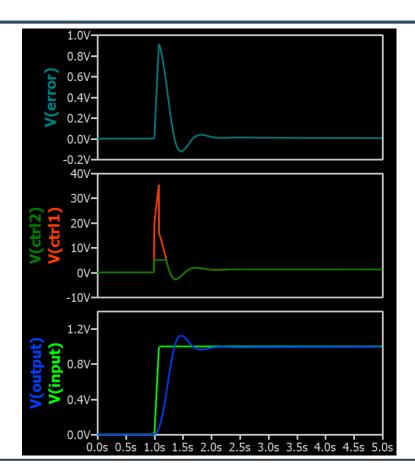


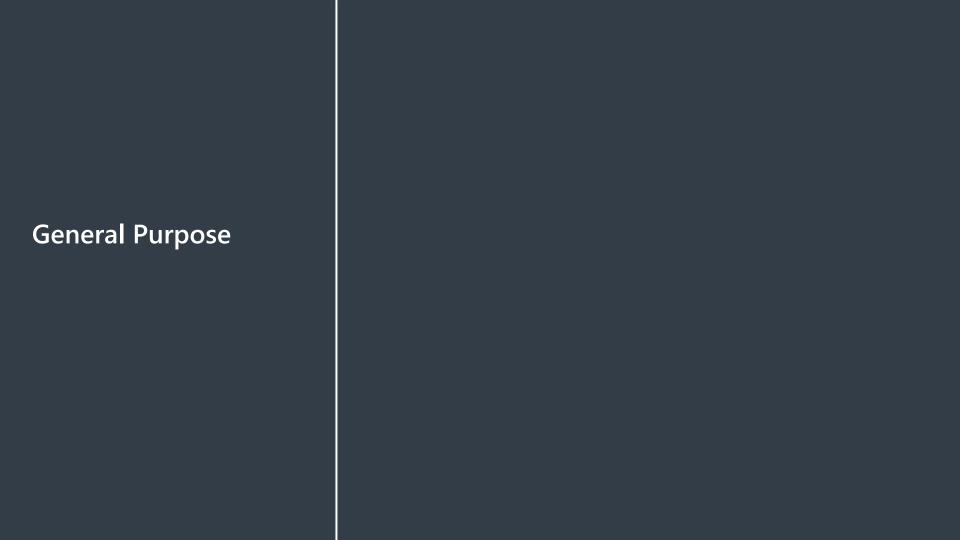


#### **Control System Symbol : Transient Simulation Example**

Parent - PID CloseLoop (.tran).qsch



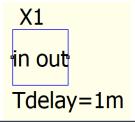


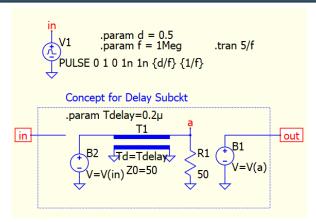


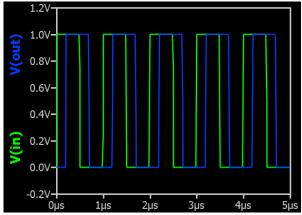
# Delay

Qspice : Delay.qsym

- Delay
  - Reason for Implementation
    - Qspice B-source not offers delay function before 09/22/2023, but after that, Mike Engelhardt implemented delay(input,time) for arbitrary behavioral sources.
  - Concept of Design
    - T1 : Td (delay) in ideal transmission line determines signal delay time
    - R1: To prevent signal reflection, transmission line must terminate with Zo
    - B1: To prevent loading effect when using delay block
  - Symbol of delay.qsym







#### **SrcXXX Special Voltage Source and Potentiometer**

**Qspice**: Scrxxxx.qsym / Potentiometer.qsym

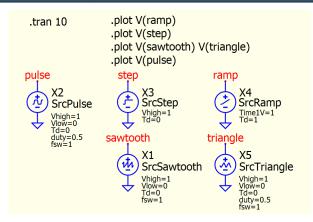
#### ScrXXX

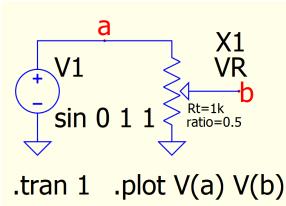
- SrcPulse.qsym
- SrcSawtooth.qsym
- SrcTriangle.qsym
- SrcStep.qsym
- SrcRamp.qsym

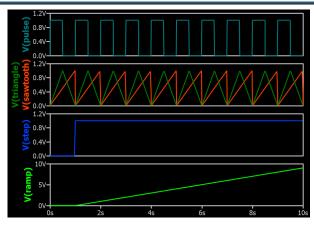
#### Potentiometer

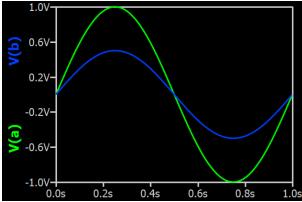
- Symbol: Potentiometer.qsym
- Ratio is limited to [1m,0.999]
- Sub-circuit script

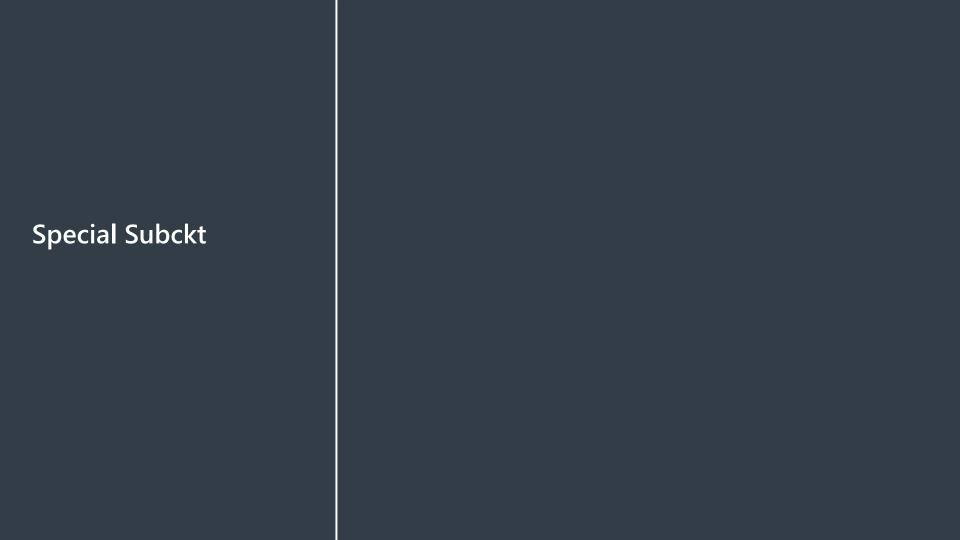
.subckt VR + - m params: Rt=1k ratio=0.5 .param w = limit(1m,ratio,0.999) R1 + m (1-w)\*Rt R2 m - (w)\*Rt .ends VR











#### **Voltage Control Current Source with Current Limit**

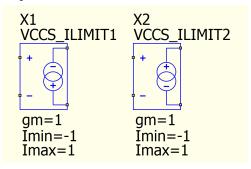
**Qspice**: VCCS\_Ilimit.qsym

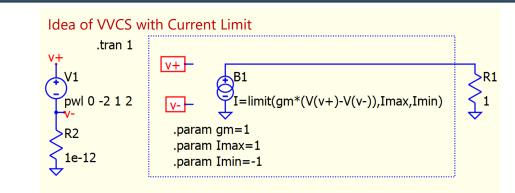
- VCCS\_Ilimit
  - Use Behavioral source with limit(x,y,z) function
    - Intermediate value of x, y, and z
  - Sub-circuit

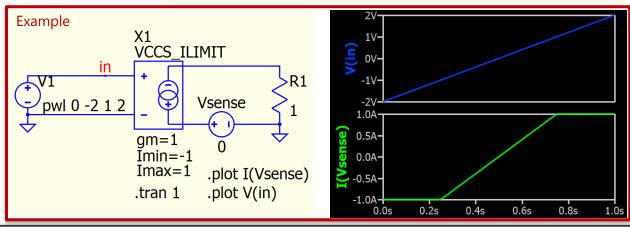
.subckt VCCS\_llimit v+ v- out+ out-B1 out- out+ l=limit(gm\*(V(v+)-V(v-)),lmax,lmin)

.ends VCCS\_Ilimit

Symbols







#### Phase Shift Pulse with Delay Control

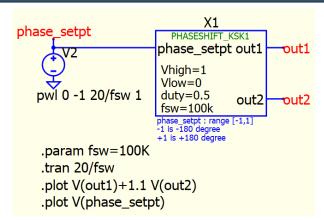
Qspice : PhaseShift\_KSK1.qsym

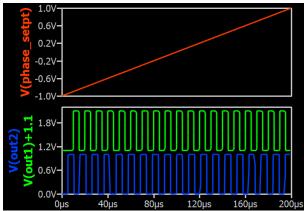
#### PhaseShift\_KSK1.qsym

- Use behavioral source with delay function to generate phase controlled pulse source
- User to define switching frequency and duty as input parameters (these cannot be change during simulation)
- Phase\_setpt is input port which control delay time in delay(), the delay is controlled with formula  $\frac{v_{phase\_setpt}}{2f_{corr}}$ 
  - A  $\frac{1}{fsw}$  is used to prevent negative y value into delay(x,y,z)
  - z set to  $2f_{sw}$  to reduce waveform memory in simulation

#### Ideal of PhaseShift\_KSK1 subckt

```
.param Vhigh=1
                          .tran 20/fsw
     .param Vlow=0
                          .plot V(out1)+1.1 V(out2)
     .param duty=0.5
                          .plot V(phase setpt)
     .param fsw=100K
      pulse Vlow Vhigh 0 0 0 duty/fsw 1/fsw
phase setpt
                           phase setpt : range [-1,1]
                           -1: -180 degree
     pwl 0 -1 20/fsw 1
                           +1: 180 degree
         =limit(V(phase_setpt),-1,1)
   out1
         =delay(V(Ref),1/fsw,2/fsw)
     =V=delay(V(Ref),1/fsw+1/fsw*V(Td)/2,2/fsw)
      delay(x,y,z) with z=2/fsw is to reduce waveform memory
```



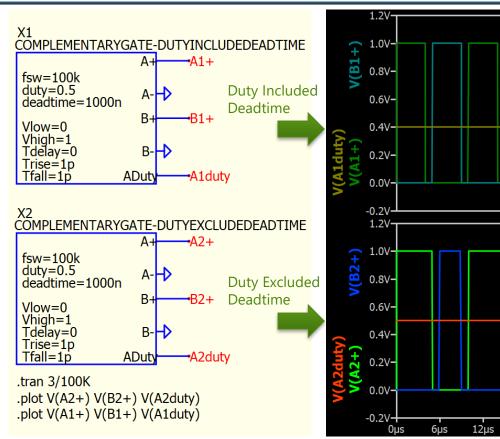


#### Complementary Gate Signal with Deadtime

 $Qspice: Complementary Gate-Duty Exclude Deadtime. qsym \mid Complementary Gate-Duty Include Deadtime. qsym \mid Complementary Gate-Duty Inc$ 

#### Complementary Gate

- To generate complementary gate signal (differential output) with deadtime
- Symbol with duty to include or exclude deadtime
  - Include Deadtime, A+ ON time is  $\frac{duty}{period}$  + deadtime
  - Exclude Deadtime, A+ ON time is  $\frac{duty}{period}$



kskelvin.net 19

18us

24µs

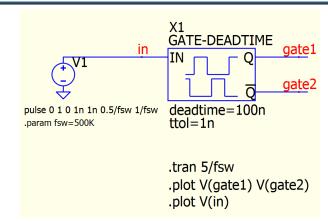
30us

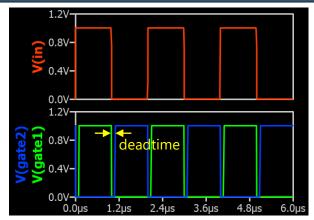
#### Complementary Gate Driver with Deadtime

**Qspice**: Gate-DeadTime.qsym

#### Complementary Driver

- Symbol
  - Gate-DeadTime.qsym
  - Gate driver with complementary output signal separated by deadtime
- Input Parameters
  - Deadtime: deadtime in second
  - TTOL: Temporal tolerance
  - (Invisible) Hi : Output High Level
  - (Invisible) Lo : Output Low Level
- \*\* beware that as deadtime is required, the ON duration of IN and Q will be different by the deadtime





# Voltage Controlled Oscillator (VCO) Behavioral Model

**Qspice**: VCO-Behavioral.qsym

- Voltage Controlled Oscillator (VCO)
  - This is a behavioral model that generates a pulsefrequency controlled output signal linearly proportional to the input
- Pin Description
  - Ctrl: control voltage to output fmin at minV and fmax at maxV
  - Duty: duty ratio ranging from 0 to 1
  - Out : oscillator output with high/low levels determined by the external voltage relative to Vdd/Vss
  - Frq: frequency value represented in voltage

